

Raw sensor data

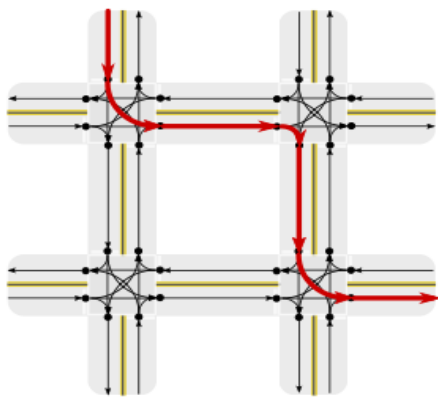
Perception

- Localisation
- Environment recognition

Perceived objects and signage

Decision

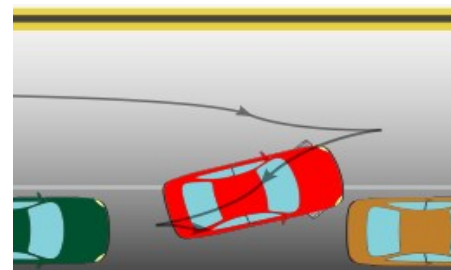
1. Route planning



2. Behavioural planning



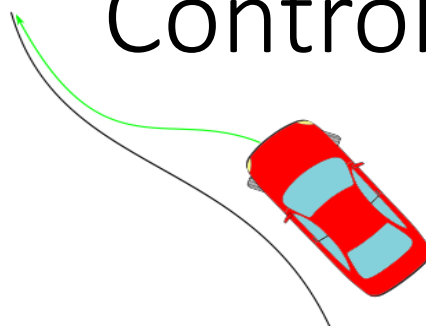
3. Motion planning



Reference trajectory

Control

- Local feedback



Throttle/steering commands