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LAB REPORT
on

Artificial Intelligence (23CS5PCAIN)

Submitted by

Bhuvan A (1BM24CS403)

in partial fulfillment for the award of the degree of
BACHELOR OF ENGINEERING
in
COMPUTER SCIENCE AND ENGINEERING



B.M.S. COLLEGE OF ENGINEERING
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CERTIFICATE

This is to certify that the Lab work entitled “Artificial Intelligence (23CS5PCAIN)” carried out by **Bhuvan A (1BM24CS403)**, who is bonafide student of **B.M.S. College of Engineering**. It is in partial fulfillment for the award of **Bachelor of Engineering in Computer Science and Engineering** of the Visvesvaraya Technological University, Belgaum. The Lab report has been approved as it satisfies the academic requirements in respect of an Artificial Intelligence (23CS5PCAIN) work prescribed for the said degree.

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Github Link:

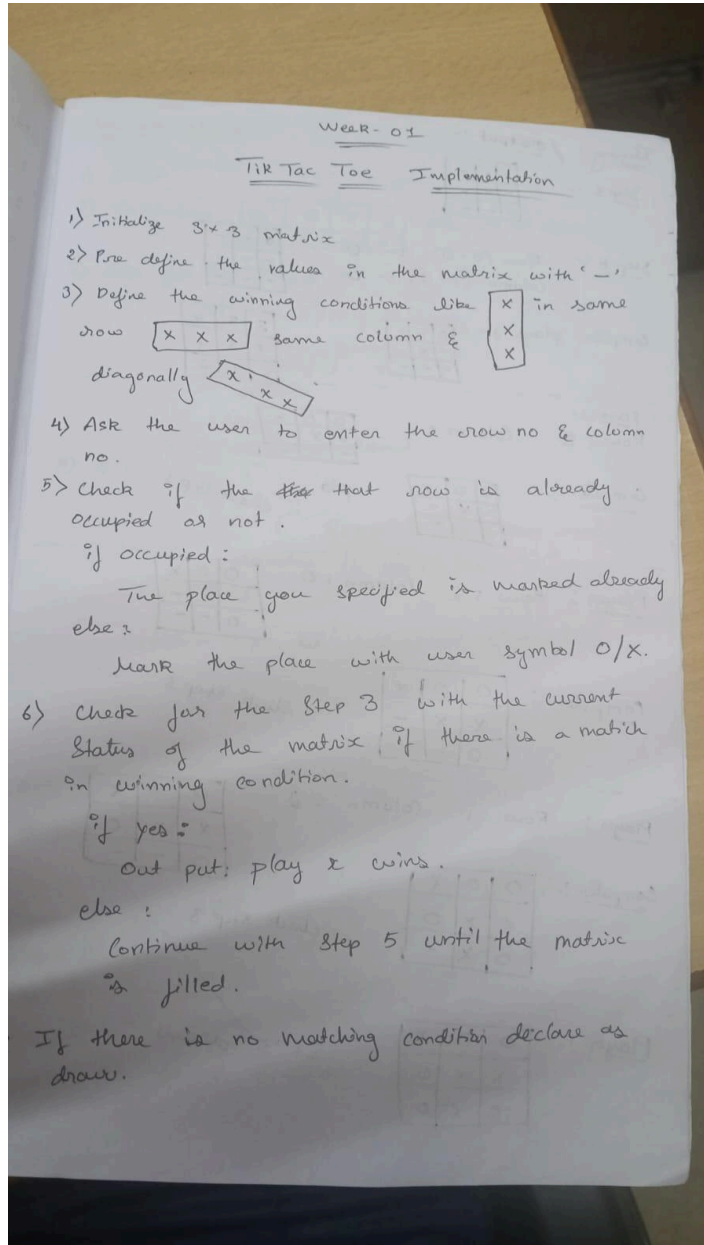
<https://github.com/abhuvan345/AI>

Program 1

Implement Tic - Tac - Toe Game

Implement vacuum cleaner agent

Algorithm:



Tic Tac Toe code:

```

import math

def print_board(board):

    for row in board:

        print(" | ".join(row))

        print("-" * 5)

def check_winner(board, player):

    # Rows, columns, diagonals

    for row in board:

        if all(cell == player for cell in row):

            return True

    for col in range(3):

        if all(board[row][col] == player for row in range(3)):

            return True

    if all(board[i][i] == player for i in range(3)) or \

        all(board[i][2-i] == player for i in range(3)):

        return True

    return False

def is_full(board):

    return all(cell != " " for row in board for cell in row)

def minimax(board, depth, is_maximizing):

    if check_winner(board, "O"): # Computer wins

        return 1

    if check_winner(board, "X"): # Player wins

        return -1

```

```

if is_full(board):

    return 0

if is_maximizing: # Computer's move

    best_score = -math.inf

    for i in range(3):

        for j in range(3):

            if board[i][j] == " ":

                board[i][j] = "O"

                score = minimax(board, depth + 1, False)

                board[i][j] = " "

                best_score = max(score, best_score)

        return best_score

else: # Player's move

    best_score = math.inf

    for i in range(3):

        for j in range(3):

            if board[i][j] == " ":

                board[i][j] = "X"

                score = minimax(board, depth + 1, True)

                board[i][j] = " "

                best_score = min(score, best_score)

        return best_score

def best_move(board):

    best_score = -math.inf

```

```

move = None

for i in range(3):
    for j in range(3):
        if board[i][j] == " ":
            board[i][j] = "O"

            score = minimax(board, 0, False)

            board[i][j] = " "

            if score > best_score:
                best_score = score

            move = (i, j)

    return move

def tic_tac_toe():
    board = [[" " for _ in range(3)] for _ in range(3)]

    print("Welcome to Tic-Tac-Toe! You are 'X' and computer is 'O'.")

    print_board(board)

    while True:
        # Player move

        while True:
            try:
                row = int(input("Enter row (0-2): "))
                col = int(input("Enter col (0-2): "))

                if board[row][col] == " ":
                    board[row][col] = "X"

                    break

```

```

    else:

        print("Cell already taken, try again.")

    except (ValueError, IndexError):

        print("Invalid input! Enter numbers 0-2.")

print_board(board)

if check_winner(board, "X"):

    print("🎉 You win!")

    break

if is_full(board):

    print("It's a draw!")

    break

# Computer move

print("Computer's turn...")

move = best_move(board)

if move:

    board[move[0]][move[1]] = "O"

    print_board(board)

    if check_winner(board, "O"):

        print("💻 Computer wins!")

        break

    if is_full(board):

        print("It's a draw!")

        break

if __name__ == "__main__":

```



```
tic_tac_toe()
```

Vaccum cleaner code:

```
import random
```

```
rooms=[1,1,1,1]
```

```
botpos =(int(input("Enter Initial Position: "))-1)
```

```
cleanedpos=[]
```

```
cost=0
```

```
def movebot(pos):
```

```
    while True:
```

```
        n= random.randint(0,3)
```

```
        if n != pos and n not in cleanedpos:
```

```
            pos = n
```

```
            break
```

```
    return pos
```

```
while True:
```

```
    print(str(rooms))
```

```
    print(botpos+1)
```

```
    if rooms[botpos]==1:
```

```
        rooms[botpos]=0
```

```
        cleanedpos.append(botpos)
```

```
        cost+=1
```

```
        if len(cleanedpos) == 4:
```

```
            break
```

```

botpos=movebot(botpos)

elif rooms[botpos]==0:

    cleanedpos.append(botpos)

    if len(cleanedpos) == 4:

        break

    botpos = movebot(botpos)

print("cost="+str(cost))

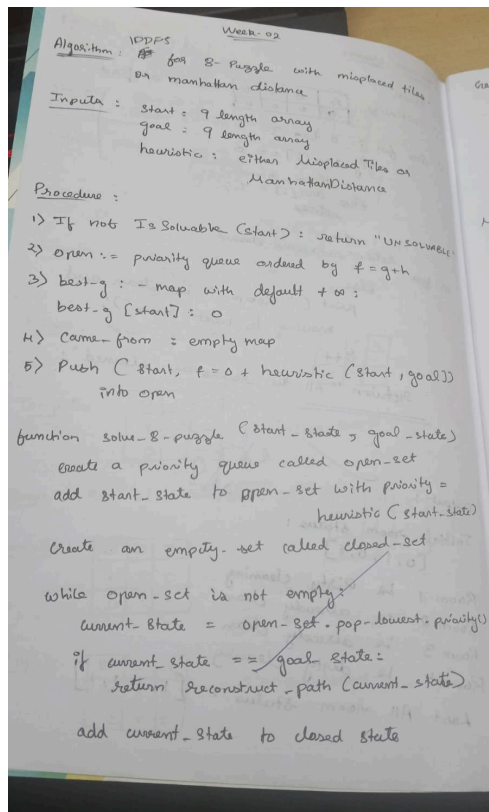
```

Program 2

Implement 8 puzzle problems using Depth First Search (DFS)

Implement Iterative deepening search algorithm

Algorithm:



DFS code:

```
import time
```

```
def find_possible_moves(state):
```

```
    index = state.index('_')
```

```
    moves = {
```

```
        0: [1, 3],
```

```
        1: [0, 2, 4],
```

```
        2: [1, 5],
```

```
        3: [0, 4, 6],
```

```
        4: [1, 3, 5, 7],
```

```
        5: [2, 4, 8],
```

```
        6: [3, 7],
```

```
        7: [6, 8, 4],
```

```
        8: [5, 7],
```

```
    }
```

```
    return moves.get(index, [])
```

```
def dfs(initial_state, goal_state, max_depth=50):
```

```
    stack = [(initial_state, [], 0)]
```

```
    visited = {tuple(initial_state)}
```

```
    states_explored = 0
```

```
    printed_depths = set()
```

```
    while stack:
```

```
        current_state, path, depth = stack.pop()
```

```
        if depth > max_depth:
```

```

        continue

    if depth not in printed_depths:

        print(f"\n--- Depth {depth} ---")

        printed_depths.add(depth)

    states_explored += 1

    print(f"State #{states_explored}: {current_state}")

    if current_state == goal_state:

        print(f"\n Goal reached at depth {depth} after exploring {states_explored} states.\n")

        return path, states_explored

    possible_moves_indices = find_possible_moves(current_state)

    for move_index in reversed(possible_moves_indices): # Reverse for DFS order

        next_state = list(current_state)

        blank_index = next_state.index('_')

        next_state[blank_index], next_state[move_index] = next_state[move_index],
next_state[blank_index]

        if tuple(next_state) not in visited:

            visited.add(tuple(next_state))

            stack.append((next_state, path + [next_state], depth + 1))

    print(f"\n Goal state not reachable within depth {max_depth}. Explored {states_explored} states.\n")

    return None, states_explored

# ----- TEST -----

initial_state = [1, 2, 3,

                4, 8, '_',

                7, 6, 5]

goal_state = [1, 2, 3,

```

4, 5, 6,

7, 8, '_']

Measure execution time

start_time = time.time()

solution_path, explored = dfs(initial_state, goal_state, max_depth=50)

end_time = time.time()

if solution_path is None:

print("No solution found.")

else:

print("Solution path:")

for step, state in enumerate(solution_path, start=1):

print(f"Step {step}: {state}")

print("\nExecution time: {:.6f} seconds".format(end_time - start_time))

print("Total states explored:", explored)

IDDFS code:

import time

----- MOVE GENERATOR -----

def find_possible_moves(state):

index = state.index('_')

if index == 0:

return [1, 3]

elif index == 1:

return [0, 2, 4]

```
elif index == 2:
```

```
    return [1, 5]
```

```
elif index == 3:
```

```
    return [0, 4, 6]
```

```
elif index == 4:
```

```
    return [1, 3, 5, 7]
```

```
elif index == 5:
```

```
    return [2, 4, 8]
```

```
elif index == 6:
```

```
    return [3, 7]
```

```
elif index == 7:
```

```
    return [4, 6, 8]
```

```
elif index == 8:
```

```
    return [5, 7]
```

```
return []
```

```
# ----- DEPTH LIMITED SEARCH -----
```

```
def depth_limited_dfs(state, goal_state, limit, path, visited):
```

```
    if state == goal_state:
```

```
        return path
```

```
    if limit <= 0:
```

```
        return None
```

```
    visited.add(tuple(state))
```

```
    for move_index in find_possible_moves(state):
```

```
        next_state = list(state)
```

```
blank_index = next_state.index('_')
```

```
next_state[blank_index], next_state[move_index] = next_state[move_index], next_state[blank_index]
```

```
if tuple(next_state) not in visited:
```

```
    result = depth_limited_dfs(next_state, goal_state, limit - 1, path + [next_state], visited)
```

```
    if result is not None:
```

```
        return result
```

```
return None
```

```
# ----- ITERATIVE DEEPENING DFS -----
```

```
def iddfs(initial_state, goal_state, max_depth=30):
```

```
    for depth in range(max_depth):
```

```
        print(f"Searching at depth limit = {depth}")
```

```
        visited = set()
```

```
        result = depth_limited_dfs(initial_state, goal_state, depth, [initial_state], visited)
```

```
        if result is not None:
```

```
            return result, depth
```

```
    return None, max_depth
```

```
# ----- TEST -----
```

```
initial_state = [1, 2, 3,
```

```
                4, 8, '_ ',
```

```
                7, 6, 5]
```

```
goal_state    = [1, 2, 3,
```

```
                4, 5, 6,
```

```
                7, 8, '_ ']
```

```
# Measure execution time
```

```

start_time = time.time()

solution_path, depth_reached = iddfs(initial_state, goal_state, max_depth=30)

end_time = time.time()

if solution_path is None:

    print("Goal state is not reachable within given depth limit.")

else:

    print("\n\nSolution path found:")

    for step, state in enumerate(solution_path, start=0):

        print(f'Step {step}: {state}')

    print("\nExecution time: {:.6f} seconds".format(end_time - start_time))

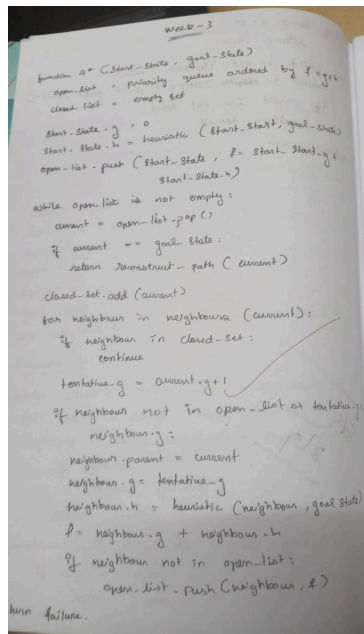
    print("Depth reached:", depth_reached)

```

Program 3

Implement A* search algorithm

Algorithm:



A* code:

```
import heapq

def state_key(state):

    return ",".join(map(str, state))

def is_solvable(state):

    inversions = 0

    arr = [x for x in state if x != 0]

    for i in range(len(arr)):

        for j in range(i+1, len(arr)):

            if arr[i] > arr[j]:

                inversions += 1

    return inversions % 2 == 0

def manhattan(state):

    total = 0

    for index, val in enumerate(state):

        if val == 0:

            continue

        goal_idx = val - 1

        curr_row, curr_col = divmod(index, 3)

        goal_row, goal_col = divmod(goal_idx, 3)

        total += abs(curr_row - goal_row) + abs(curr_col - goal_col)

    return total

def get_neighbours(state):

    neighbours = []
```

```

blank_idx = state.index(0)

row, col = divmod(blank_idx, 3)

moves = []

if row > 0: moves.append(blank_idx - 3)

if row < 2: moves.append(blank_idx + 3)

if col > 0: moves.append(blank_idx - 1)

if col < 2: moves.append(blank_idx + 1)

for m in moves:

    new_state = list(state)

    new_state[blank_idx], new_state[m] = new_state[m], new_state[blank_idx]

    neighbours.append(tuple(new_state))

return neighbours

def reconstruct_path(came_from, current_key):

    path = []

    while current_key in came_from:

        path.append(tuple(map(int, current_key.split(","))))

        current_key = came_from[current_key]

    path.append(tuple(map(int, current_key.split(","))))

    path.reverse()

    return path

def a_star(start_state, goal_state):

    if not is_solvable(start_state):

        return "UNSOLVABLE"

    start_key = state_key(start_state)

```

```

goal_key = state_key(goal_state)

if start_key == goal_key:
    return [start_state]

open_heap = []

g_score = {start_key: 0}

f_score = {start_key: manhattan(start_state)}

came_from = {}

heapq.heappush(open_heap, (f_score[start_key], manhattan(start_state), start_state))

closed = set()

while open_heap:
    f_current, h_current, current_state = heapq.heappop(open_heap)

    current_key = state_key(current_state)

    if f_current > f_score.get(current_key, float("inf")):
        continue

    if current_key == goal_key:
        return reconstruct_path(came_from, current_key)

    closed.add(current_key)

    for neighbour in get_neighbours(current_state):
        neighbour_key = state_key(neighbour)

        tentative_g = g_score[current_key] + 1

        if neighbour_key in closed and tentative_g >= g_score.get(neighbour_key, float("inf")):
            continue

        if tentative_g < g_score.get(neighbour_key, float("inf")):
            came_from[neighbour_key] = current_key

```

```

        g_score[neighbour_key] = tentative_g

        h = manhattan(neighbour)

        f = tentative_g + h

        f_score[neighbour_key] = f

        heapq.heappush(open_heap, (f, h, neighbour))

    return "FAILURE"

if __name__ == "__main__":

    print("Enter start state of the puzzle (9 numbers, 0 for blank space):")

    user_input = input().strip().split()

    if len(user_input) != 9:

        print("Invalid input! Please enter exactly 9 numbers")

        exit()

    try:

        start = tuple(map(int, user_input))

    except ValueError:

        print("Invalid input! Please enter integers only")

        exit()

    goal = (1, 2, 3,

           4, 5, 6,

           7, 8, 0)

    solution = a_star(start, goal)

    if solution == "UNSOLVABLE":

        print("Puzzle cannot be solved!")

    elif solution == "FAILURE":

```

```
print("No solution found")
```

else:

```
print("Solution found in", len(solution) - 1, "moves:")
```

for state in solution:

```
for i in range(0, 9, 3):
```

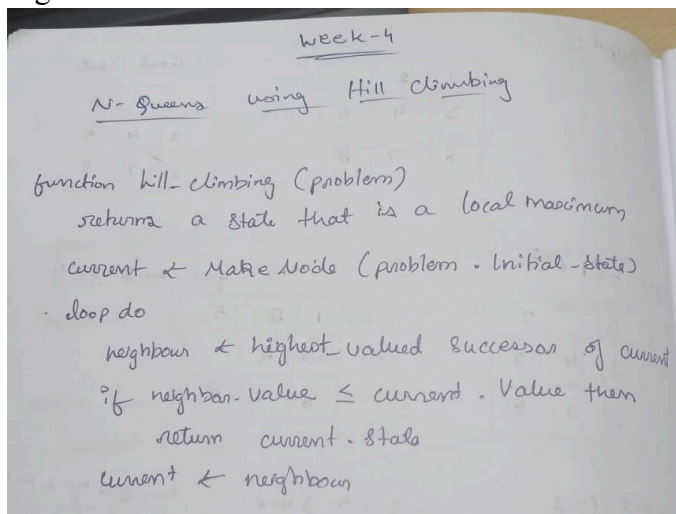
```
    print(state[i:i+3])
```

```
print("-----")
```

Program 4

Implement Hill Climbing search algorithm to solve N-Queens problem

Algorithm:



Hill Climbing code:

```
def print_board(state):
```

```
    """Prints the 4x4 board representation with 'Q' and '!'."""
```

```
    n = len(state)
```

```
    for row in range(n):
```

```
        for col in range(n):
```

```
            if state[col] == row:
```

```

        print("Q", end=" ")

    else:

        print(".", end=" ")

    print()

print()

def calculate_cost(state):

    """Returns number of attacking pairs of queens."""

    cost = 0

    n = len(state)

    for i in range(n):

        for j in range(i + 1, n):

            # same row

            if state[i] == state[j]:

                cost += 1

            # same diagonal

            elif abs(state[i] - state[j]) == abs(i - j):

                cost += 1

    return cost

def get_neighbors(state):

    """Generates all neighbors by swapping two queen positions."""

    neighbors = []

    n = len(state)

    for i in range(n):

        for j in range(i + 1, n):

```

```

        neighbor = state.copy()

        neighbor[i], neighbor[j] = neighbor[j], neighbor[i]

        neighbors.append((neighbor, (i, j)))

    return neighbors

def hill_climbing(state):

    print("\nInitial State:", state)

    print_board(state)

    current_cost = calculate_cost(state)

    step = 1

    while True:

        print(f"Step {step}: Current cost = {current_cost}")

        neighbors = get_neighbors(state)

        neighbor_costs = []

        # Calculate cost for all neighbors

        for neighbor, swapped in neighbors:

            cost = calculate_cost(neighbor)

            neighbor_costs.append((cost, neighbor, swapped))

        # Sort by cost and then by smallest column pair as per rules
        neighbor_costs.sort(key=lambda x: (x[0], x[2][0], x[2][1]))

        # Display neighbor costs

        print("Neighbor states and their costs:")

        for cost, neighbor, swapped in neighbor_costs:

            print(f"Swap x {swapped[0]} & x {swapped[1]} => {neighbor}, Cost = {cost}")

        best_cost, best_state, swap = neighbor_costs[0]

```

```

print("\nBest Neighbor after swap", swap, "is", best_state, "with cost =", best_cost)

print_board(best_state)

if best_cost >= current_cost: # No improvement (local minimum)

    print("No better neighbor found. Hill Climbing terminated.")

    print("Final state:", state)

    print_board(state)

    break

else:

    state = best_state

    current_cost = best_cost

if current_cost == 0:

    print("Goal state reached!")

    print_board(state)

    break

step += 1

# ----- MAIN -----

if __name__ == "__main__":

    print("Hill Climbing for 4-Queens Problem")

    print("Enter the row positions of 4 queens (each between 0 and 3):")

    state = list(map(int, input("Example (1 2 0 3): ").split()))

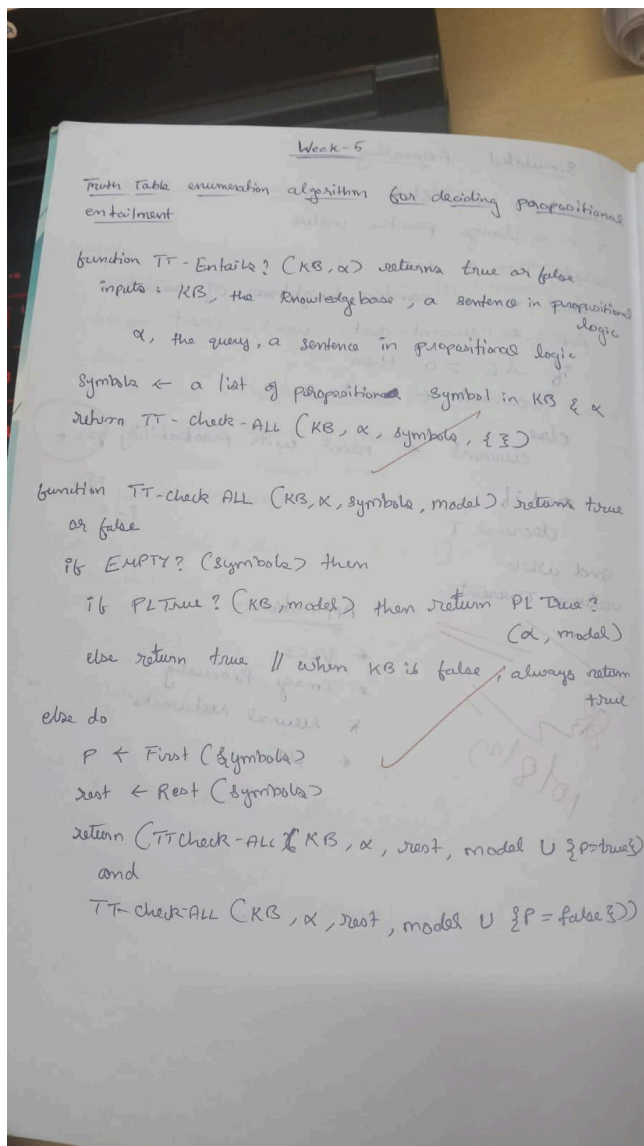
    hill_climbing(state)

```

Program 5

Simulated Annealing to Solve 8-Queens problem

Algorithm:



Simulated annealing code:

```
import random
```

```
import math
```

```
# ----- Helper functions -----
```

```
def random_state(n):
```

```
    """Generate a random state: one queen per column."""
```

```
    return [random.randint(0, n - 1) for _ in range(n)]
```

```
def cost(state):
```

```
"""Compute the number of attacking pairs of queens (lower is better)."""
```

```
n = len(state)
```

```
conflicts = 0
```

```
for i in range(n):
```

```
    for j in range(i + 1, n):
```

```
        if state[i] == state[j] or abs(state[i] - state[j]) == abs(i - j):
```

```
            conflicts += 1
```

```
return conflicts
```

```
def random_neighbour(state):
```

```
    """Generate a neighbour by moving one queen to another row."""
```

```
    n = len(state)
```

```
    neighbour = state.copy()
```

```
    col = random.randint(0, n - 1)    # random column
```

```
    new_row = random.randint(0, n - 1) # new random row
```

```
    neighbour[col] = new_row
```

```
    return neighbour
```

```
# ----- Simulated Annealing -----
```

```
def simulated_annealing(n, initial_temp=1000, cooling_rate=0.95, stop_temp=1e-3, max_iterations=10000):
```

```
    current = random_state(n)
```

```
    current_cost = cost(current)
```

```
    T = initial_temp
```

```
    iteration = 0
```

```
    print("\nInitial state:", current, "Cost:", current_cost)
```

```
    while T > stop_temp and iteration < max_iterations:
```

```

next_state = random_neighbour(current)

next_cost = cost(next_state)

deltaE = current_cost - next_cost

# Acceptance condition

if deltaE > 0:

    accepted = True

else:

    p = math.exp(deltaE / T)

    accepted = random.random() < p

# Print current step info

print(f"\nStep {iteration+1}:")

print(f" Current: {current} (Cost={current_cost})")

print(f" Next: {next_state} (Cost={next_cost})")

print(f"  $\Delta E$  = {deltaE:.3f}, T = {T:.3f}")

print(f" Accepted: {accepted}")

# Accept or reject

if accepted:

    current = next_state

    current_cost = next_cost

# Cooling

T *= cooling_rate

iteration += 1

# Stop if solved

if current_cost == 0:

```

```

        break

    return current, current_cost, iteration

# ----- Main -----

if __name__ == "__main__":

    n = int(input("Enter the number of queens (N): "))

    solution, cost_val, iterations = simulated_annealing(n)

    print("\nFinal state:", solution)

    print("Conflicts:", cost_val)

    print("Iterations:", iterations)

    if cost_val == 0:

        print("\nSolution found:\n")

        for row in range(n):

            print(" ".join("Q" if solution[col] == row else "." for col in range(n)))

    else:

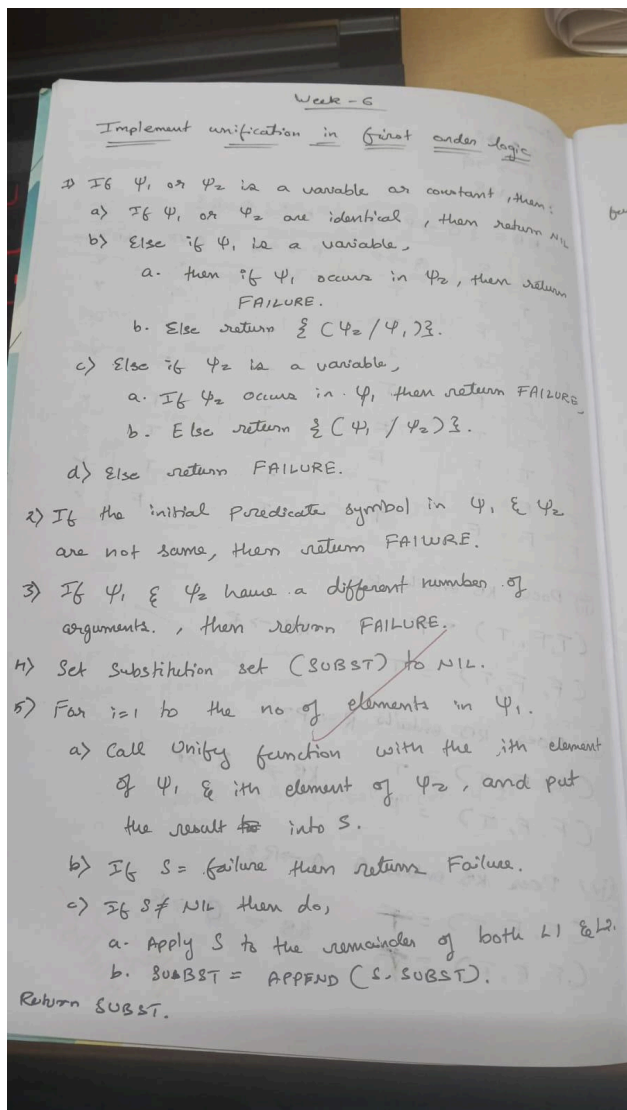
        print("\nNo perfect solution found (try rerunning; SA is stochastic).")

```

Program 6

Create a knowledge base using propositional logic and show that the given query entails the knowledge base or not.

Algorithm:



Propositional logic code:

from itertools import product

Function to safely evaluate logical expressions from user input

def eval_expr(expr, model):

Replace logical symbols for Python syntax

expr = expr.replace('v', 'or').replace('Λ', 'and').replace('¬', 'not ')

return eval(expr, {}, model)

Generate all possible truth assignments (models)

```

def all_models(symbols):

    for values in product([False, True], repeat=len(symbols)):

        yield dict(zip(symbols, values))

# Check entailment:  $KB \models \alpha$ 

def entails(KB_expr, alpha_expr, symbols):

    for model in all_models(symbols):

        kb_val = eval_expr(KB_expr, model)

        alpha_val = eval_expr(alpha_expr, model)

        if kb_val and not alpha_val:

            print(" Counterexample found:", model)

            return False

    return True

# Display truth table

def truth_table(KB_expr, alpha_expr, symbols):

    headers = " ".join(f"{s:^6}" for s in symbols)

    print(f"{headers}   {'KB':^8}   {' $\alpha$ 
```

Input propositional variables

```
symbols = input("Enter propositional symbols (comma separated, e.g., A,B,C): ").replace(" ", "").split(",")
```

Input Knowledge Base (KB) and Query (α)

```
KB_expr = input("Enter Knowledge Base (use and/or/not or  $\wedge/\vee/\neg$ ): ")
```

```
alpha_expr = input("Enter Query  $\alpha$  (use and/or/not or  $\wedge/\vee/\neg$ ): ")
```

Display truth table

```
print("\n--- Truth Table ---")
```

```
truth_table(KB_expr, alpha_expr, symbols)
```

Check entailment

```
result = entails(KB_expr, alpha_expr, symbols)
```

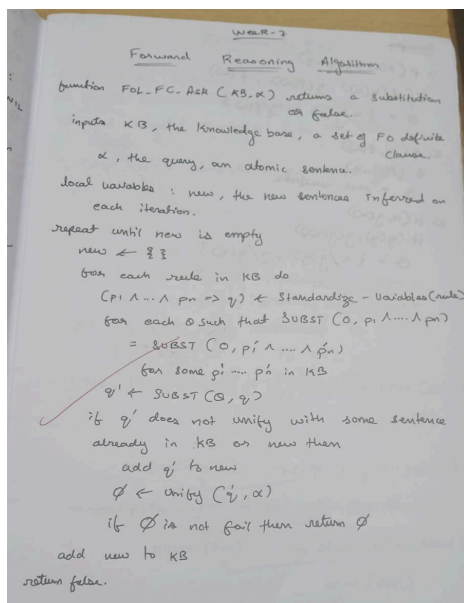
```
print("\nResult:")
```

```
print(" KB entails  $\alpha$ " if result else " KB does NOT entail  $\alpha$ ")
```

Program 7

Implement unification in first order logic

Algorithm:



Unification code:

```
import re

# Utility: parse the expression into function/operator and arguments

def parse(expr):

    expr = expr.strip()

    if '(' not in expr:

        return expr, []

    func = expr[:expr.index('(')].strip()

    args = expr[expr.index('(')+1:-1]

    args = [a.strip() for a in split_args(args)]

    return func, args

# Split arguments correctly (handles nested brackets)

def split_args(args_str):

    args, level, start = [], 0, 0

    for i, ch in enumerate(args_str):

        if ch == ',' and level == 0:

            args.append(args_str[start:i].strip())

            start = i + 1

        elif ch == '(':

            level += 1

        elif ch == ')':

            level -= 1

    args.append(args_str[start:].strip())

    return args
```


Apply substitution to an expression

```
def substitute(expr, subs):
```

```
    for var, val in subs.items():
```

```
        expr = re.sub(rf'\b{var}\b', val, expr)
```

```
    return expr
```

Check if variable occurs inside term (Occurs check)

```
def occurs_check(var, term):
```

```
    if var == term:
```

```
        return True
```

```
    if '(' not in term:
```

```
        return False
```

```
    _, args = parse(term)
```

```
    return any(occurs_check(var, arg) for arg in args)
```

Unification algorithm

```
def unify(e1, e2, subs=None):
```

```
    if subs is None:
```

```
        subs = {}
```

```
    e1 = substitute(e1, subs)
```

```
    e2 = substitute(e2, subs)
```

```
    if e1 == e2:
```

```
        return subs
```

```
    f1, args1 = parse(e1)
```

```
    f2, args2 = parse(e2)
```

Case 1: Both are compound terms

```

if args1 and args2:

    if f1 != f2 or len(args1) != len(args2):

        print(f"✗ Function symbols or arity mismatch: {f1} vs {f2}")

        return None

    for a1, a2 in zip(args1, args2):

        subs = unify(a1, a2, subs)

        if subs is None:

            return None

    return subs

# Case 2: Variable binding

elif e1.islower() and e1.isalpha(): # e1 is variable

    if occurs_check(e1, e2):

        print(f"✗ Occurs check failed: {e1} occurs in {e2}")

        return None

    subs[e1] = e2

    return subs

elif e2.islower() and e2.isalpha(): # e2 is variable

    if occurs_check(e2, e1):

        print(f"✗ Occurs check failed: {e2} occurs in {e1}")

        return None

    subs[e2] = e1

    return subs

# Otherwise mismatch

else:

```

```
print(f"✗ Cannot unify {e1} with {e2}")
```

```
return None
```

```
# --- MAIN PROGRAM ---
```

```
print("=== Unification Algorithm ===")
```

```
expr1 = input("Enter first expression: ").strip()
```

```
expr2 = input("Enter second expression: ").strip()
```

```
result = unify(expr1, expr2)
```

```
if result:
```

```
    print("\n✓ Unification Successful!")
```

```
    print("Substitutions:")
```

```
    for k, v in result.items():
```

```
        print(f" {k} / {v}")
```

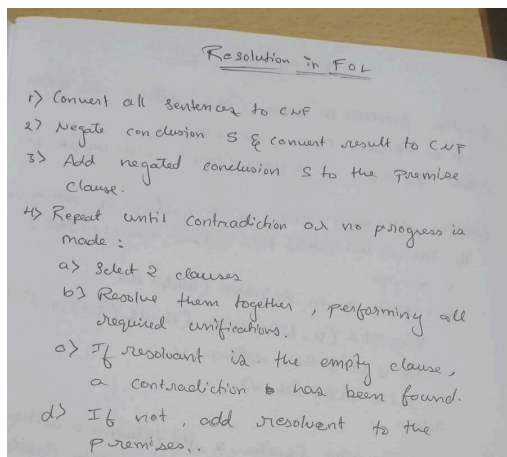
```
else:
```

```
    print("\n✗ Unification Failed.")
```

Program 8

Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.

Algorithm:



Forward reasoning code:

```
import re

def isVariable(x):

    return len(x) == 1 and x.islower() and x.isalpha()

def getAttributes(string):

    expr = r'\([^)]+\)'

    matches = re.findall(expr, string)

    return matches

def getPredicates(string):

    expr = r'([a-z~]+\)(\[^\&]+\)'

    return re.findall(expr, string)

class Fact:

    def __init__(self, expression):

        self.expression = expression

        predicate, params = self.splitExpression(expression)

        self.predicate = predicate

        self.params = params

        self.result = any(self.getConstants())

    def splitExpression(self, expression):

        predicate = getPredicates(expression)[0]

        params = getAttributes(expression)[0].strip('(').split(',')

        return [predicate, params]

    def getResult(self):

        return self.result
```

```

def getConstants(self):
    return [None if isVariable(c) else c for c in self.params]

def getVariables(self):
    return [v if isVariable(v) else None for v in self.params]

def substitute(self, constants):
    constants_copy = constants.copy()

    expr = f'{self.predicate}({','.join([constants_copy.pop(0) if isVariable(p) else p for p in self.params])})'

    return Fact(expr)

class Implication:
    def __init__(self, expression):
        self.expression = expression

        l = expression.split('=>')

        self.lhs = [Fact(f) for f in l[0].split('&')]

        self.rhs = Fact(l[1])

    def evaluate(self, facts):
        constants = {}

        new_lhs = []

        for fact in facts:
            for val in self.lhs:
                if val.predicate == fact.predicate:
                    for i, v in enumerate(val.getVariables()):
                        if v:
                            constants[v] = fact.getConstants()[i]

            new_lhs.append(fact)

```

```

predicate = getPredicates(self.rhs.expression)[0]

attributes = str(getAttributes(self.rhs.expression)[0])

for key in constants:

    if constants[key]:

        attributes = attributes.replace(key, constants[key])

expr = f'{predicate} {attributes}'

return Fact(expr) if len(new_lhs) and all([f.getResult() for f in new_lhs]) else None

```

class KB:

```

def __init__(self):

    self.facts = set()

    self.implications = set()

def tell(self, e):

    if '=>' in e:

        self.implications.add(Implication(e))

    else:

        self.facts.add(Fact(e))

    for i in self.implications:

        res = i.evaluate(self.facts)

        if res:

            self.facts.add(res)

def ask(self, e):

    facts = set([f.expression for f in self.facts])

    print(f'\nQuerying {e}:')

    i = 1

```

```
found = False
```

```
for f in facts:
```

```
    if Fact(f).predicate == Fact(e).predicate:
```

```
        print(f'\t{i}. {f}')
```

```
        i += 1
```

```
    found = True
```

```
if not found:
```

```
    print("\tNo matching facts found.")
```

```
def display(self):
```

```
    print("\nAll facts:")
```

```
    for i, f in enumerate(set([f.expression for f in self.facts])):
```

```
        print(f'\t{i+1}. {f}')
```

```
def main():
```

```
    kb = KB()
```

```
    print("Enter the number of FOL expressions present in KB:")
```

```
    n = int(input())
```

```
    print("Enter the expressions:")
```

```
    for i in range(n):
```

```
        fact = input().strip()
```

```
        kb.tell(fact)
```

```
    print("Enter the query:")
```

```
    query = input().strip()
```

```
    kb.ask(query)
```

```
    kb.display()
```

```
if __name__ == "__main__":  
    main()
```

Program 9

Create a knowledge base consisting of first order logic statements and prove the given query using Resolution

Algorithm:

Resolution code:

```
def parse_clause(clause_str):  
    return set(clause_str.split('v'))  
  
def get_complement(literal):  
    return literal[1:] if literal.startswith('~') else '~' + literal  
  
def resolve(ci, cj):  
    resolvents = set()  
    for literal in ci:  
        complement = get_complement(literal)  
        if complement in cj:  
            new_clause = (ci - {literal}) | (cj - {complement})  
            resolvents.add(frozenset(new_clause))  
    return resolvents  
  
def resolution(kb_clauses, query):  
    negated_query = get_complement(query)  
    kb = [parse_clause(clause) for clause in kb_clauses] + [parse_clause(negated_query)]  
    print("\n-----")  
    print("KnowledgeBase - Resolution")
```



```

print("-----")

print(f"\nKnowledge Base Clauses: {kb_clauses}")

print(f"Query: {query}")

print(f"Negated Query Added: {negated_query}")

print("\nResolution Steps:\n")

new = set()

while True:

    pairs = [(kb[i], kb[j]) for i in range(len(kb)) for j in range(i + 1, len(kb))]

    for (ci, cj) in pairs:

        resolvents = resolve(ci, cj)

        for resolvent in resolvents:

            print(f"Resolving {set(ci)} and {set(cj)} => {set(resolvent)}")

            if not resolvent:

                print("\n Knowledge Base entails the query (empty clause derived).")

                return True

            new.add(resolvent)

    if new.issubset(set(map(frozenset, kb))):

        print("\n Knowledge Base does NOT entail the query (no empty clause derived).")

        return False

    for clause in new:

        if clause not in kb:

            kb.append(clause)

print("KnowledgeBase - Resolution")

print("-----")

```

```
print("Enter clauses for the Knowledge Base.")
```

```
print("Use 'v' for OR between literals (e.g., '~qv~pvr'), and separate each clause with a space.\n")
```

```
kb_input = input("Enter clauses: ").split()
```

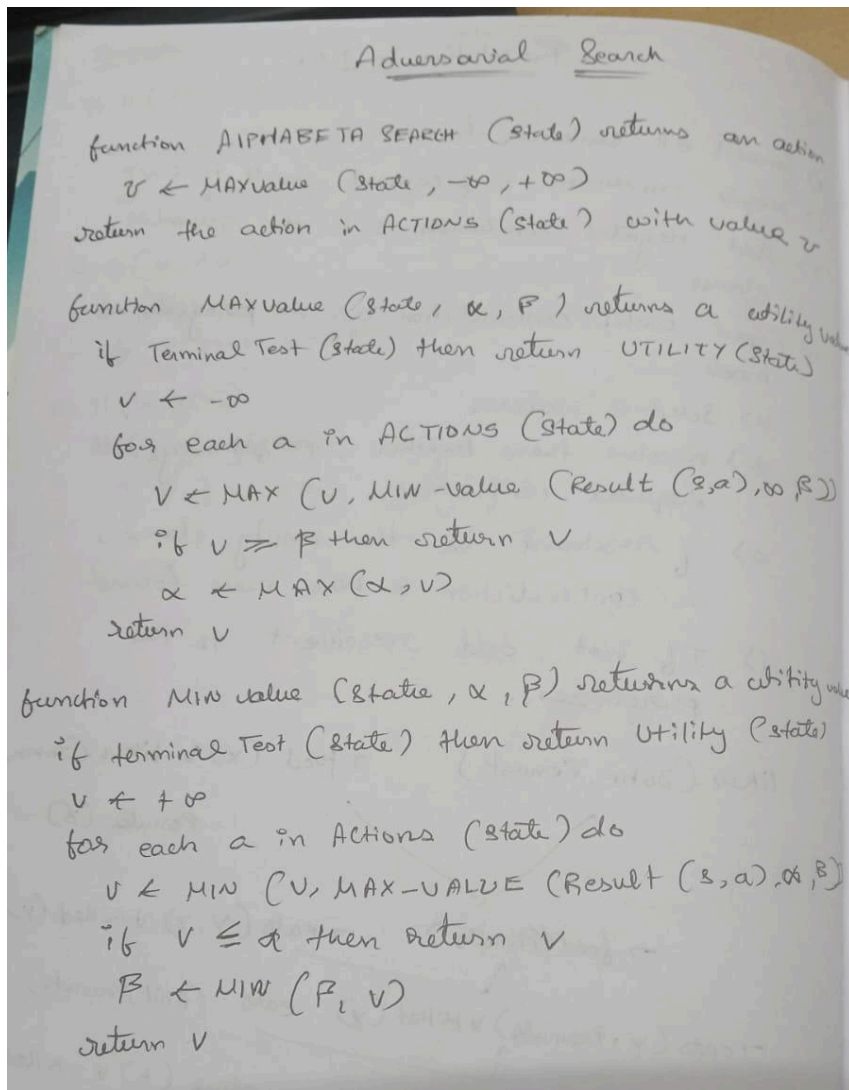
```
query_input = input("Enter the query: ")
```

```
resolution(kb_input, query_input)
```

Program 10

Implement Alpha-Beta Pruning.

Algorithm:



Adversarial Search

function ALPHABETA SEARCH (state) returns an action
 $v \leftarrow \text{MAXVALUE}(\text{state}, -\infty, +\infty)$
 return the action in ACTIONS (state) with value v

function MAXVALUE (state, α , β) returns a utility value
 if Terminal Test (state) then return UTILITY (state)
 $v \leftarrow -\infty$
 for each a in ACTIONS (state) do
 $V \leftarrow \text{MAX}(v, \text{MIN-VALUE}(\text{Result}(s, a), \alpha, \beta))$
 if $v \geq \beta$ then return v
 $\alpha \leftarrow \text{MAX}(\alpha, v)$
 return v

function MINVALUE (state, α , β) returns a utility value
 if Terminal Test (state) then return UTILITY (state)
 $v \leftarrow +\infty$
 for each a in ACTIONS (state) do
 $V \leftarrow \text{MIN}(v, \text{MAX-VALUE}(\text{Result}(s, a), \alpha, \beta))$
 if $v \leq \alpha$ then return v
 $\beta \leftarrow \text{MIN}(\beta, v)$
 return v

Alpha Beta Pruning code:

```
import math

import random

# Use an external "real" board only for the main game loop; recursive functions use state parameters.

board = [" " for _ in range(9)] # 3x3 board

def print_board(state):

    print("\n")

    for i in range(3):

        print(" " + " | ".join(state[i*3:(i+1)*3]))

        if i < 2:

            print("----+---+---")

    print("\n")

def is_winner(state, player):

    win_combinations = [

        [0, 1, 2], [3, 4, 5], [6, 7, 8],

        [0, 3, 6], [1, 4, 7], [2, 5, 8],

        [0, 4, 8], [2, 4, 6]

    ]

    return any(all(state[i] == player for i in combo) for combo in win_combinations)

def is_full(state):

    return " " not in state

def actions(state):

    return [i for i in range(9) if state[i] == " "]

def result(state, action, player):
```

```

    new_state = state.copy()

    new_state[action] = player

    return new_state

def utility(state):

    if is_winner(state, "O"):

        return +1

    elif is_winner(state, "X"):

        return -1

    else:

        return 0

def terminal_test(state):

    return is_winner(state, "X") or is_winner(state, "O") or is_full(state)

# --- Alpha-Beta Functions ---

def max_value(state, alpha, beta):

    if terminal_test(state):

        return utility(state)

    v = -math.inf

    for a in actions(state):

        v = max(v, min_value(result(state, a, "O"), alpha, beta))

        if v >= beta:

            return v

        alpha = max(alpha, v)

    return v

def min_value(state, alpha, beta):

```

```

if terminal_test(state):
    return utility(state)

v = math.inf

for a in actions(state):
    v = min(v, max_value(result(state, a, "X"), alpha, beta))

    if v <= alpha:
        return v

    beta = min(beta, v)

return v

def alpha_beta_search(state):
    best_score = -math.inf

    best_action = None

    if not actions(state):
        return None

    for a in actions(state):
        value = min_value(result(state, a, "O"), -math.inf, math.inf)

        if value > best_score:
            best_score = value

            best_action = a

    # Fallback: if something goes wrong, return a random legal move

    if best_action is None:
        legal = actions(state)

        return random.choice(legal) if legal else None

    return best_action

```

```

# --- Game Loop ---

def human_move():

    while True:

        try:

            move = int(input("Enter your move (1-9): ")) - 1

        except ValueError:

            print("Please enter a number 1-9.")

            continue

        if move < 0 or move > 8:

            print("Move out of range. Choose 1-9.")

            continue

        if board[move] != " ":

            print("Cell already taken. Try another.")

            continue

        return move

def choose_first():

    while True:

        ans = input("Who goes first? (me/ai) [me]: ").strip().lower()

        if ans == "" or ans.startswith("m"):

            return "me"

        if ans.startswith("a"):

            return "ai"

        print("Type 'me' or 'ai' (or press Enter for me).")

def main():

```

```
global board

board = [" " for _ in range(9)]

print("Welcome to Tic-Tac-Toe! You are X, AI is O.")

first = choose_first()

print_board(board)

while True:

    if first == "me":

        # Human turn

        move = human_move()

        board[move] = "X"

        print_board(board)

        if is_winner(board, "X"):

            print("You win!")

            break

        if is_full(board):

            print("It's a draw!")

            break

    # AI turn

    print("AI is thinking...")

    ai_move = alpha_beta_search(board)

    if ai_move is None:

        print("AI could not find a move — it's a draw.")

        break

    board[ai_move] = "O"
```

```
print_board(board)

if is_winner(board, "O"):

    print("AI wins!")

    break

if is_full(board):

    print("It's a draw!")

    break

else: # AI first

    print("AI is thinking...")

    ai_move = alpha_beta_search(board)

    if ai_move is None:

        print("AI could not find a move — it's a draw.")

        break

    board[ai_move] = "O"

    print_board(board)

    if is_winner(board, "O"):

        print("AI wins!")

        break

    if is_full(board):

        print("It's a draw!")

        break

# Human turn

move = human_move()

board[move] = "X"
```



```
    print_board(board)

    if is_winner(board, "X"):

        print("You win!")

        break

    if is_full(board):

        print("It's a draw!")

        break

if __name__ == "__main__":

    main()
```



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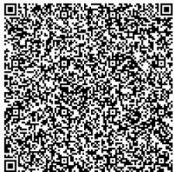
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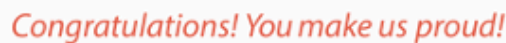
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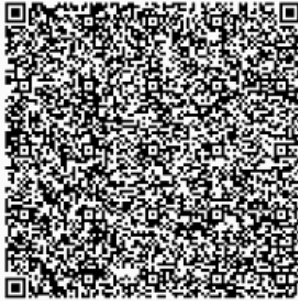
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