Convex Optimization problems Lecture #8 min f(x) is convex iff  $x \in X$   $f(\cdot)$  is a convex  $f(\cdot)$  of x-> LP (linear Program) & TX set.

Both f is linear & X is defined as intersection of halfspaces & hyperplanes min CTX minimize linear fri s.t. Ax \le b over polyhedron polyhedron Ang LP:

-> QP (anadratic Programs) 7 Minimile A \in Sn | ruminex commex commex polyhedron f(x) = = 2x A x + b x + c X: Px sq -> QCQP (anadratically constrained quadratic Program) (f(x) = 12/Ax + bxx + c 2: 2xTM, x + n, x + r, & o, i=1, m Mi e Sn Minimize convex quedratic for over the intersection of m ellipsoids and a polyhedro

-> SOCD (Second order cone program) min ftx ∠ C: x + d:, i=1,..., m 2 S.t. / | Aiz + bi ||2 A; ERn; Xn ( Fx = g F ERPXN (Aix +bi, Cix+di) If n:= 0, then LP define second order cone in Rni+1 If Ci = 0, Heen QCQP Minimize linear france 7 over intersection of polyhedron & come -> SDP (Semi-definite program) min tr(CTX) s.t.tr(AxX) ≤ bx, XESn L' linear matrix inequality

## LPCQPCQCQPCSOCPCSDP