Abhishek Naik

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EDUCATION

• Ph.D., Computing Science University of Alberta, Edmonton, Canada

• Integrated B.Tech.+M.Tech., Computer Science and Engineering Indian Institute of Technology Madras, Chennai, India Supervisor: B. Ravindran

CGPA: 4.0/4.0, 2018-ongoing

Supervisor: Richard S. Sutton

CGPA: 9.49/10, 2013-18

(* equal contribution) **PAPERS**

• Multi-Step Average-Reward Prediction via Differential $TD(\lambda)$ Abhishek Naik, Richard S. Sutton

Presented at the Conference on Reinforcement Learning and Decision Making (RLDM), 2022

Average-Reward Learning and Planning with Options

[Paper, Poster]

[Paper]

Yi Wan, Abhishek Naik, Richard S. Sutton In Advances in Neural Information Processing Systems (NeurIPS), 2021

• Towards Reinforcement Learning in the Continuing Setting. Abhishek Naik, Zaheer Abbas, Adam White, Richard S. Sutton

[Paper, Poster]

Presented at the Never-Ending Reinforcement Learning (NERL) Workshop at ICLR, 2021

• Learning and Planning in Average-Reward Markov Decision Processes Yi Wan*, Abhishek Naik*, Richard S. Sutton

[Paper, Poster]

In International Conference on Machine Learning (ICML), 2021

• Discounted Reinforcement Learning Is Not an Optimization Problem Abhishek Naik, Roshan Shariff, Niko Yasui, Hengshuai Yao, Richard S. Sutton Presented at The Optimization Foundations of RL workshop at NeurIPS, 2019

[Paper, Poster]

MADRaS: Multi Agent DRiving Simulator

[Paper]

A. Santara, S. Rudra, S.A. Buridi, M. Kaushik, Abhishek Naik, B. Kaul, B. Ravindran In Journal of Artificial Intelligence Research (JAIR), 2021

• RAIL: Risk-Averse Imitation Learning

[Paper]

A. Santara*, Abhishek Naik*, B. Ravindran, D. Das, D. Mudigere, S. Avancha, B. Kaul In International Conference on Autonomous Agents and MultiAgent Systems (AAMAS), 2018

MASTER'S THESIS

Deep Reinforcement Learning: Reliability and Multi-Agent Environments

[Thesis, Slides]

My goal was to make self-driving cars a reality in my country, India. Towards this end, I modeled it as a multi-agent learning problem in a safety-critical application and:

- proposed a risk-averse imitation learning algorithm that achieved lower tail-end risk compared to the then state-of-the-art,
- trialled a curriculum-based learning approach for multi-agent learning in RoboSoccer, and
- extended the TORCS racing game to release the first open-source driving simulator that supports multi-agent training – MADRaS (has 100+ stars on Github).

WORK EXPERIENCE

- Research Intern, Huawei Research
 Edmonton, Canada

 Began investigating the discounted-reward and average-reward formulations for continuing (non-episodic) problems in RL.
- Research Intern, Purdue University, Dept. of Computer Science
 May Jul 2016 Indiana, USA
 Advisor: Bruno Ribeiro
 Analyzed the expected activity-lifespan of social-media users based on their early profile activity.
 Curated and released a rich social-media dataset for public use via a technical paper.

TEACHING EXPERIENCE

- Teaching Assistant, **Reinforcement Learning II** (CMPUT609)

 University of Alberta, Edmonton, Canada

 Instructor: Richard S. Sutton
- Teaching Assistant, **Reinforcement Learning I** (CMPUT397) Sep Dec 2020 University of Alberta, Edmonton, Canada Instructor: Martha White
- Teaching Assistant, **Reinforcement Learning II** (CMPUT609)

 University of Alberta, Edmonton, Canada

 Instructor: Richard S. Sutton
- Content Developer, <u>Coursera Reinforcement Learning Specialization</u> Jan Oct 2019 University of Alberta, Edmonton, Canada Instructors: Adam White, Martha White
- Teaching Assistant, Machine Learning (CS4011)
 Aug Nov 2017

 Indian Institute of Technology Madras, Chennai, India
 Instructors: B. Ravindran, M. Khapra

RELEVANT AWARDS

• Best Poster Award runner-up at AICan 2019 poster competition at NeurIPS	2019
• University of Alberta Graduate Fellowship for excellent academic performance	2019
Star TA Award for outstanding work as a Teaching Assistant	2018

SELECTED TALKS

• Essentials of Reinforcement Learning 3rd Nepal Winter School in AI, Virtual	[<u>Slides</u>] Dec 2021
• Towards Reinforcement Learning in the Continuing Setting Never-Ending Reinforcement Learning (NERL) workshop at ICLR 2021, Virtual	[<u>Slides]</u> May 2021
• Personalized Brain State Targeting via Reinforcement Learning The 3rd Neuromatch Conference, Virtual	[<u>Video</u> , <u>Slides</u>] Oct 2020
• Learning and Planning in Average-Reward MDPs Tea Time Talk, Virtual	[<u>Video</u> , <u>Slides</u>] Aug 2020
• On Intelligence: A Glimpse of the Diversity in Natural Intelligence Amii AI Meetup, Edmonton, Canada	[<u>Video</u> , <u>Slides</u>] June 2020
• Figuring Out How the Mind Works Cognitive Psychology Seminar, Dept. of Psychology, University of Alberta	[<u>Video</u> , <u>Slides</u>] <i>March</i> 2020
• Discounting – Does It Make Sense? Tea Time Talk, RLAI lab and Amii, Edmonton, Canada	[<u>Video</u> , <u>Slides</u>] Aug 2019

COMMUNITY SERVICE

• Co-organizer, ICML 2021 Social on Continuing (Non-episodic) RL Problems	July 2021
• Co-organizer, NeurIPS 2020 Tutorial on Policy Optimization in RL	Dec 2020
• Organizer, Amii Tea Time Talks, Virtual	June - Aug 2020
• Executive Member, Computing Science Graduate Students' Association, UofA	Apr 2019 - Apr 2020
• Volunteer, Centre for Autism Services Alberta, Edmonton	Jan 2019 - Mar 2020
• Mentor, Student Wellness Center, IIT Madras	Aug 2015 - May 2017