

Lec 13
Subgradient Calculus (Motivation: How to handle convex but non-differentiable functions)

Recall the 1st order condition for convexity for a differentiable $f \stackrel{\text{def}}{=} f(\cdot)$:

$$f(\underline{y}) \geq f(\underline{x}) + \underbrace{\langle \nabla f(\underline{x}), \underline{y} - \underline{x} \rangle}$$

$$\begin{aligned} &\quad \downarrow \quad \forall \underline{y} \in \text{dom}(f) \\ &= (\nabla f(\underline{x}))^\top (\underline{y} - \underline{x}) \end{aligned}$$

(i.e.) 1st order Taylor approximation of $f(\cdot) @ \underline{x}$
is a global underestimator.

(r.e.) $\begin{pmatrix} \nabla f(\underline{x}) \\ -1 \end{pmatrix}$ defines a supporting hyperplane to $\text{epi}(f)$
@ $(\underline{x}, f(\underline{x}))$

Why?

$$\begin{pmatrix} \nabla f \\ -1 \end{pmatrix}^T \begin{pmatrix} (y) \\ t \end{pmatrix} - \begin{pmatrix} x \\ f(x) \end{pmatrix} \leq 0$$

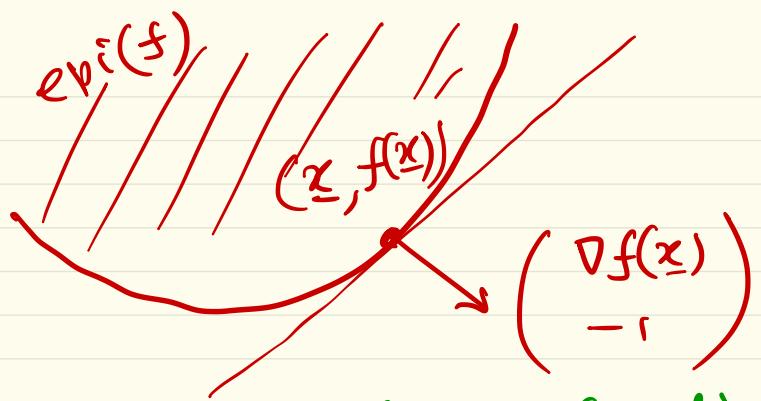
$$\nexists (y, t) \in \text{epi}(f)$$

Recall:

$$\text{epi}(f) = \left\{ \begin{pmatrix} y \\ t \end{pmatrix} \in \mathbb{R}^{n+1} \mid t \geq f(y) \right\}$$

$$t \geq f(y) \geq f(x) + (\nabla f(x))^T (y - x)$$

$$\Leftrightarrow t \geq f(x) + (\nabla f)^T (y - x)$$

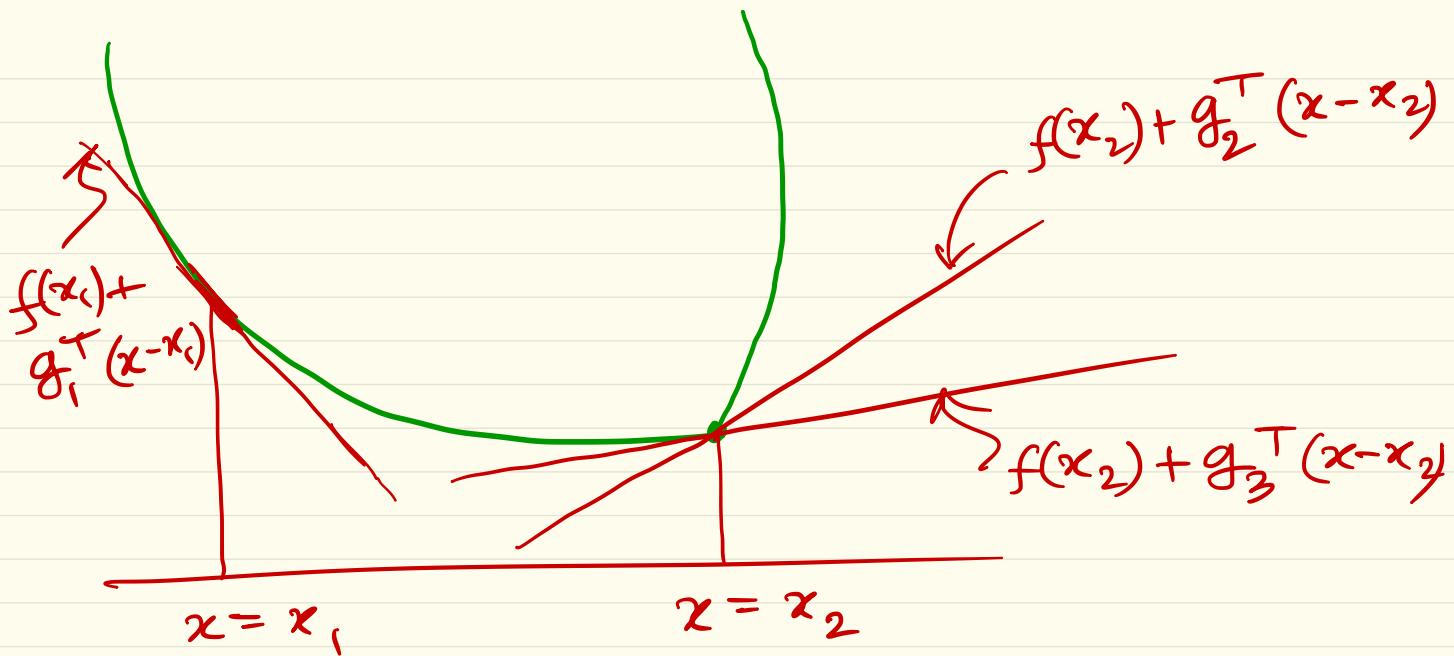


Subgradient of a function:

g is subgradient of $f(\cdot)$ @ \underline{x} if

$$f(\underline{y}) \geq f(\underline{x}) + g^T(\underline{y} - \underline{x}) \quad \forall \underline{y} \in \text{dom}(f)$$

e.g. $|y| \geq |x| + g(y - x) \quad \forall y$
 where $f(\cdot) = |\cdot|$ (absolute value function in \mathbb{R})



g_1 is a subgradient of f @ $x = x_1$

g_2, g_3 are subgradients of f @ $x = x_2$

3 equivalent statements

① g is a subgradient of f @ x

↔
② (g) supports $\text{epi}(f)$ @ $(x, f(x))$

↔
③ $f(x) + g^T(y - x)$ is global under-estimate
of f

Subdifferential : (convex)

$\partial f(x)$ of $f(\cdot)$ @ x is the set of
all subgradients :

$$\partial f(x) := \{g \mid g^T(y - x) \leq f(y) - f(x) \text{ } \forall y \in \text{dom}(f)\}$$

Properties:

$\partial f(\underline{x})$ is closed convex set (may be empty)
(Why? $\partial f(\underline{x})$ by defⁿ, is intersection of halfspaces)

If $f(\cdot)$ convex

- $\partial f(\underline{x}) = \{\nabla f(\underline{x})\}$ if f is differentiable
- If $\partial f(\underline{x}) = \underbrace{\{g\}}$ then f is differentiable & $g = \nabla f(\underline{x})$.

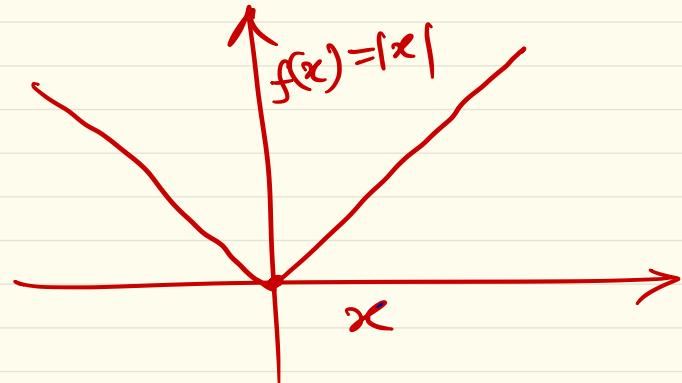
singleton

This shows gradient is special case of subgradient

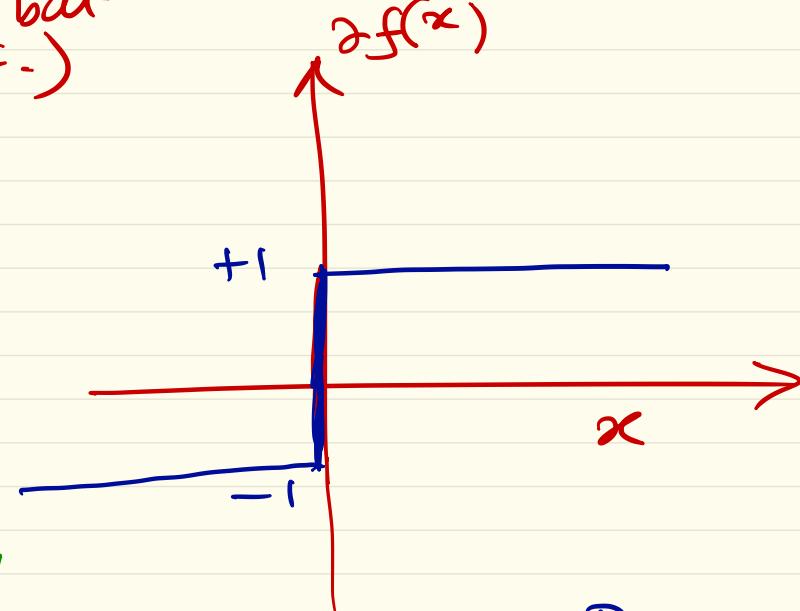
Example 1:

$$f(x) = |x|$$

(convex but
not diff.)



$$\partial f(x)$$



In other words,

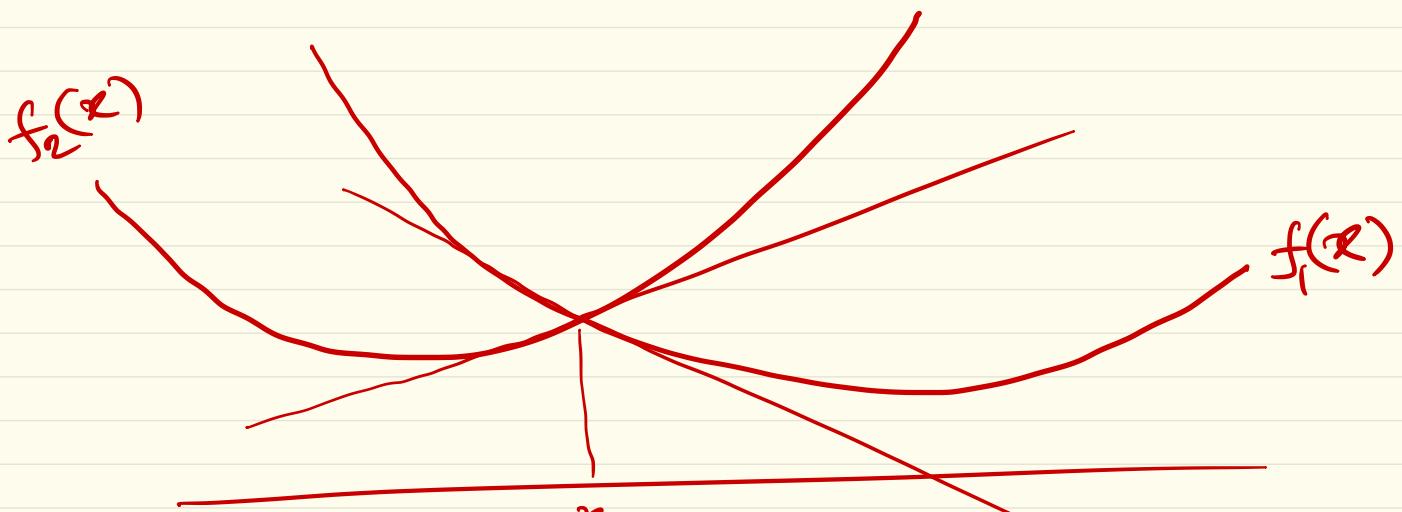
$$\partial f(x) = \begin{cases} -1 & \text{for } x < 0 \\ +1 & \text{for } x > 0 \\ [-1, 1] & \text{for } x = 0 \end{cases}$$

Plot of (x, g) : $x \in \mathbb{R}$,
 $g \in \partial f(x)$

Example 2 :

$$f(x) = \max \{ f_1(x), f_2(x) \} \text{ with } f_1 \text{ & } f_2$$

convex
& differentiable



- $f_1(x_0) > f_2(x_0)$: unique subgradient $g = \nabla f_1(x_0)$
- $f_2(x_0) > f_1(x_0)$: " " $g = \nabla f_2(x_0)$
- $f_1(x_0) = f_2(x_0)$: subgradients form a line segment $[\nabla f_1(x_0), \nabla f_2(x_0)]$

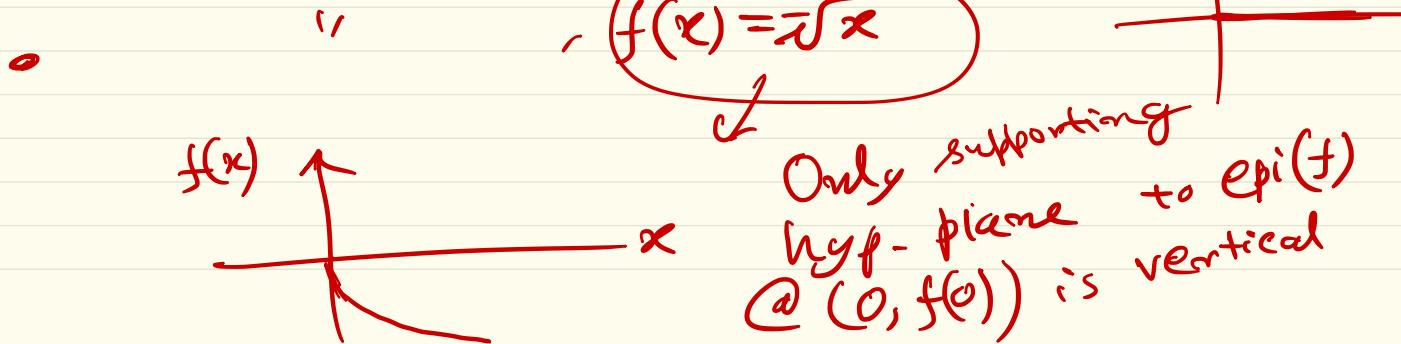
Example 3: $f(\underline{x}) = \|\underline{x}\|_2$

$$2f(\underline{x}) = \begin{cases} \underline{x}/\|\underline{x}\|_2 & \text{if } \underline{x} \neq 0 \\ \{\underline{g} \mid \|\underline{g}\|_2 \leq 1\} & \text{if } \underline{x} = 0 \end{cases}$$

Examples of non-subdifferentiable funs (in 1D)

$f(\cdot)$ NOT sub-diff. @ $\underline{x} = 0$.

• $f: \mathbb{R}_{\geq 0} \mapsto \mathbb{R}, \quad f(x) = \begin{cases} 1 & \text{if } x=0 \\ 0 & \text{if } x>0 \end{cases}$



Subgradient Calculus

Weak Sub. grad. calculus.

rules for finding ONE subgrad. $g \in \partial f(x)$

Strong Sub. grad. calculus

rules for finding ALL subgrads
(i.e. Computing the subdifferential $\partial f(x)$)

Basic Rules (assuming f convex)

① $\partial f(x) = \overline{\{\nabla f(x)\}}$ if f is diff. @ x

② scaling: $\partial(\alpha f) = \alpha \partial f$ for $\alpha > 0$

③ Addition: $\partial(f_1 + f_2) = \partial f_1 + \partial f_2$
(RHS is addition of sets)

④ Affine transformation of domain

If $f(\underline{x}) = h(A\underline{x} + \underline{b})$ then
 $\partial f(\underline{x}) = A^T \partial h(A\underline{x} + \underline{b})$

$$\left| \begin{array}{l} A \in \mathbb{R}^{m \times n} \\ \underline{b} \in \mathbb{R}^m \\ h: \mathbb{R}^m \mapsto \mathbb{R} \\ f: \mathbb{R}^n \mapsto \mathbb{R} \end{array} \right.$$

⑤ Pointwise max

If $f = \max_{i=1, \dots, m} \{f_i(\underline{x}), \dots, f_m(\underline{x})\}$

$$\partial f(\underline{x}) = \text{conv} \left(\cup \partial f_i(\underline{x}) \mid f_i(\underline{x}) = f(\underline{x}) \right)$$

i.e., convex hull of union of sub-differentials
of "active" functions @ \underline{x} .