# **HumanActivityRecognition**

This project is to build a model that predicts the human activities such as Walking, Walking\_Upstairs, Walking\_Downstairs, Sitting, Standing or Laying.

This dataset is collected from 30 persons(referred as subjects in this dataset), performing different activities with a smartphone to their waists. The data is recorded with the help of sensors (accelerometer and Gyroscope) in that smartphone. This experiment was video recorded to label the data manually.

### How data was recorded

By using the sensors(Gyroscope and accelerometer) in a smartphone, they have captured '3-axial linear acceleration'(*tAcc-XYZ*) from accelerometer and '3-axial angular velocity' (*tGyro-XYZ*) from Gyroscope with several variations.

prefix 't' in those metrics denotes time.

suffix 'XYZ' represents 3-axial signals in X, Y, and Z directions.

#### **Feature names**

- These sensor signals are preprocessed by applying noise filters and then sampled in fixedwidth windows(sliding windows) of 2.56 seconds each with 50% overlap. ie., each window has 128 readings.
- 2. From Each window, a feature vector was obtianed by calculating variables from the time and frequency domain.

In our dataset, each datapoint represents a window with different readings

- The acceleration signal was saperated into Body and Gravity acceleration signals(tBodyAcc-XYZ and tGravityAcc-XYZ) using some low pass filter with corner frequecy of 0.3Hz.
- 4. After that, the body linear acceleration and angular velocity were derived in time to obtian *jerk* signals (tBodyAccJerk-XYZ and tBodyGyroJerk-XYZ).
- The magnitude of these 3-dimensional signals were calculated using the Euclidian norm. This
  magnitudes are represented as features with names like tBodyAccMag, tGravityAccMag,
  tBodyAccJerkMag, tBodyGyroMag and tBodyGyroJerkMag.
- 6. Finally, We've got frequency domain signals from some of the available signals by applying a FFT (Fast Fourier Transform). These signals obtained were labeled with *prefix 'f'* just like original signals with *prefix 't'*. These signals are labeled as *fBodyAcc-XYZ*, *fBodyGyroMag* etc.
- These are the signals that we got so far.
  - tBodyAcc-XYZ

- tGravityAcc-XYZ
- tBodyAccJerk-XYZ
- tBodyGyro-XYZ
- tBodyGyroJerk-XYZ
- tBodyAccMag
- tGravityAccMag
- tBodyAccJerkMag
- tBodyGyroMag
- tBodyGyroJerkMag
- fBodyAcc-XYZ
- fBodyAccJerk-XYZ
- fBodyGyro-XYZ
- fBodyAccMag
- fBodyAccJerkMag
- fBodyGyroMag
- fBodyGyroJerkMag
- 8. We can esitmate some set of variables from the above signals. ie., We will estimate the following properties on each and every signal that we recoreded so far.
  - mean(): Mean value
  - std(): Standard deviation
  - mad(): Median absolute deviation
  - max(): Largest value in array
  - min(): Smallest value in array
  - sma(): Signal magnitude area
  - energy(): Energy measure. Sum of the squares divided by the number of values.
  - iqr(): Interquartile range
  - entropy(): Signal entropy
  - arCoeff(): Autorregresion coefficients with Burg order equal to 4
  - correlation(): correlation coefficient between two signals
  - maxinds(): index of the frequency component with largest magnitude
  - meanFreq(): Weighted average of the frequency components to obtain a mean frequency
  - **skewness()**: skewness of the frequency domain signal
  - kurtosis(): kurtosis of the frequency domain signal
  - bandsEnergy(): Energy of a frequency interval within the 64 bins of the FFT of each window.
  - angle(): Angle between to vectors.
- 9. We can obtain some other vectors by taking the average of signals in a single window sample. These are used on the angle() variable'
  - gravityMean
  - tBodyAccMean
  - tBodyAccJerkMean
  - tBodyGyroMean
  - tBodyGyroJerkMean

## Y\_Labels(Encoded)

• In the dataset, Y\_labels are represented as numbers from 1 to 6 as their identifiers.

- WALKING as 1
- WALKING UPSTAIRS as 2
- WALKING DOWNSTAIRS as 3
- SITTING as 4
- STANDING as 5
- LAYING as 6

# Train and test data were saperated

The readings from 70% of the volunteers were taken as trianing data and remaining 30% subjects recordings were taken for test data

#### **Data**

- All the data is present in 'UCI\_HAR\_dataset/' folder in present working directory.
  - Feature names are present in 'UCI HAR dataset/features.txt'
  - Train Data
    - 'UCI\_HAR\_dataset/train/X\_train.txt'
    - 'UCI HAR dataset/train/subject train.txt'
    - 'UCI HAR dataset/train/y train.txt'
  - Test Data
    - 'UCI HAR dataset/test/X test.txt'
    - 'UCI HAR dataset/test/subject test.txt'
    - 'UCI HAR dataset/test/y test.txt'

### Data Size:

27 MB

# Quick overview of the dataset:

- Accelerometer and Gyroscope readings are taken from 30 volunteers(referred as subjects)
   while performing the following 6 Activities.
  - 1. Walking
  - 2. WalkingUpstairs
  - 3. WalkingDownstairs
  - 4. Standing
  - 5. Sitting
  - 6. Lying.
- Readings are divided into a window of 2.56 seconds with 50% overlapping.

- Accelerometer readings are divided into gravity acceleration and body acceleration readings, which has x,y and z components each.
- Gyroscope readings are the measure of angular velocities which has x,y and z components.
- · Jerk signals are calculated for BodyAcceleration readings.
- Fourier Transforms are made on the above time readings to obtain frequency readings.
- Now, on all the base signal readings., mean, max, mad, sma, arcoefficient, engerybands,entropy etc., are calculated for each window.
- We get a feature vector of 561 features and these features are given in the dataset.
- Each window of readings is a datapoint of 561 features.

#### **Problem Framework**

- 30 subjects(volunteers) data is randomly split to 70%(21) test and 30%(7) train data.
- · Each datapoint corresponds one of the 6 Activities.

### **Problem Statement**

· Given a new datapoint we have to predict the Activity

```
In [2]: import numpy as np
import pandas as pd

# get the features from the file features.txt
features = list()
with open('D:/Data Science/DataSets/Human Activity Recognition/HAR/UCI_HAR_Datase
    features = [line.split()[1] for line in f.readlines()]
print('No of Features: {}'.format(len(features)))
```

No of Features: 561

### Obtain the train data

```
In [4]: # get the data from txt files to pandas dataffame
        X train = pd.read csv('D:/Data Science/DataSets/Human Activity Recognition/HAR/U
        # add subject column to the dataframe
        X_train['subject'] = pd.read_csv('D:/Data Science/DataSets/Human Activity Recogn:
        y train = pd.read csv('D:/Data Science/DataSets/Human Activity Recognition/HAR/U
        y_train_labels = y_train.map({1: 'WALKING', 2: 'WALKING_UPSTAIRS',3: 'WALKING_DOWN'
                                 4: 'SITTING', 5: 'STANDING', 6: 'LAYING'})
        # put all columns in a single dataframe
        train = X_train
        train['Activity'] = y_train
        train['ActivityName'] = y_train_labels
         train.sample()
        C:\Users\AbhiShek\Anaconda3\lib\site-packages\pandas\io\parsers.py:678: UserWar
        ning: Duplicate names specified. This will raise an error in the future.
           return read(filepath or buffer, kwds)
Out[4]:
               tBodyAcc-
                        tBodyAcc- tBodyAcc- tBodyAcc-
                                                                tBodyAcc- tBodyAcc-
                                                                                    tBodyAcc-
                mean()-X
                          mean()-Y
                                    mean()-Z
                                               std()-X
                                                          std()-Y
                                                                   std()-Z
                                                                            mad()-X
                                                                                      mad()-Y
         3187
                0.293261
                         -0.023525
                                   -0.032613
                                             -0.372487
                                                       -0.423219
                                                                 -0.101452
                                                                           -0.369648
                                                                                     -0.463183
        1 rows × 564 columns
In [5]:
        train.shape
Out[5]: (7352, 564)
```

## Obtain the test data

```
In [6]: # get the data from txt files to pandas dataffame
         X test = pd.read csv('D:/Data Science/DataSets/Human Activity Recognition/HAR/UC]
         # add subject column to the dataframe
         X_test['subject'] = pd.read_csv('D:/Data Science/DataSets/Human Activity Recognit
         # get y labels from the txt file
         y_test = pd.read_csv('D:/Data Science/DataSets/Human Activity Recognition/HAR/UC]
         y_test_labels = y_test.map({1: 'WALKING', 2:'WALKING_UPSTAIRS',3:'WALKING_DOWNST/
                                  4: 'SITTING', 5: 'STANDING', 6: 'LAYING'})
         # put all columns in a single dataframe
         test = X test
         test['Activity'] = y test
         test['ActivityName'] = y_test_labels
         test.sample()
Out[6]:
              tBodyAcc-
                        tBodyAcc-
                                   tBodyAcc-
                                             tBodyAcc-
                                                       tBodyAcc-
                                                                 tBodyAcc-
                                                                            tBodyAcc-
                                                                                      tBodyAcc-
                                    mean()-Z
               mean()-X
                          mean()-Y
                                                std()-X
                                                          std()-Y
                                                                    std()-Z
                                                                              mad()-X
                                                                                        mad()-Y
          916
               0.273981
                         -0.028811
                                    -0.113628
                                               -0.99482
                                                        -0.969272
                                                                  -0.983297
                                                                            -0.995276
                                                                                       -0.968838
         1 rows × 564 columns
In [7]:
        test.shape
Out[7]: (2947, 564)
```

# **Data Cleaning**

# 1. Check for Duplicates

```
In [8]: print('No of duplicates in train: {}'.format(sum(train.duplicated())))
    print('No of duplicates in test : {}'.format(sum(test.duplicated())))

    No of duplicates in train: 0
    No of duplicates in test : 0
```

# 2. Checking for NaN/null values

```
In [9]: print('We have {} NaN/Null values in train'.format(train.isnull().values.sum()))
    print('We have {} NaN/Null values in test'.format(test.isnull().values.sum()))
    We have 0 NaN/Null values in train
```

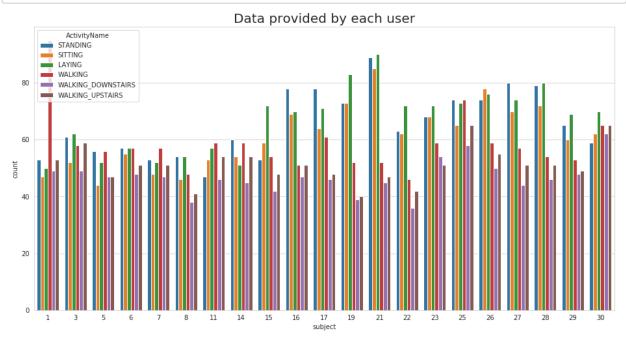
## 3. Check for data imbalance

We have 0 NaN/Null values in test

```
In [10]: import matplotlib.pyplot as plt
import seaborn as sns

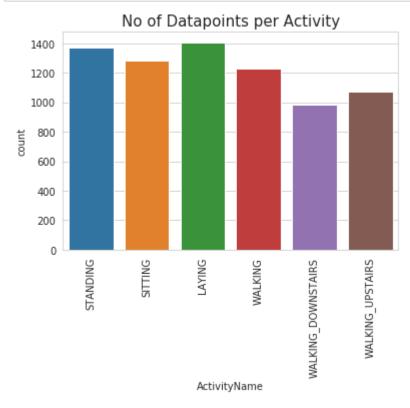
sns.set_style('whitegrid')
plt.rcParams['font.family'] = 'Dejavu Sans'
```

```
In [11]: plt.figure(figsize=(16,8))
   plt.title('Data provided by each user', fontsize=20)
   sns.countplot(x='subject',hue='ActivityName', data = train)
   plt.show()
```



We have got almost same number of reading from all the subjects

```
In [12]: plt.title('No of Datapoints per Activity', fontsize=15)
    sns.countplot(train.ActivityName)
    plt.xticks(rotation=90)
    plt.show()
```



### **Observation**

Our data is well balanced (almost)

# 4. Changing feature names

```
In [16]: | columns = train.columns
         # Removing '()' from column names
         columns = columns.str.replace('[()]','')
         columns = columns.str.replace('[-]',
          columns = columns.str.replace('[,]','')
         train.columns = columns
          test.columns = columns
         test.columns
Out[16]: Index(['tBodyAccmeanX', 'tBodyAccmeanY', 'tBodyAccmeanZ', 'tBodyAccstdX',
                 'tBodyAccstdY', 'tBodyAccstdZ', 'tBodyAccmadX', 'tBodyAccmadY',
                 'tBodyAccmadZ', 'tBodyAccmaxX',
                 'angletBodyAccMeangravity', 'angletBodyAccJerkMeangravityMean',
                 'angletBodyGyroMeangravityMean', 'angletBodyGyroJerkMeangravityMean',
                 'angleXgravityMean', 'angleYgravityMean', 'angleZgravityMean',
                 'subject', 'Activity', 'ActivityName'],
                dtype='object', length=564)
```

### 5. Save this dataframe in a csy files

```
In [17]: train.to_csv('D:/Data Science/DataSets/Human Activity Recognition/HAR/UCI_HAR_Data
test.to_csv('D:/Data Science/DataSets/Human Activity Recognition/HAR/UCI_HAR_Data
```

# **Exploratory Data Analysis**

"Without domain knowledge EDA has no meaning, without EDA a problem has no soul."

## 1. Featuring Engineering from Domain Knowledge

- Static and Dynamic Activities
  - In static activities (sit, stand, lie down) motion information will not be very useful.
  - In the dynamic activities (Walking, WalkingUpstairs, WalkingDownstairs) motion info will be significant.

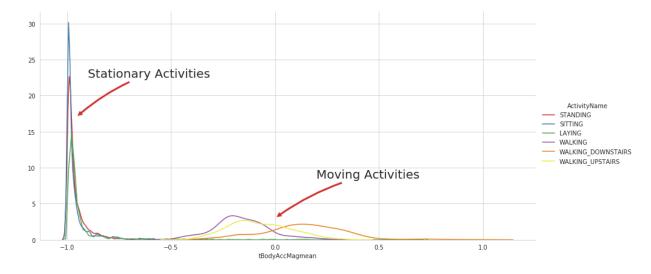
## 2. Stationary and Moving activities are completely different

```
In [18]: sns.set_palette("Set1", desat=0.80)
    facetgrid = sns.FacetGrid(train, hue='ActivityName', size=6,aspect=2)
    facetgrid.map(sns.distplot,'tBodyAccMagmean', hist=False)\
        .add_legend()
    plt.annotate("Stationary Activities", xy=(-0.956,17), xytext=(-0.9, 23), size=20
        va='center', ha='left',\
        arrowprops=dict(arrowstyle="simple",connectionstyle="arc3,rad=0.1"))
    plt.annotate("Moving Activities", xy=(0,3), xytext=(0.2, 9), size=20,\
        va='center', ha='left',\
        arrowprops=dict(arrowstyle="simple",connectionstyle="arc3,rad=0.1"))
    plt.show()
```

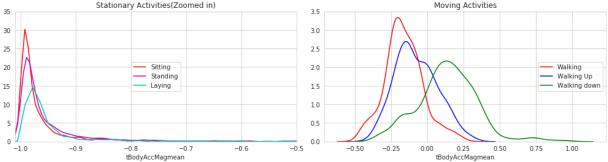
C:\Users\AbhiShek\Anaconda3\lib\site-packages\seaborn\axisgrid.py:230: UserWarn
ing: The `size` paramter has been renamed to `height`; please update your code.
 warnings.warn(msg, UserWarning)

C:\Users\AbhiShek\Anaconda3\lib\site-packages\scipy\stats\stats.py:1713: Future Warning: Using a non-tuple sequence for multidimensional indexing is deprecate d; use `arr[tuple(seq)]` instead of `arr[seq]`. In the future this will be inte rpreted as an array index, `arr[np.array(seq)]`, which will result either in an error or a different result.

return np.add.reduce(sorted[indexer] \* weights, axis=axis) / sumval

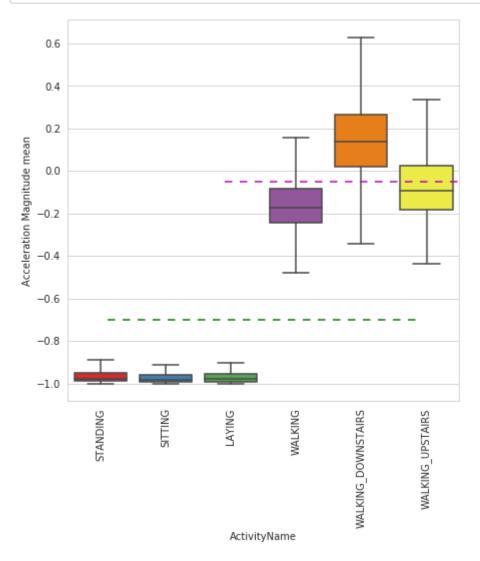


```
In [19]: # for plotting purposes taking datapoints of each activity to a different datafro
          df1 = train[train['Activity']==1]
          df2 = train[train['Activity']==2]
          df3 = train[train['Activity']==3]
          df4 = train[train['Activity']==4]
          df5 = train[train['Activity']==5]
          df6 = train[train['Activity']==6]
          plt.figure(figsize=(14,7))
          plt.subplot(2,2,1)
          plt.title('Stationary Activities(Zoomed in)')
          sns.distplot(df4['tBodyAccMagmean'],color = 'r',hist = False, label = 'Sitting')
          sns.distplot(df5['tBodyAccMagmean'],color = 'm',hist = False,label = 'Standing')
          sns.distplot(df6['tBodyAccMagmean'],color = 'c',hist = False, label = 'Laying')
          plt.axis([-1.01, -0.5, 0, 35])
          plt.legend(loc='center')
         plt.subplot(2,2,2)
          plt.title('Moving Activities')
          sns.distplot(df1['tBodyAccMagmean'],color = 'red',hist = False, label = 'Walking'
          sns.distplot(df2['tBodyAccMagmean'],color = 'blue',hist = False,label = 'Walking
          sns.distplot(df3['tBodyAccMagmean'],color = 'green',hist = False, label = 'Walking
          plt.legend(loc='center right')
          plt.tight layout()
          plt.show()
                       Stationary Activities(Zoomed in)
                                                                    Moving Activities
```



### 3. Magnitude of an acceleration can saperate it well

```
In [20]: plt.figure(figsize=(7,7))
    sns.boxplot(x='ActivityName', y='tBodyAccMagmean',data=train, showfliers=False,
    plt.ylabel('Acceleration Magnitude mean')
    plt.axhline(y=-0.7, xmin=0.1, xmax=0.9,dashes=(5,5), c='g')
    plt.axhline(y=-0.05, xmin=0.4, dashes=(5,5), c='m')
    plt.xticks(rotation=90)
    plt.show()
```

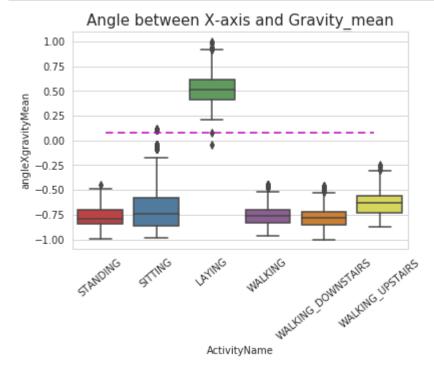


#### Observations :

- If tAccMean is < -0.8 then the Activities are either Standing or Sitting or Laying.
- If tAccMean is > -0.6 then the Activities are either Walking or WalkingDownstairs or WalkingUpstairs.
- If tAccMean > 0.0 then the Activity is WalkingDownstairs.
- We can classify 75% the Acitivity labels with some errors.

# 4. Position of GravityAccelerationComponants also matters

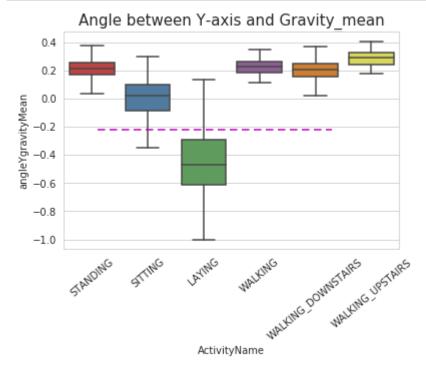
```
In [21]: sns.boxplot(x='ActivityName', y='angleXgravityMean', data=train)
  plt.axhline(y=0.08, xmin=0.1, xmax=0.9,c='m',dashes=(5,3))
  plt.title('Angle between X-axis and Gravity_mean', fontsize=15)
  plt.xticks(rotation = 40)
  plt.show()
```



#### \_\_ Observations\_ :

- If angleX,gravityMean > 0 then Activity is Laying.
- We can classify all datapoints belonging to Laying activity with just a single if else statement.

```
In [22]: sns.boxplot(x='ActivityName', y='angleYgravityMean', data = train, showfliers=Fa!
    plt.title('Angle between Y-axis and Gravity_mean', fontsize=15)
    plt.xticks(rotation = 40)
    plt.axhline(y=-0.22, xmin=0.1, xmax=0.8, dashes=(5,3), c='m')
    plt.show()
```



# Apply t-sne on the data

```
In [23]: import numpy as np
    from sklearn.manifold import TSNE
    import matplotlib.pyplot as plt
    import seaborn as sns
```

In [24]: # performs t-sne with different perplexity values and their repective plots.. def perform\_tsne(X\_data, y\_data, perplexities, n\_iter=1000, img\_name\_prefix='t-s for index,perplexity in enumerate(perplexities): # perform t-sne print('\nperforming tsne with perplexity {} and with {} iterations at max X reduced = TSNE(verbose=2, perplexity=perplexity).fit transform(X data) print('Done..') # prepare the data for seaborn print('Creating plot for this t-sne visualization..') df = pd.DataFrame({'x':X\_reduced[:,0], 'y':X\_reduced[:,1], 'label':y\_data # draw the plot in appropriate place in the grid sns.lmplot(data=df, x='x', y='y', hue='label', fit\_reg=False, size=8,\ palette="Set1", markers=['^','v','s','o', '1','2']) plt.title("perplexity : {} and max\_iter : {}".format(perplexity, n\_iter) img\_name = img\_name\_prefix + '\_perp\_{}\_iter\_{}.png'.format(perplexity, n) print('saving this plot as image in present working directory...') plt.savefig(img name) plt.show() print('Done')

```
In [25]: X pre tsne = train.drop(['subject', 'Activity', 'ActivityName'], axis=1)
         y pre tsne = train['ActivityName']
         perform_tsne(X_data = X_pre_tsne,y_data=y_pre_tsne, perplexities =[2,5,10,20,50]
         performing tsne with perplexity 2 and with 1000 iterations at max
         [t-SNE] Computing 7 nearest neighbors...
         [t-SNE] Indexed 7352 samples in 1.155s...
         [t-SNE] Computed neighbors for 7352 samples in 112.536s...
         [t-SNE] Computed conditional probabilities for sample 1000 / 7352
         [t-SNE] Computed conditional probabilities for sample 2000 / 7352
         [t-SNE] Computed conditional probabilities for sample 3000 / 7352
         [t-SNE] Computed conditional probabilities for sample 4000 / 7352
         [t-SNE] Computed conditional probabilities for sample 5000 / 7352
         [t-SNE] Computed conditional probabilities for sample 6000 / 7352
         [t-SNE] Computed conditional probabilities for sample 7000 / 7352
         [t-SNE] Computed conditional probabilities for sample 7352 / 7352
         [t-SNE] Mean sigma: 0.635855
         [t-SNE] Computed conditional probabilities in 0.230s
         [t-SNE] Iteration 50: error = 124.6072464, gradient norm = 0.0293802 (50 iterat
         ions in 63.265s)
         [t-SNE] Iteration 100: error = 106.7274857, gradient norm = 0.0284123 (50 itera
         tions in 19.866s)
         [t-SNE] Iteration 150: error = 100.5138168, gradient norm = 0.0212159 (50 itera
         tions in 14.369s)
         [t-SNE] Iteration 200: error = 97.1543350, gradient norm = 0.0138972 (50 iterat
         ions in 16.274s)
         [t-SNE] Iteration 250: error = 94.8875732, gradient norm = 0.0135609 (50 iterat
         ions in 14.600s)
         [t-SNE] KL divergence after 250 iterations with early exaggeration: 94.887573
         [t-SNE] Iteration 300: error = 4.1089158, gradient norm = 0.0015571 (50 iterati
         ons in 12.766s)
         [t-SNE] Iteration 350: error = 3.2025001, gradient norm = 0.0010133 (50 iterati
         ons in 11.476s)
         [t-SNE] Iteration 400: error = 2.7752001, gradient norm = 0.0007069 (50 iterati
         ons in 13.484s)
         [t-SNE] Iteration 450: error = 2.5115306, gradient norm = 0.0005675 (50 iterati
         ons in 15.160s)
         [t-SNE] Iteration 500: error = 2.3281095, gradient norm = 0.0004815 (50 iterati
         ons in 13.445s)
         [t-SNE] Iteration 550: error = 2.1900091, gradient norm = 0.0004182 (50 iterati
         ons in 13.676s)
         [t-SNE] Iteration 600: error = 2.0808878, gradient norm = 0.0003681 (50 iterati
         ons in 12.346s)
         [t-SNE] Iteration 650: error = 1.9910871, gradient norm = 0.0003328 (50 iterati
         ons in 11.822s)
         [t-SNE] Iteration 700: error = 1.9155139, gradient norm = 0.0003052 (50 iterati
         ons in 13.124s)
         [t-SNE] Iteration 750: error = 1.8509530, gradient norm = 0.0002780 (50 iterati
         ons in 12.298s)
         [t-SNE] Iteration 800: error = 1.7944051, gradient norm = 0.0002575 (50 iterati
         ons in 12.038s)
         [t-SNE] Iteration 850: error = 1.7443788, gradient norm = 0.0002405 (50 iterati
         ons in 12.365s)
         [t-SNE] Iteration 900: error = 1.6996990, gradient norm = 0.0002256 (50 iterati
         ons in 13.643s)
         [t-SNE] Iteration 950: error = 1.6597550, gradient norm = 0.0002102 (50 iterati
```

ons in 11.908s)

[t-SNE] Iteration 1000: error = 1.6233310, gradient norm = 0.0001996 (50 iterations in 12.070s)

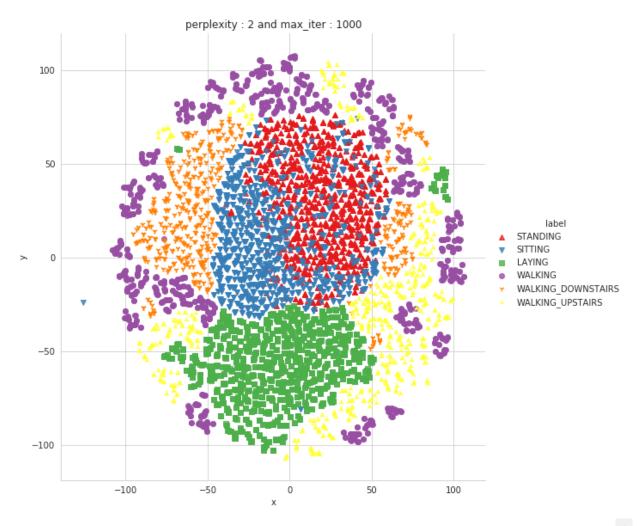
[t-SNE] KL divergence after 1000 iterations: 1.623331 Done..

Creating plot for this t-sne visualization..

C:\Users\AbhiShek\Anaconda3\lib\site-packages\seaborn\regression.py:546: UserWa
rning: The `size` paramter has been renamed to `height`; please update your cod
e.

warnings.warn(msg, UserWarning)

saving this plot as image in present working directory...



Done

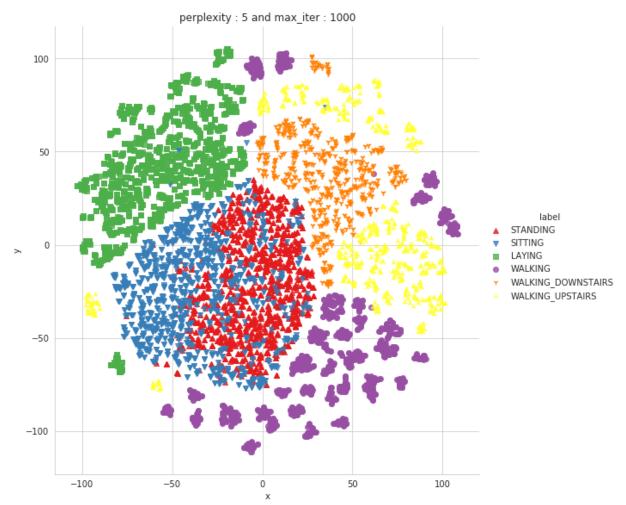
performing tsne with perplexity 5 and with 1000 iterations at max [t-SNE] Computing 16 nearest neighbors...
[t-SNE] Indexed 7352 samples in 1.053s...
[t-SNE] Computed neighbors for 7352 samples in 100.602s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352

```
[t-SNE] Mean sigma: 0.961265
[t-SNE] Computed conditional probabilities in 0.253s
[t-SNE] Iteration 50: error = 114.0863495, gradient norm = 0.0188521 (50 iter
ations in 79.557s)
[t-SNE] Iteration 100: error = 98.0800858, gradient norm = 0.0201187 (50 iter
ations in 13.542s)
[t-SNE] Iteration 150: error = 93.2168655, gradient norm = 0.0085039 (50 iter
ations in 10.792s)
[t-SNE] Iteration 200: error = 91.1977997, gradient norm = 0.0068545 (50 iter
ations in 10.614s)
[t-SNE] Iteration 250: error = 90.0160217, gradient norm = 0.0051163 (50 iter
ations in 11.121s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 90.016022
[t-SNE] Iteration 300: error = 3.5688493, gradient norm = 0.0014635 (50 itera
tions in 11.864s)
[t-SNE] Iteration 350: error = 2.8120923, gradient norm = 0.0007544 (50 itera
tions in 11.967s)
[t-SNE] Iteration 400: error = 2.4321444, gradient norm = 0.0005267 (50 itera
tions in 14.335s)
[t-SNE] Iteration 450: error = 2.2146897, gradient norm = 0.0004099 (50 itera
tions in 12.450s)
[t-SNE] Iteration 500: error = 2.0699124, gradient norm = 0.0003320 (50 itera
tions in 11.356s)
[t-SNE] Iteration 550: error = 1.9648247, gradient norm = 0.0002820 (50 itera
tions in 11.541s)
[t-SNE] Iteration 600: error = 1.8836201, gradient norm = 0.0002458 (50 itera
tions in 11.425s)
[t-SNE] Iteration 650: error = 1.8184061, gradient norm = 0.0002208 (50 itera
tions in 12.068s)
[t-SNE] Iteration 700: error = 1.7647971, gradient norm = 0.0002017 (50 itera
tions in 12.484s)
[t-SNE] Iteration 750: error = 1.7194536, gradient norm = 0.0001817 (50 itera
tions in 12.060s)
[t-SNE] Iteration 800: error = 1.6805577, gradient norm = 0.0001653 (50 itera
tions in 12.247s)
[t-SNE] Iteration 850: error = 1.6467464, gradient norm = 0.0001522 (50 itera
tions in 12.088s)
[t-SNE] Iteration 900: error = 1.6173606, gradient norm = 0.0001425 (50 itera
tions in 12.604s)
[t-SNE] Iteration 950: error = 1.5908659, gradient norm = 0.0001337 (50 itera
tions in 14.484s)
[t-SNE] Iteration 1000: error = 1.5671388, gradient norm = 0.0001258 (50 iter
ations in 11.596s)
[t-SNE] KL divergence after 1000 iterations: 1.567139
Done..
Creating plot for this t-sne visualization..
```

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rning: The `size` paramter has been renamed to `height`; please update your cod
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warnings.warn(msg, UserWarning)

saving this plot as image in present working directory...



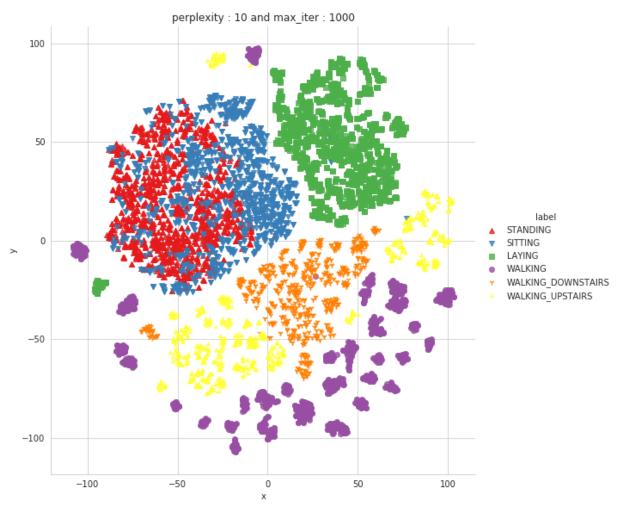
### Done performing tsne with perplexity 10 and with 1000 iterations at max [t-SNE] Computing 31 nearest neighbors... [t-SNE] Indexed 7352 samples in 1.048s... [t-SNE] Computed neighbors for 7352 samples in 103.277s... [t-SNE] Computed conditional probabilities for sample 1000 / 7352 [t-SNE] Computed conditional probabilities for sample 2000 / 7352 [t-SNE] Computed conditional probabilities for sample 3000 / 7352 [t-SNE] Computed conditional probabilities for sample 4000 / 7352 [t-SNE] Computed conditional probabilities for sample 5000 / 7352 [t-SNE] Computed conditional probabilities for sample 6000 / 7352 [t-SNE] Computed conditional probabilities for sample 7000 / 7352 [t-SNE] Computed conditional probabilities for sample 7352 / 7352 [t-SNE] Mean sigma: 1.133828 [t-SNE] Computed conditional probabilities in 0.464s [t-SNE] Iteration 50: error = 106.0009155, gradient norm = 0.0174350 (50 iter ations in 20.064s) [t-SNE] Iteration 100: error = 90.0872955, gradient norm = 0.0094683 (50 iter ations in 14.128s) [t-SNE] Iteration 150: error = 87.1639633, gradient norm = 0.0058647 (50 iter ations in 11.899s) [t-SNE] Iteration 200: error = 85.9645920, gradient norm = 0.0036640 (50 iter ations in 11.928s) [t-SNE] Iteration 250: error = 85.2860794, gradient norm = 0.0026224 (50 iter ations in 11.844s) [t-SNE] KL divergence after 250 iterations with early exaggeration: 85.286079

```
[t-SNE] Iteration 300: error = 3.1280198, gradient norm = 0.0013836 (50 itera
tions in 11.576s)
[t-SNE] Iteration 350: error = 2.4868314, gradient norm = 0.0006476 (50 itera
tions in 11.568s)
[t-SNE] Iteration 400: error = 2.1673632, gradient norm = 0.0004217 (50 itera
tions in 11.865s)
[t-SNE] Iteration 450: error = 1.9831210, gradient norm = 0.0003133 (50 itera
tions in 11.888s)
[t-SNE] Iteration 500: error = 1.8652360, gradient norm = 0.0002504 (50 itera
tions in 11.940s)
[t-SNE] Iteration 550: error = 1.7819157, gradient norm = 0.0002087 (50 itera
tions in 12.060s)
[t-SNE] Iteration 600: error = 1.7195656, gradient norm = 0.0001825 (50 itera
tions in 12.056s)
[t-SNE] Iteration 650: error = 1.6709391, gradient norm = 0.0001597 (50 itera
tions in 12.244s)
[t-SNE] Iteration 700: error = 1.6315612, gradient norm = 0.0001416 (50 itera
tions in 12.135s)
[t-SNE] Iteration 750: error = 1.5988730, gradient norm = 0.0001290 (50 itera
tions in 11.985s)
[t-SNE] Iteration 800: error = 1.5714006, gradient norm = 0.0001181 (50 itera
tions in 12.255s)
[t-SNE] Iteration 850: error = 1.5479939, gradient norm = 0.0001105 (50 itera
tions in 11.995s)
[t-SNE] Iteration 900: error = 1.5277385, gradient norm = 0.0001039 (50 itera
tions in 12.093s)
[t-SNE] Iteration 950: error = 1.5101272, gradient norm = 0.0000968 (50 itera
tions in 11.991s)
[t-SNE] Iteration 1000: error = 1.4950068, gradient norm = 0.0000900 (50 iter
ations in 11.887s)
[t-SNE] KL divergence after 1000 iterations: 1.495007
Done..
Creating plot for this t-sne visualization..
```

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rning: The `size` paramter has been renamed to `height`; please update your cod
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warnings.warn(msg, UserWarning)

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#### Done

```
performing tsne with perplexity 20 and with 1000 iterations at max
[t-SNE] Computing 61 nearest neighbors...
[t-SNE] Indexed 7352 samples in 1.122s...
[t-SNE] Computed neighbors for 7352 samples in 106.098s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 1.274335
[t-SNE] Computed conditional probabilities in 0.900s
[t-SNE] Iteration 50: error = 97.3011856, gradient norm = 0.0224332 (50 iterati
ons in 19.470s)
[t-SNE] Iteration 100: error = 83.9715042, gradient norm = 0.0070448 (50 iterat
ions in 15.226s)
[t-SNE] Iteration 150: error = 81.8507843, gradient norm = 0.0048790 (50 iterat
ions in 13.235s)
[t-SNE] Iteration 200: error = 81.1384964, gradient norm = 0.0024416 (50 iterat
ions in 12.757s)
[t-SNE] Iteration 250: error = 80.7604904, gradient norm = 0.0021101 (50 iterat
ions in 12.730s)
```

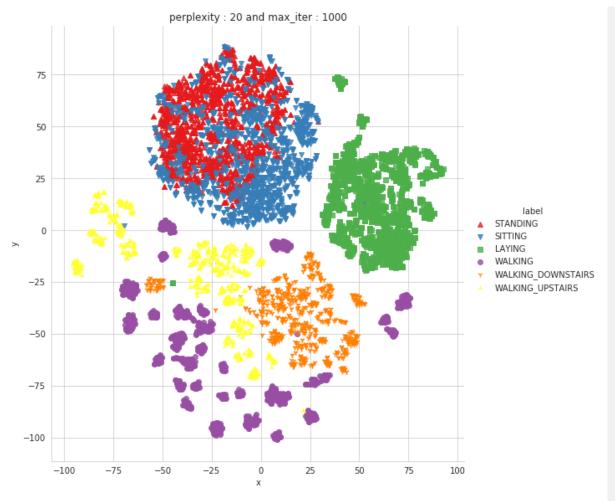
```
[t-SNE] KL divergence after 250 iterations with early exaggeration: 80.760490
[t-SNE] Iteration 300: error = 2.7005243, gradient norm = 0.0013154 (50 iterati
ons in 13.334s)
[t-SNE] Iteration 350: error = 2.1653914, gradient norm = 0.0005787 (50 iterati
ons in 12.956s)
[t-SNE] Iteration 400: error = 1.9153993, gradient norm = 0.0003486 (50 iterati
ons in 12.929s)
[t-SNE] Iteration 450: error = 1.7684736, gradient norm = 0.0002503 (50 iterati
ons in 12.914s)
[t-SNE] Iteration 500: error = 1.6739802, gradient norm = 0.0001932 (50 iterati
ons in 13.038s)
[t-SNE] Iteration 550: error = 1.6093826, gradient norm = 0.0001586 (50 iterati
ons in 12.928s)
[t-SNE] Iteration 600: error = 1.5627661, gradient norm = 0.0001349 (50 iterati
ons in 12.986s)
[t-SNE] Iteration 650: error = 1.5278101, gradient norm = 0.0001188 (50 iterati
ons in 12.941s)
[t-SNE] Iteration 700: error = 1.5009102, gradient norm = 0.0001056 (50 iterati
ons in 13.234s)
[t-SNE] Iteration 750: error = 1.4791521, gradient norm = 0.0000976 (50 iterati
ons in 13.016s)
[t-SNE] Iteration 800: error = 1.4616399, gradient norm = 0.0000922 (50 iterati
ons in 12.901s)
[t-SNE] Iteration 850: error = 1.4480585, gradient norm = 0.0000852 (50 iterati
ons in 12.841s)
[t-SNE] Iteration 900: error = 1.4368564, gradient norm = 0.0000810 (50 iterati
ons in 12.933s)
[t-SNE] Iteration 950: error = 1.4271523, gradient norm = 0.0000784 (50 iterati
ons in 13.482s)
[t-SNE] Iteration 1000: error = 1.4188796, gradient norm = 0.0000740 (50 iterat
ions in 13.092s)
[t-SNE] KL divergence after 1000 iterations: 1.418880
Done..
Creating plot for this t-sne visualization..
```

Creating plot for this t-sne visualization..

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rning: The `size` paramter has been renamed to `height`; please update your cod
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warnings.warn(msg, UserWarning)

saving this plot as image in present working directory...



#### Done

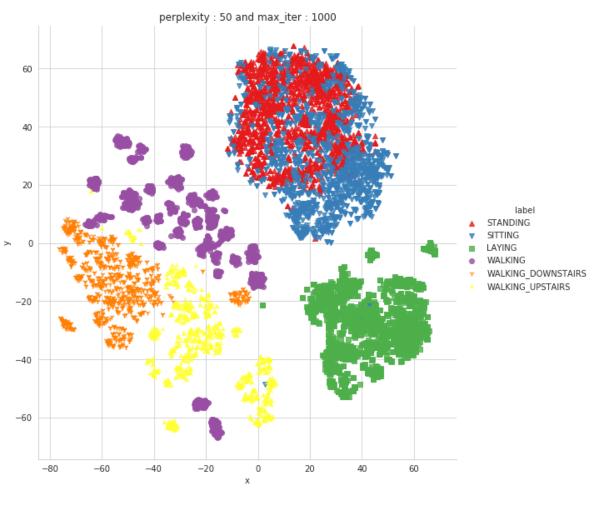
```
performing tsne with perplexity 50 and with 1000 iterations at max
[t-SNE] Computing 151 nearest neighbors...
[t-SNE] Indexed 7352 samples in 1.114s...
[t-SNE] Computed neighbors for 7352 samples in 109.793s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 1.437672
[t-SNE] Computed conditional probabilities in 2.207s
[t-SNE] Iteration 50: error = 84.0422897, gradient norm = 0.0363341 (50 iterati
ons in 24.137s)
[t-SNE] Iteration 100: error = 75.4566116, gradient norm = 0.0040860 (50 iterat
ions in 19.927s)
[t-SNE] Iteration 150: error = 74.5398560, gradient norm = 0.0021245 (50 iterat
ions in 18.829s)
[t-SNE] Iteration 200: error = 74.2107315, gradient norm = 0.0016666 (50 iterat
ions in 18.653s)
[t-SNE] Iteration 250: error = 74.0450592, gradient norm = 0.0010618 (50 iterat
ions in 18.910s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 74.045059
```

```
[t-SNE] Iteration 300: error = 2.1555035, gradient norm = 0.0011724 (50 iterati
ons in 17.270s)
[t-SNE] Iteration 350: error = 1.7573167, gradient norm = 0.0004940 (50 iterati
ons in 15.747s)
[t-SNE] Iteration 400: error = 1.5883399, gradient norm = 0.0002812 (50 iterati
ons in 15.750s)
[t-SNE] Iteration 450: error = 1.4943053, gradient norm = 0.0001912 (50 iterati
ons in 15.839s)
[t-SNE] Iteration 500: error = 1.4343805, gradient norm = 0.0001416 (50 iterati
ons in 16.133s)
[t-SNE] Iteration 550: error = 1.3932742, gradient norm = 0.0001122 (50 iterati
ons in 16.167s)
[t-SNE] Iteration 600: error = 1.3639315, gradient norm = 0.0000935 (50 iterati
ons in 16.190s)
[t-SNE] Iteration 650: error = 1.3424832, gradient norm = 0.0000867 (50 iterati
ons in 16.283s)
[t-SNE] Iteration 700: error = 1.3265698, gradient norm = 0.0000732 (50 iterati
ons in 18.066s)
[t-SNE] Iteration 750: error = 1.3144740, gradient norm = 0.0000711 (50 iterati
ons in 18.502s)
[t-SNE] Iteration 800: error = 1.3057956, gradient norm = 0.0000639 (50 iterati
ons in 17.354s)
[t-SNE] Iteration 850: error = 1.2986413, gradient norm = 0.0000584 (50 iterati
ons in 18.460s)
[t-SNE] Iteration 900: error = 1.2924331, gradient norm = 0.0000573 (50 iterati
ons in 18.420s)
[t-SNE] Iteration 950: error = 1.2876844, gradient norm = 0.0000558 (50 iterati
ons in 18.573s)
[t-SNE] Iteration 1000: error = 1.2841040, gradient norm = 0.0000517 (50 iterat
ions in 18.757s)
[t-SNE] KL divergence after 1000 iterations: 1.284104
Done..
Creating plot for this t-sne visualization..
```

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rning: The `size` paramter has been renamed to `height`; please update your cod
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