

## 9 Lecture 9

[9.1] **Theorem** (Bfs means a vertex) A point  $w$  is a bfs of  $Ax = b$  iff  $w$  is a vertex of the polyhedron  $T = \{x \mid Ax = b, x \geq 0\}$ .

$$\text{Vertex } v \text{ of } T = \left\{ x \mid \begin{bmatrix} A \\ -A \\ I \end{bmatrix} x \geq \begin{bmatrix} b \\ -b \\ 0 \end{bmatrix} \right\}$$

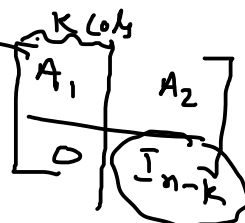
$\tilde{A}_v$   $\tilde{b}$

$\text{rank } \tilde{A}_v = n$ .  $\tilde{A}_v$  contain  $A$   
 $-A$   
 some rows of  $I$

Suppose  $v_{k+1}, \dots, v_n = 0$ .

Then

cols are lin ind.



$\rightarrow \text{rank } n$

cols of  $A$  corresp to +ve entries of  $v$  are lin ind.  
 $\Rightarrow v$  is a bfs.

*Proof.* Let  $w$  be a bfs of  $Ax = b$  with a basis matrix, say,  $B$ . For simplicity, assume  $A = [B|C]$ . First write

$$T = \{x \mid A'x \leq b'\}, \text{ where } A' = \begin{bmatrix} A \\ -A \\ -I \end{bmatrix} = \begin{bmatrix} B & C \\ -B & -C \\ -I & 0 \end{bmatrix} \text{ and } b' = \begin{bmatrix} b \\ -b \\ 0 \end{bmatrix}. \text{ The submatrix } \begin{bmatrix} B & C \\ 0 & -I \end{bmatrix} \text{ has rank } n$$

and rows in this matrix correspond equalities in  $A'w \leq b'$ . By [5.22],  $w$  is a vertex of  $T$ .

Conversely, let  $w$  be a vertex of  $T$ . This means  $A'w \leq b'$  and  $A'_w$  has rank  $n$ . Notice that  $A'w \leq b'$  itself implies that  $Aw = b$ . Hence  $A'_w$  must contain  $A$ ,  $-A$  and a few rows from  $-I$ . For simplicity, assume that  $A'_w$  contains the last  $n - k$  rows of  $-I$ . (This means  $w_{k+1} = \dots = w_n = 0$ .) As the rows in  $A'_w$  which are from  $-A$  are negatives of those which are from  $A$ , we see that the matrix obtained from  $A'_w$  by deleting the rows of  $-A$ , also has rank  $n$ . But the matrix must look like

$$\left[ \begin{array}{ccc|ccc} a_{11} & \cdots & a_{1k} & a_{1,k+1} & \cdots & a_{1n} \\ \vdots & & & & & \\ a_{m1} & \cdots & a_{mk} & a_{m,k+1} & \cdots & a_{mn} \\ \hline 0 & \cdots & 0 & -1 & \cdots & 0 \\ \vdots & & & & & \\ 0 & \cdots & 0 & 0 & \cdots & -1 \end{array} \right].$$

Further, as the rank of this matrix is  $n$ , we see the top left  $k$  columns are linearly independent. (These are columns of  $A$  corresponding to the nonzero entries in  $w$ .) So by [8.22],  $w$  is a bfs. ■

[9.2] **Corollary** (Existence of a bfs) If  $\{x \mid Ax = b, x \geq 0\} \neq \emptyset$ , then  $Ax = b$  has a bfs.

*Proof.* The set  $T = \{x \mid Ax = b, x \geq 0\}$  being a nonempty polyhedron which is bounded below, has a vertex. By [9.1], a vertex of  $T$  is a bfs of  $Ax = b$ . ■

How to define a bfs when  $\text{rank } A_{m \times n} = k < m$ ? If the system  $Ax = b$  is inconsistent, then the set is empty and we do not have to do anything.

If it is consistent, then one way is to remove some redundant equations to make it look like  $A_{k \times n}x = b'$ . We proceed from there.

Another way is to take some linearly independent columns  $i_1, i_2, \dots, i_k$ . Then a basic solution of  $Ax = b$  is a solution with  $x_j = 0$  for each  $j \notin \{i_1, \dots, i_k\}$ . A nonnegative basic solution is a bfs.

## Drawing basic solutions

Consider

$$\begin{array}{ll} \min & x_2 - 5x_1 \\ \text{s.t.} & x_1 \leq 2, x_2 \leq 2, x_1 + x_2 \leq 3, x_1 - x_2 \leq 3, x_i \geq 0 \end{array}$$

a) Write the set  $T$  in  $\{x \mid \tilde{A}x \leq \tilde{b}\}$  form.

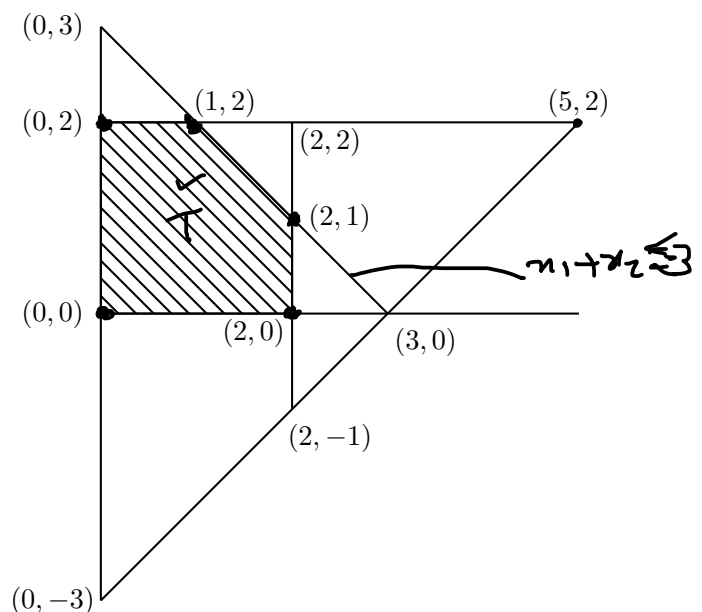
$$T = \{x \mid \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \\ 1 & -1 \\ -1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 3 \\ 3 \\ 0 \\ 0 \end{bmatrix}\}.$$

$$\begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 & 0 \\ -1 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 3 \\ 3 \end{bmatrix}$$

$A \quad x = b$

b) Draw its feasible region  $T$ .

$p = (5, 2)$  —  $p' = (5, 2, -3, 0, -4, 0)$   
b.s. & slpp



c) Observe that the point  $p = (5, 2)$  has been obtained due to  $n$  linearly independent hyperplanes passing through it. What are they? Here they are given by rows two and four of  $\tilde{A}$ .

d) Write the slpp.

Slpp:  $\min \frac{c^t x}{\text{s.t. } Ax = b, x_i \geq 0}$ , where  $c^t = [-5 \ 1 \ 0 \ 0 \ 0 \ 0]$ ,  $A = \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 & 0 \\ 1 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$  and  $b = \begin{bmatrix} 2 \\ 2 \\ 3 \\ 3 \end{bmatrix}$ .

e) What is the basic solution corresponding to  $p = (5, 2)$ ?

Take  $x_1 = 5$  and  $x_2 = 2$ . Use them in the slpp to get  $p' = (5, 2, -3, 0, -4, 0)$ .

f) Could you tell before hand that  $p'$  will not be a bfs for the slpp?

Yes. There is a half space, namely  $x_1 \leq 2$  which does not contain  $p$ . Hence for the slpp, the corresponding slack variable (namely  $x_3$ ) must be negative.

g) Find out the different basic solutions for the slpp. What are the points  $T$  related to these basic solutions?

$6 \leq 15$

basis	basic solution ✓	point in figure
$x_1, x_2, x_3, x_4$	$(3, 0, -1, 2, 0, 0)$	$(3, 0)$
$x_1, x_2, x_3, x_5$	$(5, 2, -3, 0, -4, 0)$	$(5, 2)$ →
$x_1, x_2, x_3, x_6$	$(1, 2, 1, 0, 0, 4)$	$(1, 2)$
$x_1, x_2, x_4, x_5$	$(2, -1, 0, 3, 2, 0)$	$(2, -1)$
$x_1, x_2, x_4, x_6$	$(2, 1, 0, 1, 0, 2)$	$(2, 1)$
$x_1, x_2, x_5, x_6$	$(2, 2, 0, 0, -1, 3)$	$(2, 2)$
$x_1, x_3, x_4, x_5$	$(3, 0, -1, 2, 0, 0)$ repeat	$(3, 0)$
$x_1, x_3, x_4, x_6$	$(3, 0, -1, 2, 0, 0)$ repeat	$(3, 0)$
$x_1, x_3, x_5, x_6$	not a basis	
$x_1, x_4, x_5, x_6$	$(2, 0, 0, 2, 1, 1)$	$(2, 0)$
$x_2, x_3, x_4, x_5$	$(0, -3, 2, 5, 6, 0)$	$(0, -3)$
$x_2, x_3, x_4, x_6$	$(0, 3, 2, -1, 0, 6)$	$(0, 3)$
$x_2, x_3, x_5, x_6$	$(0, 2, 2, 0, 1, 5)$	$(0, 2)$
$x_2, x_4, x_5, x_6$	not a basis	
$x_3, x_4, x_5, x_6$	$(0, 0, 2, 2, 3, 3)$	$(0, 0)$

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## Some exercises

[9.3] **Exercise(E)** Let  $\text{rank } A_{m \times n} = r \leq m$  and  $T = \{x \mid Ax = b, x \geq 0\} \neq \emptyset$ . It is given that  $w$  is a vertex of  $T$ . How many nonzero entries can  $w$  have at the most?

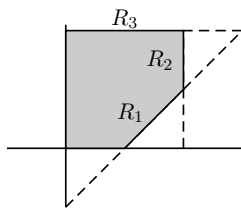
[9.4] **Exercise(H)** (One-one correspondence of corner points of lpp and slpp.)

$\{u\} Ax = b$   
 $u \geq v$

Let  $\text{rank } A_{m \times n} = m$ . Take the lpp  $\min \frac{c^t x}{\text{s.t. } Ax \leq b, x \geq 0}$ . The slpp  $\min \frac{[c^t \ 0] \begin{bmatrix} x \\ y \end{bmatrix}}{\text{s.t. } [A \ I_m] \begin{bmatrix} x \\ y \end{bmatrix} = b, x \geq 0, y \geq 0}$

is in a higher dimensional space. Let  $T$  and  $T'$  be the feasible sets for the lpp and the slpp, respectively. Assume that both are nonempty. Then show that  $v$  is a corner point (through which  $n$  linearly independent hyperplanes pass) of  $T$  iff  $\begin{bmatrix} v \\ b - Av \end{bmatrix}$  is a bs of  $[A \ I] \begin{bmatrix} x \\ y \end{bmatrix} = b$  (equivalently iff  $\begin{bmatrix} v \\ b - Av \end{bmatrix}$  is a corner point of  $T'$ ).

[9.5] **Exercise(E+)** Consider the region  $P = \text{conv}((0, 0), (1, 0), (2, 1), (2, 2), (0, 2)) \subseteq \mathbb{R}^2$ .



a) Write this region as  $\{x \mid \hat{A}_{3 \times 2} x \leq \hat{b}, x \geq 0\}$ , where the  $i$ th row of  $\hat{A}$  should correspond to the line  $R_i$  in the figure.

b) Consider minimizing  $x_1 + x_2$  on this region. Write the lpp using the matrix  $\hat{A}$  used in the previous item. Write the corresponding slpp in the form  $\min \frac{c^T x}{Ax = b, x \geq 0}$ .

c) List down the basic solutions of  $Ax = b$  and the points of  $\mathbb{R}^2$  which correspond to these basic solutions. Fill the table. Write 'NA' for 'not applicable'.

choice	basis?	basic sol	corresponding pt of $\mathbb{R}^2$
$x_1, x_2, x_3$	yes	$(2, 2, 1, 0, 0)$	$(2, 2)$
$x_1, x_2, x_4$			
$x_1, x_2, x_5$			
$x_1, x_3, x_4$	no	NA	NA
$x_1, x_3, x_5$			
$x_1, x_4, x_5$			
$x_2, x_3, x_4$			
$x_2, x_3, x_5$			
$x_2, x_4, x_5$			
$x_3, x_4, x_5$			

## Cost of basic feasible solutions

So, we have understood how to identify the vertices of the slpp. These are the bfs's. Now, suppose that I am at a bfs. How do I know whether it is cheaper than the remaining? The following result gives a way to answer that.

[9.6] **Lemma** (Cost difference of any point w.r.t a given vertex) Let  $\text{rank}(A_{m \times n}) = m$  and  $w$  be a bfs of  $Ax = b$  with basis matrix  $B$ . Let  $p$  be any solution of  $Ax = b$ . Then their cost difference  $c^T p - c^T w = \bar{c}^T p$ , where  $\bar{c} = c^T - c_B^T B^{-1} A$ .

$$\underline{c^T x - c^T w} = c^T x - c_B^T w_B = c^T x - c_B^T B^{-1} b$$

$$= c^T x - c_B^T B^{-1} A x$$

$$= [c^T - c_B^T B^{-1} A] x$$

Handwritten diagram showing a line segment from  $w$  to  $p$  with a vector  $x$  from  $w$  to  $p$ . To the right,  $w = \begin{bmatrix} w_B \\ w_C \end{bmatrix} = \begin{bmatrix} B^{-1} b \\ 0 \end{bmatrix}$ .

*Proof.* The cost difference is

$$c^T p - c^T w = c^T p - c_B^T w_B = c^T p - c_B^T B^{-1} b = c^T p - c_B^T B^{-1} A p = [c^T - c_B^T B^{-1} A] p,$$

as  $w_B = B^{-1} b$  and  $w_C = 0$ . ■

[9.7] **Definition** Let  $\text{rank}(A_{m \times n}) = m$  and  $w$  be a bfs of  $Ax = b$  with basis matrix  $B$ . Then the vector  $\bar{c} = c^T - c_B^T B^{-1} A$  used in [9.6] is called the RELATIVE COST vector at the vertex  $w$ .

relative cost  $\bar{c}^T = \frac{c^T}{c_B^T B^{-1} A}$

$$\bar{c}_B^T = c_B^T - c_B^T B^{-1} A_B = c_B^T - c_B^T B^{-1} B = 0 \dots 0$$

$$\bar{c}_C^T = c_C^T - c_B^T B^{-1} C$$

[9.8] **Facts** (About  $\bar{c}$ ) Let  $\text{rank}(A_{m \times n}) = m$  and  $w$  be a bfs of  $Ax = b$  with basis matrix  $B$  and  $\bar{c}$  be the relative cost vector at  $w$ .

✓ a) Then  $\bar{c}_B^T = [c^t - c_B^t B^{-1} A]_B = [c_B^t - c_B B^{-1} B] = 0$ . ✓

$$c^T - \underbrace{c_B^T B^{-1}}_{\text{circled}} A$$

b) Then  $\bar{c}_C^T = [c^t - c_B^t B^{-1} A]_C = [c_C^t - c_B B^{-1} C]$ . ✓ ✓ > 0

c) The relative cost vector depends only on the basis matrix  $B$  of  $w$ .

[9.9] **Theorem** (Minimality of a given bfs) Let  $\text{rank } A_{m,n} = m$  and consider  $\text{opt } \frac{c^t x}{\text{s.t. } Ax = b, x \geq 0}$ . Assume that  $w$  is a bfs of  $Ax = b$ . Then the following are true.

✓ a) If  $\bar{c}_C^t \geq 0$  (equivalently, if  $\bar{c}^t \geq 0$ ), then  $w$  is a point of local minimum.

b) If  $\bar{c}_C^t > 0$ , then  $w$  is a strict minimum.

✓ c) If  $\bar{c}_C^t \leq 0$ , then  $w$  is point of maximum and if  $\bar{c}_C^t < 0$ , then  $w$  is a point of strict maximum.

a)  $\bar{c}^T x - \bar{c}^T w = \bar{c}^T x = \underbrace{\bar{c}_C^T}_{\text{circled}} x_C > 0$

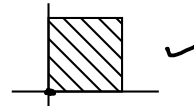
b)  $\underbrace{\bar{c}_C^T}_{\text{circled}} > 0$ , then  $w$  is a strict min.  $y \neq w$ .  $y_C = 0$ ?  
 $\bar{c}^T y - \bar{c}^T w = \bar{c}^T y = \underbrace{\bar{c}_C^T}_{\text{circled}} y_C > 0$   
 $y_C = w_C$   
 $y_B = B^{-1} b = w_B$

*Proof.* a) For any  $x \in T$ , we have  $c^t x - c^t w = \bar{c}^t x \geq 0$ , as  $x \geq 0$ .

b) Note that, if  $x \neq w$  then  $x_C$  cannot be 0, because, in that case  $x_B = B^{-1}b = w_B$  and so  $w = x$ , not possible. Now, as  $\bar{c}_C > 0$  and  $x \geq 0$  with  $x_C$  having at least one positive entry, we get  $\bar{c}^t x > 0$ .

c) Similar. ■

[9.10] **Example** Consider  $\text{opt } \frac{x_1 + x_2}{\text{s.t. } x_1 \leq 1, x_2 \leq 1, x_i \geq 0}$ .



a) Write the slpp.

$$x_1 + x_3 = 1$$

$$x_2 + x_4 = 1$$

$(0,0) \rightarrow (0,0,1,1)$   $\xrightarrow{\text{slpp}}$   
 $w$   
 $\beta = \begin{bmatrix} x_3 & x_4 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$

*Answer.* It is  $\min \frac{c^t x}{\text{s.t. } Ax = b, x \geq 0}$ , where  $A = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}$ ,  $b = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  and  $c^t = [1 \ 1 \ 0 \ 0]$ .

b) The point  $(0,0)$  is a vertex in our picture (of lpp). What is the corresponding vertex  $w$  of the slpp?

*Answer.* It is  $w = (0,0,1,1)$ .  
 $\bar{c}^T = [1 \ 1 \ 0 \ 0] - [0 \ 0] \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$   
 $= [1 \ 1 \ 0 \ 0]$   $\bar{c}_C^T \Rightarrow w$  is st min

c) By our earlier result, it must be a bfs of  $Ax = b$  for some basis. Write one such basis?

Answer. One basis  $(x_3, x_4)$ .

d) Compute the relative cost at  $w$ .

Answer. At  $w$  the relative cost is

$$\bar{c}^t = c^t - c_B^t B^{-1} A = [1 \ 1 \ 0 \ 0] - [0 \ 0] \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} = [1 \ 1 \ 0 \ 0]. \checkmark$$

e) Will the test conclude that  $w$  is a point of strict minimum?

Answer. Yes, as  $\bar{c}_C$  has all entries positive.

f)(Self) The point  $(1, 1)$  is a vertex in our picture. The corresponding vertex of the slpp is  $w = (1, 1, 0, 0)$ . It is a bfs of  $Ax = b$  with basis  $(x_1, x_2)$ . At  $w$  the relative cost is

$$\bar{c}^t = c^t - c_B^t B^{-1} A = [1 \ 1 \ 0 \ 0] - [1 \ 1] \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} = [0 \ 0 \ -1 \ -1].$$

So  $w$  is a point of strict maximum.

g)(Self) Compute and observe  $\bar{c}$  at the two other vertices and see whether the test supplies any conclusions.

Shift b-  
10 min  
Thur 26  
11-12  
10:55 → upkud  
12:10 → upbal Ans

$x_1 \leq 1, x_2 \leq 1$   
 $x_1 + x_3 = 1$   
 $x_2 + x_4 = 1$

$\begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

$f(x) = [1 \ 1] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$   
 $f(x) = [1 \ 1 \ 0 \ 0] \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$

$\bar{c}^T = c^T - c_B^T B^{-1} A = [1 \ 1 \ 0 \ 0] - [1 \ 1] \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}$

$= [1 \ 1 \ 0 \ 0] - [1 \ 1 \ 1 \ 1] = [0 \ 0 \ -1 \ -1]$

$\bar{c}_C^T < 0 \checkmark$

$(1, 0) \rightarrow (1, 0, 0, 1)$   
 $B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

$[1 \ 1 \ 0 \ 0] - [0 \ 0] B^{-1} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}$   
 $[1 \ 1 \ 0 \ 0] - [1 \ 0 \ 1 \ 0] = [0 \ 1 \ -1 \ 0]$

no conclusion