



MA5960: Project Proposal and Progress

Modelling a Permanent Magnet Synchronous Motor (PMSM) using Finite Element Method in FEniCS

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Agenda

- Objective
- Introduction
- Timeline
- TEAM 30 Problem Induction Motor Analysis
- The Maxwell's Equations
- Weak formulation of induction motor problem
- Mesh Generation using GMSH
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- Future work
- Link References

Objective

Efficient PMSM Modelling using FEM in FEniCSx Literature insights from TEAM 30 - Induction Motor problem

Weak formulation using Dolfinx

Analyze magnetic flux density

Shift from 2D to 3D mathematical representation

Contribute to transportation electrification

Direct collaboration and mentorship from developer of FEniCS, Jørgen Dokken (Simula)

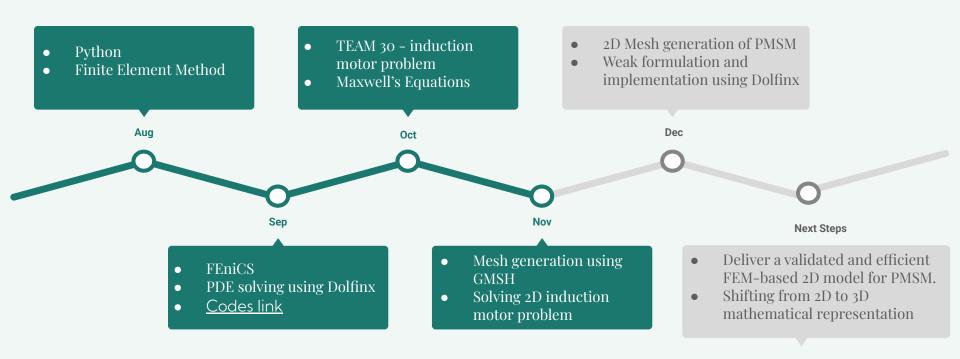


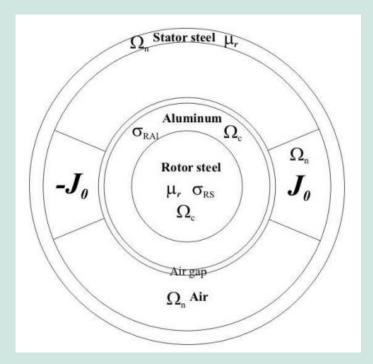


Introduction |

- Electrifying heavy-duty vehicles and aviation lags due to the need for more efficient, power-dense,
 and lightweight motors.
- Permanent Magnet Synchronous Motors (PMSM) offer high efficiency and torque density for electric heavy vehicles and aviation.
- **Finite Element Method (FEM)** is used extensively for analyzing and improving performance of these electric machines.
- **FEniCS**: open-source computing platform for solving PDEs with FEM enables scalable, efficient simulations.
- This project focuses on implementing a 2D computational model and understanding the 3D implementation for simulating the electromagnetic behavior of PMSMs using FEM in FEniCSx.

Timeline





The structure of the eddy current field problem

Induction Motor Analysis

TEAM 30 Problem

Given

- o angular velocity of rotor and stator (ω)
- source current density (Jo)
- o conductivity (σ) &
- o relative permeability of each material (μr)

• To compute:

- Electromagnetic torque
- Induced voltage in the phase coil A
- Average power dissipation (eddy current -Rotor Loss and Steel Loss)

The Maxwell's Equations

$$\nabla \times \vec{H} = \vec{J_0}, \quad \text{in } \Omega_n,$$

$$\nabla \cdot \vec{B} = 0, \quad \text{in } \Omega_n,$$

$$\nabla \times \vec{H} = \vec{J}, \quad \text{in } \Omega_c,$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}, \quad \text{in } \Omega_c,$$

$$\nabla \cdot \vec{B} = 0, \quad \text{in } \Omega_c,$$

$$\nabla \cdot \vec{J} = 0, \quad \text{in } \Omega_c,$$

$$\vec{B} = \begin{cases} \mu_0 \vec{H}, & \text{in air, } \Omega_n, \\ \mu_0 \mu_r \vec{H}, & \text{in magnetically linear material, } \Omega_c, \end{cases}$$

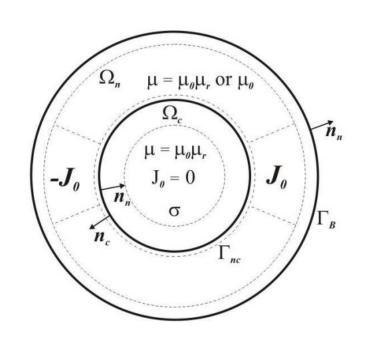
$$\vec{J} = \sigma \vec{E}, & \text{in } \Omega_c.$$

$$\vec{H} = \begin{cases} \nu_0 \vec{B}, & \text{in air, } \Omega_n, \\ \nu_0 \nu_r \vec{B}, & \text{in magnetically linear material, } \Omega_c. \end{cases}$$

 $\vec{E} = \rho \vec{J}$, in Ω_c .

Boundary conditions

$$\vec{B} \cdot \vec{n} = 0$$
, on Γ_B ,
 $\vec{H_c} \times \vec{n_c} + \vec{H_n} \times \vec{n_n} = \vec{0}$, on Γ_{nc} ,
 $\vec{B_c} \cdot \vec{n_c} + \vec{B_n} \cdot \vec{n_n} = 0$, on Γ_{nc} ,
 $\vec{J} \cdot \vec{n_c} = 0$, on Γ_{nc} ,



Weak formulation of induction motor problem

2D weak formulation of potential formulation in the time domain

$$\vec{B} = \nabla \times \vec{A}$$

$$\vec{E} + \frac{\partial \vec{A}}{\partial t} = -\nabla V,$$

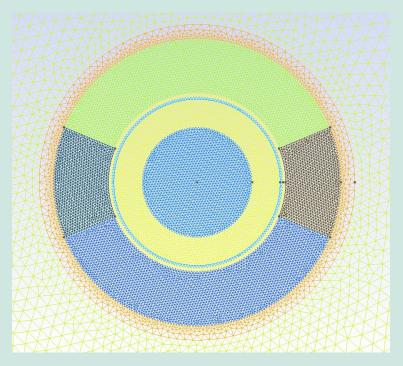
$$\int_{\Omega_{c} \cup \Omega_{n}} \nu(\nabla \times \vec{W}_{k}) \cdot (\nabla \times \vec{A}^{\kappa}) d\Omega$$

$$+ \int_{\Omega_{c}} \vec{W}_{k} \cdot \sigma \left(\frac{\partial \vec{A}^{\kappa}}{\partial t} - \vec{v} \times \nabla \times \vec{A}^{\kappa} \right) d\Omega$$

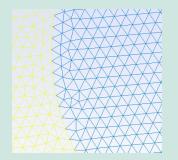
$$= \int_{\Omega} \vec{W}_{k} \cdot \vec{J}_{0}^{\kappa} d\Omega.$$

Steps in weak formulation: Weak formulation derivation

Mesh Generation using GMSH



2D mesh

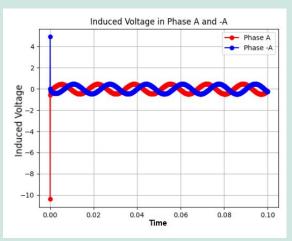


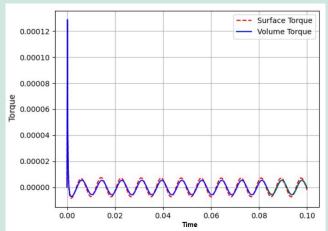
zoomed view

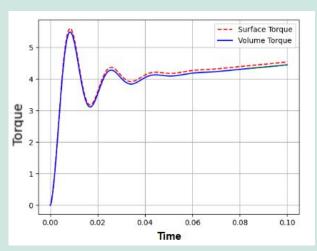
- 2D finite element mesh discretized by triangular elements.
- Generated using GMSH, an open-source mesh generator.



Outputs of existing Dolfinx code







Solve the Single-Phase Problem

Solve the Three-Phase Problem with Applied Torque





Future work

- Mesh generation of PMSM using GMSH.
- Applying the methodology of induction motor problem for the simulation of PMSM model.
- Deliver a validated and efficient FEM-based model for PMSMs.
- Shifting from 2D to 3D mathematical representation of the model.



Link References

- Modelling a permanent magnet synchronous motor in FEniCSx for parallel high-performance simulations James McDonagh, et al.
- Documentation | FEniCS Project
- GitHub Wells-Group/TEAM30: A repository for the TEAM-30 benchmark using DOLFINx
- Using the GMSH Python API to generate complex meshes | Jørgen S. Dokken
- Computational Electromagnetics YouTube
- Performance Comparison of High-Speed Motors for Electric Vehicle







Thank you

