

Abhishek Venkataraman

SENIOR ROBOTICS ENGINEER

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Experience

May Mobility

Ann Arbor, Michigan

SENIOR ROBOTICS ENGINEER

Jun 2018 - Present

- Product lead for development and deployment of hardware and software for classification of traffic lights with vehicle camera
- Developed tools for supporting development and operations team. (camera calibrator, infrastructure monitor, mapping tools, etc.)
- Shipped production-ready software for vision-based traffic light classification on fixed infrastructure nodes
- Supported new and existing deployments by providing on-site support for vehicle hardware and software

University of Michigan

Ann Arbor, Michigan

GRADUATE STUDENT RESEARCH ASSOCIATE

May 2017 - Apr 2018

- Kinematically-informed Interactive perception [Link], enables robots to classify objects by building 3D models through observations from a RGBD camera while manipulating the object. Method was validated on Toyota's HSR Robot
- SPARE [Link], extendable articulated object RGBD dataset, using simulation environment Gazebo. Our method could randomize number of links, their lengths and color and be observed from multiples viewpoints over time. Proposed deep learning architecture (Conv3D/Conv+LSTM, FC) to count links and estimate link lengths(Tensorflow)

GRADUATE STUDENT INSTRUCTOR, MATHEMATICS FOR ROBOTICS

Sep 2017 - Dec 2017

- Lectured on topics in linear algebra. Set assignments, term exams and held office hours (88 graduate students)

GRADUATE STUDENT INSTRUCTOR, ADVANCED TOPICS IN COMPUTER VISION

Jan 2017 - Apr 2017

- Covered pictorial structures, graphical models, CNN, GAN, RNN, LSTM, auto-encoders, etc. Created weekly in-class problems, and programming assignments and held office hours (class of 75 graduate students)

Ather Energy Pvt. Ltd.

Bangalore, India

SENIOR ENGINEER, ELECTRONICS INTEGRATION

Jul 2015 - Jul 2016

- Headed a team of 6, responsible for designing electrical (signal and power) interface between all subsystems, waterproof housings for vehicle dashboard and power distribution unit
- Performed system level DFMEA and incorporated hardware changes to accommodate on-board diagnostics

Schlumberger Asia Services Ltd.

Mumbai, India

SENIOR FIELD ENGINEER, WIRELINE

Jul 2012 - May 2015

- Lead Engineer for ONGC offshore wireline operations; carried out over 80 logging jobs as the engineer in charge
- Planned and executed many high profile (\$400K revenue/job) operations in offshore oil rigs, lasting over 150 hours while keeping quality and safety as priority, taking critical decisions while operating with limited connectivity to base
- Worked in culturally diverse teams with varied nationality, heading teams consisting up to 8 crew members

Education

University of Michigan

Ann Arbor, Michigan

MASTER'S IN ROBOTICS (GPA: **3.96** / 4.0)

2016 - 2018

Indian Institute of Technology Madras

Chennai, India

B.TECH IN MECHANICAL ENGINEERING AND M.TECH IN PRODUCT DESIGN

2007 - 2012

Academic Projects

Directed Research, (Prof. Jason Corso)

Sep 2017 - Dec 2017

- Developed a ROS node for object detection using point cloud data from RGBD camera on Fetch Robot
- Implemented voice commands for Fetch Robot on ROS by creating an Amazon Echo skill

Digitization of a Chess game using a moving camera

Sep 2016 - Dec 2016

- Isolated chess board from background by detecting ArUco markers and applying 2D homographic transformations
- Identified moves using template matching, distance based clustering, color clustering and color histograms

Skills

Programming

C/C++, Python, MATLAB, Tensor-flow, OpenCV, ROS, Gazebo, Linux OS, Git, LCM

Courses

Advanced / Foundations Computer Vision, Mobile Robotics (SLAM), Machine Learning, Artificial Intelligence

Hardware

RGB/RGBD Cameras, Lidars, Nvidia Jetson, Arduino, GPS, IMU, Personal Robots (Fetch, HSR)