Experiment 3: Hardware Wiring and Assembly Programming using Atmel Atmega(8) AVR

Abhinav I S EE23B002

September 3, 2024

1 Objectives

- 1. Wire the microontroller with the peripherals in a breadboard.
- 2. Program the microcontroller to read the DIP switch values and display it in an LED using assembly programming.
- 3. Program the microcontroller to perform the addition and multiplication of two four-bit numbers which are read from the DIP switches connected to a port and display the result using LED's connected to another port.

2 Procedure

2.1 Blinking LED Light

2.1.1 Code

```
.include "m8def.inc"
                                                      ; mask register
    .def
                 mask
                               = r16
    .def
                 ledR.
                               = r17
                                                      ; led register
    .def
                 oLoopR
                                 = r18
                                                        ; outer loop register
    . {\tt def}
                 iLoopRl = r24
                                                ; inner loop register low
                 iLoopRh = r25
    .def
                                                ; inner loop register high
                 oVal
                               = 71
                                                     ; outer loop value
    .equ
                 iVal
                               = 1760
                                                       ; inner loop value
    .equ
    .cseg
    .org
                 0x00
                ledR
    clr
                                              ; clear led register
                mask, (1<<PINBO)
                                                 ; load 00000001 into mask register
    ldi
    out
                DDRB, mask
                                           ; set PINBO to output
start:
                ledR,mask
                                           ; toggle PINBO in led register
    eor
                PORTB, ledR
                                            ; write led register to PORTB
    out
    ldi
                oLoopR,oVal
                                             ; initialize outer loop count
oLoop:
```

```
ldi
               iLoopRl,LOW(iVal)
                                          ; intialize inner loop count in inner
    ldi
               iLoopRh,HIGH(iVal)
                                           ; loop high and low registers
iLoop:
                                    ; decrement inner loop registers
          iLoopRl,1
    sbiw
                                               ; branch to iLoop if iLoop registers != 0
    brne
                iLoop
    dec
               oLoopR
                                               ; decrement outer loop register
    brne
                oLoop
                                               ; branch to oLoop if outer loop register !=
                                               ; jump back to start
                start
    rjmp
```

1. out DDRB, mask:

DDRB is a data direction register for port B. This line sets PINB0 to output. since mask contains the bit for pin 0 set.

- 2. The above code XORs the mask register with the LED register continuously after a delay element, created by two nested loops.
- 3. the outer loop runs for 71 iterations and the inner loop runs for 1760 loops, which is implemented using a word, and we use the sbiw instruction (Subtract Immediate from Word) to decrement the inner loop variable
- 4. Calculating delay time, with instructions
 - (a) Starting from oLoop, the first two ldi instruction takes 1 clock cycle each
 - (b) The time for this loop is actually easy to calculate. We will go through the loop iVal times. Each sbiw instruction will take 2 clock cycles and the brne instruction will take 2 cycles eveytime except for the last iteration, which will only take 1.
 - (c) dec oLoopR will take 1 cycle
 - (d) brne oLoop will take 1 cycle normally, and 2 for the last iteration
 - (e) rjmp start will take 2 cycles
 - (f) eor, out, ldi takes one cycle each
 - (g) so totally, delay gets estimated to

$$outerloop count = oVal*(1+1+innerLoopCount+1+2)-1$$
 no of clock cycles = 1+1+1+outerLoopCount+2

(h) The frequency of our chip is 1Mhz,

$$total = 4 + 4 * oVal * (1 + iVal)$$
$$500000 = total$$
$$letoLoop = 71$$
$$\implies iLoop \approx 1760$$

- 5. After writing the code, compile it, copy the hex file, use Burn O Mat to burn the program onto the microcontroller.
- 6. Wire the AVR programmer accordingly, and connect the led throw a pulldown resistor to pin B0.

2.1.2 output

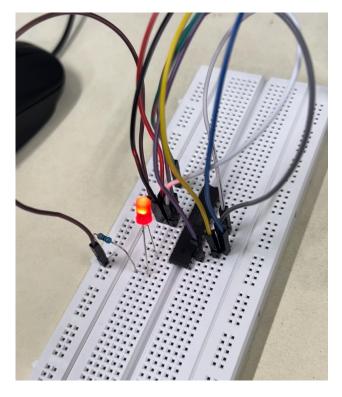


Figure 1: LED Pulse

2.2 Controlling LED using push button switch

2.2.1 Code

```
start:
        .cseg
                    0x00
        .org
        ldi r16, 0x00; load pinb0 to r16
        out DDRB,r16 ;setting it to input
check_input:
        SBIS PINB, 0;0-> switch on
        rjmp light_led
        ldi r17, 0x0
        OUT PORTD, r17
        rjmp check_input
light_led:
        ldi r16, 0xFF
        OUT DDRD, r16
        ldi r17, 0x1
        OUT PORTD, r17
```

- 1. First we set pinb0 to input.
- 2. then we check if switch is on, since is switch is pulled up to 5V when off, we have to check if it is 0 when on.
- 3. If button is pressed, go to light_led, which sets PORTD pin 0 to 1.
- 4. If button is not pressed, turn off led.
- 5. Similar to last assignment, compile the program, burn to microcontroller using Burn O Mat.
- 6. Wire the switch, pulled up to 5V to pin D0 and, ground the other side.

2.2.2 output

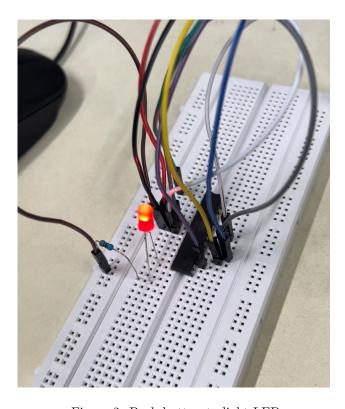


Figure 2: Push button to light LED

2.3 Adding two 4 bit numbers from DIP switch inputs

```
.include "m8def.inc"

start:

.cseg
.org 0x00

ldi r16, 0x00
out DDRB,r16 ;setting it to input
```

```
check_input:
        IN r16, PINB
        COM r16
        mov r17, r16
        mov r18, r16
        ANDI R17, OxOF
        ANDI R18, OXFO
        LSR R18
        LSR R18
        LSR R18
        LSR R18
        add r17, r18
        ldi r16, 0xFF
        OUT DDRD, r16
        OUT PORTD, r17
        rjmp check_input
```

- 1. First we set every pin in PORTB to input
- 2. In the subroutine check_input
 - (a) First we take PINB Input into register r16.
 - (b) We take complement because the switches are pulled up in OFF condition
 - (c) Copy r16 into r17 and r18
 - (d) AND R17 with 0x0F to take the 4 least significant bits
 - (e) AND R18 with 0xF0 to take the 4 most significant bits
 - (f) then we right shift R18 four times.
- 3. Then we add r17 and r18
- 4. Set portD to output
- 5. Then we copy r17 into PORTD

2.3.1 Output

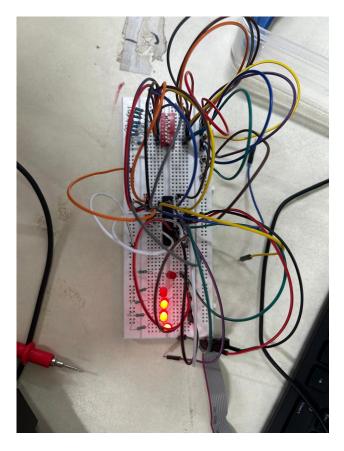


Figure 3: Adder circuit

3 My Contribution

I have written the code for all three sections, while my teammates have done majority of the wiring.