ABHISHEK BAMOTRA

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EDUCATION

Carnegie Mellon University, Pittsburgh, PA

Master of Science in Computational Design and Manufacturing

Dec 2020 GPA 4.0/4.0

◆ Intermediate Deep Learning* ◆ Robot Localization & Mapping* ◆ ML for Large Dataset ◆ Computer Vision

Thapar Institute of Engineering & Technology, India

Jun 2019

Bachelor of Engineering in Mechatronics Engineering

GPA 9.09/10.0

♦ *Robotics Engineering* ◆ Industrial Automation

♦ Digital Signal Processing

♦ Machine Design

WORK EXPERIENCE

Research Fellow, Computational Engineering and Robotics Laboratory, CMU

Jan 2020 - Present

- ♦ Developing machine learning algorithms for Point Cloud data.
- ♦ Object detection and warpage measuring using PCL.
- ◆ Developing algorithms to generate 3-D reconstruction using multi-light 2-D images.

Teaching Assistant, Machine Learning & Artificial Intelligence for Engineers (24-787), CMU Aug 2020 - Present

- ◆ Preparing and teaching recitations, Holding Office Hours to assist students clarifying doubts.
- ◆ Mentor groups of students with their course project, Prepare and Grade assignments.

Course Assistant, Intro to Scientific Computing (24-281), CMU

Jan 2020 - May 2020

♦ Assist professor with Homework, Quizzes, Projects and Tests

Robotics Intern, BioMechatronics Lab, National University of Singapore, Singapore

Feb 2018 - Jul 2018

- *♦ Hand-on experience with soft material fabrication.*
- ◆ Designed robotic hand gripper and an ultra-sensitive tactile sensor using 3-D printing and soft material.
- ◆ Soft gripper could lift 200 times its own weight and sensor was sensitive to 0.5 mN force.

Robotics Intern, Robotics Lab, Universidad Carlos III de Madrid, Spain

May 2017 - Jul 2017

- *♦ Hands-on experience with ROS, C++, and Linux.*
- ◆ Programmed Arduino to control mini robots.
- ♦ Developed automatic wireless communication between micro and mini robot.

Advanced: Python, C/C++, MATLAB, Spark, Arduino, 3-D Printing, PTC Creo

Intermediate: SQL, OpenCV, TensorFlow, PyTorch, PCL, AWS, RSLogix, AutoCAD, Solidworks, OpenGL

Basic: Java, OpenAI Gym, NI Multisim, ROS, Keil, R

PROJECTS

New York City Taxi Fare Prediction (CMU)

Jan 2020 - May 2020

- ◆ Developed a pipeline for a large-scale dataset (~1Tb)
- ◆ Algorithms based on Linear Regression, Decision Tree, Random Forest and XGBoost. RSME: 0.73\$

Multi-View Keypoint 3D-Reconstruction to track object's orientation and motion (CMU) Jan 2020 – May 2020

- ◆ Developed a pipeline involving fundamental, essential matrices and triangulation to extract epipolar correspondences.
- ◆ Integrated the pipeline with bundle adjustment to 3D reconstruct keypoint to track object's state.

KeyDetect - Detection of anomalies and user based on Keystroke Dynamics (CMU)

Oct 2019 – Dec 2019

- ◆ Developed a 2-step authentication model to learn and verify the user based on the typing patterns.
- ◆ Algorithms based on SVM, Neural Networks (1-D Conv., with Negative Class), Decision Trees.

Controller Design for an Autonomous Vehicle to track the route (CMU)

Oct 2019 - Dec 2019

- ♦ De-noised the input sensor data using Kalman Filter.
- ◆ Developed PID, Feedback, Optimal controller for the vehicle and bagged position in top 20 %.

PATENTS & PUBLICATIONS

Kirigami-Inspired soft end-effector with layer jamming for stiffness control (Patent)
Abhishek Bamotra, Pushpinder Walia, A.V. Prituja & H. Ren

Under review Jun 2018

Tri-axial Force Sensor (Patent)

Under review

Pushpinder Walia, Abhishek Bamotra & H. Ren

Jun 2018

Layer-Jamming Suction Grippers with Variable Stiffness

ASME JMR Jan 2019

Abhishek Bamotra, Pushpinder Walia, A.V. Prituja & H. Ren 10.1115/1.4042630 Fabrication and Characterization of Novel Soft Compliant Robotic End-Effectors

IEEE ICARM

with Negative Pressure and Mechanical Advantages

Jul 2018

Abhishek Bamotra, Pushpinder Walia, A.V. Prituja & H. Ren 10.1109/ICARM.2018.8610688

Design and Fabrication of Soft-bodied 3-D Tactile Sensors with Magnetometers

IEEE ICIA Aug 2018

Pushpinder Walia, Abhishek Bamotra, A.V. Prituja & H. Ren 10.1109/ICInfA.2018.8812448

IEEE CASE Aug 2019

Active Contact Enhancements With Stretchable Soft Layers and Piezoresistive Tactile Array for **Robotic Grippers**

G. Ponraj, A.V. Prituja, Abhishek Bamotra, Zhu G., H. Ren, et al. 10.1109/COASE.2019.8842882