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EE5609 Assignment 9

Abhishek Thakur

Abstract—This document solves problem based on solution of vector space.

Download all solutions from

https://github.com/abhishekt711/EE5609/tree/ master/Assignment 9

1 Problem

let $\alpha = (x_1, x_2)$ and $\beta = (y_1, y_2)$ be vectors in \mathbb{R}^2 such that

$$x_1y_1 + x_2y_2 = 0;$$
 $x_1^2 + x_2^2 = y_1^2 + y_2^2 = 1.$

Proove that $\beta = \{\alpha, \beta\}$ is a basis of \mathbb{R}^2 . Find the coordinates of the vector (a, b) in the ordered basis $\beta = \{\alpha, \beta\}$. (The conditions on α and β say, geometrically, that α and β are perpendicular and each has length 1).

2 Solution

we need to show that α and β are independent in order to proove that $\beta = \{\alpha, \beta\}$ is a basis of \mathbb{R}^2

$$x_1 y_1 + x_2 y_2 = 0 (2.0.1)$$

$$x_1^2 + x_2^2 = y_1^2 + y_2^2 = 1$$
 (2.0.2)

2.0.2 show that α and β are non zero vector. Let suppose,

$$\beta = c\alpha \tag{2.0.3}$$

$$\implies y_1 = cx_1; \quad y_2 = cx_2$$
 (2.0.4)

$$\implies x_1 y_1 + x_2 y_2 = 0 \tag{2.0.5}$$

$$\implies x_1y_1 + x_2y_2 = cx_1^2 + cx_2^2 = c(x_1^2 + x_2^2) = c$$
(2.0.6)

The given equation 2.0.5 and 2.0.6 contradicts the equation 2.0.3 for any non-zero value of c. Equation 2.0.5 and 2.0.6 satisfy only when c = 0. Thus, α and β are independent.

Hence, $\beta = \{\alpha, \beta\}$ is a basis of \mathbb{R}^2 .

To, find the coordinates of the vector (a, b) in the

ordered basis $\beta = \{\alpha, \beta\}$. We can row-reduce the augmented matrix

$$\begin{pmatrix} x_1 & y_1 & a \\ x_2 & y_2 & b \end{pmatrix} \qquad (2.0.7)$$

$$\stackrel{R_1 = \frac{R_1}{x_1}}{\longleftrightarrow} \begin{pmatrix} 1 & \frac{y_1}{x_1} & \frac{a}{x_1} \\ x_2 & y_2 & b \end{pmatrix} \qquad (2.0.8)$$

$$\stackrel{R_2 = R_2 - x_2 R_1}{\longleftrightarrow} \begin{pmatrix} 1 & \frac{y_1}{x_1} \\ 0 & y_2 - \frac{x_2 y_1}{x_1} \end{pmatrix} \qquad b - \frac{a}{x_1} \tag{2.0.9}$$

$$= \begin{pmatrix} 1 & \frac{y_1}{x_1} \\ 0 & \frac{x_1 y_2 - x_2 y_1}{x_1} \end{pmatrix} \begin{pmatrix} \frac{a}{x_1} \\ \frac{x_1 b - x_2 a}{x_1} \end{pmatrix}$$
(2.0.10)

$$\stackrel{R_2 = \left(\frac{x_1}{x_1 y_2 - x_2 y_1}\right) R_2}{\longleftrightarrow} \begin{pmatrix} 1 & \frac{y_1}{x_1} & \frac{a}{x_1} \\ 0 & 1 & \frac{x_1 b - x_2 a}{x_1 y_2 - x_2 y_1} \end{pmatrix}$$
(2.0.11)

$$\stackrel{R_1=R_1-\left(\frac{y_1}{x_1}\right)R_2}{\longleftrightarrow} \begin{pmatrix} 1 & 0 & \frac{ay_2-by_1}{x_1y_2-x_2y_1} \\ 0 & 1 & \frac{x_1b-x_2a}{x_1y_2-x_2y_1} \end{pmatrix}$$
(2.0.12)

Using 2.0.1 and 2.0.2 and simplifying in 2.0.12,

$$= \begin{pmatrix} 1 & 0 & ax_1 + bx_2 \\ 0 & 1 & ay_1 + by_2 \end{pmatrix}$$
 (2.0.13)

Hence,

$$\implies (a,b) = (ax_1 + bx_2)\alpha + (ay_1 + by_2)\beta$$
(2.0.14)

$$\therefore (a,b) = (ax_1 + bx_2)(x_1, x_2) + (ay_1 + by_2)(y_1, y_2)$$
(2.0.15)