▼ Game: Rock / Paper / Scissors

Description:

Experience the classic game of Rock-Paper-Scissors like never before with our cutting-edge AI opponent!

Step into the arena of digital strategy and quick thinking as you face off against a formidable artificial intelligence that learns and adapts to your every move.

```
RULES :
 Rock && paper => paper wins
 paper && scissor => scissor wins
 Scissor && Rock => Rock wins
 if both are same then it will be tie ( No one get points)
print("Hello world ")
     Hello world
# import the Dataset from G-Drive
! gdown --id 1r-Y_7hOAzKFRnnAp1Tx1RHCL9mDDAz9_
     /usr/local/lib/python3.10/dist-packages/gdown/cli.py:121: FutureWarning: Option `--id` was deprecated in version 4.3.1 and will be
       warnings.warn(
     Downloading...
     From: <a href="https://drive.google.com/uc?id=1r-Y_7h0AzKFRnnAp1Tx1RHCL9mDDAz9">https://drive.google.com/uc?id=1r-Y_7h0AzKFRnnAp1Tx1RHCL9mDDAz9</a>
     To: /content/Rock-Paper-Scissors.zip
     100% 237M/237M [00:09<00:00, 24.5MB/s]
# Dataset is in .zip file. so unzip it
import zipfile
zip_ref = zipfile.ZipFile('/content/Rock-Paper-Scissors.zip', 'r')
zip_ref.extractall('/content') # Destination
zip_ref.close()
import tensorflow as tf
import numpy as np
# Data Loading and Preprocessing:
from tensorflow.keras.preprocessing.image import ImageDataGenerator
# Define data generators for train and test data
train_datagen = ImageDataGenerator(
   rescale=1.0/255.0, # Rescale pixel values to [0, 1]
    rotation_range=20, # random rotation
    width_shift_range=0.2, # horizontal shift
    height_shift_range=0.2, # vertical shift
    shear_range=0.2,
    zoom_range=0.2,
    horizontal_flip=True,
    fill_mode='nearest'
test_datagen = ImageDataGenerator(rescale=1.0/255.0) # Only rescale for test data
# Define batch size and target image size
batch_size = 32
img_size = 300
# Create data generators
train_generator = train_datagen.flow_from_directory(
    '/content/Rock-Paper-Scissors/train',
    target_size=(img_size, img_size),
    batch_size=batch_size,
    class_mode='categorical'
test_generator = test_datagen.flow_from_directory(
    '/content/Rock-Paper-Scissors/test',
```

```
target_size=(img_size, img_size),
batch_size=batch_size,
class_mode='categorical'
)
```

 $\ \ \Box \ \ \$ Found 2520 images belonging to 3 classes. Found 372 images belonging to 3 classes.

```
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Conv2D, MaxPooling2D, Flatten, Dense, Dropout
model = Sequential()
# Convolutional Layer 1
model.add(Conv2D(32, (3, 3), activation='relu', input_shape=(img_size, img_size, 3)))
model.add(MaxPooling2D((2, 2)))
# Convolutional Layer 2
model.add(Conv2D(64, (3, 3), activation='relu'))
model.add(MaxPooling2D((2, 2)))
# Convolutional Layer 3
model.add(Conv2D(128, (3, 3), activation='relu'))
model.add(MaxPooling2D((2, 2)))
# Flatten the output for the dense layers
model.add(Flatten())
# Dense (fully connected) layers
model.add(Dense(128, activation='relu'))
model.add(Dropout(0.5)) # Dropout for regularization
model.add(Dense(3, activation='softmax')) # 3 output classes
# Compile the model
model.compile(optimizer='adam',
              loss='categorical_crossentropy',
              metrics=['accuracy'])
```

model.summary()

Model: "sequential"

·		
Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 298, 298, 32)	896
<pre>max_pooling2d (MaxPooling2D)</pre>	(None, 149, 149, 32)	0
conv2d_1 (Conv2D)	(None, 147, 147, 64)	18496
<pre>max_pooling2d_1 (MaxPooling 2D)</pre>	(None, 73, 73, 64)	0
conv2d_2 (Conv2D)	(None, 71, 71, 128)	73856
<pre>max_pooling2d_2 (MaxPooling 2D)</pre>	(None, 35, 35, 128)	0
flatten (Flatten)	(None, 156800)	0
dense (Dense)	(None, 128)	20070528
dropout (Dropout)	(None, 128)	0
dense_1 (Dense)	(None, 3)	387
Total params: 20,164,163 Trainable params: 20,164,163 Non-trainable params: 0		

```
history = model.fit(train_generator, # from tain folder
epochs=7,
validation_data=test_generator) # from test folder
```

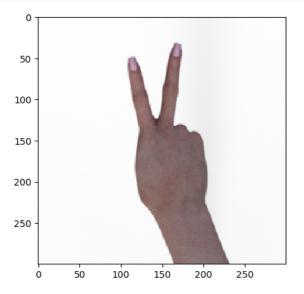
```
Epoch 3/7
    79/79 [==
                         ========] - 380s 5s/step - loss: 0.5654 - accuracy: 0.7746 - val_loss: 0.3227 - val_accuracy: 0.9516
    Epoch 4/7
    Epoch 5/7
                     =========] - 379s 5s/step - loss: 0.3601 - accuracy: 0.8722 - val_loss: 0.1169 - val_accuracy: 0.9704
    79/79 [===
    Epoch 6/7
    79/79 [============== ] - 371s 5s/step - loss: 0.3689 - accuracy: 0.8635 - val_loss: 0.1369 - val_accuracy: 0.9651
    Epoch 7/7
    79/79 [====
                ==========] - 374s 5s/step - loss: 0.2957 - accuracy: 0.8976 - val_loss: 0.0926 - val_accuracy: 0.9785
test_loss, test_accuracy = model.evaluate(test_generator)
print(f'Test loss: {test_loss}')
print(f'Test accuracy: {test_accuracy}')
    12/12 [===========] - 14s 1s/step - loss: 0.0926 - accuracy: 0.9785
    Test loss: 0.09263648092746735
    Test accuracy: 0.9784946441650391
# if want to save model
model.save('GameModel.h5')
```

Model trained successfully, now start testing

JUst a smaple test predict

```
path = '/content/Rock-Paper-Scissors/validation/scissors4.png'

import matplotlib.pyplot as plt
from tensorflow.keras.preprocessing import image
img = image.load_img(path, target_size=(img_size, img_size))
plt.imshow(img, interpolation='nearest')
plt.show()
```



```
img_array = np.array(img).reshape(1,300,300,3)
img_array.shape
```

(1, 300, 300, 3)

```
a = model.predict(img_array)
print(a)
user_choice = a.tolist()[0]
print(user_choice)
```

```
1/1 [======] - 0s 158ms/step [[0. 0. 1.]] [0.0, 0.0, 1.0]
```

User has successfully select a option

- 1. Paper
- 2. Rock

Mechine start to pick a option

```
import random

def random_choice():
    options = [[1, 0, 0, 0,], [0, 1, 0,], [0, 0, 1,]]
    return random.choice(options)

# [1, 0, 0, 0,] => Paper

# [0, 1, 0, 0,] => Rock

# [0, 0, 1,] => Scissor

mechine_choice = random_choice()
print(mechine_choice)
```

[0.0, 1.0, 0.0]

Mechine picked a choice

```
# Geme logic functions
score = { # for storing score of each time
    "User" : 0,
    "Machine" : 0
def game_logic(user, machine):
    # using dictionary to check the conditons
    outcomes = {
       ((1.0, 0.0, 0.0), (0.0, 0.0, 1.0)): "User",
        ((0.0, 1.0, 0.0), (1.0, 0.0, 0.0)): "User",
       ((0.0, 0.0, 1.0), (0.0, 1.0, 0.0)): "User",
   if machine == user:
       return "Tie, no one wins"
    who_wins = outcomes.get((tuple(machine), tuple(user)), "Machine")
    score[who_wins] += 1
    return who_wins + " is the winner"
def which_option(choice):
    options = {
       (1.0, 0.0, 0.0): "Paper",
        (0.0, 1.0, 0.0): "Rock",
        (0.0, 0.0, 1.0): "Scissors"
    return options.get(tuple(choice), "Invalid Choice")
def game_result():
                     # function to print result
   print("\n")
    print("USER : " + which_option(user_choice))
    print("MECHINE : "+ which_option(mechine_choice))
    print("\t")
    print("=>> " + game_logic(user_choice, mechine_choice))
# function to replay the game. better to change Gesture
def replay(newpath):
 img = image.load_img(newpath, target_size=(img_size, img_size))
 # plt.imshow(img, interpolation='nearest')
 # plt.show()
 img_array = np.array(img).reshape(1,300,300,3)
 a = model.predict(img_array)
 global user_choice, mechine_choice
 user_choice = a.tolist()[0]
                               # user choice assigned
 mechine_choice = random_choice() # mechine choice assigned
 # print(user_choice)
 # print(mechine_choice)
 game_result()
# function to show the points between User and mechine
def point_system():
   print("\n----")
    print("User\t| Machine")
   print("-----
```

→ Only for first play

```
game_result()

USER : Scissors
MECHINE : Rock
=>> Machine is the winner
```

→ IF YOU WANT OT PLAY AGAIN, RUN THE CELL BELLOW

MECHINE : Paper

=>> User is the winner

User | Machine

