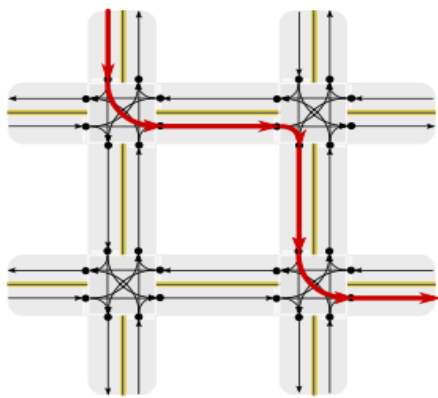Raw sensor data

Perception

- Localisation
- Environment recognition

Perceived objects and signage

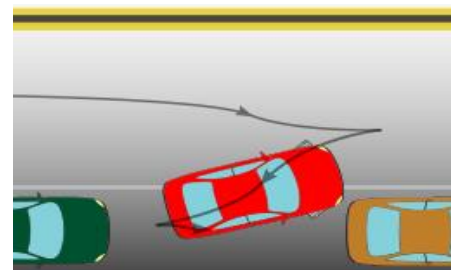# Decision

- **Route planning**
- **Behavioural planning**
- **Motion planning**

Negotiate Intersection

Parking Maneuver

Lane Following

Change Lanes

Unstructured Environment
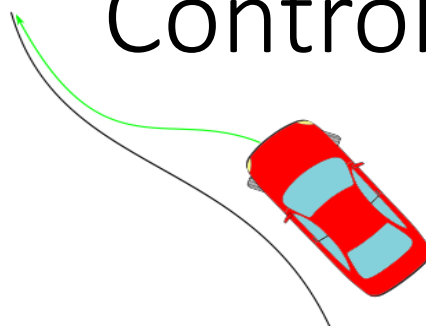
Reference trajectory

Control

- **Local feedback**

Throttle/steering commands