## Preliminary Single-Phase Variable-Area Results

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■ The variable-area Euler equations are [1]:

$$\frac{\partial \left( \mathcal{A} \mathbf{U} \right)}{\partial t} + \frac{\partial \left( \mathcal{A} \mathbf{F} \right)}{\partial x} = \begin{bmatrix} 0 \\ p \frac{\partial \mathcal{A}}{\partial x} \\ 0 \end{bmatrix} \tag{1}$$

where **U** and **F** are given by

$$\mathbf{U} = \begin{bmatrix} \rho \\ \rho u \\ \rho E \end{bmatrix} \qquad \mathbf{F} = \begin{bmatrix} \rho u \\ \rho u^2 + p \\ u (\rho E + p) \end{bmatrix}$$
 (2)

■ Define the change of variables  $\mathbf{V} \equiv \mathcal{A}\mathbf{U} = [V_0, V_1, V_2]^T$ , and let

$$\tilde{\mathbf{F}} \equiv \mathcal{A}\mathbf{F} = \begin{bmatrix} V_1 \\ \frac{V_1^2}{V_0} + p\mathcal{A} \\ \frac{V_1}{V_0} (V_2 + p\mathcal{A}) \end{bmatrix}$$
(3)

■ Then the variable-area equations can be written as

$$\frac{\partial \mathbf{V}}{\partial t} + \frac{\partial \tilde{\mathbf{F}}}{\partial x} = \begin{bmatrix} 0 \\ p \frac{\partial A}{\partial x} \\ 0 \end{bmatrix} \tag{4}$$

■ The weak statement, which proceeds by dotting (4) with a test function  $\mathbf{W}$  and integrating over the domain  $\Omega$ , is: find  $\mathbf{V}$  such that

$$\int_{\Omega} \left( \frac{\partial \mathbf{V}}{\partial t} \cdot \mathbf{W} - \tilde{\mathbf{F}} \cdot \frac{\partial \mathbf{W}}{\partial x} - \mathbf{S} \cdot \mathbf{W} \right) dx + \int_{\Gamma} \left( \tilde{\mathbf{F}} \cdot \mathbf{W} \right) \hat{n}_{x} ds = 0$$
(5)

holds for all admissible W, where

$$\mathbf{S} \equiv \left[0, \rho \frac{\partial \mathcal{A}}{\partial x}, 0\right]^{T} \tag{6}$$

- The analytical area function A(x) should not be used directly.
- Instead,  $\mathcal{A}$  and  $\frac{\partial \mathcal{A}}{\partial x}$  should be replaced by

$$\mathcal{A}^{h}(x) \equiv \sum_{i} \mathcal{A}(x_{i})\phi_{i}(x) \tag{7}$$

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$$\frac{\partial \mathcal{A}^{h}}{\partial x} = \sum_{i} \mathcal{A}(x_{i})\frac{\partial \phi_{i}}{\partial x} \tag{8}$$

respectively.

To motivate the quasi-linear form, consider the identities

$$\mathbf{A}\frac{\partial \mathbf{V}}{\partial x} = \mathbf{A} \left( \mathcal{A}\frac{\partial \mathbf{U}}{\partial x} + \frac{\partial \mathcal{A}}{\partial x} \mathbf{U} \right)$$
$$= \mathcal{A}\frac{\partial \mathbf{F}}{\partial x} + \frac{\partial \mathcal{A}}{\partial x} \mathbf{A} \mathbf{U}$$
(9)

$$\frac{\partial \tilde{\mathbf{F}}}{\partial x} = \mathcal{A} \frac{\partial \mathbf{F}}{\partial x} + \frac{\partial \mathcal{A}}{\partial x} \mathbf{F}$$
 (10)

where **A** is the constant-area flux Jacobian,  $\mathbf{A} \frac{\partial \mathbf{U}}{\partial x} = \frac{\partial \mathbf{F}}{\partial x}$ .

• Rearranging (9) and substituting into (10), we get

$$\frac{\partial \tilde{\mathbf{F}}}{\partial x} = \mathbf{A} \frac{\partial \mathbf{V}}{\partial x} + (\mathbf{F} - \mathbf{A}\mathbf{U}) \frac{\partial \mathcal{A}}{\partial x}$$
 (11)

■ Thus, the quasi-linear form of the governing equations reads

$$\frac{\partial \mathbf{V}}{\partial t} + \mathbf{A} \frac{\partial \mathbf{V}}{\partial x} + (\mathbf{F} - \mathbf{AU}) \frac{\partial \mathcal{A}}{\partial x} - \mathbf{S} = \mathbf{0}$$
 (12)

- We note that in the special case where F is a "homogeneous function of degree 1," we have F = AU, and the term in red vanishes.
- **F** is HFOD1 for the ideal gas equation of state, but not in general.
- The term in red also vanishes when there is no change in area.

■ For a general EOS, we have

$$\mathbf{F} - \mathbf{A}\mathbf{U} = \begin{bmatrix} 0 \\ \hat{p} \\ u\hat{p} \end{bmatrix} \tag{13}$$

where

$$\hat{p} \equiv p - \left(\frac{\partial p}{\partial U_0}, \frac{\partial p}{\partial U_1}, \frac{\partial p}{\partial U_2}\right) \cdot \mathbf{U}$$

$$= p - p_{,0}\rho - p_{,1}\rho u - p_{,2}\rho E \tag{14}$$

For an ideal gas, where

$$p = (\gamma - 1)\rho e$$
 $p_{,0} = \frac{(\gamma - 1)}{2}u^2$ 
 $p_{,1} = (\gamma - 1)(-u)$ 
 $p_{,2} = \gamma - 1$ 

it is easy to check that  $\hat{p} = 0$ .

 This implies that the SUPG formulation carries over (almost directly) from the constant-area case.

- The eigenvectors and eigenvalues are the same, so no new analysis needed.
- Of course, the strong form of the residual is slightly different...



**E.** F. Toro, Riemann solvers and numerical methods for fluid dynamics: A practical introduction, 2nd ed.

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