# **ABHISHEK CHOTHANI**

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### **EDUCATION**

Florida Institute of Technology | Melbourne, Florida, USA

Jan 2023 - Dec 2024

Master of Science in Mechanical Engineering | Specialization in Robotics and Automation Thesis: End-to-End Learning for a Low-Cost Robotics Arm, advised by <u>Dr. Ryan White</u>

**Gujarat Technological University |** Ahmedabad, Gujarat, India

Aug 2017 – May 2021

Bachelor of Engineering in Mechanical Engineering

### RESEARCH EXPERIENCE

Research Assistant | NEural TransmissionS (NETS) Lab | Melbourne, Florida

Jan 2024 – Dec 2024

- Explored **imitation learning** and **reinforcement learning** for custom 6 DOF robotic manipulators using tools like **PyTorch**, **Drake**, **Isaac Sim**, and **Isaac Lab**.
- Explored approaches including **Action Chunking with Transformers (ACT)**, **Diffusion Policies and PPO** achieving a high success rate in dynamic manipulation tasks.
- Conducted comparative analysis of classical robotics vs. Al-driven methods for industrial adaptability. (Master's Thesis Link)

## **WORK EXPERIENCE**

Robotics Project Developer Intern | Kennedy Space Center Visitor Complex | FL | June 2024 – Jan 2024

- Designed and built a functional NASA Perseverance Rover model using **Fusion 360, Raspberry Pi, and STM32.**
- Developed real-time motion control with ROS2, C++, and PID algorithms.
- Integrated IMUs, ultrasonic sensors, and cameras for autonomous operation. (Project Link)

Mechanical Engineer Intern | Jaycon Systems | Melbourne, Florida

Sep 2024 – Dec 2024

- Designed and tested AR device components using Fusion 360 and ANSYS.
- Deployed deep learning-based object detection/tracking on NVIDIA Jetson Orin using YOLO and OpenCV. (Project Link)

Robotics Engineer | BandG Robotics | Ahmedabad, India

Jan 2021 – Dec 2022

- Developed robotic manipulator control using ROS and Python.
- Optimized CNC manufacturing using **SolidWorks** and **Mastercam**.

### SKILLS

- Programming: Python, C/C++, MATLAB, PyTorch, ROS and ROS2, OpenCV, PX4 autopilot
- **Simulation**: Isaac Sim, Drake, Gazebo
- CAD/CAM: Fusion 360, SolidWorks, Ansys, Mastercam

## **PROJECTS**

- Bipedal Training of Spot using IsaacLab & PPO (2025) (Project Link)
- ROS Noetic Tutorials (2024) Step-by-step tutorials for learning ROS Noetic. (Project Link)
- Pan and Tilt Object Tracking (2024) Tracking system using YOLO. (Project Link)
- Gesture-Controlled Drone (2023) Vision-based Drone Control using PX4. (Project Link)
- ARM Cortex-M4 Development (2023) Embedded programming with RTOS. (Project Link)