Abhishek Naik

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EDUCATION

• **Ph.D., Computing Science** *University of Alberta*, Edmonton, Canada

• Integrated B.Tech.+M.Tech., Computer Science and Engineering

Indian Institute of Technology Madras, Chennai, India

CGPA: 9.49/10, 2013-18

Supervisor: B. Ravindran

SELECTED RESEARCH

(* equal contribution)

CGPA: 4.0/4.0, Sep 2018-March 2024

Supervisor: Richard S. Sutton

• Reward Centering

Abhishek Naik, Yi Wan, Manan Tomar, Richard S. Sutton
In Reinforcement Learning Conference (RLC), 2024

[<u>Paper</u>, <u>Poster</u>]

- Investigating Action-space Generalization in RL for Recommender Systems [Paper, Poster] Abhishek Naik, Bo Chang, Alexandros Karatzoglou, Martin Mladenov, Ed H. Chi, Minmin Chen Oral presentation at the Decision Making for RecSys workshop at WWW, 2023
- Multi-Step Average-Reward Prediction via Differential TD(λ) [Paper, Poster]
 Abhishek Naik, Richard S. Sutton
 Presented at the Conference on Reinforcement Learning and Decision Making (RLDM), 2022
- Average-Reward Learning and Planning with Options
 [Paper, Poster]
 Yi Wan, Abhishek Naik, Richard S. Sutton
 In Advances in Neural Information Processing Systems (NeurIPS), 2021
- Towards Reinforcement Learning in the Continuing Setting. [Paper, Poster]

 Abhishek Naik, Zaheer Abbas, Adam White, Richard S. Sutton

 Presented at the Never-Ending Reinforcement Learning (NERL) workshop at ICLR, 2021
- Learning and Planning in Average-Reward Markov Decision Processes

 Yi Wan*, Abhishek Naik*, Richard S. Sutton

 In International Conference on Machine Learning (ICML), 2021
- Discounted Reinforcement Learning Is Not an Optimization Problem

 Abhishek Naik, Roshan Shariff, Niko Yasui, Hengshuai Yao, Richard S. Sutton

 Presented at The Optimization Foundations of RL workshop at NeurIPS, 2019
- MADRaS: Multi Agent DRiving Simulator [Paper]

 A. Santara, S. Rudra, S.A. Buridi, M. Kaushik, Abhishek Naik, B. Kaul, B. Ravindran
 In Journal of Artificial Intelligence Research (JAIR), 2021
- RAIL: Risk-Averse Imitation Learning

 A. Santara*, Abhishek Naik*, B. Ravindran, D. Das, D. Mudigere, S. Avancha, B. Kaul
 In International Conference on Autonomous Agents and MultiAgent Systems (AAMAS), 2018

WORK EXPERIENCE

- Postdoctoral Fellow, National Research Council (NRC) Canada
 Sep 2024—ongoing
 Ottawa, Canada
 Developing fast and efficient reinforcement-learning algorithms for space-related applications, including for enabling reliable terabit satellite-to-ground optical communication.
- Software, Automation, and Testing Team Member, AlbertaSat
 April 2023–Aug 2024

 Edmonton, Canada
 AlbertaSat is University of Alberta's student group that designs, builds, and operates nano satellites. I wrote software and simulated various operational and safety scenarios of AlbertaSat's upcoming satellite to ensure it could robustly achieve all the mission objectives.
- Research Intern, Huawei Research
 Edmonton, Canada

 Began investigating the discounted-reward and average-reward formulations for continuing (non-episodic) problems in reinforcement learning.
- Research Intern, Purdue University, Dept. of Computer Science
 May–Jul 2016 Indiana, USA
 Analyzed the expected activity-lifespan of social-media users based on their early profile activity.
 Curated and released a rich social-media dataset for public use via a technical paper.
- Software Engg. Intern, **Amazon Development Center** *Chennai, India*Helped build a classifier to determine the start-reading-location of books.

 Now in production, this feature helps Kindle users start reading a book quicker after downloading it without having to flip through pages like acknowledgements or copyright notices.

PH.D. DISSERTATION

Reinforcement Learning for Continuing Problems Using Average Reward [Dissertation, Slides] During my Ph.D., I developed simple and practical algorithms from first principles for long-lived artificial decision-making systems. In particular, I developed algorithms within the reinforcement-learning framework for continuing (non-episodic) problems—in which the agent-environment interaction goes on ad infinitum—with the goal of maximizing the average reward obtained per step. Empirically, the algorithms are easy to implement and use.

MASTER'S THESIS

Deep Reinforcement Learning: Reliability and Multi-Agent Environments [Thesis, Slides]

My goal was to make self-driving cars a reality in my country, India. I modeled this as a safety-critical multi-agent learning problem and:

- proposed a risk-averse imitation learning algorithm that achieved lower tail-end risk compared to the then state-of-the-art,
- trialled a curriculum-based learning approach for multi-agent learning in RoboSoccer, and
- extended the TORCS racing game to release the first open-source driving simulator that supports multi-agent training <u>MADRaS</u> (has 100+ stars on Github).

SELECTED TALKS

Demystifying the Discount Factor	[<u>Slides</u>]
Guest lecture at a graduate course at the University of Alberta	Nov 2024
• An Experimentalist's Venture into RL Theory: Two Success and a Failure	[<u>Video</u> , <u>Slides</u>]
Amii AI Seminar, University of Alberta	Feb 2024
• Unifying Perspectives on Intelligence	[<u>Slides</u>]
Summer School at the Science of Intelligence Institute, Berlin, Germany	Aug 2023
Essentials of Reinforcement Learning	[<u>Slides</u>]
3rd Nepal Winter School in AI, Virtual	Dec 2021
• Towards Reinforcement Learning in the Continuing Setting	[<u>Slides</u>]
Never-Ending Reinforcement Learning (NERL) workshop at ICLR 2021, Virtual	May 2021
Personalized Brain State Targeting via Reinforcement Learning	[<u>Video</u> , <u>Slides</u>]
The 3rd Neuromatch Conference, Virtual	Oct 2020
• Learning and Planning in Average-Reward MDPs	[<u>Video</u> , <u>Slides</u>]
Tea Time Talk, Virtual	Aug 2020
• On Intelligence: A Glimpse of the Diversity in Natural Intelligence	[<u>Video</u> , <u>Slides</u>]
Amii AI Meetup, Edmonton, Canada	June 2020
• Figuring Out How the Mind Works	[<u>Video</u> , <u>Slides</u>]
Cognitive Psychology Seminar, Dept. of Psychology, University of Alberta	March 2020
• Discounting – Does It Make Sense?	[<u>Video</u> , <u>Slides</u>]
Tea Time Talk, RLAI lab and Amii, Edmonton, Canada	Aug 2019

COMMUNITY SERVICE

•	Reviewer, Artific	cial Intelligence, RLC [•]	'25, ICLR '20, AAAI	'21, RL4RL at ICML	'21 and <i>NeurIPS</i> '22
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• Co-organizer , <i>ICML 2021 Social</i> on Continuing (Non-episodic) RL Problems	July 2021
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• Co-organizer, NeurIPS 2020 Tutorial on Policy Optimization in RL Dec 2020

• Organizer, Amii Tea Time Talks

June - Aug 2020

• Executive Member, Computing Science Graduate Students' Association, UofA Apr 2019 - Apr 2020

• **Volunteer**, Centre for Autism Services Alberta, Edmonton Jan 2019 - Mar 2020

• Mentor, Student Wellness Center, IIT Madras Aug 2015 - May 2017

RECENT AWARDS

• Winner, natHACKS 2023 hackathon with Khurram Javed. Using new advances in RL, [Video] we showed we can learn to control on-screen objects via our brains' EEG signals within seconds.

TEACHING EXPERIENCE

- Teaching Assistant, **Reinforcement Learning II** (CMPUT609) *Jan-Apr* 2020, 2021, 2023, 2024 University of Alberta, Edmonton, Canada Instructor: Richard S. Sutton
- Teaching Assistant, **Reinforcement Learning I** (CMPUT397) Sep—Dec 2020 University of Alberta, Edmonton, Canada Instructor: Martha White
- Content Developer, <u>Coursera Reinforcement Learning Specialization</u> Jan–Oct 2019
 University of Alberta, Edmonton, Canada Instructors: Adam White, Martha White
- Teaching Assistant, **Machine Learning** (CS4011) Aug-Nov 2017 Indian Institute of Technology Madras, Chennai, India Instructors: B. Ravindran, M. Khapra