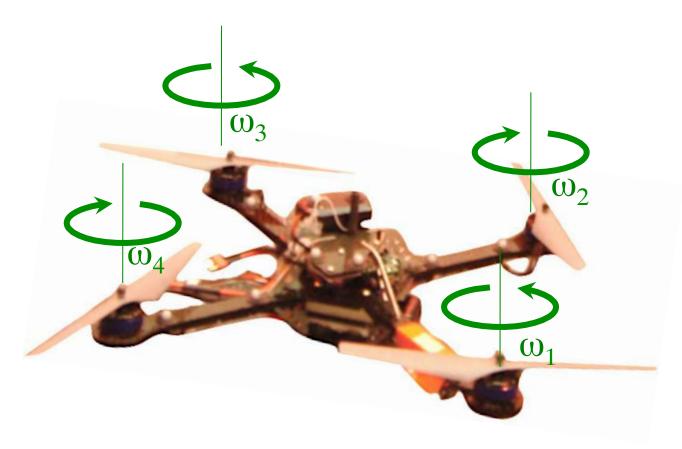


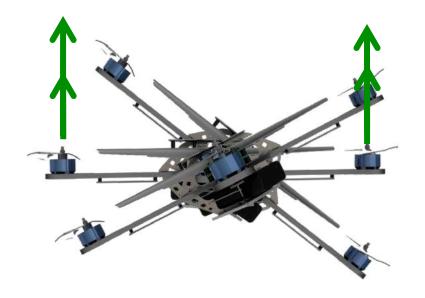
Quadrotor



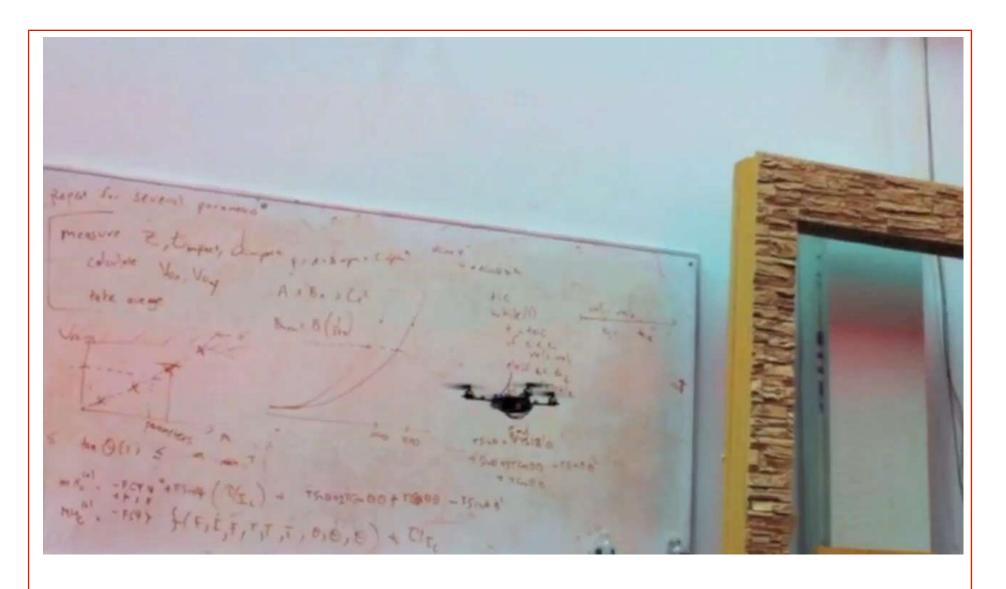
Vary the speeds of the rotors to control the position and orientation of the robot



Roll and Pitch



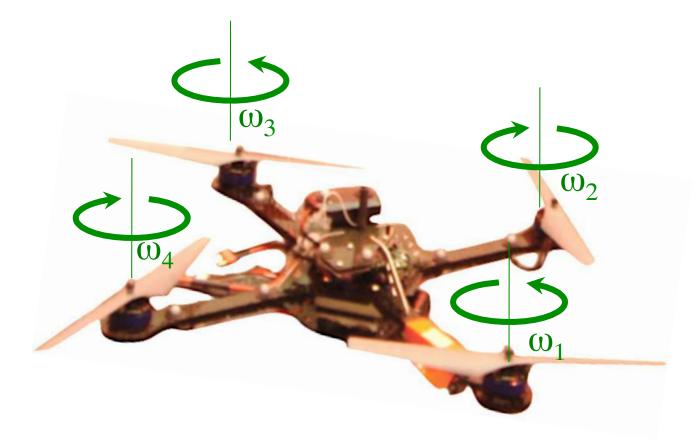




KMel Nano Maximum pitch velocity of 2000 deg/sec



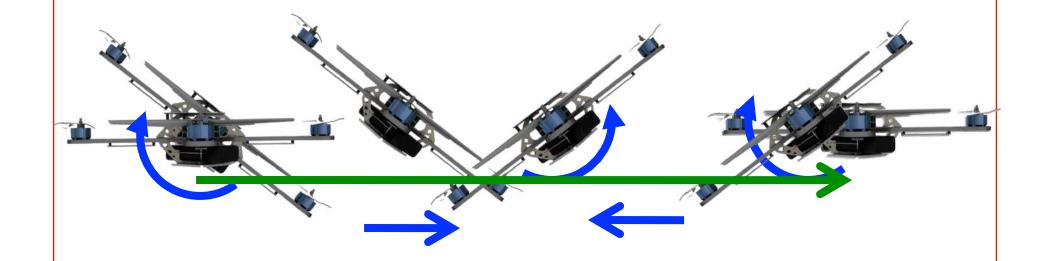
Yaw



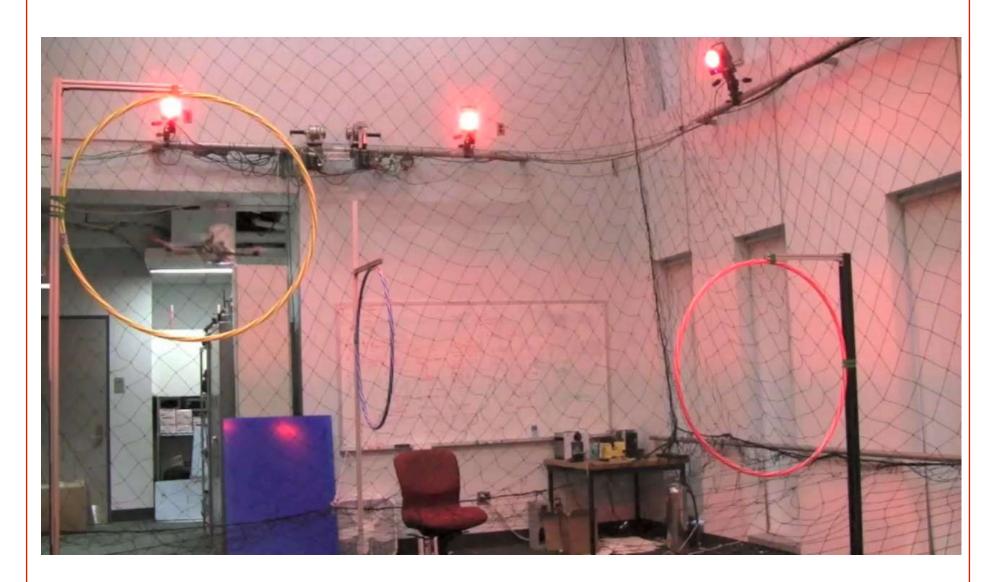
How do you get the robot to yaw (steer)?



Translation









The robot has six degrees of freedom!

How many different ways can you rotate or translate the robot?

