## Lecture 10: Interpolation Contd..

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$$f[x_0,x_1] = f(x_1) - f(x_0)$$

Recall the interpolation error in Newton interpolating polynomial:

If t is a point such that  $t \neq x_0, x_1, \ldots, x_n$ , then

Recall the error in Lagrange's wherposetry 
$$f(t)-p_n(t)=f[x_0,x_1,\ldots,x_n,t]\prod_{j=0}^n(t-x_j).$$

Remark. Note that, we cannot evaluate the term  $f[x_0, x_1, \ldots, x_n, t]$  without knowing the number f(t). We now prove that the number  $f[x_0, x_1, \ldots, x_n, t]$  is closely to the (n+1)th derivative of f(x).

Theorem. Let  $f \in C^k([a, b])$ . If  $x_0, x_1, \ldots, x_k$  are k+1 distinct point [a, b], then there exists  $\mathcal{E} \in (a, b)$  such that Remark. Note that, we cannot evaluate the term  $f[x_0, x_1, \dots, x_n, t]$ 

Theorem. Let  $f \in C^k([a,b])$ . If  $x_0, x_1, \ldots, x_k$  are k+1 distinct points in [a,b], then there exists  $\xi \in (a,b)$  such that

$$f[x_0, x_1, \ldots, x_k] = \frac{f^{(k)}(\xi)}{k!}.$$

**Proof.** Take k = 1. Then by MVT,

$$f[x_0,x_1]=\frac{f(x_1)-f(x_0)}{x_1-x_0}=f'(\xi),$$

for some  $\xi \in (a, b)$ . For the general case, observe that

$$e_k(x) = f(x) - p_k(x)$$

 $e_{K}(ai) = f(ni) - P(ni)$  = f(ni) - f(ni) = f(ni) - f(ni) = 0, i = 0,1,...K.

has (at least) k+1 distinct zeros  $x_0, x_1, \ldots, x_k$  in [a, b]. By Rolle's theorem,  $e'_k(x)$  has at least k zeros in  $(a, b) \implies e''_k(x)$  has at least k-1 zeros in (a, b). Likewise, one can show that  $e''_k(x)$  has at least one zero in (a, b). That is, there exists  $\xi \in (a, b)$  such that

$$e_k^{(k)}(\xi) = 0 \implies f^{(k)}(\xi) - p_k^{(k)}(\xi) = 0.$$

Since, for any x,  $p_k^{(k)}(x) = f[x_0, x_1, \dots, x_k] k!$ , we have at once

$$f[x_0, x_1, \dots, x_k] = \frac{f^{(k)}(\xi)}{k!}.$$

$$e_{K}(n) = f(n) - f(n)$$
 $e_{K}(n) = f(n) - f(n)$ 
 $e_{K}(n) = f(n)$ 

In view of the above result, we have the following expression for the interpolation error.

Theorem. Let  $f \in C^{n+1}([a,b])$ . If  $p_n(x)$  is a polynomial of degree  $\leq n$  such that

$$p_n(x_i) = f(x_i), \quad i = 0, 1, ..., n.$$

Then, for all  $t \in [a, b]$ , there exists  $\xi = \xi(t) \in (a, b)$  such that

$$f(t)-p_n(t)=rac{f^{(n+1)}(\xi)}{(n+1)!}\prod_{j=0}^n(t-x_j).$$

**Proof.** We know

$$f(t) - p_n(t) = f[x_0, x_1, \dots, x_n, t] \prod_{j=0}^n (t - x_j).$$

Since  $f[x_0, x_1, \ldots, x_n, t] = \frac{f^{(n+1)}(\xi)}{(n+1)!}$ , we immediately obtain

$$f(t) - p_n(t) = \frac{f^{(n+1)}(\xi)}{(n+1)!} \prod_{j=0}^n (t-x_j).$$

Note that

$$\lim_{x \to x_0} f[x_0, x] = \lim_{x \to x_0} \frac{f(x) - f(x_0)}{x - x_0} = f'(x_0).$$

This suggest that the first divided difference at two identical points be defined as

$$f[x_0, x_0] = f'(x_0).$$

For any n+1 distinct points  $x_0, x_1, \ldots, x_n$  in [a; b] and any  $f \in C^n[a, b]$ , we have

$$f[x_0, x_1, \ldots, x_n] = \frac{f^{(n)}(\xi)}{n!}.$$

Letting all  $x_i \to x_0$ ,  $i \ge 1$ , and  $\xi$  being trapped between them,  $\xi \to x_0$ ,

we obtain 
$$f\left[\underbrace{x_0,x_0,\ldots,x_0}_{\text{(n+1) times}}\right] = \frac{f^{(n)}(x_0)}{n!}.$$

## Inverse Interpolation

 An interesting application of interpolation, (in particular, of Newton's interpolation formula) is to approximate the solution of nonlinear equation

$$f(x) = 0. f(\xi) = 0. (1)$$

Let  $x_0 \approx \xi$ ,  $x_1 \approx \xi$  be two approximations of a root  $\xi$  of (1). Assume that f is monotone near  $\xi$ . Then

$$y = f(x) \implies x = f^{-1}(y).$$

Denote  $g(y) = f^{-1}(y)$ . Since  $\xi = f^{-1}(0) = g(0)$ , our aim is now to evaluate g(0). Compute

$$y_0 = f(x_0), \ y_1 = f(x_1) \implies x_0 = g(y_0), \ x_1 = g(y_1).$$

The divided difference for inverse function g:

$$y_0 \quad x_0 \quad g[y_0, y_1]$$
  
 $y_1 \quad x_1$ 

$$\chi_{2} = g[y_{0}] + g[y_{0}, y_{1}](y_{1} - y_{0})$$

$$\therefore y_{1} = 0, \quad \chi_{2} = g(y_{0}), \quad \chi_{2} = \chi_{3} + (0 - y_{0})g[y_{0}, y_{1}]$$

$$= \chi_{3} - g[y_{3}, y_{1}]y_{0}$$
To compute  $g(0)$ , an improved approximation by linear interpolation

 $x^{2} = x^{2} + 2[x^{0},y^{1},y^{2}]x$  (0-3)(0-3)

$$x_2 = x_0 + (0 - y_0)g[y_0, y_1] = x_0 - y_0 g[y_0, y_1].$$

Now evaluating  $y_2 = f(x_2)$ , we get  $x_2 = g(y_2)$ . The divided difference table can be updated as

$$y_0$$
  $x_0$   $g[y_0, y_1]$   $g[y_0, y_1, y_2]$   
 $y_1$   $x_1$   $g[y_1, y_2]$   
 $y_2$   $x_2$ 

This allows us to use quadratic interpolation to get

$$x_3 = x_2 + (0 - y_0)(0 - y_1)g[y_0, y_1, y_2] = x_2 + y_0y_1 g[y_0, y_1, y_2],$$

and then

$$y_3 = f(x_3)$$
 and  $x_3 = g(y_3)$ .

If necessary, we can continue updating the difference table,

$$y_0$$
  $x_0$   $g[y_0, y_1]$   $g[y_0, y_1, y_2]$   $g[y_0, y_1, y_2, y_3]$   
 $y_1$   $x_1$   $g[y_1, y_2]$   $g[y_1, y_2, y_3]$   
 $y_2$   $x_2$   $g[y_2, y_3]$   
 $y_3$   $x_3$  
$$x_4 = x_3 - g[y_0, y_1, y_2, y_3] \times (0 - y_0)(0 - y_1)(0 - y_2)$$

and compute

$$x_4 = x_3 - y_0 y_1 y_2 g[y_0, y_1, y_2, y_3], \quad y_4 = f(x_4), \quad x_4 = g(y_4)$$

so on. In general, the process will converge:  $x_k \to \xi$  as  $k \to \infty$ .