



Gajendra Purohit

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~~One-One linear transformation~~ : Let $T : V \rightarrow V'$ be a linear transformation with $\eta(T) = 0$ then T is called one-one linear transformation.

Onto linear transformation : Let $T : V \rightarrow V'$ be a linear transformation with $\rho(T) = \dim V'$ Then T is called onto linear transformation.

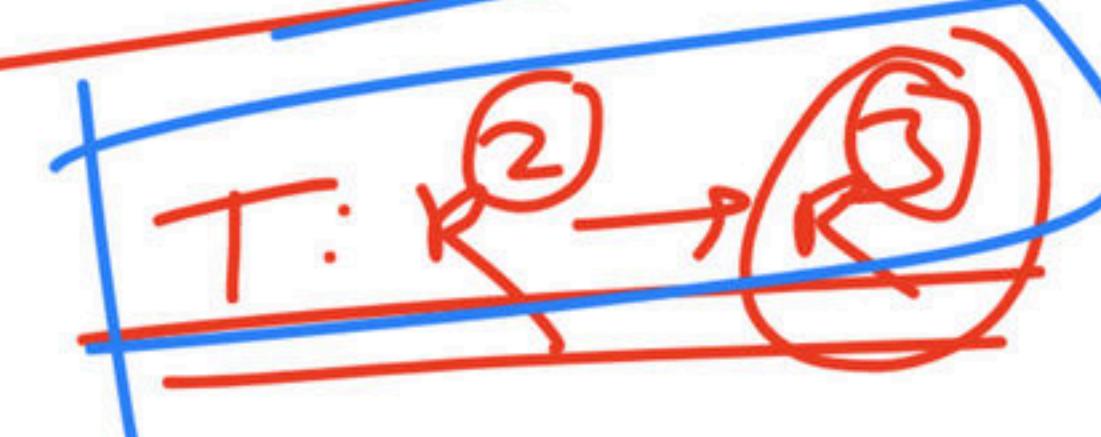
$$\begin{bmatrix} 2 & 1 \\ 3 & 5 \\ 1 & 5 \end{bmatrix}$$

$$\rho(T) \leq 2$$

$$\eta(T) \geq 1$$

$$\rho(T) = 2$$

$$\eta(T) + \rho(T) = \dim V'$$



$$\eta(T) = 0$$
$$\rho(T) = \dim V'$$

$$\begin{bmatrix} 2 & 3 & 1 \\ 5 & 7 & 2 \end{bmatrix}$$

$$2 \times 1$$

~~Singular and non-singular linear transformation :~~

A linear transformation $T : V \rightarrow V'$ is called singular linear

transformation if $\eta(T) \geq 1$ and if $\eta(T) = 0$ then T will be non-singular.

$$T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

A red hand-drawn diagram on a white background. It features several vertical and horizontal lines that form brackets of different sizes. In the center, there is an oval shape outlined in red. Inside this oval, the letters '2x3' are written in a cursive style. The entire drawing is done with a single continuous red line.

Matrix representation : Let $V(F)$ be an n -dimensional vector space and $V'(F)$ be an m -dimensional vector space over F .

Let $\beta_1 = \{x_1, x_2, \dots, x_n\}$ & $\beta_2 = \{y_1, y_2, \dots, y_m\}$ are ordered basis of $V(F)$ & $V'(F)$ respectively and $T : V(F) \rightarrow V'(F)$ be a linear transformation s.t.

$$\underline{T(x_1)} = a_{11}y_1 + a_{21}y_2 + \dots + a_{m1}y_m$$

$$\underline{T(x_2)} = a_{12}y_1 + a_{22}y_2 + \dots + a_{m2}y_m$$

⋮

$$\underline{T(x_n)} = a_{1n}y_1 + a_{2n}y_2 + \dots + a_{mn}y_m$$

Then matrix representation of T relative to the ordered basis $\beta_1 \& \beta_2$ is denoted by

$$[T : \beta_1, \beta_2] = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}_{m \times n}$$

$T : \underline{V(F)} \rightarrow \underline{V'(F)}$

$$T(v_1) = a_{11}y_1 + a_{21}y_2 + \dots + a_{m1}y_m$$

$$T(v_2) = a_{12}y_1 + a_{22}y_2 + \dots + a_{m2}y_m$$

$$T(v_3) = a_{13}y_1 + a_{23}y_2 + \dots + a_{m3}y_m$$

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & a_{m3} \end{bmatrix}_{3 \times 3}$$

$T: \mathbb{R}^3(\mathbb{R}) \rightarrow \mathbb{R}^{3 \times 3}$

$T(x_1, y_1, z_1) = (x_1, y_1, z_1)$

$T(1, 0, 0) = (1, 0, 0)$

$T(0, 0, 0) = (0, 0, 1)$

$T(0, 0, 1) = (0, 1, 0)$

$\text{Im } T \neq 0$

$\begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$

$\text{rank } T = 0$

$\text{det } T = 3$

$$T: K^2(R) \rightarrow R^3(L)$$

$$+ \langle \underline{\gamma_1} \rangle = (\underline{n+\gamma_1}, \underline{n-\gamma_1}, 0)$$

$$T(v_1) = a_{11}\omega_1 + a_{21}\omega_2 + a_{31}\omega_3$$

$$T(v_2) = a_{12}\underline{\omega_1} + a_{22}\omega_2 + a_{32}\omega_3$$

$$\underline{T(1,0)} = a_{12}(1,0,0) + a_{22}(0,1,0) + a_{32}(1,1,0) \quad a_{11} + a_{31} = 1 \quad a_2 + a_{31} = 1$$

$$\langle 2, \underline{a_1, 0} \rangle = (a_{12} + a_{32}, a_{22} + a_{32}, a_{32}) \quad a_{12} = 0 \quad a_{22} = 0$$

$$T = \begin{bmatrix} a_{11} & a_{12} \\ a_2 & a_{22} \\ a_{31} & a_{32} \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 1 & 0 \\ 0 & 0 \end{bmatrix}$$

$$B = \left\langle \underline{(1,0)}, \underline{(1,1)} \right\rangle$$

$$P' = \left\langle \underline{(1,0,0)}, \underline{(0,1,0)}, \underline{(1,1,1)} \right\rangle$$

$$\underline{T(1,0)} = \underline{a_{11}(1,0,0)} + \underline{a_{21}(0,1,0)} + \underline{a_{31}(1,1,0)}$$

$$(1,1,0) = (a_{11} + a_{31}, a_{21} + a_{31}, a_{31})$$

$$a_2 + a_{31} = 1 \\ a_{31} = 0, a_4 = 1 \\ a_{11} = 1$$

$$a_{12} = 2$$

Q.2. Let $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the linear transformation defined by

$T(x, y, z) = (x + y, y + z, z + x)$ for all $(x, y, z) \in \mathbb{R}^3$.

Then

(a) rank $(T) = 0$, nullity $(T) = 3$

(b) rank $(T) = 2$, nullity $(T) = 1$

(c) rank $(T) = 1$, nullity $(T) = 2$

(d) rank $(T) = 3$, nullity $(T) = 0$

$$T(1, 0, 0) = (1, 0, 1)$$
$$T(0, 1, 0) = (1, 1, 0)$$
$$T(0, 0, 1) = (0, 1, 1)$$

$$\left(\begin{array}{ccc} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{array} \right)$$

$$\left(\begin{array}{ccc} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{array} \right)$$

$$\left(\begin{array}{ccc} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{array} \right)$$

$$T: \mathbb{R}^2 \rightarrow \text{Circular Motion}$$

$$\begin{aligned} T(1, 0, 0) &= (1, 1) \\ T(0, 1, 0) &= (0, 0) \\ T(0, 1, 1) &= (-1, 1) \end{aligned}$$

$$T(\gamma_1, \gamma_2, \gamma)$$

$$T^{-1}(r, \varphi)$$

$$(\gamma_1, \gamma_2) = \alpha \underbrace{(1, 0, 0)}_{\text{rotation}} + \beta \underbrace{(0, 1, 0)}_{\text{shear}} + \gamma \underbrace{(0, 1, 1)}_{\text{rotation}} = (\alpha + \beta, \alpha + \gamma, \gamma)$$

$$\begin{aligned} T(\gamma_1, \gamma_2, \gamma) &= \gamma T(1, 0, 0) + \gamma T(0, 1, 0) + \gamma T(0, 1, 1) \\ &= \gamma(1, 1) + \gamma(0, 0) + \gamma(-1, 1) \\ &= (\gamma + 0 - \gamma, \gamma + \gamma + \gamma) \end{aligned}$$

$$T(\gamma_1, \gamma_2, \gamma) = (\gamma - \gamma, \gamma + \gamma)$$

$$(\gamma_1, \gamma_2, \gamma) = T^{-1}(\gamma - \gamma, \gamma + \gamma)$$

$$T^{-1}(r, \varphi) = \left(\frac{r + \varphi}{2}, \frac{r - \varphi}{2}, 0 \right)$$

$$\begin{aligned} \gamma - \gamma &= r \\ \gamma + \gamma &= \varphi \\ \hline 2\gamma &= r + \varphi \\ \gamma &= \frac{r + \varphi}{2} \\ \gamma - \gamma &= \varphi - \varphi \\ \gamma &= 0 \end{aligned}$$

Q.3

Let $T : \mathbb{R}^4 \rightarrow \mathbb{R}^4$ be a linear map defined by
 $T(x, y, z, w) = (x + z, 2x + y + 3z, 2y + 2z, w)$. The rank
of T is equal to

- (a) 1
- (b) 2
- (c) 3
- (d) 4

$$\begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 3 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

Ⓐ $(\xi_1, -1)$

Ⓑ $(-\zeta_1, 1)$

Ⓒ $(1, \zeta)$

Ⓓ $(1, -\zeta)$

$$T(1, 2) = (\zeta_1, 3)$$

$$T(0, 1) = (-\zeta_1, 4)$$

$$\underline{T(\xi_1, \zeta)} = ?$$

$$\underline{(\xi_1, \zeta)} = \alpha(-1, 2) + \beta(0, 1)$$

$$\underline{(\xi_1, \zeta)} = (\alpha, 2\alpha + \beta) \quad \begin{cases} \alpha = \xi \\ 2\alpha + \beta = \zeta \end{cases}$$

$$\Delta = -4$$

$$T(\xi_1, \zeta) = S T(\underline{1, 2}) - 4 T(\underline{0, 1})$$

$$T(\xi_1, \zeta) = S(\underline{2, 3}) - 4(\underline{1, 4})$$

$$= (15-4, 15-11)$$

$$= (\underline{\xi_1, -1})$$

Q.4. Let N be the vector space of all real polynomial of degree atmost 3. Define $S : N \rightarrow N$ by $(S)p(x) = p(\underline{x+1})$, $p \in N$. and the matrix of S in the basis $\{1, x, x^2, x^3\}$ considered as column vector then which of the following is true?

- (a) S is upper triangular matrix with determinant 1.
- (b) S is singular matrix
- (c) S is upper triangular matrix with trace 1.
- (d) S is identity matrix.

$$\begin{matrix} & \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & 3 & 3 \\ 0 & 1 & 3 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \\ \begin{matrix} 1 \\ x \\ x^2 \\ x^3 \end{matrix} & \xrightarrow{\quad S \quad} \end{matrix}$$

$$\begin{aligned} T(x^3) &= (x+1)^3 \\ &= (x+1)(x+1)^2 \\ &\xrightarrow{T(1)=1} \\ T(x^2) &= x+1 \\ T(x^3) &= (x+1)^2 \\ &= (1+2x+x^2) \end{aligned}$$

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Result :

- (1) Let $T : M_2(\mathbb{R}) \rightarrow M_2(\mathbb{R})$ be a linear transformation such that $\underline{T(X) = AX}$, where A is given matrix. If A is diagonalizable then T is also diagonalizable.
- (2) If $T : \mathbb{R}^{m \times n} \rightarrow \mathbb{R}^{n \times p}$ be a linear transformation such that $\underline{T(X) = AX}$ then
- (a) Rank (T) = n.Rank (A)
 - (b) Trace(T) = n.Trace(A)
 - (c) Nullity(T) = n.Nullity(A)

Q.5. Let A be a matrix of order n and let V be the vector space of all real $n \times n$ matrix X such that $AX = 0$. what is dimension of V. **CSIR NET JUNE 2022**

$$\text{P}(A) = r$$

(a) nr

(c) $n^2 - nr$

(b) n^2r

(d) n

$$T: M_{n \times n} \rightarrow M_{n \times n}$$

$$T(X) = AX$$

$$n(T) = ?$$

$$P(T) = n P(A) = \underline{n}$$

$$n(T) + \cancel{P(T)} = n^2$$

$$n(T) = n^2 - \cancel{P(T)}$$

$$= \cancel{n^2} = n$$

Q.6 Let $M_2(\mathbb{R})$ denote the set of 2×2 real matrices. Let $A \in M_2(\mathbb{R})$ be a trace 2 and determinant -3. Identifying $M_2(\mathbb{R})$ with \mathbb{R}^4 , consider the linear transformation $T : M_2(\mathbb{R}) \rightarrow M_2(\mathbb{R})$ defined by $T(B) = AB$. Then which of the following statements are true?

- (a) T is diagonalizable
- (b) 2 is an eigenvalues of T
- (c) T is invertible
- (d) $T(B) = B$ for some $0 \neq B$ is $M_2(\mathbb{R})$

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\lambda_1 + \lambda_2 = 2$$

$$\lambda_1 \lambda_2 = -3$$

$$A = \begin{pmatrix} \lambda_1 & * \\ * & \lambda_2 \end{pmatrix}$$

$$\det(A - \lambda I) = (\lambda_1 + \lambda_2 - \lambda)^2$$

$$= 4 + 1 = 16$$

$$\lambda_1 - \lambda_2 = 4$$

$$\lambda_1 = 1$$

$$P(A) =$$

$$P^{-1} =$$

$$T^{-1} =$$

$$A = \begin{pmatrix} a & c \\ b & d \end{pmatrix}$$

$$B = \begin{pmatrix} c & b \\ d & a \end{pmatrix}$$

Q7 Let $T : \mathbb{R}^4 \rightarrow \mathbb{R}^4$ be the linear map satisfying $T(e_1) = e_2$, $T(e_2) = e_3$, $T(e_3) = 0$, $T(e_4) = e_3$ where $\{e_1, e_2, e_3, e_4\}$ is the standard basis of \mathbb{R}^4 . Then

- (a) T is idempotent
 (c) $\text{Rank}(T) = 3$

- (b) T is invertible
 (d) T is nilpotent

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\mid A = 0$$

$$A^{\sim} =$$

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{aligned} T(1,0,0,0) &= (0,1,0,0) \\ T(0,1,0,0) &= (0,0,1,0) \\ T(0,0,1,0) &= (0,0,0,1) \\ T(0,0,0,1) &= (0,0,1,0) \end{aligned}$$

$$A \not\sim A$$

Q.8

Let $\mathbb{R}^{2 \times 2}$ be the real vector space of all 2×2 real matrices

for $Q = \begin{bmatrix} 1 & -2 \\ -2 & 4 \end{bmatrix}$, define a linear transformation T on

$\mathbb{R}^{2 \times 2}$ as $T(P) = QP$. Then the rank of T is

- (a) 1
- (b) 2
- (c) 3
- (d) 4

$$T(X) = \cancel{AX}$$

=

$$\cancel{P(X)} = \cancel{P(Q)}$$
$$= \underline{\underline{2 \times 1}}$$

450



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Educator highlights

- 📍 Works at Pacific Science College
- 📍 Studied at M.Sc., NET, PhD(Algebra), MBA(Finance), BEd
- 📍 PhD, NET | Plus Educator For CSIR NET | Youtuber (260K+Subs.) | Director Pacific Science College |
- 📍 Lives in Udaipur, Rajasthan, India
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