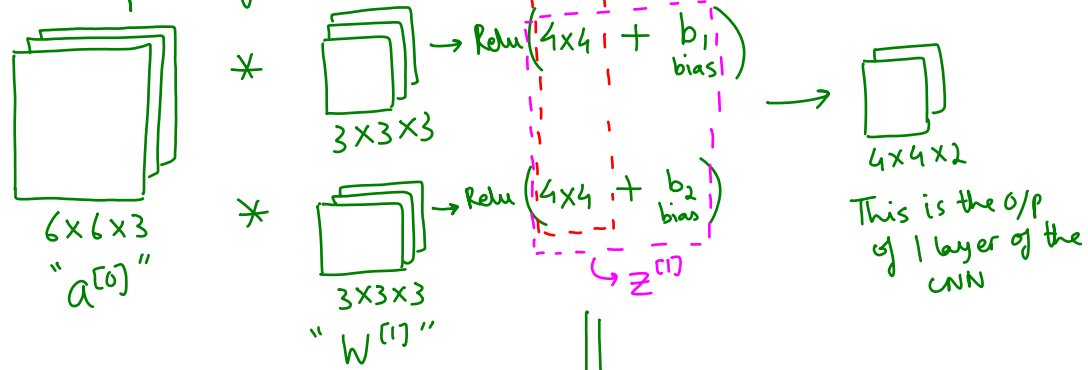


Example of a layer  $b_1, b_2 = \text{Real number broadcasted to all members of o/p image}$

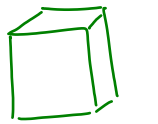


$$a^{[1]} = g(z^{[1]})$$

where  $g$  is "Relu"

$\Rightarrow$  we went from  $6 \times 6 \times 3$  ( $a^{[0]}$ )  
to  $4 \times 4 \times 2$  ( $a^{[1]}$ )

Q If you have 10 filters that are  $3 \times 3 \times 3$  in 1 layer of a NN,  
how many params does that layer have?



$3 \times 3 \times 3$

+ 1 bias

ie,  $28 \times 10 \text{ Filters} = 280 \text{ params}$

$\Rightarrow$  # params Remain small  
irrespective of the Image  
size

# Summary of Notation

- ① \* In layer "L" of CNN  
 $f^{[L]}$  = filter size in layer L  
 $p^{[L]}$  = padding size, can be 0 (valid padding)  
 $s^{[L]}$  = stride for this layer

② \* Input coming into this layer "L"  
 $n_H^{[L-1]} \times n_W^{[L-1]} \times n_C^{[L-1]}$   
 $\downarrow$  height of Image in prev layer  
 $\downarrow$  width of Image in prev. layer  
 $n_C^{[L-1]}$  # channels

③ \* Output  
 $n_H^{[L]} \times n_W^{[L]} \times n_C^{[L]} \rightarrow$  # channels  
 $\downarrow$  height of convoluted Image  
 $\downarrow$  width of convoluted Image

④ Height of Image in output layer

$$n_H^{[L]} = \left\lfloor \frac{n_H^{[L-1]} + 2p^{[L]} - f^{[L]}}{s^{[L]}} + 1 \right\rfloor$$

⑤ Width of Image in output layer

$$n_W^{[L]} = \left\lfloor \frac{n_W^{[L-1]} + 2p^{[L]} - f^{[L]}}{s^{[L]}} + 1 \right\rfloor$$

⑩ \* weights of the layer "L"

$$\underbrace{f^{[L]} \times f^{[L]}}_{\text{filter dim}} \times \underbrace{n_C^{[L-1]} \times n_C^{[L]}}_{\text{\# filters}}$$

⑥ \*  $n_C^{[L]}$  = number of filters in layer L (= # channels that are outputted in layer L)

⑦ \* Filter dimension  
 $f^{[L]} \times f^{[L]} \times n_C^{[L-1]}$   
 $\downarrow$  This must match # channels of input

⑧ \* Activation dimension  
 $a^{[L]} = g(z^{[L]})$   
 $z^{[L]} =$  output at  $L^{\text{th}}$  layer  
 $\hookrightarrow$  ie,  $n_H^{[L]} \times n_W^{[L]} \times n_C^{[L]}$

$$\Downarrow$$

$$\dim(a^{[L]}) = n_H^{[L]} \times n_W^{[L]} \times n_C^{[L]}$$

⑨ \* Vectorized Activation  
 $A^{[L]} = m \times n_H^{[L]} \times n_W^{[L]} \times n_C^{[L]}$   
 $\uparrow$  # examples

⑪ \* Bias  
 $n_C^{[L]} = \text{\# filters}$ , can be written as  $(1 \times 1 \times 1 \times n_C^{[L]})$



