

# Lecture 29: Stability Analysis Contd.. and Lax Equivalence Theorem

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# Stability Criteria for Derivative BCs

Consider

$$\begin{aligned}\frac{\partial U}{\partial t} &= \frac{\partial^2 U}{\partial x^2}, \quad 0 < x < 1, \\ \frac{\partial U}{\partial x} &= C_1(U - V_1) \quad \text{at } x = 0, \quad t > 0 \\ \frac{\partial U}{\partial x} &= -C_2(U - V_2) \quad \text{at } x = 1, \quad t > 0 \\ U(x, 0) &= f(x), \quad 0 \leq x \leq 1,\end{aligned}$$

where  $C_1$ ,  $C_2$ ,  $V_1$  and  $V_2$  are constants with  $C_1 \geq 0$ ,  $C_2 \geq 0$ .

Approximate the BCs by central difference scheme

$$\begin{aligned}\frac{u_{1,j} - u_{-1,j}}{2h} &= C_1(u_{0,j} - V_1), \\ \frac{u_{N+1,j} - u_{N-1,j}}{2h} &= -C_2(u_{N,j} - V_2)\end{aligned}$$

and the PDE by the explicit scheme

$$u_{i,j+1} = ru_{i-1,j} + (1 - 2r)u_{i,j} + ru_{i+1,j}.$$

Elimination of  $u_{-1,j}$  and  $u_{N+1,j}$ , leads to the system

$$\begin{bmatrix} u_{0,j+1} \\ u_{1,j+1} \\ \vdots \\ u_{N-1,j+1} \\ u_{N,j+1} \end{bmatrix} = \begin{bmatrix} \{1 - 2r(1 + C_1 h)\} & 2r & & & \\ r & (1 - 2r) & r & & \\ & \ddots & \ddots & \ddots & \\ & & & r & (1 - 2r) \\ & & & 2r & \{1 - 2r(1 + C_2 h)\} \end{bmatrix} \begin{bmatrix} u_{0,j} \\ u_{1,j} \\ \vdots \\ u_{N-1,j} \\ u_{N,j} \end{bmatrix} + \begin{bmatrix} 2rC_1 V_1 h \\ 0 \\ \vdots \\ 0 \\ 2rC_2 V_2 h \end{bmatrix}$$

The amplification matrix ( $A$ ) determining the propagation error is

$$\begin{bmatrix} \{1 - 2r(1 + C_1 h)\} & 2r & & & \\ r & (1 - 2r) & r & & \\ & \ddots & \ddots & \ddots & \\ & & & r & (1 - 2r) \\ & & & 2r & \{1 - 2r(1 + C_2 h)\} \end{bmatrix}$$

**Note:** Since the off-diagonal elements of this real matrix  $A$  are one-signed, all its eigenvalues are real.

### Theorem (Gerschgorin's theorem)

Let  $P_s$  be the sum of the moduli of the elements along the  $s$ th row excluding the diagonal element  $a_{s,s}$ . Then each eigenvalue of the matrix  $M$  lies inside or on the boundary of at least one of the circles

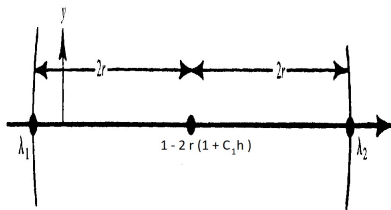
$$|\lambda - a_{s,s}| = P_s.$$

Application of the Gerschgorin's theorem to the amplification matrix  $A$ , with

$$a_{ss} = 1 - 2r(1 + C_1 h) \quad \text{and} \quad P_s = 2r$$

shows that some of its eigenvalues  $\lambda$  may lie on or within the circle

$$|\lambda - (1 - 2r(1 + C_1 h))| \leq 2r.$$



$$\lambda_1 = 1 - 2r(2 + C_1 h), \quad \lambda_2 = 1 - 2rC_1 h$$

For stability,

$$|\lambda_1| \leq 1, \quad |\lambda_2| \leq 1.$$

$$|\lambda_1| \leq 1 \implies -1 \leq 1 - 2r(2 + C_1 h) \leq 1 \implies r \leq \frac{1}{2 + C_1 h},$$

$$|\lambda_2| \leq 1 \implies -1 \leq 1 - 2rC_1 h \leq 1 \implies r \leq \frac{1}{C_1 h}.$$

The least of these is  $r \leq \frac{1}{2 + C_1 h}$ . Similarly, for the last row  $i = N$ , we have

$$r \leq \frac{1}{2 + C_2 h}.$$

For the row  $i = 2, \dots, N - 1$ , we have

$$a_{ss} = 1 - 2r, \quad P_s = 2r \implies r \leq \frac{1}{2}.$$

Therefore, for overall stability,

$$r \leq \min\left\{\frac{1}{2 + C_1 h}; \frac{1}{2 + C_2 h}\right\}.$$

**von Neumann's stability:** This method applies to linear difference equation with constant coefficients. Strictly speaking only to initial value problems with periodic data.

Consider

$$\begin{aligned}U_t &= U_{xx}, \quad 0 \leq x \leq L, \quad 0 < t \leq T, \\U(x, 0) &= f(x), \quad 0 \leq x \leq L.\end{aligned}$$

**Basic idea:**

- Express initial data by finite fourier series along the initial mesh-point at  $t = 0$ .
- Study the growth of a function that reduced to this series at  $t = 0$  by variable separable method.

The fourier series in complex exponential form can be expressed as

$$f(x) = \sum A_n e^{\frac{i\pi nx}{L}}, \quad i = \sqrt{-1}.$$

**Notation:** Let

$$x_p = ph, \quad p = 0, 1, 2, \dots, N \quad \text{with } Nh = L$$

$$t_q = qk, \quad q = 0, 1, 2, \dots, J \quad \text{with } Jk = T.$$

$$u(x_p, t_q) = u_{p,q} = u(ph, qk)$$

Note that

$$A_n e^{\frac{i\pi n x p}{L}} = A_n e^{\frac{i\pi n p h}{Nh}} = A_n e^{i\beta_n p h}, \text{ where } \beta_n = \frac{\pi n}{Nh}.$$

At  $q = 0$ ,

$$u_{p,0} = u(ph, 0) = \sum_{n=0}^N A_n e^{i\beta_n p h}.$$

Using the given  $u_{p,0}$  ( $p=0,1,2,\dots, N$ ), the constants  $A_n$  can be uniquely determined.

Since it is a linear problem, it is enough to investigate the propagation of only one initial value, such as  $e^{i\beta p h}$ , because separate solutions are additive. The coefficient  $A_n$  is a constant and can be neglected.

$$u_{p,q} = e^{i\beta x_p} e^{\alpha t_q} = e^{i\beta p h} \cdot e^{\alpha q k} = e^{i\beta p h} \cdot \xi^q,$$

where  $\xi = e^{\alpha k}$ ,  $\alpha$  is a constant.

By Lax-Richtmyer's definition of stability,

$$|u_{p,q}| \leq C \quad \forall q \leq J,$$

as  $h \rightarrow 0$  and  $k \rightarrow 0$ , and for all values of  $\beta$  needed to satisfy the initial conditions. Thus,  $u_{p,q}$  remains bounded if

$$|\xi| \leq 1,$$

which is the **necessary and sufficient** condition for stability (**von Neumann stability** condition).

**Example.** Investigate the stability of Crank-Nicolson scheme

$$-ru_{p-1,q+1} + (2+2r)u_{p,q+1} - ru_{p+1,q+1} = ru_{p-1,q} + (2-2r)u_{p,q} + ru_{p+1,q}.$$

approximating  $U_t = U_{xx}$ .

Substituting  $u_{p,q} = e^{i\beta ph} \xi^q$  in the difference equation, we obtain

$$\begin{aligned} & e^{i\beta ph} \xi^{q+1} (-re^{-i\beta h} + (2+2r) - re^{i\beta h}) \\ & = e^{i\beta ph} \xi^q (re^{-i\beta h} + (2-2r) + re^{i\beta h}) \\ \implies & \xi \{(2+2r) - 2r \cos(\beta h)\} = \{(2-2r) + 2r \cos(\beta h)\} \\ \implies & \xi \{1 + r(1 - \cos(\beta h))\} = \{1 - r(1 - \cos(\beta h))\} \end{aligned}$$



$$\implies \xi = \frac{1 - 2r \sin^2(\frac{\beta h}{2})}{1 + 2r \sin^2(\frac{\beta h}{2})} \leq 1 \quad \forall r > 0, \text{ (always true)}$$

and for all  $\beta$ . Thus, von Neumann's stability condition is satisfied and hence the finite difference equations are **unconditionally stable**.

**Exercise.** Investigate the stability of the two-level explicit and Euler's implicit schemes approximating the heat equation  $U_t = U_{xx}$  by von Neumann's stability method.

**Remarks.**

- **Consistency** is related to truncation error. We say a finite difference scheme is consistent with given PDE if the truncation error  $T_{i,j} \rightarrow 0$  as  $h \rightarrow 0$ ,  $k \rightarrow 0$ .
- **Stability** is related to the round-off error. We say that a finite difference scheme is stable if the exact solution of the finite difference equation does not grow with time.

**Convergence.** Let  $U_{i,j}$  is the exact solution of the PDE at the mesh point  $(ih, jk)$ , and let  $u_{i,j}$  be its finite difference approximation. Then, we say  $u_{i,j}$  converges to  $U_{i,j}$  if  $|u_{i,j} - U_{i,j}| \rightarrow 0$  as  $h \rightarrow 0$  and  $k \rightarrow 0$ .

**Lax Equivalence Theorem.** Given a well-posed linear initial value problem and a consistent linear finite difference equation approximating it. Then stability is the **necessary and sufficient** condition for convergence. That is, for a consistent finite difference scheme,

$$\text{Stability} \iff \text{Convergence}$$

**Remark.**

$$\text{Consistency} + \text{Stability} \implies \text{Convergence}$$

\*\*\* Ends \*\*\*