

# Matrices used in

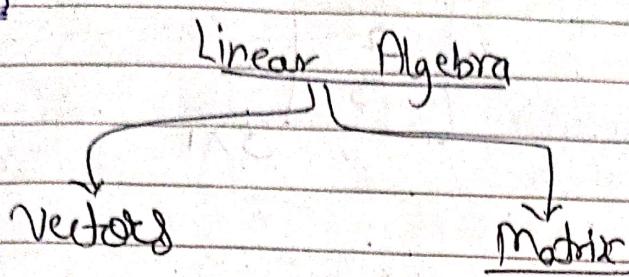
Field →

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## \* Linear Algebra - 2 \*

RCCap



### Matrices?

- A matrix is a rectangular array of no.s, symbols or expressions arranged in rows and columns. The numbers, symbols or expressions are called the elements of the matrix.

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$$

Order of  
matrix

# rows X # columns.

$\boxed{2 \times 3}$  Here  $\boxed{2 \times 3}$  is shape or  
order of matrix.

### Types of Matrix

- 1) Row Matrix → row vector

$$\begin{bmatrix} 1 & 2 & 3 & 4 \end{bmatrix}$$

$1 \times 4$

2) (1) Matrix

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$3 \times 1$

3) Square Matrix -

o no. of rows = no. of columns

$$\begin{bmatrix} a_{11} & 2 \\ 3 & a_{22} \end{bmatrix} \quad 2 \times 2$$

$$\begin{bmatrix} a_{11} & 2 & 3 \\ 4 & a_{22} & 6 \\ 7 & 8 & a_{33} \end{bmatrix} \quad 3 \times 3$$

o diagonal of square matrix is  
which value of  $i = j$        $i = \text{row}$   
means rows = columns.       $j = \text{column}$

4) Diagonal Matrix → square

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \quad 3 \times 3$$

Here, ~~non~~ diagonal  
elements are non  
zero & ~~all~~ non-diagonal  
elements are zero.  
 $i = j \neq 0$

5) Scalar Matrix → diagonal matrix

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad 3 \times 3$$

all diagonal elements  
are ~~not~~ equal.

## 6) Identity Matrix -

In which all diagonal elements are 1.

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow \text{order } \rightarrow 3$$

$3 \times 3$

## 7) Zero Matrix -

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

## \* Matrix Equality -

$$A = B$$

1) Order should be same.

If A is  $2 \times 2$  then B should  $2 \times 2$ .

$$\Rightarrow [A_{ij} = B_{ij}]$$

$$A = B$$

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}_{2 \times 2} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}_{2 \times 2}$$

• If both conditions are true then matrices are equal.

## \* Scalar Operations

- Scalar is single no. i.e. 2, 3, -5
- Two ways do scalar operations
  - By add
  - By multiply

◦  $K + A = K = 2 \quad A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$

$$\rightarrow K + A = \begin{bmatrix} 3 & 3 \\ 5 & 6 \end{bmatrix}$$

◦  $K \cdot A = K = 2 \quad A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$

$$\rightarrow KA = \begin{bmatrix} 2 & 4 \\ 6 & 8 \end{bmatrix}$$

- By using scalar matrix one can make negative.

$$A = -A$$

$$A = \begin{bmatrix} 1 & -2 \\ 3 & -4 \end{bmatrix} \quad K = -1$$

Now,  $K \cdot A = -1 \times \begin{bmatrix} 1 & -2 \\ 3 & -4 \end{bmatrix}$

$$= \begin{bmatrix} -1 & 2 \\ -3 & 4 \end{bmatrix}$$

Now this matrix is  $-A$   
 Also called as Negative of a Matrix.

o Rule -

Suppose you have  $[A, B] K$

You can also use above scalar operation as  $K(A+B) = KA + KB$

So, Both gives Same result.

### \* Matrix Addition & Subtraction-

- add
- Sub
- multi
- div

① for addition,  
order should be same of  
both matrices

A B → order same

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} + \begin{bmatrix} 5 & 6 \\ 7 & 8 \end{bmatrix} \quad 2 \times 2 \quad 2 \times 2$$

$$= \begin{bmatrix} 1+5=6 \\ 7+3=10 \end{bmatrix} \quad \begin{bmatrix} 2+6=8 \\ 4+8=12 \end{bmatrix} \quad 2 \times 2$$

## ② for subtraction-

To use subtraction in matrices,  
you have to use  
scalar multiplication then  
scalar matrix addition

o eg  $\rightarrow A - B$  (for perform this),

① Scalar multiplication

$$A + (-1)B$$

so, B become negative B

② Then matrix addition.

$$A + (-1)B$$

o Some rules do remember -

①  $A+B = B+A \rightarrow$  Commutative

②  $(A+B)+C = A+(B+C) \rightarrow$  Associative

o 1] Additive Identity -

$$A + [x] = A$$

$$\begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} + \begin{bmatrix} x \\ 2x_2 \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix}$$

So, for above  $X$  is  $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ .

## 2] Additive Inverse-

$$A - \boxed{X} = 0$$

$$\begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} - \boxed{X} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Use negative of  $A$  to get result.

## \* Matrix Multiplication-

- Remember even order is not same then also multiplication can be done between two matrices.

- Matrix multiplication only possible if A's no. of columns is equal to B's no. of rows.

-  $A \times B$

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \times \begin{bmatrix} 4 & 5 \\ 6 & 7 \end{bmatrix} = \begin{bmatrix} ? \end{bmatrix}$$

$2 \times 2$        $2 \times 2$

This should  
Same

- Result's shape will be A's no. of rows X B's no. of Column

$$\text{egs} - \begin{array}{l} \text{• } 1 \times 3 \neq 1 \times 3 \\ \text{• } 2 \times 3 = \underline{3 \times 3} \end{array} \quad \checkmark$$

Shape will be  $\frac{1}{2 \times 3}$

row vector      col<sup>n</sup> vector

$$\begin{array}{l} \text{• } \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}_{2 \times 3} \cdot \begin{bmatrix} 1 \\ 4 \\ 7 \end{bmatrix}^{\leftarrow} \begin{bmatrix} 2 & 3 \\ 5 & 6 \\ 8 & 9 \end{bmatrix}_{3 \times 3} \end{array}$$

(Doing dot product)

$$= \begin{bmatrix} (1 \times 1 + 2 \times 4 + 3 \times 7) & 36 & 42 \\ (4 \times 1 + 5 \times 4 + 6 \times 7) & 71 & 96 \end{bmatrix}$$

$$= \begin{bmatrix} 30 & 36 & 42 \\ 66 & 71 & 96 \end{bmatrix}$$

Now understand Ruled-

$$\rightarrow A \cdot B^T = B \cdot A$$

Here, placing matters means  
Suppose  $A_{2 \times 3} \cdot B_{3 \times 3}$ , here multiplication happens but

If we take this  $B_{3 \times 3} \cdot A_{2 \times 3}$

then multiplication doesn't happen.

$$\therefore A \cdot B^T = B \cdot A$$

$$\rightarrow (AB)C = A(BC)$$

(Associative rule follows.)

$$\rightarrow A(B+C) = AB + AC$$

Distributive Law/Rule

$\rightarrow$  Multiplicative identity.

$$AX = A$$

I

$$\text{eg} \rightarrow \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} \boxed{X} = \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix}$$

What type of matrix it is by which answer will be A.

$$\begin{bmatrix} A \\ 2 & 3 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix}$$

$$AI = A$$

A<sup>-1</sup>

In deep learning, matrix multiplication and backpropagation are mostly used.

\* Transpose of Matrix -

Here, rows become  $(n)^T$  and columns become rows.

$$\text{Eg} \rightarrow A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$A^T = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$

$$B^T = \begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix}$$

$$C = \begin{bmatrix} 2 & 1 & 3 \\ 1 & 2 & 4 \end{bmatrix}_{2 \times 3}$$

$$C^T = \begin{bmatrix} 2 & 1 \\ 3 & 2 \\ 4 & 4 \end{bmatrix}_{3 \times 2}$$

○ Symmetric matrix -

$$A = A^T$$

In which, no changes  
shown in result  
after transpose.

$$\text{Eg} \rightarrow A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}_{2 \times 2}$$

$$A^T = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}_{2 \times 2}$$

- Skew Symmetric matrix -

$$AT = -A$$

- Rules

$$\rightarrow (AT)^T = A$$

$$\rightarrow (A+B)^T = AT + BT$$

$$\rightarrow (AB)^T = BT \cdot AT$$

- \* Determinant -

- It is a scalar value computed from a square matrix that carries important information about the matrix.

- It has several uses in linear algebra, including determining the invertibility of a matrix, finding the solution to systems of linear equations and calculating the volume scaling factor for linear transformation.

By the way, this is a matrix eqn.

$$A X = B$$

Suppose we know the values of matrix A.

Don't know the value

Know the value

Had to find X matrix / these values.

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$$\begin{bmatrix} 1 & 2 \\ 6 & 5 \end{bmatrix} \xrightarrow{\downarrow} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 4 \\ 11 \end{bmatrix}$$

$\boxed{X}$

To find X matrix, had to

$$X = \frac{B}{A}$$

- But  $B + A$  is matrices not scalar. In matrices, division doesn't happen. But multiplication can done.
- Multiplication is possible  
So, we can do,

$$X = B \cdot A^{-1}$$

$\uparrow$

Note -  
 $\frac{I}{A} = A^{-1}$

- We had B but don't have  $A^{-1}$  value.  
new problem is how to calculate inverse A ( $A^{-1}$ ).

- Suppose given A matrix is invertible  
then it should be squared  
matrix only and even if both  
condn satisfied we can't tell  
that it can be invertible.

$$A^{-1} = \frac{1}{\text{determinant}(A)} \text{Adj}(A)$$

- Note - To inverse non-square matrix it  
(can be) done by Pseudoinverse.  
Sometimes.

- Now goal to learn
- ① Determinant
  - ② minor
  - ③ Cofactor
  - ④ Adjoint.

By these 4 things  
we can do  
Inverse.

## ① Determinant -

$1 \times 1$

$2 \times 2$

$2 \times 2$

$$A = \begin{bmatrix} 1 \end{bmatrix}_{1 \times 1}$$

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}_{2 \times 2}$$

$$B = \begin{bmatrix} -2 & 5 \\ -6 & 7 \end{bmatrix}_{2 \times 2}$$

$$\det(A) = 1$$

$$\det(A) = \Delta = \begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix}$$

$$\det(B) = \Delta = \begin{vmatrix} -2 & 5 \\ -6 & 7 \end{vmatrix}$$

$$= 1 \times 4 - 3 \times 2$$

$$= -14 - (-30)$$

$$= -2$$

$$= 30 - 14$$

$$= 16$$

- Now how to decide if inverse of a matrix is possible.

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}_{2 \times 2}$$

Rule ① Square ✓

Rule ②  $\det(A) \neq 0$ . if  $\det(A)$  is zero

then you can't calculate inverse  
and called it singular matrix.

- only non-singular matrices have inverses

$3 \times 3$ 

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \quad 3 \times 3$$

$$\det(A) = \Delta = \begin{vmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{vmatrix}$$

Here, we have done only one single coln. but that's enough. See next pages, you'll understand.

$$= 1 \times \begin{vmatrix} 5 & 6 \\ 8 & 9 \end{vmatrix} - 2 \times \begin{vmatrix} 4 & 6 \\ 7 & 9 \end{vmatrix} + 3 \times \begin{vmatrix} 4 & 5 \\ 7 & 8 \end{vmatrix}$$

$$= -3 + 12 - 9$$

$$= 0$$

So,  $\det(A) = 0 \rightarrow$  singular matrix  
means inverse isn't done

## ② Minor -

o Minor of an element  $a_{ij}$  of a determinant is the determinant obtained by deleting its  $i$ th row and  $j$ th coln.

? It is denoted by  $M_{ij}$ .

Suppose,

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

$a_{11}$  has its  
own minor

$$M_{11} = a_{22}$$

$$M_{12} = a_{21}$$

$$M_{21} = a_{12}$$

$$M_{22} = a_{11}$$

$$\det(A) = \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & M_{22} \end{vmatrix}$$

for  $a_{11}$ , delete its  $i$ th &  $j$ th row,  
Means determinant of  $a_{22}$  is the  
minor of  $a_{11}$ .

This way, is apply to all.

Note  $\rightarrow |a_{22}|$  is scalar so  $|a_{22}|$  is  $M_{22}$ .

Now, See for  $3 \times 3$  matrix.

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$\circ M_{11} = \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} = a_{22}a_{33} - a_{23}a_{32}$$

$$\circ M_{12} = \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} = a_{21}a_{33} - a_{23}a_{31}$$

$$\circ M_{13} = \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix} = a_{21}a_{32} - a_{22}a_{31}$$

$$\circ M_{33} = \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} = a_{11}a_{22} - a_{12}a_{21}$$

$\circ$  This is how we calculate minor.

③

Cofactor -

$\circ$  Cofactor of an element of  $a_{ij}$  of a determinant is defined by  
 $A_{ij} = (-1)^{i+j} M_{ij}$  where  $M_{ij}$  is the minor of  $a_{ij}$ .

$\circ$  Cofactor is denoted by Capital A.  
 $\circ$  Every item has cofactor.

$\circ$  Suppose you have matrix B.

$$B = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

Now, you had to find  $a_{11}$  cofactor then,

$$\text{for, } A_{11} = (-1)^{1+1} M_{11}$$

$$\text{for, } A_{21} = (-1)^{2+1} M_{21} = -M_{21}$$

• Basically, signs reverse alternatively.

• Suppose, for  $3 \times 3$  matrix,

$$B = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$\therefore A_{32} = (-1)^{3+2} M_{32}$$

you know,  
how to find minor.

Note →

Determinant = Sum of the product of  
element of any row (or col) with  
their corresponding cofactor

$$\text{det} = a_{11} A_{11} + a_{12} A_{12} + a_{13} A_{13}$$

(4)

Adjoint -

Suppose you have matrix A.

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

↓  
you find every minor (cofactor).

$$= \begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ A_{31} & A_{32} & A_{33} \end{bmatrix}$$

Then you transpose it

$$\text{adj}(A) = \begin{bmatrix} A_{11} & A_{21} & A_{31} \\ A_{12} & A_{22} & A_{32} \\ A_{13} & A_{23} & A_{33} \end{bmatrix}$$

This is your adjoint of A.

Inverse of Matrix -

$$A^{-1} = \frac{1}{\det(A)} \text{adj}(A)$$

- An inverse matrix is a matrix that, when multiplied by original matrix, results in the identity matrix.

$$A \cdot A^{-1} = I$$

- The inverse matrix is defined only for square matrices (matrices with the same number of rows and cols) and not all square matrices have an inverse.

- A matrix is invertible if and only if it is non-singular, meaning its determinant is non-zero. If  $|A| = 0$ , A is called a singular matrix, and it does not have an inverse.

- Note Suppose,  $A \cdot X = B$ .  
 ↗ Don't know value of X.  
 ↘ You know values of  $A$  &  $B$ .

So, inverse A both sides.

$$A^{-1} \cdot A \cdot X = A^{-1} \cdot B$$

$$\therefore A \cdot A^{-1} = A^{-1} \cdot A = I \quad \text{-- (Commutative law)}$$

$$I \cdot X = A^{-1} \cdot B$$

→ multiplicative identity.

$$X = A^{-1} \cdot B$$

That's how we solve / calculate eqn.

• Inverse matrices play a crucial role in linear algebra and have many applications, such as solving systems of linear equations, finding the determinant of a matrix, and performing various matrix operations.

• Several methods for finding the inverse of a matrix; including Gaussian elimination, the adjugate method, and LU decomposition.

Just note,  $(AB)^{-1} = B^{-1} \cdot A^{-1}$

\* Solving a system of linear equations

$$\textcircled{1} \quad \begin{cases} x + y = 5 \\ 4x + 3y = 15 \end{cases}$$

$$\begin{bmatrix} 1 & 1 \\ 4 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 5 \\ 15 \end{bmatrix}$$

$$\begin{bmatrix} x+y \\ 4x+3y \end{bmatrix} = \begin{bmatrix} 5 \\ 15 \end{bmatrix}$$

$$\Rightarrow \boxed{\begin{cases} x+y=5 \\ 4x+3y=15 \end{cases}}$$

Meaning, you can write it into matrix form,

$$\begin{bmatrix} 1 & 1 \\ 4 & 3 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 5 \\ 15 \end{bmatrix}$$

A                  X                  B

$$AX = B \quad \underline{\text{matrix form}}$$

$$A^{-1} A X = A^{-1} B$$

$$I X = A^{-1} B$$

$$X = [A^{-1} B]$$

$$\Rightarrow A = \begin{bmatrix} 1 & 1 \\ 4 & 3 \end{bmatrix}$$

$$\Rightarrow A^{-1} = \frac{1}{\det(A)} \text{adj}(A)$$

$$\circ \det(A) = \Delta = 3 - 4 = -1$$

$$\circ \text{Cofactor} = \begin{bmatrix} (-1)^{1+1} 3 & (-1)^{1+2} 4 \\ (-1)^{2+1} 1 & (-1)^{2+2} 1 \end{bmatrix}$$

$$= \begin{bmatrix} 3 & -4 \\ -1 & 1 \end{bmatrix}^T$$

$$\circ \text{Adjoint} = \begin{bmatrix} 3 & -1 \\ -4 & 1 \end{bmatrix}$$

$$\text{So, } A^{-1} = \frac{1}{-1} \begin{bmatrix} 3 & -1 \\ -4 & 1 \end{bmatrix}$$

$$A^{-1} = \begin{bmatrix} -3 & 1 \\ 4 & -1 \end{bmatrix}$$

$$\text{Now, } X = A^{-1} B$$

$$= \begin{bmatrix} -3 & 1 \\ 4 & -1 \end{bmatrix} \cdot \begin{bmatrix} 5 \\ 15 \end{bmatrix}$$

2x2      2x1

$$= \begin{bmatrix} -15 + 15 \\ 20 - 15 \end{bmatrix}$$

2x1

$$= \begin{bmatrix} 0 \\ 5 \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\therefore x = 0 \quad y = 5$$

①.2

$$x + 3y + 4z = 5$$

$$6x + 4y + z = 16$$

$$2x + 2y + 2z = 11$$

→

① Matrix form,

$$\begin{bmatrix} 1 & 3 & 4 \\ 6 & 4 & 1 \\ 2 & 2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 5 \\ 16 \\ 11 \end{bmatrix}$$

A

X

B

$$AX = B$$

$$X = A^{-1} B$$

let's solve by program,

Import numpy as np

A = np.array([ [1, 3, 9], [6, 4, 1], [2, 2, 3] ])

B = np.array ([5, 6, 11])

A\_inv = np.linalg.inv(A)

np.dot (A\_inv, B)

sol → array ([10.125, -13.375, 8.75]).

