Abhishek Pachorkar

Sophomore @ Mathematics and Computing, IIT Kharagpur

FDUCATION

INDIAN INSTITUTE OF TECHNOLOGY KHARAGPUR

INTEGRATED M.SC IN
MATHEMATICS AND COMPUTING
CGPA: 8.40/10
2018-2023 | West Bengal, India

MAHARASHTRA STATE BOARD OF SECONDARY EDUCATION

HIGHER SECONDARY EDUCATION
CERTIFICATE EXAMINATION

Percentage: 85.08%

May 2018 | Nasik, Maharashtra, India

MAHARASHTRA STATE BOARD OF SECONDARY EDUCATION

SECONDARY SCHOOL
CERTIFICATE EXAMINATION

Percentage: 94.40%

May 2016 | Nasik, Maharashtra, India

CONTACT

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LINKS

- → abhipachorkar296@gmail.com
- nabhipachorkar296
- in abhishek-pachorkar

COURSEWORK

T - Theory | L - Laboratory

COMPLETED

Programming & Data Structures (T/L)

ONGOING

Design & Analysis of Algorithm (T/L)

Online Courses

Machine Learning - Andrew Ng Algorithms Specialization (Ongoing) deeplearning.ai (Ongoing)

PROJECTS

AERIAL ROBOTICS KHARAGPUR SOFTWARE TEAM MEMBER

- Aerial Robotics Kharagpur is a research group mainly involved in the development of autonomous drones performing various tasks.
- Part of a software team which worked on ORB-SLAM (Simultaneous Localisation and Mapping) which is an indoor localisation algorithm for drones.

CRUSADE KSHITIJ 2019 CHALLENGE

- *Problem Statement*: Used a monocular camera to guide a bot through grey-scale environment.
- Executed different approaches using Python-OpenCV functions to extract exact path boundaries including implementing generalized Huff Transform and contour detection using gradients.
- Used the path boundaries to estimate state of bot and required control inputs to guide it to destination.

PATH PLANNING USING RRT* ALGORITHM ARK TASK ROUND

- Optimized multiple data structures and path-finding algorithms such as RRT*(Rapidly-exploring random trees) to find a solution for a given dynamic maze with moving obstacles in random motion. Implemented it in C++ using OpenCV.
- Developed a new algorithm to plot disparity map of two stereo images and applied it to plot depth gradients .

TECHNICAL SKILLS

Programming Languages
Libraries / Frameworks
Robotic and Control
Systems and Platforms

nguages | C | C++ | Python | GNU Octave eworks | OpenCV | Numpy | flask Control | ROS | Solidworks | Simulink atforms | Git | Linux Others | HTML | CSS | MySQL

SCHOLASTIC ACHIEVEMENTS

- *Inspire Scholarship*: Among the top 1% students in the country to receive the scholarship for academic prowess.
- JEE Advanced AIR 3359: Under top 1% amongst more than 2,00,000 students
- JEE Main AIR 249: In top 0.02% amongst more than 12,00,000 students.
- Secured Bronze Medal in Homi Bhabha Bal Vaidnyanik Science Talent Competition
- Among Top 10% in National Standard Examination In Junior Science Examination
- Completed IEEE certified workshop in image processing
- Secured 34 rank in Maharashtra Olympiad Movement examination