

Proof:- claim  $g(t, x(t))$ ,  $0 \leq t \leq T$  is a martingale.

By previous theorem

$$g(t, x(t)) = \mathbb{E}[h(x(T)) | \mathcal{F}(t)]$$

Thus for  $s < t$

$$\begin{aligned} \mathbb{E}[g(t, x(t)) | \mathcal{F}(s)] &= \mathbb{E}[\mathbb{E}[h(x(T)) | \mathcal{F}(t)] | \mathcal{F}(s)] \\ &= \mathbb{E}[h(x(T)) | \mathcal{F}(s)] = g(s, x(s)). \end{aligned}$$

Hence the claim. Now

$$\begin{aligned} d(g(t, x(t))) &= g_t(t, x(t)) dt + g_x(t, x(t)) dx(t) \\ &\quad + \frac{1}{2} g_{xx}(t, x(t)) dx(t) dx(t). \\ &= g_t(t, x(t)) dt + g_x(t, x(t)) b(t, x(t)) dt + g_x(t, x(t)) \sigma(t, x(t)) dw(t) \\ &\quad + \frac{1}{2} g_{xx}(t, x(t)) \sigma^2(t, x(t)) dt \\ &= [g_t(t, x(t)) + b(t, x(t)) g_x(t, x(t)) + \frac{1}{2} g_{xx}(t, x(t)) \sigma^2(t, x(t))] dt \\ &\quad + g_x(t, x(t)) \sigma(t, x(t)) dw(t). \end{aligned}$$

since  $g(t, x(t))$  is a martingale so the  $dt$  term must be equal to 0. Thus we must have

$$g_t(t, x) + g_x(t, x) b(t, x) + \frac{1}{2} \sigma^2(t, x) g_{xx}(t, x) = 0.$$

Theorem:- consider the stochastic differential equation

$$dx(t) = b(t, x(t)) dt + \sigma(t, x(t)) dw(t).$$

Let  $h(y)$  be a Borel-measurable function. Define

$$f(t, x) = \mathbb{E}^{t, x}[e^{r(T-t)} h(x(T))]$$

where  $r$  is a constant. Then  $f(t, x)$  satisfies the partial differential equation  $f_t(t, x) + b(t, x) f_x(t, x) + \frac{1}{2} \sigma^2(t, x) f_{xx}(t, x) = r f(t, x)$  with  $f(T, x) = h(x)$ .

Proof:-  $f(t, x) = e^{-r(\tau-t)} g(t, x)$ . Thus

$$\begin{aligned} f(t, x(t)) &= e^{-r(\tau-t)} g(t, x(t)) \\ &= e^{-r(\tau-t)} \mathbb{E}[h(x(\tau)) | \mathcal{F}(t)] \\ &= \mathbb{E}[e^{-r(\tau-t)} h(x(\tau)) | \mathcal{F}(t)]. \end{aligned}$$

For  $s < t$

$$\begin{aligned} \mathbb{E}[f(t, x(t)) | \mathcal{F}(s)] &= \mathbb{E}[\mathbb{E}[e^{-r(\tau-t)} h(x(\tau)) | \mathcal{F}(t)] | \mathcal{F}(s)] \\ &= \mathbb{E}[e^{-r(\tau-t)} h(x(\tau)) | \mathcal{F}(s)]. \end{aligned}$$

$$\text{But } f(s, x(s)) = \mathbb{E}[e^{-r(\tau-s)} h(x(\tau)) | \mathcal{F}(s)].$$

Therefore  $f(t, x(t))$  is not a martingale. But

$$\begin{aligned} \mathbb{E}[e^{-rt} f(t, x(t)) | \mathcal{F}(s)] &= \mathbb{E}[e^{-rt} \mathbb{E}[e^{-r(\tau-t)} h(x(\tau)) | \mathcal{F}(t)] | \mathcal{F}(s)] \\ &= \mathbb{E}[e^{-r\tau} h(x(\tau)) | \mathcal{F}(s)] \\ &= \mathbb{E}[e^{-rs} e^{-r(\tau-s)} h(x(\tau)) | \mathcal{F}(s)] = e^{-rs} f(s, x(s)) \end{aligned}$$

Thus  $e^{-rt} f(t, x(t))$  is a martingale. Now

$$\begin{aligned} d(e^{-rt} f(t, x(t))) &= e^{-rt} df(t, x(t)) - r e^{-rt} f(t, x(t)) dt \\ &= e^{-rt} [-r f(t, x(t)) + f_t(t, x(t)) + f_x(t, x(t)) b(t, x(t)) \\ &\quad + \frac{1}{2} \sigma^2(t, x(t)) f_{xx}(t, x(t))] dt + e^{-rt} \sigma(t, x(t)) f_x(t, x(t)) dW(t). \end{aligned}$$

so by setting dt term equal to 0 we have

$$f_t + b f_x + \frac{1}{2} \sigma^2 f_{xx} = r f. \text{ \& } f(\tau, x) = h(x).$$

Multidimensional Feynman-Kac Theorems

Let  $W(t) = (W_1(t), W_2(t))$  be a two-dimensional Brownian motion (12)  
 Consider two stochastic differential equations.

$$dx_1(t) = \beta_1(t, x_1(t), x_2(t)) dt + \gamma_{11}(t, x_1(t), x_2(t)) dW_1(t) \\ + \gamma_{12}(t, x_1(t), x_2(t)) dW_2(t).$$

$$dx_2(t) = \beta_2(t, x_1(t), x_2(t)) dt + \gamma_{21}(t, x_1(t), x_2(t)) dW_1(t) \\ + \gamma_{22}(t, x_1(t), x_2(t)) dW_2(t).$$

$$x_1(0) = x_0^1 \text{ \& } x_2(0) = x_0^2.$$

Let  $h(y_1, y_2)$  be a Borel measurable function. We define

$$g(t, x_1, x_2) = \mathbb{E}^{t, x_1, x_2} [h(x_1(T), x_2(T))]$$

$$f(t, x_1, x_2) = \mathbb{E}^{t, x_1, x_2} [e^{-r(T-t)} h(x_1(T), x_2(T))].$$

Then  $g_t + \beta_1 g_{x_1} + \beta_2 g_{x_2}$

$$+ \frac{1}{2}(\gamma_{11}^2 + \gamma_{12}^2) g_{x_1 x_1} + (\gamma_{11} \gamma_{21} + \gamma_{12} \gamma_{22}) g_{x_1 x_2} + \frac{1}{2}(\gamma_{21}^2 + \gamma_{22}^2) g_{x_2 x_2} = 0$$

$$f_t + \beta_1 f_{x_1} + \beta_2 f_{x_2} + \frac{1}{2}(\gamma_{11}^2 + \gamma_{12}^2) f_{x_1 x_1}$$

$$+ (\gamma_{11} \gamma_{21} + \gamma_{12} \gamma_{22}) f_{x_1 x_2} + \frac{1}{2}(\gamma_{21}^2 + \gamma_{22}^2) f_{x_2 x_2} = -r f$$

Also satisfy the terminal conditions

$$g(T, x_1, x_2) = f(T, x_1, x_2) = h(x_1, x_2) \quad \forall x_1, x_2.$$



Problem:- Let  $X(t)$  be the solution to the SDE

$$dX(t) = \alpha X(t)dt + \sigma dW(t), \quad X(0) = x_0.$$

Where  $\alpha, \sigma, x_0$  are constant and  $W(t)$  is a Brownian motion.

- ① Determine  $\mathbb{E}[X(t)]$
- ② Determine  $\text{Var}(X(t))$
- ③ Find the solution of the SDE.

Solution:- ①  $X(t) = x_0 + \alpha \int_0^t X(s)ds + \sigma \int_0^t dW(s).$

$$\Rightarrow \mathbb{E}[X(t)] = x_0 + \alpha \mathbb{E}\left[\int_0^t X(s)ds\right] + \sigma \mathbb{E}\left[\int_0^t dW(s)\right].$$

$$= x_0 + \alpha \mathbb{E}\left[\int_0^t X(s)ds\right].$$

which leads to the ordinary differential equation.

$$\frac{d}{dt} \mathbb{E}[X(t)] = \alpha \mathbb{E}[X(t)].$$

$$\& \mathbb{E}[X(0)] = x_0.$$

which has the solution  $\mathbb{E}[X(t)] = x_0 e^{\alpha t}$ .

$$\textcircled{2} \quad \text{Var}(X(t)) = \mathbb{E}[X(t)^2] - (\mathbb{E}[X(t)])^2$$

$$= \mathbb{E}[X(t)^2] - x_0^2 e^{2\alpha t}$$

$$dX(t)^2 = 2X(t)dX(t) + dX(t)dX(t)$$

$$= 2X(t)(\alpha X(t)dt + \sigma dW(t)) + \sigma^2 dt$$

$$= (2\alpha X(t)^2 + \sigma^2)dt + 2\sigma X(t)dW(t).$$

$$\mathbb{E}[X(t)^2] = x_0^2 + \mathbb{E}\left[\int_0^t (2\alpha X(s)^2 + \sigma^2)ds\right] + 2\sigma \mathbb{E}\left[\int_0^t X(s)dW(s)\right]$$

$$= x_0^2 + \int_0^t 2\alpha \mathbb{E}[X(s)^2]ds + \sigma^2 t$$

Let  $g(t) = \mathbb{E}[X(t)^2]$ , the problem leads to the ordinary differential equation  $\frac{d}{dt} g(t) = 2\alpha g(t) + \sigma^2$

$$\Rightarrow \frac{d}{dt}(\bar{e}^{2\alpha t} g(t)) = \bar{e}^{2\alpha t} \sigma^2$$

(14)

$$\Rightarrow g(t) = e^{2\alpha t} \left( x_0^2 + \sigma^2 \int_0^t \bar{e}^{2\alpha s} ds \right)$$

$$= x_0^2 e^{2\alpha t} + \sigma^2 \frac{e^{2\alpha t} - 1}{2\alpha}$$

so the variance is  $\text{var}(x(t)) = \sigma^2 \frac{e^{2\alpha t} - 1}{2\alpha}$ .

$$(3) \quad x(t) = e^{\alpha t} \left( x_0 + \int_0^t \bar{e}^{-\alpha s} \sigma dw(s) \right).$$

Problem:- Let  $K(x)$  be a non-negative, continuous function and let  $f(x)$  be a bounded and continuous. Suppose that  $u(t, x)$  is a bounded function that satisfies the partial differential equation

$$\frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial^2 u}{\partial x^2} - K(x)u \quad \dots (*)$$

and the initial condition  $u(0, x) = f(x)$ .

Then the stochastic representation of the solution  $u(t, x)$  is

$$u(t, x) = \mathbb{E} \left[ \exp \left\{ - \int_0^t K(w(s)) ds \right\} f(w(t)) \right],$$

where  $w(t)$  is a Brownian motion started at  $x$  ( $w(0) = x$ ).

Solution:- Fix  $t > 0$  and consider the stochastic process

$$Y(s) = e^{-R(s)} u(t-s, w(s)), \text{ where}$$

$$R(s) = - \int_0^s K(w(u)) du.$$

$$dY(s) = -K(w(s)) e^{-R(s)} u(t-s, w(s)) ds$$

$$- u_t(t-s, w(s)) e^{-R(s)} ds + u_x(t-s, w(s)) e^{-R(s)} dw(s)$$

$$+ \frac{1}{2} u_{xx}(t-s, w(s)) e^{-R(s)} ds.$$

$$dY(s) = \bar{e}^{R(s)} \left[ -u_t(t-s, W(s)) - K(W(s)) u(t-s, W(s)) \right. \\ \left. + \frac{1}{2} u_{xx}(t-s, W(s)) \right] ds + u_x(t-s, W(s)) \bar{e}^{R(s)} dW(s).$$

Since  $u$  satisfies the PDE  $(*)$ , the  $ds$  terms in the last expression sum to zero, leaving

$$dY(s) = u_x(t-s, W(s)) \bar{e}^{R(s)} dW(s).$$

Thus  $Y(s)$  is a martingale up to time  $t$ . Hence

$$Y(0) = u(t, W(0)) = \mathbb{E}[Y(t)]$$

$$\Rightarrow u(t, x) = \mathbb{E}[\bar{e}^{R(t)} u(0, W(t))]$$

$$= \mathbb{E}[\bar{e}^{R(t)} f(W(t))]$$

$$= \mathbb{E}\left[\exp\left\{-\int_0^t K(W(s)) ds\right\} f(W(t))\right].$$