# Convex Optimization Methods for Computing Channel Capacity

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#### The Problem Statement:

- The source possess M distinct messages, one of which it wishes to communicate with the destination.
- The noisy channel takes in one of the N input-symbol (say i) and produces one of the M output symbol with probability distribution Q<sub>i</sub> independently of everything else.



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#### Maximum Achievable Rate

Over all encoding and decoding schemes, what is the maximum achievable rate, for arbitrarily small probability of error ?

$$\max \liminf \frac{\log M}{n} \tag{1}$$

s t

$$\mathbb{P}_n(M \neq \hat{M}) \setminus 0$$

(2)

# Where it all started - Shannon (1948)

34 The Mathematical Theory of Communication

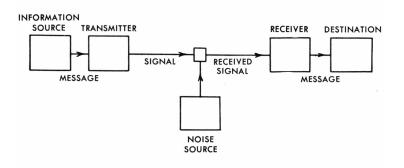
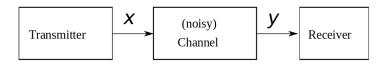


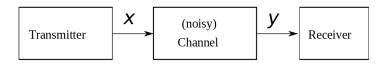
Fig. 1. — Schematic diagram of a general communication system.

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#### Theorem: Shannon 1948

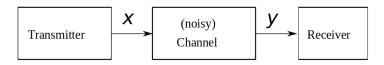
For every channel matrix Q, maximum achievable rate is given by

$$C = \max_{\mathbf{p}_{\chi}} I(X; Y) \tag{3}$$

Where I(X;Y) denotes the *mutual information* between the random variables X and Y.



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### Objective of this talk

Solve the optimization problem 3.



### Review of some useful functionals

• For two PMF  $\mathbf{p}$  and  $\mathbf{q}$  with the same support, the K-L divergence between  $\mathbf{p}$  and  $\mathbf{q}$  is given by,

$$D(\mathbf{p}||\mathbf{q}) = \sum_{x \in X} p_x \log \frac{p_x}{q_x}$$

Property:

$$D(\mathbf{p}||\mathbf{q}) \ge 0 \tag{4}$$

With equality iff  $\mathbf{p} = \mathbf{q}$ .

Mutual Information

$$I(X;Y) = I(\mathbf{p}, \mathbf{Q}) = \sum_{i=1}^{N} p_i \left( \sum_{j=1}^{M} Q_{ij} \log Q_{ij} \right) - \sum_{j=1}^{M} q_j \log q_j$$
 (5)

Where,

$$Qq = p$$

The PMF  $\mathbf{q}$  is known as the output distribution.



# Some Properties of mutual information $I(X; Y) = I(\mathbf{p}, \mathbf{Q})$

#### Lemma

 $I(X; Y) \equiv I(\mathbf{p}, \mathbf{Q})$  is concave in the variable  $\mathbf{p}$ .

Thus the problem 3 corresponds to maximizing a differentiable concave function over the probability simplex.

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Thus the problem 3 corresponds to maximizing a differentiable concave function over the probability simplex.

- All off-the-shelf constrained convex optimization methods are applicable.
- Slow in practice as they do not take into account the structure of the problem.

We describe the celebrated Blahut-Arimoto Algorithm for solving the problem.

 we need to obtain a variational characterization of the mutual information I(X;Y).



# A Variational Characterization of $I(X; Y) = I(\mathbf{p}, \mathbf{Q})$

For a set of conditional input distributions  $\Phi = \{\phi(\cdot|j), j \in \mathcal{Y}\}$  indexed by the output symbol j, define the functional

$$\tilde{I}(\mathbf{p}, \mathbf{Q}; \phi) = \sum_{i=1}^{N} \sum_{j=1}^{M} p_i Q_{ij} \log \frac{\phi(i|j)}{p_i}$$

**Proposition:** For a fixed  $\mathbf{Q} \tilde{I}(\mathbf{p}, \mathbf{Q}; \phi)$  is concave individually in  $\mathbf{p}$  and  $\phi$ .



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#### Theorem

For any matrix of conditional probabilities  $\phi$ , we have

$$\max_{\phi} \tilde{I}(\mathbf{p}, \mathbf{Q}; \phi) = I(\mathbf{p}, \mathbf{Q}) \tag{7}$$

where maxima is achieved for  $\phi(i|j) = \phi^*(i|j) = p_i \frac{Q_{ij}}{\sum_{i=1}^{N} p_i Q_{ij}}$ .



With the help from the previous theorem we can reformulate the original optimization problem OPT as follows

### Capacity Reformulation

$$C = \max_{\mathbf{p}} \max_{\phi} \tilde{I}(\mathbf{p}, \mathbf{Q}; \phi)$$
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- An intuitively obvious algorithm for solving the above problem would be to repeatedly fix one set of variables ( $\mathbf{p}$  or  $\phi$ ) and optimize over the other.
- This is attractive in this case as there are closed form solutions for both the optimization problems.
- Concave character of  $\tilde{I}(\mathbf{p}, \mathbf{Q}; \phi)$  guarantees that the method converges to optima.



# Iterative Algorithm for solving OPT

#### Blahut-Arimoto Algorithm for Channel Capacity

**Step 1:** Initialize  $\mathbf{p}^{(1)}$  to the uniform distribution over  $\mathcal{X}$ , i.e.  $p_i^{(1)} = \frac{1}{|\mathcal{X}|}$  for all  $i \in \mathcal{X}$ . Set t to 1.

**Step 2:** Find  $\phi^{(t+1)}$  as follows:

$$\phi^{(t+1)}(i|j) = \frac{p_i^{(t)} Q_{ij}}{\sum_k p_k^{(t)} Q_{kj}}, \quad \forall i, j$$
 (9)

**Step 3:** Update  $\mathbf{p}^{(t+1)}$  as follows:

$$p_i^{(t+1)} = \frac{r_i^{(t+1)}}{\sum_{k \in \mathcal{X}} r_k^{(t+1)}}$$
 (10)

Where,

$$r_i^{(t+1)} = \exp\left(\sum_j Q_{ij} \log \phi^{(t+1)}(i|j)\right)$$
 (11)

**Step 4:** Set  $t \leftarrow t + 1$  and goto Step 2.





# Convergence Rates and Improvements

#### Theorem

The BA algorithm has a convergence rate  $\Theta(\frac{1}{t})$ .

Can we do better?



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#### Can we do better?

• By plugging-in the solution  $\phi^*$  can re-write the BA iteration as follows

$$\mathbf{p}^{t+1} = rg \max_{\mathbf{p}} \left( \sum_{i=1}^{N} p_i D(\mathbf{Q}_i || \mathbf{q}^t) - D(\mathbf{p} || \mathbf{p}^t) \right)$$

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Interpreting the last term as a proximal term, the BA iteration nicely fits into the framework of proximal algorithms.

• Using the idea of appropriately emphasizing/attenuating the penalty term via a weighting factor  $\gamma_t$ , we try the following iteration instead

$$\mathbf{p}^{t+1} = \arg\max_{\mathbf{p}} \left( \sum_{i=1}^{N} p_i D(\mathbf{Q}_i || \mathbf{q}^t) - \gamma_t D(\mathbf{p} || \mathbf{p}^t) \right)$$



### Proximal Reformulations Contd.

The sequence  $\{\gamma_t\}$  is chosen so that we have strict improvement of Capacity estimate at every iteration. Define the *maximum KLD-induced eigenvalue* of **Q** as

$$\lambda_{\mathit{KL}}^2(\mathbf{Q}) = \sup_{\mathbf{p} \neq \mathbf{p}'} \frac{D(\mathbf{p}\mathbf{Q}||\mathbf{p}'\mathbf{Q})}{D(\mathbf{p}||\mathbf{p}')}$$

It can be shown that  $0 \le \lambda_{KL}^2(\mathbf{Q}) \le 1$ .



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#### Lemma

The capacity estimates improves at every iteration if we take  $\gamma_t \geq \lambda_{KI}^2(\mathbf{Q})$ .



### Proximal Reformulations Contd.

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It can be shown that  $0 \le \lambda_{KL}^2(\mathbf{Q}) \le 1$ .

#### Lemma

The capacity estimates improves at every iteration if we take  $\gamma_t \geq \lambda_{KI}^2(\mathbf{Q})$ .

- However  $\lambda_{KI}^2(\mathbf{Q})$  might be difficult to estimate.
- A step-size  $\gamma_t = \frac{D(\mathbf{p}^{(t)}\mathbf{Q}||\mathbf{p}^{(t-1)}\mathbf{Q})}{D(\mathbf{p}^{(t)}||\mathbf{p}^{(t-1)})}$  is found to work well in practice.
- Convergence rate boosted by at least a factor of  $\gamma_{\infty}^{-1}$ .



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**Step 1:** Initialize  $\mathbf{p}^{(1)}$  to the uniform distribution over  $\mathcal{X}$ , i.e.  $p_i^{(1)} = \frac{1}{|\mathcal{X}|}$  for all  $i \in \mathcal{X}$ . Set t to 1.

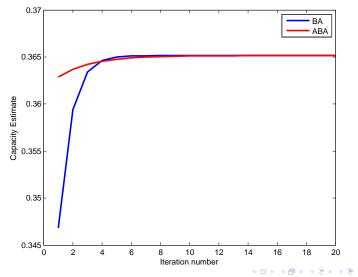
Step 2: Repeat until convergence:

$$\mathbf{q}^{(t)} = \mathbf{p}^{(t)}\mathbf{Q} \tag{12}$$

$$p_i^{(t+1)} = p_i^{(t)} \frac{\exp\left(\gamma_t^{-1} D(\mathbf{Q}_i || \mathbf{q}^{(t)})\right)}{\sum_k p_k^{(t)} \exp\left(\gamma_t^{-1} D(\mathbf{Q}_k || \mathbf{q}^{(t)})\right)} , \forall i \in \mathcal{X}$$
(13)



### **Numerical Simulation**



### Dual Approach

Finally we take the Lagrange dual of the problem OPT. By straight-forward calculations, it turns out to be the following Geometric Program

$$\min_{\mathbf{z}} \sum_{j=1}^{M} z_j$$

Subject to,

$$\prod_{j=1}^{M} z_{j}^{P_{ij}} \geq \exp\left(-H(\mathbf{Q}_{i})\right), \quad i=1,2,\ldots,N$$
 $\mathbf{z} \geq \mathbf{0}$ 

• The above GP is useful for deriving outer bounds on capacity.



### Conclusion and References

- We have discussed both classical and accelerated Blahut-Arimoto Algorithm for computing Channel capacity of a discrete memoryless channel.
- We have discussed their convergence properties and connection with proximal algorithms

#### References:

- S. Arimoto, An algorithm for computing the capacity of arbitrary discrete memoryless channels,
- G. Matz and P. Duhamel, Information geometric formulation and interpretation of accelerated blahut-arimoto-type algorithms,
- M. Chiang and S. Boyd, Geometric programming duals of channel capacity and rate distortion.

