

Problem Solving by Search

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Search Frameworks

- **State space search**
 - ◆ Uninformed / Blind search
 - ◆ Informed / Heuristic search
- **Problem reduction search**
- **Game tree search**
- **Advances**
 - ◆ Memory bounded search
 - ◆ Multi-objective search
 - ◆ Learning how to search

State space search

■ Basic Search Problem:

- ◆ Given: $[S, s, O, G]$ where
 - ◆ S is the (implicitly specified) set of states
 - ◆ s is the start state
 - ◆ O is the set of state transition operators
 - ◆ G is the set of goal states
- ◆ To find a sequence of state transitions leading from s to a goal state

8-puzzle problem

- **State description (S)**
 - ◆ Location of each of the eight tiles (and the blank)
- **Start state (s)**
 - ◆ The starting configuration (given)
- **Operators (O)**
 - ◆ Four operators, for moving the blank left, right, up or down
- **Goals (G)**
 - ◆ One or more goal configurations (given)

8-queens problem

Placing 8 queens on a chess board, so that none attacks the other

■ Formulation – I

- ◆ A state is any arrangement of 0 to 8 queens on board
- ◆ Operators add a queen to any square

8-queens problem

■ Formulation – II

- ◆ A state is any arrangement of 0-8 queens with none attacked
- ◆ Operators place a queen in the left-most empty column

8-queens problem

■ Formulation – III

- ◆ A state is any arrangement of 8 queens, one in each column
- ◆ Operators move an attacked queen to another square in the same column

Missionaries and cannibals

- **Three missionaries and three cannibals are on one side of a river, along with a boat that can hold one or two people. Find a way to get everyone to the other side, without ever leaving a group of missionaries outnumbered by cannibals**

Missionaries and cannibals

■ **State:** (#m, #c, 1/0)

- ◆ #m: number of missionaries in the first bank
- ◆ #c: number of cannibals in the first bank
- ◆ The last bit indicates whether the boat is in the first bank.

■ **Start state:** (3, 3, 1) **Goal state:** (0, 0, 0)

■ **Operators:**

Boat carries (1, 0) or (0, 1) or (1, 1)
or (2, 0) or (0, 2)

Outline of a search algorithm

1. Initialize: Set $OPEN = \{s\}$

2. Fail:

If $OPEN = \{ \}$, Terminate with failure

3. Select: Select a state, n , from $OPEN$

4. Terminate:

If $n \in G$, terminate with success

5. Expand:

Generate the successors of n using O and insert them in $OPEN$

6. Loop: Go To Step 2.

Basics of the search algorithm

- OPEN is a queue (FIFO) vs a stack (LIFO)
- Is this algorithm guaranteed to terminate?
- Under what circumstances will it terminate?

Complexity

- **b: branching factor** **d: depth of the goal**
- **Breadth-first search:**
 - ◆ Time: $1 + b + b^2 + b^3 + \dots + b^d = O(b^d)$
 - ◆ Space: $O(b^d)$
- **Depth-first search:**
 - ◆ Time: $O(b^m)$,
where m: depth of state space tree
 - ◆ Space: $O(bm)$

Tradeoff between space and time

■ Iterative deepening

- ◆ Perform DFS repeatedly using increasing depth bounds
- ◆ Works in $O(b^d)$ time and $O(bd)$ space

■ Bi-directional search

- ◆ Possible only if the operators are reversible
- ◆ Works in $O(b^{d/2})$ time and $O(b^{d/2})$ space

Saving the explicit space

1. Initialize: Set $OPEN = \{s\}$, **CLOSED = { }**
2. Fail: If $OPEN = \{ \}$,
 Terminate with failure
3. Select: Select a state, n , from $OPEN$ and
 save n in CLOSED
4. Terminate: If $n \in G$, terminate with success
5. Expand:
 Generate the successors of n using O .
 **For each successor, m , insert m in $OPEN$
 only if $m \notin [OPEN \cup CLOSED]$**
6. Loop: Go To Step 2.

Search and Optimization

- **Given:** $[S, s, O, G]$
- **To find:**
 - **A minimum cost sequence of transitions to a goal state**
 - **A sequence of transitions to the minimum cost goal**
 - **A minimum cost sequence of transitions to a min cost goal**

Uniform Cost Search

This algorithm assumes that all operators have a cost:

1. Initialize: Set $OPEN = \{s\}$,
 $CLOSED = \{\}$ **Set $C(s) = 0$**
2. Fail: If $OPEN = \{\}$, Terminate & fail
3. Select:
 Select the minimum cost state, n ,
 from $OPEN$ and save n in $CLOSED$
4. Terminate:
 If $n \in G$, terminate with success

Uniform Cost Search

5. Expand:

Generate the successors of n using O .

For each successor, m :

If $m \notin [\text{OPEN} \cup \text{CLOSED}]$

Set $C(m) = C(n) + C(n, m)$

and insert m in OPEN

If $m \in [\text{OPEN} \cup \text{CLOSED}]$

Set $C(m) = \min \{C(m), C(n) + C(n, m)\}$

If $C(m)$ has decreased and

$m \in \text{CLOSED}$, move it to OPEN

Searching with costs

- If all operator costs are positive, then the algorithm finds the minimum cost sequence of transitions to a goal.
 - ◆ No state comes back to OPEN from CLOSED
- If operators have unit cost, then this is same as BFS
- What happens if negative operator costs are allowed?

Branch-and-bound

1. Initialize: Set $OPEN = \{s\}$, $CLOSED = \{ \}$.
Set $C(s) = 0$, $C^* = \infty$
2. Terminate: If $OPEN = \{ \}$, then return C^*
3. Select: Select a state, n , from $OPEN$
and save in $CLOSED$
4. Terminate: If $n \in G$ and $C(n) < C^*$, then
Set $C^* = C(n)$ and Go To Step 2.

Branch-and-bound

5. Expand:

If $C(n) < C^*$ generate the successors of n

For each successor, m :

If $m \notin [\text{OPEN} \cup \text{CLOSED}]$

Set $C(m) = C(n) + C(n,m)$ and insert m in OPEN

If $m \in [\text{OPEN} \cup \text{CLOSED}]$

Set $C(m) = \min \{C(m), C(n) + C(n,m)\}$

**If $C(m)$ has decreased and $m \in \text{CLOSED}$,
move it to OPEN**

6. Loop: Go To Step 2.