## Indian Institute of Technology Jammu

## **Department of Computer Science & Engineering**

## **Class Test 2, June 14, 2025**

Course Name : Computer Vision

Course Code :CSC003P5E Time :1 hour

Total Marks : 10

## Instructions:

• Conditions of Examination: Closed book; No Mobile; No Laptop; Scientific calculator is allowed.

• This question paper contains a total of 3 Questions. Make an appropriate assumption wherever necessary.

1. [4 Point] A given camera is calibrated to produce the following intrinsic matrix.

$$\begin{bmatrix} 300 & 0 & 300 \\ 0 & 300 & 200 \\ 0 & 0 & 1 \end{bmatrix}$$

Consider a situation where the camera is oriented relative to the world coordinate system such that it has a pose described by the following rotation matrix and translation vector.

$$R = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, t = \begin{bmatrix} 10 \\ 15 \\ 10 \end{bmatrix}$$

Compute the corresponding 3 x 4 camera matrix.

Using the resulting camera matrix compute the projection of the 3D world point P (Consider as a homogeneous point)

$$\begin{bmatrix} 20\\20\\-10\\1 \end{bmatrix}$$

- **2.** (a) [1.5 Point] Given two ideal pinhole cameras where:
  - the baseline of the two cameras is parallel to their scanlines,
  - the optical axes of the two cameras intersect to form an angle of 90 degrees,
  - the two centers of projection are at equal distances from the intersection of the optical axis, and
  - the field of view of each camera is 90 degrees.

Draw the epipoles and a few epipolar lines.

- (b) [1.5 Point] Draw illustration to show brightness constancy and smoothness constancy constraints in terms of (in terms of I,  $I_t$  u, v, uu, vv). Also write the supporting equations.
- (c) [1 Point] Explain the use of first and second order derivatives in optical flow.
- **3.** [2 Point] Given a 3D scene and *you have two images* taken of this scene from the *same camera* at different position and orientation.
  - (a) How can you estimate the Fundamental Matrix from this setup?
  - (b) How can you estimate the Essential Matrix?

Provide the steps in answer as short bullet points.