35 Lecture 35

KT necessary condition and sufficient conditions

The following is the result we were expecting earlier. This allows us to directly search for kt points in order to find local minimums, when ktcq1 holds on T.

<u>Lemma</u> (Kuhn-Tucker necessary condition (ktnc) for a local minimum) <u>local minimum</u> of (P2) satisfying ktcq1. Then $Z(a) = \emptyset$ must hold, that is, a must be a kt point.

Proof.
$$d \in \mathcal{D}(n) = \nabla f(n)^{\dagger} d \geq 0$$
. Let $d \in \mathcal{D}(n)$.

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$$f(x) = f(x) = f(x$$

a) Let
$$d \in \mathcal{D}(a)$$
. As ktcq1 holds at a , there is a curve $\alpha(t)$, $t \in [0, \epsilon]$ such that $\alpha(0) = a$ and $\alpha(t) \in T$, $\forall t \in [0, \epsilon]$ and $d = \lim_{t \to 0+} \frac{\alpha(t) - a}{t}$.

b) As a is a local minimum, $\exists \delta > 0$, $\delta \nearrow \epsilon$ such that $f(a) \leq f(x)$, $\forall x \in T \cap B_{\delta}(a)$.

c) By Taylor's theorem, for each $t \in (0, \delta)$, we have $(1, \delta)$ theorem, for each $t \in (0, \delta)$, we have

$$0 \le f(\alpha(t)) - f(\alpha(0)) = f'\Big(\alpha(0)) + \theta(\alpha(t) - \alpha(0))\Big)(\alpha(t) - \alpha(0)),$$

for some $0 < \theta < 1$. Dividing by t and letting $t \to 0+$, we get

$$f'(a)d = \lim_{t \to 0+} f'\left(\alpha(0)\right) + \theta(\alpha(t) - \alpha(0)) \frac{\alpha(t) - \alpha(0)}{t} \ge 0.$$

Thus $Z(a) = \emptyset$.

Thus
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.
 $\forall L(a) = 0$ $H_L(a)$ pad in $B_B(a)$
 $\Rightarrow a$ is Lx min $fw \perp L$. $\frac{207}{F}w + \frac{h}{mall}$
 $o \leq L(a+h) - L(a) = f(a+h) - \Sigma \lambda (g(a+h) - \Sigma w) \frac{h}{mall}$

$$-f(\alpha) - \sum \lambda_i g_i(\alpha)$$

$$f(\alpha+h) - f(\alpha) = \sum \lambda_i g_i(\alpha+h) >_{i} 0 => f(\alpha+h) >_{i} f(\alpha)$$

$$= \sum_{i} \alpha_i i \ln \min_{i} \ln f_i$$

 $\overline{ ext{Theorem}}$ (Sufficient condition for a kt point to be a local minimum (ktsc)) Let a be a kt point for (P2) with functions in C^2 . Let

ii) $\mathcal{D}_+(a) = \{d \in \mathcal{D}(a) \mid \nabla g_i(a)^t d = 0 \text{ for all } i \in A_+(a)\}.$ (Thus $\mathcal{D}_+(a) = \mathcal{D}(a)$ if $A_+(a) = \emptyset.$)

Recall that $L \equiv f - \sum_i \lambda_i g_i - \sum_j w_j h_j$ is the Lagrangian function. Then the following are true.

(a) If $d^t H(L)_a d > 0$ for each nonzero $d \in \mathcal{D}_+(a)$, then a is a strict local minimum.

✓b) If $H(L)_a$ is pd, then a is strict local minimum.

 \mathcal{L}) If H(L) is psd in some $B_{\delta}(a)$, then a is a local minimum.

Proof a) suppose At Hi of >0 & de D(a), d =0.

Suppose it is not. 3 a = 0 s.t a = a, fear seta).

$$a_{K}-a = ||a_{K}-a|| (a_{K}-a)| = d_{K} d_{K} | ||dd_{K}||=1 | (a_{K})d_{K}| - 1 | (a_{K})d_{K}| + o(t_{K}^{2}) ||dd_{K}||=1 ||dd_{K}||=$$

a) Suppose that a is not a local minimum. Then \exists a sequence $a_k \to a$, $a_k \neq a$ and $f(a_k) \leq f(a)$. Write

$$a_k = a + (a_k - a) = a + ||a_k - a|| \frac{a_k - a}{||a_k - a||} = a + t_k d_k.$$

As $a_k \to a$, we have $t_k = ||a_k - a|| \to 0$. As $(d_k = \frac{a_k - a}{||a_k - a||})$ is a bounded sequence (being unit vectors), and the unit sphere is compact, it has a convergent subsequence converging to (a unit vector) d, say. Without loss, we assume that d_k itself is converging to d. So, using Taylor's theorem, we get

$$0 \geq f(a_k) - f(a) = t_k \nabla f(a)^t d_k + \frac{1}{2} t_k^2 d_k^t H_f d_k + o(t_k^2)$$

$$0 = h_j(a_k) = t_k \nabla h_j(a)^t d_k + \frac{1}{2} t_k^2 d_k^t H_{h_j} d_k + o(t_k^2)$$

$$0 \leq g_i(a_k) = t_k \nabla g_i(a)^t d_k + \frac{1}{2} t_k^2 d_k^t H_{g_i} d_k + o(t_k^2), \ i \in A(a).$$

We get (as a is a KT point)

$$0 \ge t_k \bigtriangledown L^t d_k + \frac{1}{2} t_k^2 d_k^t H_L d_k + o(t_k^2) = \frac{1}{2} t_k^2 d_k^t H_L d_k + o(t_k^2).$$

Dividing by t_k^2 and taking limit, we see that $d^t H_l d \leq 0$. Hence $d \notin \mathcal{D}_+(a)$. Dividing last two by t_k and taking the limit, we see that $\nabla h_j^t d = 0$ and $\nabla g_i^t d \geq 0$ for $i \in A(a)$ and so $d \in \mathcal{D}(a)$. That is, $\exists i \in A_+(a)$ such that $\nabla g_i^t d > 0$. But, then $\nabla f^t d > 0$ as $\nabla L = 0$. But, now dividing the first inequation by t_k and taking limit, we see that $\nabla f^t d \leq 0$. This is a contradiction.

The proof of b) follows from a).

To prove c) note that as $\nabla L = 0$, and H_L is psd in a neighborhood, we see that a is a point of local minimum of L. Thus

$$0 \le L(a+h) - L(a) = f(a+h) - \sum \lambda_i g_i(a+h) - f(a) - \sum \lambda_i g_i(a) = f(a+h) - \sum \lambda_i g_i(a+h) - f(a),$$
as $\lambda_i g_i(a) = 0$ for each i . So

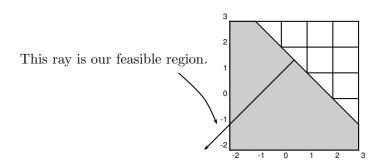
$$f(a+h) - f(a) \ge \sum \lambda_i g_i(a+h) \ge 0.$$

Thus a is a point of local minimum for f.

[35.3] Exercise(E) Write an alternate proof of part b) of [35.2] in the line of the proof of part c).

[35.4] Example Consider min
$$f(x) = (x_1 - 1)^2 + x_2 - 2$$

s.t. $g(x) = 2 - x_1 - x_2 \ge 0, h(x) = x_2 - x_1 - 1 = 0.$



o Constraints are linear. So ktcq1 holds at each feasible point. So by ktnc, each point of local minimum is a kt point.

$$\text{o We find kt points: } \begin{bmatrix} 2(x_1-1) \\ 1 \end{bmatrix} = \lambda \begin{bmatrix} -1 \\ -1 \end{bmatrix} + w \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \text{ and } \lambda(2-x_1-x_2) = 0.$$

 \circ If $\lambda = 0$, then w = 1. Equating the first row we get $x_1 = .5$. Applying h(x), we get $x_2 = 1.5$. Thus (.5, 1.5) being feasible, is a KT point with $\lambda = 0, w = 1$.

 \circ If $\lambda > 0$, then $x_1 + x_2 = 2$. Using h(x), we get $x_1 = .5$. But as w > 1, we must have $2x_1 < 1$, not possible. So we do not get any kt point here.

 \circ Going with $\lambda = 0$, w = 1, we have $A_+(a) = \emptyset$. So $\mathcal{D}_+(a) = \mathcal{D}(a) = \{d \mid d_1 + d_2 \leq 0, d_1 = d_2\}$. We have $H(L)_a = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$. For any nonzero $d = \begin{bmatrix} -t \\ -t \end{bmatrix}$, with t > 0, we have $d^t H(L)_a d = 2t^2 > 0$. By ktsc, a is a strict local minimum.

[35.5] Example (One dimensional example.) Consider
$$\min \frac{x^2}{s.t.}$$
 and $\max \frac{x^2}{x \ge 5, x \le 6}$.

Find the kt points for both the problems apply ktsc.

Answer.

- a) First consider the minimization problem. We have $L = x^2 \lambda_1(x-5) \lambda_2(6-x)$.
- b) Constraints are linear. So ktcq1 holds at all feasible points. Any local minimum must be a kt point.
- c) Find kt points:

$$2x = \lambda_1 - \lambda_2.$$

If $\lambda_2 > 0$, then x = 6. As $\lambda_1 g_1(a) = 0$, we must have $\lambda_1 = 0$. But then $12 = 0 - \lambda_2$ is not possible.

So $\lambda_2 = 0$. If $\lambda_1 > 0$, then x = 5. Notice that x = 5 is a kt point with $\lambda_1 = 10$ and $\lambda_2 = 0$. Notice that H(L) = [2] is pd. Hence the point x = 5 is a strict local minimum by ktsc.

- A) Consider the maximization problem, that is, minimizing $-x^2$. Approaching similarly, we get x=6 as a kt point.
 - B) However, H(L) = -2. So we cannot use part b) of ktsc.
- C) However, we can use part a). Note that $A_{+}(6) = \{2\}$ and $\mathcal{D}_{+}(6) = \{0\}$. Hence, for each nonzero $d \in \mathcal{D}_{+}(6)$ we have $d^{t}H(L)d > 0$. So x = 6 satisfies ktsc part a), to be a point of strict minimum for $-x^{2}$.

Exercises

[35.6]

NoPen Let
$$a$$
 be any feasible point for $\max \frac{f(x)}{g_i(x) \geq 0, \ i=1,\ldots,m,}$ s.t. $a_j(x) \geq 0, \ i=1,\ldots,m,$ $a_j(x) = 0, \ j=1,\ldots,p.$

Suppose that $\mathcal{D}(a) \cap \{d \mid \nabla f(a)^t d > 0\} = \emptyset$. Is it necessary that a is a KT point?

[35.7] **Exercise(M)** Let a be a local minimum for

$$\min_{\text{s.t.}} \frac{f(x)}{g_i(x) \ge 0, i = 1, \dots, m, h_j(x) = 0, j = 1, \dots, p, x_k \ge 0, k = 1, \dots, n.}$$

a) Assume that $Z(a) = \emptyset$. Let

$$L(x, \lambda, w) = f(x) - \sum_{i=1}^{m} \lambda_i g_i(x) - \sum_{j=1}^{p} w_j h_j(x).$$

Prove that $\exists \lambda_i \geq 0, i = 1, \dots, m, w_j, j = 1, \dots, p$ such that the following KT conditions are satisfied

$$\nabla L(a, \lambda, w) \ge 0, \quad \lambda_i g_i(a) = 0, \forall i = 1, \dots, m, \quad a^t \nabla L(a, \lambda, w) = 0.$$

- b) Is the converse of a) true?
- c) Is $a = (0, \sqrt{2}, \sqrt{2})$ a KT point of

min
$$f = x_1^3 - 6x_1^2 + 11x_1 + x_3$$

s.t. $g_1 \equiv -x_1^2 - x_2^2 + x_3^2 \ge 0, g_2 \equiv x_1^2 + x_2^2 + x_3^2 - 4 \ge 0, g_3 \equiv 5 - x_3 \ge 0, x_i \ge 0$

[35.8] Practice Consider the problem opt $x_1 + x_2^2 + x_3^3$ s.t. $x_1 + x_2 + x_3 = 1, x_i \ge 0$.

- a) Consider the minimization problem first and let a = (0, 1, 0). Compute D(a), $\mathcal{D}(a)$, Z(a). Does ktcq1 hold at a? Is a a kt point? Is it a local minimum?
 - b) Can (0,1,0) be a point of local maximum?
 - c) Does ktcq1 hold for every feasible point?

[35.9] Practice Consider the problem
$$\max_{x} \frac{x^2 + y}{x \ge 0, \ x^2 + y^2 = 1.}$$

- a) Do you think, at each $a \in T$, KTCQ1 holds?
- b) Find the KT points.
- c) Conclude, whether these points are local maxima.

[35.10] Practice Find all local minimums for min
$$x^2 + y^2 + z^2 - x - y - z$$

s.t. $0 \le x, y, z \le 1$.

[35.11] Exercise(E) Consider the problems min
$$\frac{x^4}{\text{s.t.}}$$
 and min $\frac{x^3}{|x| \le 1}$.

- a) Argue that a = 0 is a KT point for both.
- b) Now show that ktsc part a) is not a necessary condition. Hence, conclude that if $d^tH(L)(a)d = 0$ for some nonzero $d \in \mathcal{D}_+(a)$, then a may or may not be a point of local minimum.
- c) However, show that we can still apply the ktsc part c) to conclude that 0 is a point of local minimum for the first One.

[35.12] Exercise(M) Consider the problem $\max_{s.t.} \frac{x_1x_2x_3x_4}{x_1 + x_2 + x_3 + x_4 = 5, x_i \ge 0.}$ We already know one

way to find the absolute maximum. Find all KT points and give another solution using KT theory. Also search for all local maximums.

- [35.13] Practice Consider minimizing $x^2 + y^2 + xy$ over the region $T = \{x^2 + y^2 \ge 1, \ x^2 + 4y^2 \le 4\}$. Show that a point of local minimum must be a KT point.
- [35.14] Practice Consider minimizing $x^2 + y^2 + xy$ over the region $T = \{x^2 + y^2 \ge 1, \ x^2 + y^2 \le 4\}$. Assume that the points of local minimums are KT points. Find all KT points. Apply KTSC at these points.