

Autopilot Development

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Objective

Requirements

Hardware selection

1. Propellers
2. Actuators
3. Motor drivers
4. Power distribution unit
5. Power source
6. Airframe
7. Sensors
 - 7.1. Gyroscope
 - 7.2. Accelerometer
 - 7.3. Magnetometer
 - 7.4. Barometer
 - 7.5. LIDAR
 - 7.6. SONAR
 - 7.7. GPS
 - 7.8. Temperature sensor
 - 7.9. Humidity sensor
8. Processors
 - 8.1. Primary processor
 - 8.2. Secondary processor
9. Communication module
 - 9.1. Receiver
 - 9.2. Transceiver
10. Data logging module
 - 10.1. EEPROM
 - 10.2. SD card
 - 10.3. Flash drive
11. Audio-visual feedback module
 - 11.1. LED
 - 11.2. Buzzer

Software development

1. Constants
2. Math
 - 2.1. Utility
 - 2.2. Linear algebra
 - 2.2.1. Vector2
 - 2.2.2. Vector3
 - 2.2.3. Matrix22
 - 2.2.4. Matrix23
 - 2.2.5. Matrix32
 - 2.2.6. Matrix33
 - 2.2.7. MatrixNN
 - 2.3. Quaternion
 - 2.4. Axis angle
 - 2.5. Rotation matrix
 - 2.6. Direction cosine
 - 2.7. Cartesian 2D
 - 2.8. Cartesian 3D

2.9. Polar

2.10. Spherical

2.11. Cylindrical

2.12. Elliptical

2.13. Ellipsoidal

2.14. Coordinate transformations

3. Filters

4. Analyzers

5. System identification

6. Control

7. Monitor

8. Estimation

9. WMM

10. WGM

11. WAM

Test rig development