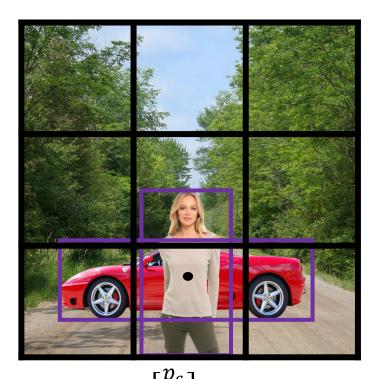


Object Detection

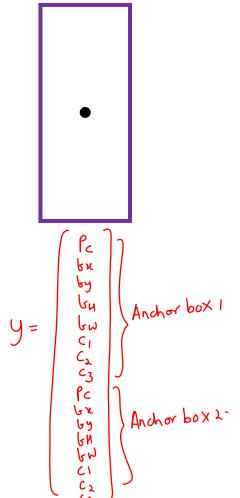
Anchor boxes

Overlapping objects:



$$y = \begin{bmatrix} b_x \\ b_y \\ b_h \\ b_w \\ c_1 \\ c_2 \\ c_3 \end{bmatrix}$$
 pedestrian, car, motorcycle

Anchor box 1:



Anchor box 2:

•

[Redmon et al., 2015, You Only Look Once: Unified real-time object detection]

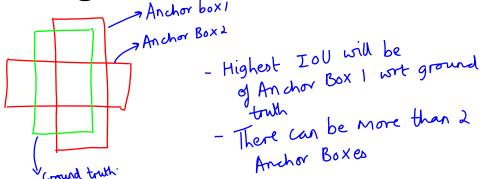
Anchor box algorithm

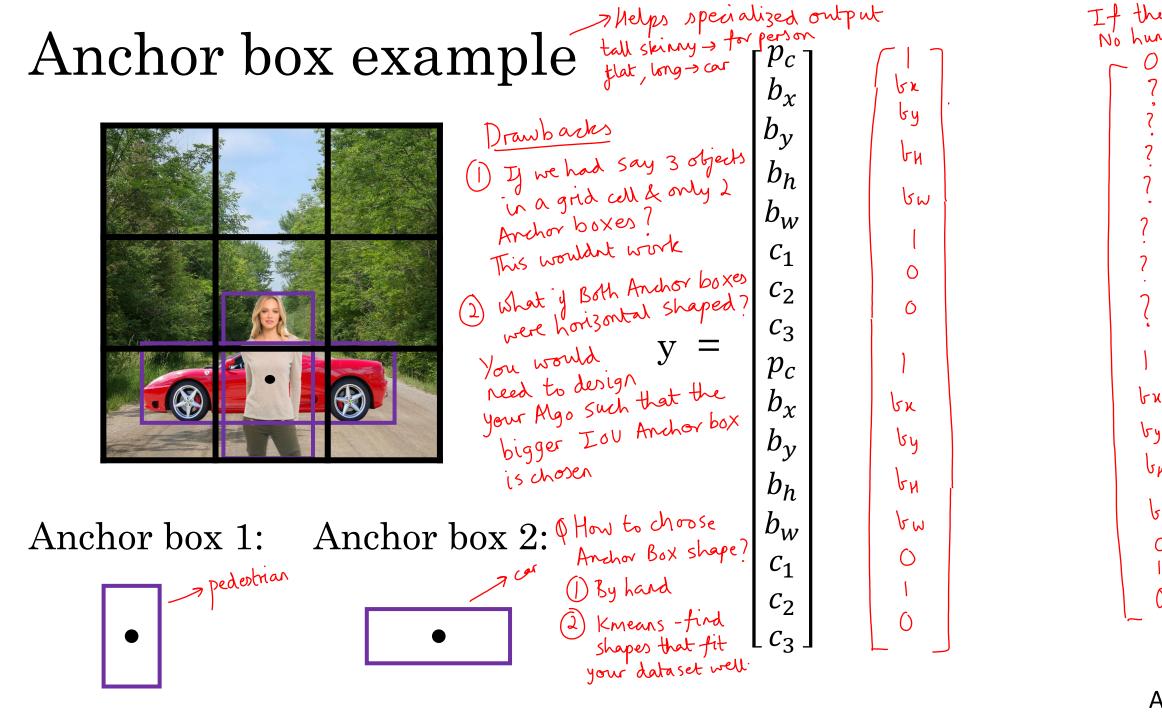
Previously:

Each object in training image is assigned to grid cell that contains that object's midpoint.

With two anchor boxes:

Each object in training image is assigned to grid cell that contains object's midpoint and anchor box for the grid cell with highest IoU.





5 W

Anchor

BOXI