

Lec. 20 (Last!!)

Completely observable case (i.e., $y \equiv x$)

Deterministic HJB

$$\text{Problem:} \quad \min_{\gamma(\cdot) \in \Gamma} \phi(x(T), T) + \int_0^T L(t, x, u) dt$$

$$\text{s.t.} \quad \dot{x} = f(x, u, t), \quad x \in X \subseteq \mathbb{R}^n, \quad u \in U \subseteq \mathbb{R}^m$$

$$\text{Find } u^*(x, t) = \gamma^*(x, t)$$

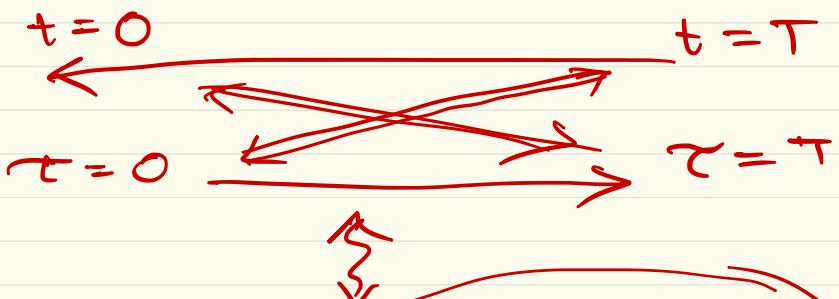
PDE for the value $f^m V(x, t)$ is called HJB PDE

$$\frac{\partial V}{\partial t} + \min_{u \in U} \left\{ L(t, x, u) + \left\langle \frac{\partial V}{\partial x}, f(t, x, u) \right\rangle \right\} = 0, \quad \text{s.t.} \quad V(x(T), T) = \phi(x(T), T)$$

$$\frac{\partial V}{\partial t} + H_{\text{opt}}(t, x, \frac{\partial V}{\partial x}) = 0 \quad \text{s.t. (crys)}$$

1st order PDE, nonlinear PDE

Terminal value problem \Leftrightarrow IVP by $\gamma := T - t$



IVP:

$$\frac{\partial V}{\partial \gamma} + H_{\text{opt}}(\gamma, \underline{x}, \frac{\partial V}{\partial \underline{x}}) = 0$$

s.t. $V(\gamma=0, \underline{x}) = \phi(\underline{x})$

How to Solve: Numerical sol \approx Method of characteristics

Analytical: $V(t, \underline{x}) \equiv \frac{1}{2} \underline{x}^T P(t) \underline{x}$ (causes)

e.g. LQR Derive Riccati ODE etc.

Kalman gain

Moral: Guess can help solve this PDE.

Analytical: (no guess)

Suppose OCP is time invariant.

Suppose also that H_{opt} is indep. of \underline{x} .

(i.e.) $H_{\text{opt}}(\cdot) = H_{\text{opt}}\left(\frac{\partial V}{\partial \underline{x}}\right)$

AND $H_{\text{opt}}(\underline{z})$ is convx in \underline{z}

AND $H_{\text{opt}}(\underline{z})$ is $\frac{1}{2}$ -coercive, (i.e.) $\lim_{\|\underline{z}\| \rightarrow \infty} \frac{H(\underline{z})}{\|\underline{z}\|} = +\infty$
(superlinear)

Then we can give
semi-analytical variational formula

for $V(t, \underline{z})$

Hopf - Lax Representation Formula:

$$V(\underline{z}, \underline{x}) = \min_{\underline{y} \in \mathbb{R}^n} \left\{ \phi(\underline{y}) + \underline{z}^T H_{\text{opt}}^* \left(\frac{\underline{x} - \underline{y}}{\underline{z}} \right) \right\}$$

$$H^*(\underline{a}) := \max_{\underline{z} \in \mathbb{R}^n} \left\{ \underline{a}^T \underline{z} - H(\underline{z}) \right\}$$

Legendre-Fenchel conjugate
or Convex Conjugate of $H(\cdot)$

||
Lagrangian
(L)

Example: If HJB PDE: $\frac{\partial V}{\partial t} + \frac{1}{2} \left\| \frac{\partial V}{\partial \underline{x}} \right\|_2^2 = 0$

$$H(\underline{z}) = \frac{1}{2} \underline{z}^T \underline{z}$$

$$\text{Then } H^*(\underline{a}) = \frac{1}{2} \underline{a}^T \underline{a} \Rightarrow \therefore \underline{x}^T H_{\text{opt}}^* \left(\frac{\underline{x} - \underline{y}}{\underline{z}} \right) = \frac{1}{2} \|\underline{x} - \underline{y}\|_2^2$$

∴ By Hopf-Lax :

$$V(\underline{x}, \gamma) = \min_{\underline{y} \in \mathbb{R}^n} \left\{ \phi(\underline{y}) + \frac{1}{2\gamma} \|\underline{x} - \underline{y}\|_2^2 \right\}$$

$$= \frac{1}{\gamma} \min_{\underline{y} \in \mathbb{R}^n} \left\{ \frac{1}{2} \|\underline{x} - \underline{y}\|_2^2 + \gamma \phi(\underline{y}) \right\}$$

$$= \frac{1}{\gamma} \underbrace{\text{prox}_{\gamma\phi(\cdot)}^{\|\cdot\|_2}}_{(\underline{x})}$$

Moreau-Yosida proximal
operator

Stochastic HJB (still completely observed):

$$\dot{\underline{x}} = f(t, \underline{x}, u) + g(t, \underline{x}, u) \times \text{noise} \quad \text{px}_1$$

$$\Leftrightarrow \frac{d\underline{x}}{dt} = \underbrace{f(t, \underline{x}, u)}_{\substack{\text{nx1} \\ \text{Stochastic} \\ \text{differential} \\ \text{coeff.}}} dt + \underbrace{g(t, \underline{x}, u)}_{\substack{\text{nxp} \\ \text{Diffusion} \\ \text{coeff.}}} d\underline{w}$$

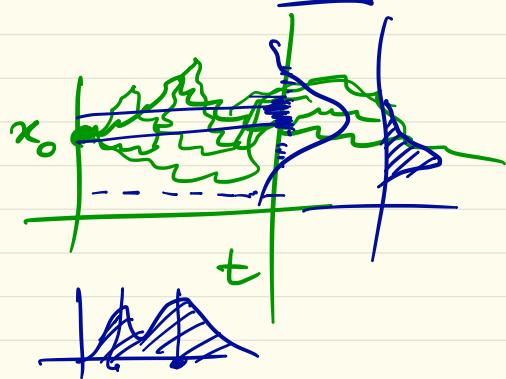
process noise
 $d\underline{w} \sim N(0, Idt)$

Objective

$$\min_{\gamma \in \Gamma(\cdot)} \mathbb{E} \left[\phi(\underline{x}(T), T) + \int_0^T L(\underline{x}, u, t) dt \right]$$

s.t.

this dynamics.
find $u^* = \gamma^*(\underline{x}, t)$



Stochastic HJB:

(Remember:
Here, we have
no PMP)

Define Hamiltonian:

$$H(x, u, t, V, \frac{\partial V}{\partial x}, \frac{\partial^2 V}{\partial x^2})$$

\Downarrow
 $Hess(V)$

$$\begin{aligned} &:= L(t, x, u) + \left\langle \frac{\partial V}{\partial x}, f(t, x, u) \right\rangle + \\ &\quad \underbrace{\frac{1}{2} \operatorname{tr} \left(\underbrace{g^T(t, x, u)}_{p \times n} \underbrace{Hess(V)}_{n \times n} \underbrace{g(t, x, u)}_{n \times p} \right)}_{+} \\ &\quad \underbrace{\frac{1}{2} \operatorname{tr} (gg^T Hes(V))}_{\text{Diffusion tensor}} \end{aligned}$$

Stoc. HJB :

$$\frac{\partial V}{\partial t} + \min_{u \in U} H(t, \underline{x}, u, V, \frac{\partial V}{\partial \underline{x}}, \frac{\partial^2 V}{\partial \underline{x}^2}) = 0$$

$$\Leftrightarrow \frac{\partial V}{\partial t} + H_{\text{opt}}(t, \underline{x}, V, \frac{\partial V}{\partial \underline{x}}, \frac{\partial^2 V}{\partial \underline{x}^2}) = 0,$$

2nd order
nonlinear PDE

$$V(\underline{x}(T), T) = \phi(\underline{x})$$

Side remark: $d\underline{x} = f(\underline{x}, t) dt + g(\underline{x}, t) d\uomega$

$$y: \mathbb{R}^n \mapsto \mathbb{R} \quad y = y(\underline{x}, t) \leftarrow \text{Deterministic function}$$

Ito's Lemma :

$$\begin{aligned} dy &= \frac{\partial y}{\partial t} dt + (\nabla y)^T d\underline{x} + \frac{1}{2} (d\underline{x})^T (\text{Hess}(y)) d\underline{x} \\ &= \left\{ \frac{\partial y}{\partial t} + (\nabla y)^T f(\underline{x}, t) + \frac{1}{2} \text{tr}(g^T \text{Hess}(y) g) \right\} dt \\ &\quad + (\nabla y)^T g(\underline{x}, t) d\uomega \end{aligned}$$

Fokker-Plack or Kolmogorov Forward PDE:

$$\frac{\partial p}{\partial t} = -\nabla_x \cdot (p f) + \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \frac{\partial^2}{\partial x_i \partial x_j} (g g^T p)$$

$$p(x, t=0) = p_0(x)$$

$$\Leftrightarrow \frac{\partial p}{\partial t} = L_{\text{Fokker-Plack}} p$$

$$\text{or } L_{\text{Forward Kolmogorov}} p$$

Backward Kolmogorov PDE

$$\frac{\partial p}{\partial s} = L_{\text{Backward Kolmogorov}} p,$$

$$= \left\langle \frac{\partial p}{\partial x} + \frac{f}{2}, \operatorname{tr}(g g^T \operatorname{Hess}(p)) \right\rangle$$

Formally,
Backward $= (L^*)^*$
Forward.

$$\langle L^* p, v \rangle = \langle p L^* v \rangle$$

\downarrow adjoint

Stochastic HJB:

$$\frac{\partial V}{\partial t} + \min_{u \in U} \left\{ L(t, x, u) + \underset{\substack{\text{Backward} \\ \text{Kolmogorov}}}{\mathcal{L}} V \right\} = 0$$