Technical Strategy Write-Up

1. Problem Framing

• **Objective**: Build an agent that plays Hangman via a remote API, leveraging both reinforcement learning (RL) with deep Q-learning and periodic masked-language-model (MLM) fine-tuning to maximize win rate.

Constraints:

- Only the provided 250 K-word dictionary may be used.
- External API enforces a limit of 20 new games/minute and distinguishes "practice" (unrecorded) vs. "recorded" runs.
- Must slot into the existing notebook by overriding a single guess(self, word) hook.

2. Environment Design (

HangmanEnv

)

1. State Representation

A fixed-length vector encoding the current word pattern, e.g. _ A _ _ E → [_, A, _,
_, E], padded to the longest word.

2. Action Space & Masking

- o 27 discrete actions (letters 'a'-'z' plus underscore).
- Maintain a binary "legal mask" that zeroes out already-tried letters so the policy never re-guesses.

3. Reward Structure

- Correct guess: +10 base reward + "bonus" computed from:
 - Global frequency of that letter in the entire dictionary.
 - Relative frequency of that letter among candidate words consistent with the current pattern.
 - Dynamically weight these two based on how many blanks remain (early guesses favor broad frequency; later guesses favor pattern-specific frequency).
- o **Incorrect guess**: –5 penalty and decrement a life.
- Repeated guess: -2 penalty and decrement a life.
- Win bonus: +50 when all letters are revealed.

3. Policy Architecture

- Backbone: bert-tiny pretrained transformer repurposed as a feature extractor on each masked word.
- **Head**: Two small fully-connected layers projecting BERT's 128-dim "pooler output" to 27 Q-values.
- **Action Masking**: After producing raw Q's, set illegal actions to a large negative constant so argmax ignores them.

4. Deep Q-Learning Agent

1. Experience Replay

- Store transitions (state, mask, action, reward, next_state, next_mask, done) in a large ring buffer (~50 K entries).
- Sample mini-batches of size 128 to break temporal correlation and stabilize learning.

2. Double-DQN Updates

- Online network selects next action; target network evaluates its Q-value.
- Periodically (every 500 episodes) copy online → target weights.

3. ε-Greedy Exploration

○ Start with ε=1.0 and exponentially decay to ε=0.01 over the course of training (decay span ≈ total episodes).

5. Hybrid MLM Warm-Up

- **Motivation**: Prevent catastrophic forgetting of letter-level language priors during RL fine-tuning.
- Mechanism: Every 1 000 RL episodes, perform a small number (≈20) of masked LM gradient steps on the training word list (character-masking at p=0.15).
- Weight Sync: Copy the MLM's updated transformer weights back into the RL policy's BERT backbone.

6. Training Loop

1. Optional Head Pretraining

 (Separate CLI mode) Fine-tune BERT's MLM head on single words for ≈20 000 steps. Saves bert_output.pth.

2. RL+MLM Cycle

Initialize agent, target networks, replay buffer

For episode = 1..N:

Reset HangmanEnv on training set

Perform two "rule-based" guesses ('e' then 'a') to seed learning

Loop until terminal:

Select a via ε-greedy Q-policy

Execute step, receive r, next state, done

Store transition; optimize Q-network on sampled batch

If episode % 500 == 0: sync target ← online

If episode % 1000 == 0: run 20 MLM batches → sync into online.bert

Periodically evaluate on held-out words and checkpoint best Q-head

3. Hyperparameters

Episodes: 20 000–50 000

o Replay buffer: 50 000; batch size 128

γ=0.99; Ir=1e-3; ε decay ≈ total episodes

MLM interval = 1 000 episodes; MLM steps = 20

7. Notebook Integration & API Flow

1. **Upload Artifacts**: best_qhead.pth, your pretrained_rl_hangman.py, and words_250000_train.txt into Colab.

2. Load Policy:

- Instantiate prl.Agent with zero episodes for CLI args.
- Load best_ghead.pth into agent.policy and set policy.eval().
- 3. **Patch the API**: Override HangmanAPI.guess(self, word) to:
 - Spin up a local HangmanEnv with the same dictionary.
 - Manually set env.word_state and env.tried_letters from the API's mask & guessed letters.
 - Call agent.select(state, mask) to produce your guess.

4. Practice vs. Recorded:

- o **Practice** (practice=1) uses unrecorded runs (up to 100 000).
- Recorded (practice=0) logs your 1 000 final games for judge scoring.

5. End-to-End Call Sequence:

• Notebook calls api.start_game(practice=..., verbose=...).

- API returns initial mask (e.g. _ p _ _ e).
- SDK invokes your guess hook → your RL policy picks the next letter.
- SDK sends /guess_letter → server responds with updated mask & remaining tries.
- Loop continues until win/lose.
- Stats fetched via api.my_status().

Outcome: By combining a frequency-aware reward shaping, rule-based "vowel seeds," Double-DQN on a BERT backbone, and periodic MLM regularization, this agent substantially outperforms the ~18 % baseline and slots seamlessly into TrexQuant's existing API notebook without modifying any of their networking code.