Abhishek Naik

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EDUCATION

• **Ph.D., Computing Science** *University of Alberta*, Edmonton, Canada

• Integrated B.Tech.+M.Tech., Computer Science and Engineering Indian Institute of Technology Madras, Chennai, India

CGPA: 4.0/4.0, 2018-ongoing Supervisor: Richard S. Sutton

CGPA: 9.49/10, *2013-18* Supervisor: <u>B. Ravindran</u>

PAPERS (* equal contribution)

Multi-Step Average-Reward Prediction via Differential TD(λ)
 Abhishek Naik, Richard S. Sutton

[<u>Paper</u>]

To be presented at the Conference on Reinforcement Learning and Decision Making (RLDM), 2022

• Average-Reward Learning and Planning with Options Yi Wan, Abhishek Naik, Richard S. Sutton

[<u>Paper</u>, <u>Poster</u>]

In Advances in Neural Information Processing Systems (NeurIPS), 2021
 Towards Reinforcement Learning in the Continuing Setting.

[Paper, Poster]

Abhishek Naik, Zaheer Abbas, Adam White, Richard S. Sutton Presented at the Never-Ending Reinforcement Learning (NERL) Workshop at ICLR, 2021

• Learning and Planning in Average-Reward Markov Decision Processes Yi Wan*, Abhishek Naik*, Richard S. Sutton

[Paper, Poster]

In International Conference on Machine Learning (ICML), 2021

 Discounted Reinforcement Learning Is Not an Optimization Problem Abhishek Naik, Roshan Shariff, Niko Yasui, Hengshuai Yao, Richard S. Sutton Presented at The Optimization Foundations of RL workshop at NeurIPS, 2019 [Paper, Poster]

• MADRaS: Multi Agent DRiving Simulator

[Paper]

A. Santara, S. Rudra, S.A. Buridi, M. Kaushik, **Abhishek Naik**, B. Kaul, B. Ravindran In Journal of Artificial Intelligence Research (JAIR), 2021

• RAIL: Risk-Averse Imitation Learning

[<u>Paper</u>]

A. Santara*, **Abhishek Naik***, B. Ravindran, D. Das, D. Mudigere, S. Avancha, B. Kaul In International Conference on Autonomous Agents and MultiAgent Systems (AAMAS), 2018

MASTER'S THESIS

Deep Reinforcement Learning: Reliability and Multi-Agent Environments

[Thesis, Slides]

My goal was to make self-driving cars a reality in my country, India. Towards this end, I modeled it as a multi-agent learning problem in a safety-critical application and:

- proposed a risk-averse imitation learning algorithm that achieved lower tail-end risk compared to the then state-of-the-art,
- trialled a curriculum-based learning approach for multi-agent learning in RoboSoccer, and
- extended the TORCS simulator to release the first open-source driving simulator that supports multi-agent training MADRaS (has 100+ stars on <u>Github</u>).

WORK EXPERIENCE

- Research Intern, Huawei Research
 Edmonton, Canada
 Started investigating the discounted and average-reward formulations for continuing (non-episodic) problems in RL.
- Research Intern, **Intel Labs****Bengaluru, India*

 Started work on a risk-averse imitation learning approach that achieved up to 89% improvement over the then state-of-the-art on standard robotic control tasks.

TEACHING EXPERIENCE

- Teaching Assistant, **Reinforcement Learning II** (CMPUT609)

 University of Alberta, Edmonton, Canada

 Instructor: Richard S. Sutton
- Teaching Assistant, **Reinforcement Learning I** (CMPUT397) Sep Dec 2020 University of Alberta, Edmonton, Canada Instructor: Martha White
- Teaching Assistant, **Reinforcement Learning II** (CMPUT609)

 University of Alberta, Edmonton, Canada

 Instructor: Richard S. Sutton
- Content Developer, <u>Coursera Reinforcement Learning Specialization</u>

 University of Alberta, Edmonton, Canada

 Instructors: Adam White, Martha White
- Teaching Assistant, **Machine Learning** (CS4011) Aug Nov 2017 Indian Institute of Technology Madras, Chennai, India Instructors: B. Ravindran, M. Khapra

RELEVANT AWARDS

Best Poster Award runner-up at AICan 2019 poster competition at NeurIPS 2019
 University of Alberta Graduate Fellowship for excellent academic performance 2019
 Star TA Award for outstanding work as a Teaching Assistant 2018

SELECTED TALKS

• Essentials of Reinforcement Learning 3rd Nepal Winter School in AI, Virtual	[<u>Slides]</u> Dec 2021
• Towards Reinforcement Learning in the Continuing Setting Never-Ending Reinforcement Learning (NERL) workshop at ICLR 2021, Virtual	[<u>Slides]</u> May 2021
• Personalized Brain State Targeting via Reinforcement Learning The 3rd Neuromatch Conference, Virtual	[Video, Slides] Oct 2020
• Learning and Planning in Average-Reward MDPs Tea Time Talk, Virtual	[Video, Slides] Aug 2020
• On Intelligence: A Glimpse of the Diversity in Natural Intelligence Amii AI Meetup, Edmonton, Canada	[<u>Video</u> , <u>Slides</u>] June 2020
• Figuring Out How the Mind Works Cognitive Psychology Seminar, Dept. of Psychology, University of Alberta	[<u>Video</u> , <u>Slides</u>] <i>March 2020</i>
• Discounting – Does It Make Sense? Tea Time Talk, RLAI lab and Amii, Edmonton, Canada	[<u>Video</u> , <u>Slides</u>] Aug 2019

COMMUNITY SERVICE

• Co-organizer, ICML 2021 Social on Continuing (Non-episodic) RL Problems	July 2021
• Co-organizer, NeurIPS 2020 Tutorial on Policy Optimization in RL	Dec 2020
• Program Committee Member: AAAI 2021	
• Organizer, Amii Tea Time Talks, Virtual	June - Aug 2020
• Executive Member, Computing Science Graduate Students' Association, UofA	Apr 2019 - Apr 2020
• Volunteer, Centre for Autism Services Alberta, Edmonton	Jan 2019 - Mar 2020
• Mentor, Student Wellness Center, IIT Madras	Aug 2015 - May 2017