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EE5609 Assignment 10

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Abstract—This document solves problem based on solution of vector space.

Download all solutions from

https://github.com/abhishekt711/EE5609/tree/master/Assignment_10

1 Problem

Consider the vectors in \mathbb{R}^4 defined by:

$$\alpha_1 = \begin{pmatrix} -1\\0\\1\\2 \end{pmatrix}, \ \alpha_2 = \begin{pmatrix} 3\\4\\-2\\5 \end{pmatrix} \text{ and } \alpha_3 = \begin{pmatrix} 1\\4\\0\\9 \end{pmatrix}.$$

Find a system of homogeneous linear equations for which the space of solutions is exactly the subspace of \mathbb{R}^4 spanned by the given three vectors.

2 Solution

A system of linear equations is homogeneous if all of the constant terms are zero. It can be represented as,

$$\mathbf{AX} = 0 \tag{2.0.1}$$

Let **R** be a echelon matrix which is reduced to A. Then the systems $\mathbf{AX} = 0$ and $\mathbf{RX} = 0$ have the same solutions. Here,

$$\mathbf{A} = \begin{pmatrix} -1 & 3 & 1\\ 0 & 4 & 4\\ 1 & -2 & 0\\ 2 & 5 & 9 \end{pmatrix} \tag{2.0.2}$$

By operating column operation on A, we get:

$$\begin{pmatrix} -1 & 3 & 1 \\ 0 & 4 & 4 \\ 1 & -2 & 0 \\ 2 & 5 & 9 \end{pmatrix} \xrightarrow{C_3 = C_3 - 2C_1 - C_2} \begin{pmatrix} -1 & 3 & 0 \\ 0 & 4 & 0 \\ 1 & -2 & 0 \\ 2 & 5 & 0 \end{pmatrix} (2.0.3)$$

$$\stackrel{C_1 = -C_1}{\longleftrightarrow} \begin{pmatrix} 1 & 3 & 0 \\ 0 & 4 & 0 \\ -1 & -2 & 0 \\ -2 & 5 & 0 \end{pmatrix} (2.0.4)$$

$$\stackrel{C_2=C_2-3C_1}{\longleftrightarrow} \begin{pmatrix}
1 & 0 & 0 \\
0 & 4 & 0 \\
-1 & 1 & 0 \\
-2 & 11 & 0
\end{pmatrix} (2.0.5)$$

$$\stackrel{C_2 = \frac{1}{4}C_2}{\longleftrightarrow} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & \frac{1}{4} & 0 \\ -2 & \frac{11}{4} & 0 \end{pmatrix} (2.0.6)$$

The bais vector is non zero vector which are given from 2.0.6,

$$\rho_{1} = \begin{pmatrix} 1 \\ 0 \\ -1 \\ -2 \end{pmatrix}, \rho_{2} = \begin{pmatrix} 0 \\ 1 \\ \frac{1}{4} \\ \frac{11}{4} \end{pmatrix}$$
 (2.0.7)

Vector V formed using the above basis vectors are given as,

$$c_1 \rho_1 + c_2 \rho_2 = \begin{pmatrix} c_1 \\ c_2 \\ -c_1 + \frac{1}{4}c_2 \\ -2c_2 + \frac{11}{4} \end{pmatrix}$$
 (2.0.8)

If **X** is in **V**, so it can be written in this form.

$$\implies \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ -1 & \frac{1}{4} \\ -2 & \frac{11}{4} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \mathbf{X}$$
 (2.0.9)

The augmented matrix using 2.0.9 can be written as,

$$\begin{pmatrix}
1 & 0 & x_1 \\
0 & 1 & x_2 \\
-1 & \frac{1}{4} & x_3 \\
-2 & \frac{11}{4} & x_4
\end{pmatrix}$$
(2.0.10)

Converting the above augmented matrix into row reduced echelon form:

$$\begin{pmatrix}
1 & 0 & x_1 \\
0 & 1 & x_2 \\
-1 & \frac{1}{4} & x_3 \\
-2 & \frac{11}{4} & x_4
\end{pmatrix}
\xrightarrow{R_3 = R_3 + R_1 - \frac{1}{4}R_2, R_4 = R_4 + 2R_1 - \frac{11}{4}R_2}$$

$$\begin{pmatrix}
1 & 0 & x_1 \\
0 & 1 & x_2 \\
0 & 0 & x_1 - \frac{1}{4}x_2 + x_3 \\
0 & 0 & 2x_1 - \frac{11}{4}x_2 + x_4
\end{pmatrix} (2.0.11)$$

From 2.0.11, the basis vector for the solution space is $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$.