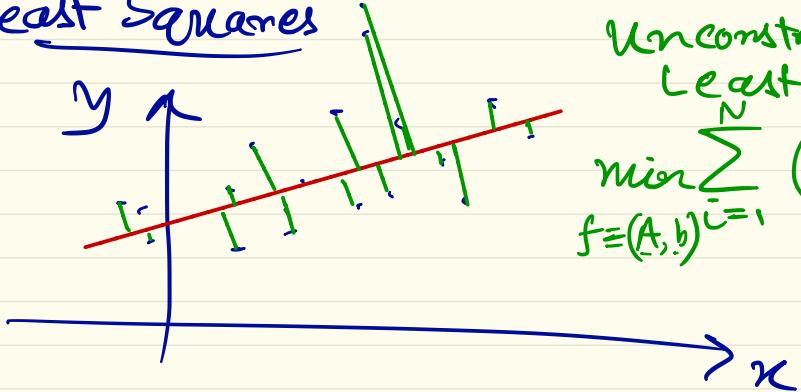


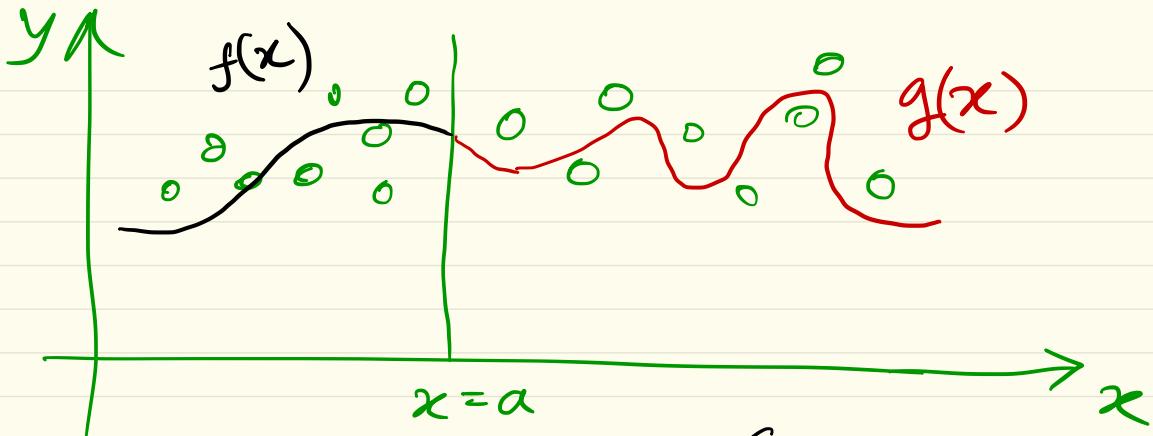
## Lecture #11

### Least Squares



Unconstrained  
Least squares:

$$\min_{f \in \{\underline{A}, \underline{b}\}} \sum_{i=1}^N (f(x_i) - y_i)^2$$



Problem:

fit piecewise polynomial to given data.

Suppose data:  $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$

Suppose,

$x_1, \dots, x_M \leq a, x_{M+1}, \dots, x_N > a$

$$\underset{(\theta_1, \theta_2, \dots, \theta_{2d}) \in \mathbb{R}^M}{\text{minimize}} \sum_{i=1}^M (f(x_i) - y_i)^2 + \sum_{i=M+1}^N (g(x_i) - y_i)^2$$

s.t.

$$f(a) = g(a)$$

$$f'(a) = g'(a)$$

Polynomial f & g (of degree d-1)

$$f(x) = \theta_1 + \theta_2 x + \theta_3 x^2 + \dots + \theta_d x^{d-1}$$

$$g(x) = \theta_{d+1} + \theta_{d+2} x + \theta_{d+3} x^2 + \dots + \theta_{2d} x^{d-1}$$

Verify that:  
 prev. problem  
 can be  
 re-written as:

$$\min_{z \in \mathbb{R}^{2d}} \|A z - b\|_2^2 \quad (\text{acceptable by } \text{cvx})$$

s.t.

$$C z = h$$

where

$$A = \begin{bmatrix} 1 & x_1 & \dots & x_1^{d-1} & 0 & 0 & \dots & 0 \\ \vdots & \vdots & & \vdots & \vdots & \vdots & & \vdots \\ 1 & x_M & \dots & x_M^{d-1} & 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 & 1 & x_{M+1} & \dots & x_{M+1}^{d-1} \\ \vdots & \vdots & & \vdots & 1 & x_N & \dots & x_N^{d-1} \end{bmatrix} \quad z = \begin{pmatrix} \theta_1 \\ \vdots \\ \theta_{2d} \end{pmatrix} \in \mathbb{R}^{2d}$$

$$b = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_M \\ y_{M+1} \\ \vdots \\ y_N \end{pmatrix}, \quad C = \begin{bmatrix} 1 & a & \dots & a^{d-1} & -1 & -a & \dots & -a^{d-1} \\ 0 & 1 & \dots & (d-1)a^{d-2} & 0 & -1 & \dots & -(d-1)a^{d-2} \end{bmatrix}, \quad h = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

Ineq. Constrained Least Squares problem

$$\min_{\underline{x} \in \mathbb{R}^n} \|\mathbf{A}\underline{x} - \mathbf{b}\|^2$$

$$\underline{x} \in \mathbb{R}^n$$

s.t.  $0 \leq \underline{x} \leq 1$

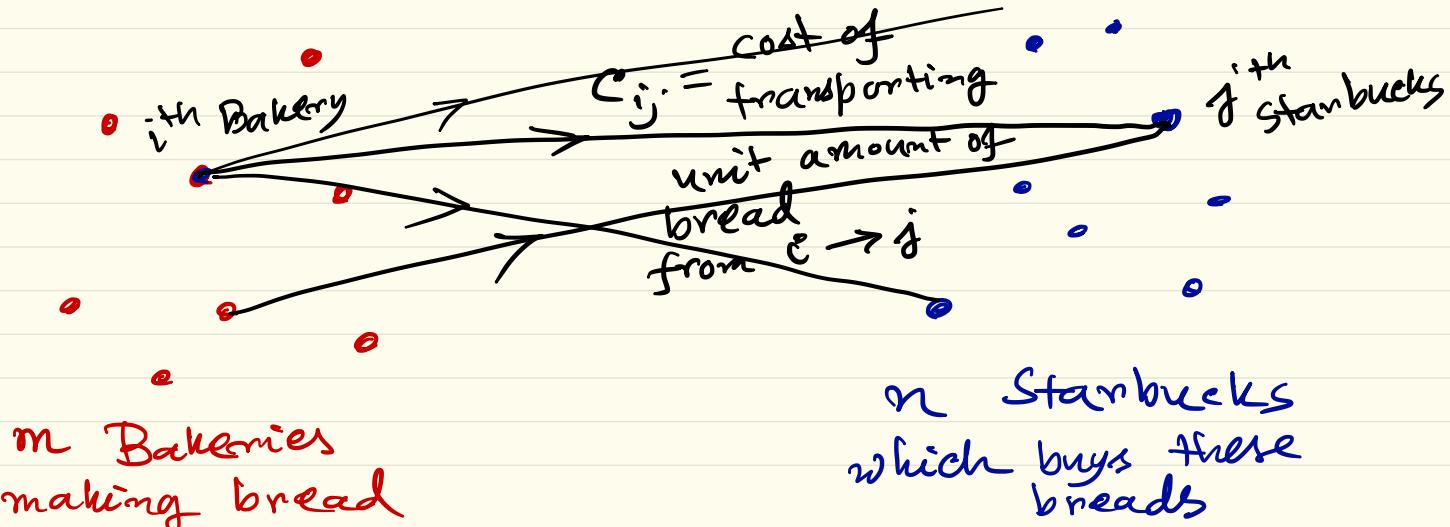
Can solve in  
 $\mathbb{C}^{n \times n}$

$$i=1, \dots, m$$

a

$$j=1, \dots, n$$

## Transportation Problem



Objective:

minimize total transport cost:

$$= \sum_{i=1}^m \sum_{j=1}^n c_{ij} m_{ij}$$

$$\boxed{\sum_{i=1}^m \sum_{j=1}^n m_{ij} = 1}$$

$$\min m_{ij}$$

$$\sum_{i=1}^m \sum_{j=1}^n c_{ij} m_{ij}$$

Model cost as:

$$c_{ij} = \frac{\|\underline{x}(i) - \underline{x}(j)\|_2^2}{2} \geq 0$$

$$\text{s.t. } \sum_{j=1}^n m_{ij} \geq 0$$

$$\sum_{j=1}^n m_{ij} = \alpha_i \quad (\text{production capacity of } i^{\text{th}} \text{ bakery})$$

$$\sum_{i=1}^m m_{ij} = \beta_j \quad (\text{storage capacity of } j^{\text{th}} \text{ Starbucks})$$

LP

$$c_{ij} = \|\underline{x}(i) - \underline{x}(j)\|_2 \quad \begin{array}{l} (\text{SG } C_{ij} = [c_{ij}]) \\ \text{defines Euclidean} \\ \text{distance matrix} \end{array}$$

$$= \sqrt{\left(x_{\text{Bakery}_1}(i) - x_{\text{Starbucks}_1}(j)\right)^2 + \left(x_{\text{Bakery}_2}(i) - x_{\text{Starbucks}_2}(j)\right)^2}$$

Matrix form

$$\min_M \sum_{i=1}^m \sum_{j=1}^n c_{ij} m_{ij} = \text{tr}(C^T M)$$

s.t.  $M \geqslant 0$  (elementwise)

$$M \mathbf{1} = \alpha_{n \times 1}$$

$$M^T \mathbf{1} = \beta_{n \times 1}$$

Duality: Optimization problem (we call this "Primal" problem)

$$p^* = \min_{\underline{x} \in \mathbb{R}^n} f_0(\underline{x})$$

$$\begin{aligned} \underline{f}(\underline{x}) &= \begin{pmatrix} f_0 \\ \vdots \\ f_m \end{pmatrix} \\ \underline{h}(\underline{x}) &= \begin{pmatrix} h_1 \\ \vdots \\ h_p \end{pmatrix} \end{aligned}$$

$$\begin{aligned} f_i(\underline{x}) &\leq 0, \quad i=1, \dots, m \\ h_j(\underline{x}) &= 0 \quad j=1, \dots, p \end{aligned}$$

for Lagrange multipliers  
inequality constraints

$$L(\underline{x}, \underline{\lambda}, \underline{\nu}) := f_0(\underline{x}) + \langle \underline{\lambda}, \underline{f}(\underline{x}) \rangle + \langle \underline{\nu}, \underline{h}(\underline{x}) \rangle$$

"Lagrangian"

Lagrange multipliers for equality constraints

$$L: \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}^p \mapsto \mathbb{R}$$

Lagrange dual/dual :

$$g : \mathbb{R}^m \times \mathbb{R}^p \mapsto \mathbb{R}$$

"minimum of  $L$  over  $\underline{x}$ :

$$g\left(\frac{\lambda}{\pi}, \frac{\nu}{\pi}\right) = \inf_{\underline{x}} L(\underline{x}, \underline{\lambda}, \underline{\nu})$$

If  $L$  is unbounded below, then  $\boxed{g = -\infty}$

$g(\underline{\lambda}, \underline{\nu})$  is always CONCAVE in  $(\underline{\lambda}, \underline{\nu})$   
(pointwise inf of affine)

Even when the original problem  
is Non-convex,  $g(\underline{\lambda}, \underline{\nu})$  is still concave.

Relation between  $g(\underline{\lambda}, \underline{v})$  &  $p^*$   
(original/primal  
optimal value)

Claim: For any  $\underline{\lambda} \in \mathbb{R}_{\geq 0}^m$  & any  $\underline{v} \in \mathbb{R}^p$

$$\boxed{g(\underline{\lambda}, \underline{v}) \leq p^*}$$

(Lower bound for original problem's answer)

Proof: Let  $\underline{x}$  be feasible &  $\underline{\lambda} \in \mathbb{R}_{\geq 0}^m$

Then,

$$\underbrace{\langle \underline{\lambda}, f(\underline{x}) \rangle}_{\leq 0} + \underbrace{\langle \underline{v}, h(\underline{x}) \rangle}_{\geq 0} \leq 0$$

$$\Rightarrow L(\underline{x}, \underline{\lambda}, \underline{v}) = f_0(\underline{x}) + \underline{\lambda}^T \underline{f} + \underline{v}^T \underline{h} \leq f_0(\underline{x})$$

$$\Rightarrow \underbrace{\inf_{\underline{x}} L(\underline{x}, \underline{\lambda}, \underline{v})}_{!!} \leq L(\tilde{x}, \underline{\lambda}, \underline{v}) \leq f_0(\tilde{x})$$

$$g(\underline{\lambda}, \underline{v})$$

Since  $g(\underline{\lambda}, \underline{v}) \leq f_0(\tilde{x})$  &  $\tilde{x}$  feasible

$$\boxed{- \vdash g(\underline{\lambda}, \underline{v}) \leq p^*}$$

QED.

If  $g(\underline{\lambda}, \underline{v}) = -\infty$ , then  $-\infty \leq p^*$ .

Example :

$$\begin{aligned} & \min_{\underline{x} \in \mathbb{R}^n} \underline{x}^T \underline{x} \\ & \text{s.t. } A\underline{x} = \underline{b} \end{aligned}$$

QP

$$A \in \mathbb{R}^{p \times n}$$

$$\begin{aligned} L(\underline{x}, \underline{\nu}) &= \underline{x}^T \underline{x} + \langle \underline{\nu}, (A\underline{x} - \underline{b}) \rangle \\ (\text{Lagrangian}) &= \underline{x}^T \underline{x} + \underline{\nu}^T (A\underline{x} - \underline{b}) \end{aligned}$$

$$\text{dom}(L) = \mathbb{R}^n \times \mathbb{R}^p$$

$$\underbrace{g(\underline{\nu})}_{\text{Dual}} = \inf_{\underline{x} \in \mathbb{R}^n} \underbrace{L(\underline{x}, \underline{\nu})}_{\text{convex quadratic in } \underline{x}}$$

$$\begin{aligned} \therefore \nabla_{\underline{x}} L(\underline{x}, \underline{\nu}) &= 2\underline{x} + A^T \underline{\nu} = 0 \\ \Rightarrow \underline{x} &= -\frac{1}{2} A^T \underline{\nu} \end{aligned}$$

set derivative = 0

Substitute back:

$$\begin{aligned}g(\underline{v}) &= L\left(\underline{x} = -\frac{1}{2}A^T\underline{v}, \underline{v}\right) \\&= -\frac{1}{4}\underline{v}^T(AA^T)\underline{v} - \underline{b}^T\underline{v}\end{aligned}$$

which is concave quadratic over  $\mathbb{R}^p$ .

$\therefore$  Lower bound says:  $\forall \underline{v} \in \mathbb{R}^p$ ,

$$\boxed{-\left(\frac{1}{4}\right)\underline{v}^T A A^T \underline{v} - \underline{b}^T \underline{v} \leq p^*}$$