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# Graph and matrix algorithms for visualizing high dimensional data

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*To my Mother, Father, Professors and Friends. I owe a lot to My  
professors Ricard Gavalda and Marta Arias and to Babaji at Gurudwara*

## **Abstract**

Motivated by the problem of understanding data from the medical domain, we consider algorithms for visually representing highly dimensional data so that "similar" entities appear close together. We will study, implement and compare several algorithms based on graph and on matrix representation of the data. The first kind are known as "community detection" algorithms, the second kind as "clustering" algorithms. The implementations should be robust, scalable, and provide a visually appealing representation of the main structures in the data.

## Acknowledgement

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# Chapter 1

## Introduction

In this section an entire overview of the full project is provided. We mention the context of the project we have studied and the goal of the project. We also provide the intended planning, economic estimate and sustainability of the work that has been done.

### 1.1 Context Of the Project

In the present day scenario, the modern science of algorithms and graph theory has brought significant advances to our understanding of complex data. Many complex systems are representable in the form of graphs. Graphs have time and again been used to represent real world networks. One of the most pertinent feature of graphs representing real system is community structures or otherwise known as clusters. Community can be defined as the organization of vertices in groups or clusters, with many edges joining the vertices of the same cluster and comparatively fewer vertices joining the vertices in another neighbouring cluster. Such communities form an independent compartment of a graph exhibiting similar role. Thus, community detection is the key for understanding the structure of complex graphs, and ultimately deduce information from them.

The networks and highly dimensional data that motivate this problem emerge from the healthcare domain, and particularly from the analysis of complex, chronic disease, which is the major cost factor in modern societies. In the current scenario, a patient does not have one disease but a set of diseases. For example a person with diabetes has a heart disease, kidney



disease, high blood pressure etc. This may vary between sexes, ages etc and thus is a very complex landscape to explore. Visualizing this landscape of diseases would help to analyse the source, the treatment and even the path way of research to done. Thus, such a visualization would be helpful for the medical experts and health planner to understand the landscape of diseases much better.

Within the perspective of the LARCA project, two kinds of networks could be useful to study in this scenario: one in which nodes are patients and edges indicate their similarity, and another one in which nodes are diagnostics/diseases, and edges indicate their association in a population. Hence, we address this visualization of such high dimensional data using the algorithms and visualization technologies. LARCA has been involved in [11] . A few solutions that are possible to resolve the problem will be analysed and the best solution will be determined. The project will also involve study of various algorithms and their respective analysis based on the quality and quantity of data using multiple appropriate experiments.

## 1.2 Goal of the Project

The project is built with due recommendations from the director of the project. The project is aimed at using medical domain and thus slides to the side of faster implemenation for better visualization. Hence, there are 4 facets of goals for the project which are enumerated as below:

1. First objective of the project is to survey a few algorithms that aim in community finding keeping in mind that the input is from the medical domain
2. Next, to choose couple of algorithms that benefit the purpose of graphs from medical domain and for the purpose of visualization.
3. Implement the algorithms and test the efficiency of the algorithm using variety of graphs.
4. Lastly but more importantly to build a Graphic User Interface (GUI) which enables visualization of the raw input on a web browser.

## 1.3 Planning

Planning is essential component of any project. It helps to keep pace with the time. The total duration of the project is 5 months starting from early February 2016 to the end of June 2016. The following describes the tasks that were planned to be performed in the project.

### 1.3.0.1 Task Description

The tasks for the project have been subdivided into various task phases which are enumerated below :

- **Required knowledge acquisition**

Necessary knowledge to understand the problem needs to be gained in order to deal with the original topic. In this phase we familiarize with the term of community detection, graph theory and understand all the possible methods that are in practice to deal with the problem. Knowledge about a few visualization methods is also necessary to implement the visualization of the project.

- **Paper Analysis**

Analysis of paper related to community detection and clustering algorithms over high dimensional graph data is done in this phase of the project. This phase is necessary to understand various functionalities that the project deals with and to assist in the subsequent phases of the project.

- **Design and Implementation**

The required functionalities are listed and implemented using a programming language. In this phase the methods of the project are designed and programmed using the chosen language. The implementation is done for both the community detection algorithm and for the visualization aspect of the project.

- **Testing I**

In this phase the program is tested using generated test cases and errors are identified and corrected. Multiple recoding is done in this phase of the project. In this phase we test the program in order to identify errors in the implementation. It includes the successive recoding.

- **Testing II**

In this phase we perform tests are performed on the GUI to ensure the limits of GUI.

- **Report Writing**

In this phase the report of the project is written.

## **1.4 Economic Budget**

### **1.4.1 An Introduction to Economic Budget**

Economic management is primarily based on an estimate of income and expenditure called as budget. Development of a sustainable budget leads to proper economic management of the project. Budget and sustainability is one of the most important phase of the project management. In this phase we analyse the budget for the project. We also aim at providing an estimate of the project budget and optimize the same. We look at the expenditure from various aspects such as software costs, hardware costs, license costs and human resource costs. Additionally we also account the software for its sustainability. One important factor to note is that the budget that we describe in this section is subject to change and it may increase depending on the unexpected obstacles that we may face. For an instance when we don't get the expected results with a particular software we may have to go in for another software that may incur extra installation and operational charges.

### **1.4.2 Estimation of Economic Budget**

We divide the overall expenditure into three categories namely hardware, software and human resources. One very important factor that we need to consider is that we only get an estimate of the total cost. This may vary depending on the systems in use. To calculate the amortization we consider to factors namely, first the overall life of the hardware or software in use. Second that the project is completed in 5 months. Hence the amortization cost comes one eighth of the actual life of the component.

#### 1.4.2.1 Hardware Budget

Hardware budget accounts for the actual and the amortized costs of the hardware elements used by the project. The cost is fictitious as it has not been developed commercially. Table 1. intends to estimate the economic cost of each of the hardware component of the project.

Table 1 - Hardware Budget				
Sno:	Hardware Component	Useful Life	Total Cost(in €)	Amortized Cost(in €)
1	PC System	4	1000€	125 €
	<b>Total</b>		<b>1000€</b>	<b>125 €</b>

#### 1.4.2.2 Software Budget

The software budget shows an estimate for the various software used in the project along with the estimate of the software costs. It is a myth that the software doesn't get old with time just as a software gets but it wears out with time. Thus for every software there is a fixed time during which it gives maximum performance. In addition freeware software and open source software incur no cost. The cost is fictitious as it has not been developed commercially. Table 2 intends to estimate the economic cost of each of the software component of the project.

Table 2 - Software Budget				
Sno:	Software Component	Useful Life(in years)	Total Cost(in €)	Amortized Cost(in €)
1	Linux OS	5	0€	0 €
2	JavaScript Engine	1	0€	0 €
3	Python Components	1	0€	0 €
4	Web.py	1	0€	0 €
5	TexMaker	1	0€	0 €
	<b>Total</b>		<b>0€</b>	<b>0 €</b>

### 1.4.2.3 Human Resource Budget

The human resource budget deals with the overall expenditure spent on human resources. Every phase of the project has a cost associated with it in per hour calculation. The cost is fictitious as it has not been developed commercially. Table 3 intends to estimate the economic cost of each of the phases of the project. The cost per hour is intended as an approximation of the current cost per work hour of young analysts and developers in our environment.

Table 3 - Human Resource Budget					
Sno:	Phase	Deadline	Hours	Cost(per hour in €)	Total(in €)
1	Required Knowledge Acquisition	1 Mar 2016	70	15€/h	1050 €
2	Paper Analysis	1 Apr 2016	150	15€/h	2250 €
3	Design and Implementation	30 Apr 2016	230	20€/h	4600 €
4	Testing I	15 May 2016	75	15€/h	0 1125€
5	Testing II	31 May 2016	75	15€/h	0 1125€
6	Report Writing	15 Jun 2016	100	15€/h	1500€
	<b>Total</b>		<b>600</b>		<b>10525 €</b>

### 1.4.2.4 Total Budget

The following table, Table 4, summarizes the total budget for the project. This encompasses the hardware, software and human resources budget.

Table 4 - Total Budget		
Sno:	Resource	Total Cost(in €)
1	Hardware Budget	1000 €
2	Software Budget	0 €
3	Software Budget	10525 €
	<b>Total</b>	<b>11525 €</b>

## **1.5 Sustainability**

Sustainability is a key factor in any project design. We evaluate the project based on three factors of sustainability namely economic sustainability, social sustainability and environmental sustainability.

### **1.5.1 Economic Sustainability**

In this document we specify the budget estimation of the project. From our estimation it can be said that this will be the maximum bound on the budget for the project. This takes into account all the factors namely the hardware costs, software costs and human resource costs. The cost estimated in the project is the least possible cost and hence is a nonpareil project estimate for any indistinguishable project. The budget may exceed our calculations only during unexpected times. When the proposed plan is precisely followed the estimated lower costs gets achieved. Also the product that we aim at developing here is tested with all kinds of data and we aim at building a very high quality software which in turn provides a durable software that will not wear out easily. Most of the software used in the project is open source which has zero product cost. The hardware required is nothing but computers that becomes a mandatory part of any project in the present days.

### **1.5.2 Social Sustainability**

The project aims at developing web based platform to perform learning cum visualization analytics. This is indirectly going to analyze the learning characteristics of the patients and provide a feedback both to the medical analyzer and health planner. This is going to improve the quality of health analysis in the state. All this requires is a simple computer connected to the internet. This has very keen social motive and this project when completed is going to improve the standard of learning in schools. Thus this has a great social responsibility. This in turn justifies why this project has a great social sustainability.

### **1.5.3 Environmental Sustainability**

From the sections of temporal planning and the budget planning we understand that we have a computer running throughout the project. If we make

an assumption that the amount of energy used by a single computer comes to around 250 watts. And given that we spend 500 hours on the project then the energy expended is 125KW. This amounts to 48.125 kg of  $CO_2$  . This is indeed a high amount but well within the permissible limits. This can be reduced by reducing the code size which is possible by reusing the already existing code. But the project is actually environmentally sustainable.

# Chapter 2

## Background Knowledge

### 2.1 Introduction

In this section we present the background knowledge required to understand and solve the problem

#### 2.1.1 Graph Notation

##### 2.1.1.1 Graph Definition

Graph  $G$ , is construct consisting of two finite sets, the set  $V = \{v_1, v_2, \dots, v_n\}$  of vertices and the set  $E = \{e_1, e_2, \dots, e_n\}$  of edges where each edge is a pair of vertices from  $V$ , for instance,

$$e_i = (v_j, v_k)$$

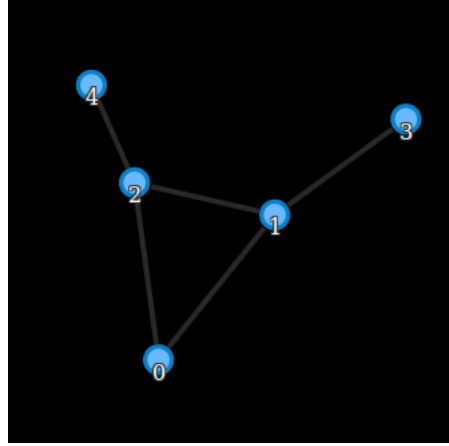
is an edge from  $v_j$  to  $v_k$  represented as  $G=(V,E)$ . In other words  $E \subset V^2$ , which is the set of all unordered. The vertices  $(v_j$  and  $v_k)$  that represent an edge are called *endpoints* and the edge is said to be adjacent to each of its end points. The definition has been framed accordint to the book on An "Introduction to Formal Languages and Automata" [6]

The neighbourhood of a node  $v_i$  is the set of nodes  $v_i$  is connected to,  $N(v_i) = \{v_j | (v_i, v_j) \in E, v_i \neq v_j, 1 \leq j \leq n\}$ . The degree of a node  $v_i$ , or the size of the neighbourhood connected to  $v_i$ , is denoted as  $d(v_i) = |N(v_i)|$ .

A degree sequence,  $D$ , specifies the set of all node degrees as tuples, such that  $D = (v_i, d(v_i))$  and follows a probability distribution called the *degree distribution* with mean  $d_m$ . [9]



Figure 2.1: Example Graph  $G=(V,E)$  Bull Graph



### 2.1.2 Graph Matrix Notation

Graphs can be appropriately represented in the form of matrices for instance, adjacency matrix, admittance matrix etc.,

Let  $G=(V,E)$  be a simple graph with vertex set  $\mathbf{V}$  and edge set  $\mathbf{E}$ , then the adjacency matrix is square  $|V|^2$  matrix  $\mathbf{M}$  such that its element  $M_{i,j}$  is 1 when there is an edge from  $v_i$  to  $v_j$ , where  $v_i \in \mathbf{V}$ ,  $v_j \in \mathbf{V}$  and 0 when there is no edge. The adjacency matrix of a graph of order  $n$  entitles the entire the topology of a graph. The diagonal elements of the adjacency matrix are all 0 for undirected graphs  $\mathbf{M}$ .

The sum of the elements of  $i$ -th row or column yields the degree of node  $i$ . If the edges are weighted, one defines the weight matrix  $\mathbf{W}$ , whose element  $W_{ij}$  expresses the weight of the edges between vertices  $i$  and  $j$ .

The *spectrum* of a graph  $\mathbf{G}$  is the set of eigenvalues of it's adjacency matrix  $\mathbf{M}$ . If  $\mathbf{D}$  is the diagonal matrix whose element  $D_{i,i}$  equals the degree of vertex  $i$  ( $v_i \in V$ ).

### 2.1.3 Approaches

In this section we discuss the various approaches that are involved in dealing with the input to the project for community identification, for clustering and for visualization purposes.

### **2.1.3.1 For Community Identification**

Virtually in every scientific field dealing with empirical data, primary approach to get a first impression on the data is by trying to identify groups having "similar" behaviour in data. There are numerous methods to achieve this objective of which

- Community Detection
- Clustering

#### **2.1.3.1.1 Community Detection**

**2.1.3.1.2 Definition of a Community** Communities are a part of the graph that has fewer ties with the rest of the system. Community detection traditionally focuses on the graph structure while clustering algorithms focus on node attributes.

Several types of community detection algorithms can be distinguished

**2.1.3.1.3 Divisive algorithms** Divisive algorithms detect inter-community links and remove them from the network

**2.1.3.1.4 Agglomerative algorithms** Agglomerative algorithm merges similar nodes or communities in a recursive manner.

**2.1.3.1.5 Optimization Methods** Optimization methods are mainly based on maximization of an objective function.

#### **2.1.3.2 Clustering**

According to the paper "Community detection in graph" [4] there are 4 major traditional clustering methods namely :

- Graph Partitioning
- Hierarchical Clustering
- Partitional Clustering
- Spectral Clustering

**2.1.3.2.1 Graph Partitioning** This problem deals with dividing graph into groups of predefined size such that the number of edges between the groups is minimized. The paper [4] also defines cut size as the number of edges lying between the clusters. Figure 2.2 shows a problem with 14 vertices and presents a solution for splitting into 2 groups.

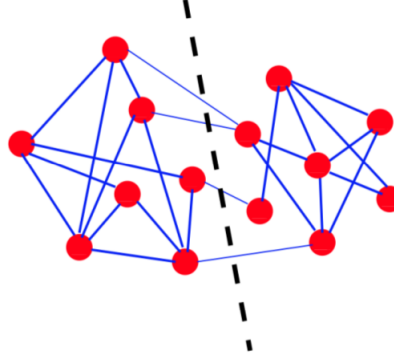


Figure 2.2: Graph Partitioning [4]

*Minimum Bisection Problem*, is a special problem case that considers partitioning the network into 2 groups of equal size. This problem is an NP-Hard problem. Intuitively, to obtain full partitioning we need to iteratively find all the minimum partition. This is not of significant use in the current problem of finding communities.

**2.1.3.2.2 Hierarchical Clustering** Hierarchical clustering aims to identify groups of vertices with high similarities. It can be classified into two categories:

1. *Agglomerative algorithm* : in one in which Agglomerative algorithms, in which clusters are iteratively merged if their similarity is sufficiently high
2. *Divisive algorithms*, in which clusters are iteratively split by removing edges connecting vertices with low similarity. The figure 2.3 demonstrates the hierarchical clustering in a diagrammatic manner.

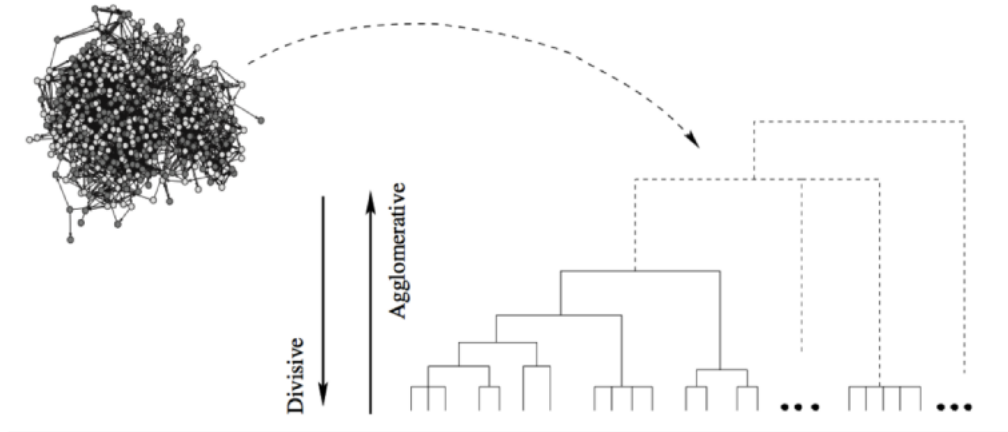


Figure 2.3: From a thickly knit graph to a dendrogram

#### 2.1.3.2.3 Partitional Clustering

#### 2.1.3.2.4 Spectral Clustering

#### 2.1.3.3 For Visualization

Graph visualization is an important task in various scientific applications. Visualizing these data as graphs provides non-experts with an intuitive means to explore the content of the data, identify interesting patterns, etc. Such operations require interactive visualizations (as opposed to a static image) in which graph elements are rendered as distinct visual objects; e.g., DOM objects in a web browser. This way, the user can manipulate the graph directly from the UI, e.g., click on a node or an edge to get additional information (metadata), highlight parts of the graph, etc. Given that graphs in many real-world scenarios are huge, the aforementioned visualizations pose significant technical challenges from a data management perspective.

##### 2.1.3.3.1 Web UI and Time per Query

1. *Program execution and Computation :*
2. *Building the JSON Object*

### 3. *Communication Time*

### 4. *Rendering*

The total time is the sum of all the above times.

#### 2.1.3.4 Computational Complexity

The estimate of the amount of resources required for by the algorithm to perform a task is defined as computational complexity. The humongous amount of data on the real graphs or real networks that are available in the current scenario causes the efficiency of the clustering algorithm to be crucial.

In a brief, Algorithms that have polynomial complexity describe the Class **P**. Problems whose solutions can be verified in a polynomial time span the class **NP** of *non-deterministic polynomial time* problems, which includes **P**. problem is **NP**-hard if a solution for it can be translated into a solution for any **NP**-problem. However, a **NP**-hard problem needs not be in the class **NP**. If it does belong to **NP** it is called **NP**-complete. The class of **NP**-complete problems has drawn a special attention in computer science, as it includes many famous problems like the Travelling Salesman, Boolean Satisfiability (**SAT**), Linear Programming, etc. The fact that **NP** problems have a solution which is verifiable in polynomial time does not mean that **NP** problems have polynomial complexity, i. e., that they are in **P**. In fact, the question of whether **NP**=**P** is the most important open problem in theoretical computer science. **NP**-hard problems need not be in **NP** (in which case they would be **NP**-complete), but they are at least as hard as **NP**-complete problems, so they are unlikely to have polynomial complexity, although a proof of that is still missing.

Many clustering Algorithms or problems related to clustering are **NP**-hard. This makes it irrelevant to use the exact algorithm, in which case we use an approximation algorithm. Approximation algorithm are methods that do not deliver the exact solution but an approximate solution but with an advantage of lower complexity. [4]

#### 2.1.4 State-of-the-art in Community Detection

Modularity is the objective function that is widely used both as a measure and as a optimizing method for partitioning community. As said before there

are various algorithms that can be used for community detection . In reference to the paper [10] which discusses 6 different community detection algorithms namely:

- Louvain Method
- Le Martelot
- Newman’s greedy algorithm (NGA)
- Newman’s spectral algorithm with refinement
- simulated annealing
- extremal optimization

The following figure 2.4 the average normalized performance rank of each algorithm in terms of partitioning quality and speed. Taken from the paper that proposed Combo algorithm [10]. The main Objective of the project is to

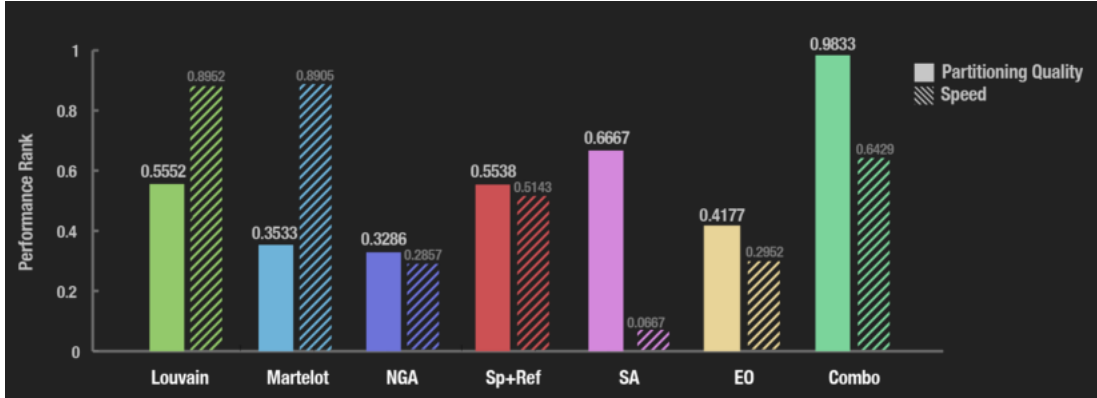


Figure 2.4: Average normalized performance rank of each algorithm in terms of partitioning quality and speed

visualize the data on screen thus needs an algorithm that is fast and should be effective. Hence louvain algorithm was chosen for the implementation. The implementation can be found in the later section of the project.

Louvain algorithm is considered as state-of-the art algorithm for community detection [2]. The algorithm is fast, recursive and is more effective on real world graphs. Owing to our object of projecting medical domain we require an algorithm that gives a better trade off between being effective and being fast. Hence Louvain algorithm was chosen.

### 2.1.5 State-of-the-art in Graph Visualization

## Chapter 3

# Community Detection Algorithm

### 3.1 Introduction

In this section we would describe the community detection algorithms such as louvain and various tests that were performed to choose the algorithm.

### 3.2 Louvain Algorithm

#### 3.2.1 Introduction

The problem of community detection requires the graph to be split into communities of tightly packed or in other words densely connected nodes with nodes of different community being sparsely connected.

Several algorithms have been proposed for performing good partition in a reasonably good speed. Distinguishably there are several types of community detection algorithms, namely: divisive algorithms, which aims in removal of the inter-community links, agglomerative algorithms, which aim in merging similar nodes and optimization methods which aim in maximizing the objective function.



### 3.2.2 Modularity

The quality of partitioning that results from application of method is often measured using modularity. The *modularity* of a partition is hence a scalar value between -1 and 1 that is used to measure the density of the links inside the communities as compared to the density of the links between the communities.

Modularity not only serves as a quality measure for detecting the quality of split or partition, but also acts as an objective function to optimize. Exact modularity optimization is **NP-Complete** in the strong sense [3].

#### 3.2.2.1 Definition

Let  $G=(V,E)$  be a simple graph, where  $V$  is the set of vertices and  $E$  is the set of undirected edges. Let  $n = |V|$  and  $m = |E|$ . Let degree of a vertex  $v$  be,  $\deg(v)$  where  $v \in V$ . Let  $C$  be the community,  $C \subseteq V$ , be the subset of vertices. A *clustering*  $C_s = \{C_1, C_2, \dots, C_k\}$  of  $G$  is a partition of  $V$  such each vertex is present exactly in one cluster. We thus define *modularity* as follows: [3]

$$Q(C_s) = \sum_{C \in C_s} \left[ \frac{|E(C)|}{m} - \left( \frac{|E(C) + \sum_{k \in C_s} |E(C, k)|}{2m} \right)^2 \right] \quad (3.1)$$

where  $E(I,J)$  is set of all edges between vertices in cluster  $I$  and  $J$ .  $E(C) = E(C,C)$ . The above equation can be continently rewritten as follows:

$$Q(C_s) = \sum_{C \in C_s} \left[ \frac{|E(C)|}{m} - \left( \frac{\sum_{v \in C} \deg(v)}{2m} \right)^2 \right] \quad (3.2)$$

In simpler terms the value of  $Q$  can be expressed as

$$Q = (\text{Number of Intra-Cluster Communities}) - (\text{Expected number of Edges}) \quad (3.3)$$

As given in [2]

$$Q = \frac{1}{2m} \sum_{ij} (A_{ij} - P_{ij}) \delta(C_i, C_j) \quad (3.4)$$

$$\delta(C_i, C_j) = \begin{cases} 1, & \text{if } C_i = C_j \\ 0, & \text{otherwise} \end{cases} \quad (3.5)$$

where,  $P_{ij}$  is the expected number of edges between nodes  $v_i$  and  $v_j$ .  $P_{ij}$  is  $\frac{k_i k_j}{2m}$  where  $k_x$  is sum of the weights of the edges attached to the vertex  $v_x$  for a given random graph G (This is otherwise called as a null model).

### 3.2.2.2 Properties of Modularity

1. Q depends on nodes in the same clusters only.
2. Larger modularity implies better Communities.
- 3.

$$Q(C_s) \leq \frac{1}{2m} \sum_{ij} A_{ij} \delta(C_i, C_j) \leq \frac{1}{2m} \sum_{ij} A_{ij} \leq 1 \quad (3.6)$$

4. Value taken by Q can be negative

### 3.2.3 Louvain

Louvian algorithm is considered as the state-of-the art algorithm for community detection for identifying community structures [2]. Louvain algorithm consists of two phases:

### 3.2.4 Implementation

The implementation of the algorithm is based on the paper "Fast unfolding of communities in large networks" [2]. The implementation is done using basic python packages. The Algorithm has two phases that are repeated iteratively to bring the final solution to the problem. The following figure 3.1 demonstrates the algorithm in the form of a flow diagram,

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**Algorithm 1** Louvain Algorithm Pseudocode

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**Require:** A graph  $G = (V, E)$

**Ensure:** Local optimum community split has happened

**while** *LocalOptimumReached* **do**

    Phase1 : Split or partition the graph by optimizing modularity greedily

    Phase2 : Agglomerate the found clusters into new nodes

**end while**

---

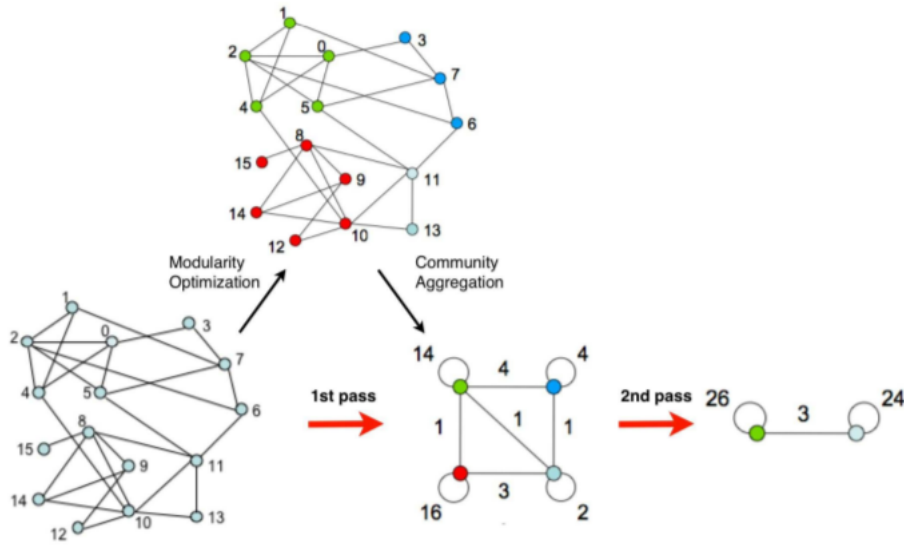


Figure 3.1: Visualization of the steps of our algorithm. Each pass is made of two phases: one where modularity is optimized by allowing only local changes of communities; one where the found communities are aggregated in order to build a new network of communities. The passes are repeated iteratively until no increase of modularity is possible. This was taken from the paper "Fast unfolding of communities in large networks" [2]

### 3.2.4.1 First Phase : Optimizing Modularity

The first phase of louvain algorithm Let  $G$  be a graph with  $N$  nodes in the network. The algorithm assigns a different community to each node in the network. The number of nodes is equal to the number of communities in the graph. The report uses the terms node and vertices interchangeably. Let  $v_i$

be be a node such that  $v_j \in N(v_i)$ . The gain of modularity is then calculated by removing  $v_i$  and placing it in community of  $v_j$ . If the gain is positive the  $v_i$  is moved to the community of  $v_j$  else  $v_i$  stays in it's original community. This procedure is iterated and the phase one stops when a local maxima of the modularity is achieved, that is when no more move of nodes from one community to another is possible. The ordering of the nodes can affect or effect the computation time which can be a part of future works.

---

**Algorithm 2** Phase 1 in Louvain Algorithm Pseudocode

---

**Require:** A graph  $G = (V, E)$

**Ensure:** Partition network greedily using modularity

Assign a different community to each node

**while** *LocalOptimumReached* **do**

**for all** Each node  $v_i$  **do**

    For each node  $v_j \in N(v_i)$ , consider removing  $v_i$  from community of  $v_i$  and place it in the community of  $v_j$

    Calculate the modularity gain

**if** *ModularityGain* is Positive **then**

      remove  $v_i$  from community of  $v_i$  and place it in the community of  $v_j$

**else**

      No Change

**end if**

**end for**

**end while**

---

The main algorithm relies on the calculation of modularity. Listing 3.1 demonstarted the calculation using a python snippet. The first phase of the algorithm has been written into a python code snippet and is presented in the Listing 3.2. In the paper it is stated that the gain in modularity as  $\Delta Q$

$$\Delta Q = \left[ \frac{\sum_{in} + k_{i,in}}{2m} - \left( \frac{\sum_{tot} + k_i}{2m} \right)^2 \right] - \left[ \frac{\sum_{in}}{2m} - \left( \frac{\sum_{tot}}{2m} \right)^2 - \left( \frac{k_i}{2m} \right)^2 \right] \quad (3.7)$$

where  $\sum_{in}$  is the sum of the weights of the links inside C and  $\sum_{tot}$  is the sum of the weights of the links incident to nodes in C,  $k_i$  is the sum of weights of

the links incident to node  $i$ ,  $k_{i,in}$  is the sum of the weights of all the links in the network.

**3.2.4.1.1 Second Phase : Agglomerating the communities found in first phase into new nodes** In the second phase the algorithm builds the new network. The communities that are found during the first phase are now the nodes here. According to the paper [2], the weights of the links between the new nodes are given by the sum of the weight of the links between nodes in the corresponding two communities. The edges between nodes of the same community lead to self-loops for this community in the new network. The resulting new weighted network is then subjected to first phase and this process is iteratively done.

---

**Algorithm 3** Phase 2 in Louvain Algorithm Pseudocode

---

**Require:** A graph  $G = (V, E)$

**Ensure:** Agglomeration of nodes

Every community  $C_i$  forms a new node  $v_i$

$W_{ij} = \sum \{\text{All edges between } C_i \text{ and } C_j\}$  where  $W_{ij}$  is the edge between newly formed nodes  $v_i$  and  $v_j$

---

### 3.2.4.2 Observations of Louvain

1. The final output of the louvain algorithm forms a complete hierarchical structure.
2. Resolution limit problem [5] has been resolved in the algorithm stated in the current paper under discussion [2] due to the multi-level nature of louvain algorithm.
3. Modularity can be redefined for weighted graphs and Louvain works well with weighted graphs.

### 3.2.4.3 Usage of Louvain in the project

In the project the above algorithm has been implemented in python taking inspiration and reusing some part of the pylouvain program API for implementation [8]. Python was chosen as the programming language as recommended by the project Director. The project work is said to form a part

of a major project work on medical domain in LARCA. The director of the project informed that the main project is written in javascript and python hence, python was choosen as the programming language for the project.

#### **3.2.4.4 Experiments**

[9]

#### **3.2.4.5 Result**

### **3.3 Matrix Based Algorithm**

#### **3.3.1 Matrix Algorithm**

##### **3.3.1.1 Introduction**

##### **3.3.1.2 Reasoning**

##### **3.3.1.3 Description**

##### **3.3.1.4 Implementation**

##### **3.3.1.5 Experiments**

##### **3.3.1.6 Result**

# Chapter 4

## Visualization Techniques

### 4.1 Introduction

Listing 4.1: Creation of JSON Object using Python

```
import json as j
from copy import deepcopy
la=[]
lb=[]
jd = {"nodes":la,"edges":lb}
# for the node
k = {}
k['id'] = "1"
k['cluster']= "1"
k['title'] = "Abc"
k["relatedness"]="0.5"
jd['nodes'].append(deepcopy(k))
print jd
k['id'] = "2"
k['cluster']= "2"
k['title'] = "two"
k["relatedness"]="0.5"
jd['nodes'].append(deepcopy(k))

#For the Edge
m = {}
```

```

m["source"] = "1"
m["target"] = "2"
m["relatedness"] = "0.5"
jd['edges'].append(m)

prin = j.dumps(jd, indent = 4)
print prin

f = open("crea.json", "w")
f.write(prin)
f.close()

```

## 4.2 Alchemy.js

According to the creator of the Alchemy.js Software [1] Alchemy.js is a graph drawing software built on *d3*. Alchemy.js is an application which provides graph visualization with very little over head.

### 4.2.1 Dependencies

Alchemy needs 3 main units to form as an application namely: *alchemy.css*, *alchemy.js* and *data*. CSS and JavaScript are major dependencies in Alchemy.js. Installation of *jQuery* and *d3* is also useful. *alchemy.min.js*, *alchemy.css* and *alchemy.min.css* will be updated in the CDN (Content Delivery network)

### 4.2.2 Steps to use the Alchemy.js

In this project we have uploaded the *alchemy.min.js*, *alchemy.css* and *alchemy.min.css* into the project's file repository <http://abhinavsv3.github.io/javascriptsal> and hence will be using the link in the following explanation. The following describes the steps that are followed in use of Alchemy.js :

1. *Include the files in this format*

```

<link rel="stylesheet" href="http://abhinavsv3.github.io/javascriptsal/alchemy.min.css" />
...
<script src="http://abhinavsv3.github.io/javascriptsal/alchemy.min1.js"><
/script >

```



2. *Include an element with "alchemy" ID as the id and class*  
 The alchemy class is used to apply styles while the alchemy id is used programatically. By default Alchemy.js looks for the alchemy div but this can be overridden. `<div class="alchemy" id="alchemy"></div>`
3. *Provide Alchemy.js with a JSON dataSource*
4. *Begin Alchemy.js* `<script> alchemy.begin({"dataSource" : someData}) </script>`

## 4.3 Getting the data from the Louvain Python code to Alchemy

According to the authors of Alchemy.js. Alchemy.js takes a simple data format called GraphJSON. GraphJSON serves as a light weight and flexible representation of graph data, easily consumed locally or over the web.

GraphJSON is a JSON Object which has 2 object namely: *nodes* and *edges* . These are individual arrays that represent the nodes and edges that will be represented in the graph visualization.

**Nodes** : id key is the only unique value that should be present in the nodes

**Edges** : source and target key are the only unique value that should be present in the edges.

### 4.3.0.1 Introduction

### 4.3.0.2 Reasoning

### 4.3.0.3 Description

### 4.3.0.4 Methods and Library

### 4.3.0.5 Result

# Chapter 5

## Overall System Description

### 5.1 Overall System Description

#### 5.1.1 Web.py

##### 5.1.1.1 Introduction

##### 5.1.1.2 Implementation Benefits

sdgbf akjsfkldsnfksndafnadfa fasfadf adfasfasfadf asfasfadf afadfadf

##### 5.1.1.3 Description

git hub repository : <https://github.com/abhinavsv3/webproject>

##### 5.1.1.4 Result

#### 5.1.2 Benefits to the community

This can be used in places where there is difficulty in visualization of a very complex landscape of data such as medical domain. In Medical domain a patient can be a vector of diseases and visualization of such patients (patients graph—which shows relations of how two patients are similar, a graph in which patient-patient edge weight is the similarity value ) would be useful for analyzing and predicting the disease landscape of a region and in turn multiple regions.

# Chapter 6

## Conclusion and Future Works

### 6.1 Goals Achieved

### 6.2 Revision of Planning and Budget

### 6.3 Future Works

Order of inputs can influence the computation time. The problem of finding specific heuristics to solve this ordering problem can improve the louvain algorithms computation time. Zooming effect merging the dashboard to the graph board. The project relies fully on louvain. One can speculate on whether modularity is the only measure that exists. Thinking about a completely new measure would be interesting.

### 6.4 Availability and requirements

1. **Project Name:** Graph and matrix algorithms for visualizing high dimensional
2. **Project Homepage:** <https://github.com/abhinavsv3/webprojectdimensional>
3. **Operating System:** Platform Independent. Preferably Unix-like operating system
4. **Programming Language:** Python 2.7

## 5. Other Requirements : Alchemy.js, Python Packages, Web.py

### 6.4.1 Conclusion

This is one of the greatest project experience.

### 6.4.2 Personal Conclusion

This is one of the greatest project experience.

Listing 6.1: Modularity Calculation

```
# a method from the louvain class.
# The variables are as equivalent as
# in the above formula 3.2
def modularity_calc(self, partition):
    q = 0
    m2 = self.m * 2
    for i in range(len(partition)):
        q += self.s_in[i] / m2 - (self.s_tot[i] /
        ↪ m2) ** 2
    return q
```

Listing 6.2: First Phase of Louvain Algorithm

```
best_partition = self.make_initial_partition(network)
while 1:
    improvement = 0
    for node in network[0]:
        node_community = self.communities[node]
        # default best community is its own
        best_community = node_community
        best_gain = 0
        # remove node from its community
        best_partition[node_community].remove(node)
        best_shared_links = 0
        for e in self.edges_of_node[node]:
            if e[0][0] == e[0][1]:
                continue
```

```

        if e[0][0] == node and self.communities[e
            ↪ [0][1]] == node_community or e[0][1]
            ↪ == node and self.communities[e[0][0]]
            ↪ == node_community:
            best_shared_links += e[1]
self.s_in[node_community] -= 2 * (
    ↪ best_shared_links + self.w[node])
self.s_tot[node_community] -= self.e_sum[node]
self.communities[node] = -1
communities = {} # only consider neighbors of
    ↪ different communities
for neighbor in self.get_neighbors(node):
    community = self.communities[neighbor]
    if community in communities:
        continue
    communities[community] = 1
    shared_links = 0
    for e in self.edges_of_node[node]:
        if e[0][0] == e[0][1]:
            continue
        if e[0][0] == node and self.communities
            ↪ [e[0][1]] == community or e[0][1]
            ↪ == node and self.communities[e
            ↪ [0][0]] == community:
            shared_links += e[1]
    # compute modularity gain obtained by
    ↪ moving _node to the community of
    ↪ _neighbor
    gain = self.modularity_calc_gain(node,
        ↪ community, shared_links)
    if gain > best_gain:
        best_community = community
        best_gain = gain
        best_shared_links = shared_links
# insert _node into the community maximizing
    ↪ the modularity gain
best_partition[best_community].append(node)
self.communities[node] = best_community

```

```
        self.s_in[best_community] += 2 * (  
            ↪ best_shared_links + self.w[node])  
        self.s_tot[best_community] += self.e_sum[node]  
        if node_community != best_community:  
            improvement = 1  
    if not improvement:  
        break  
return best_partition
```

# Listings

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