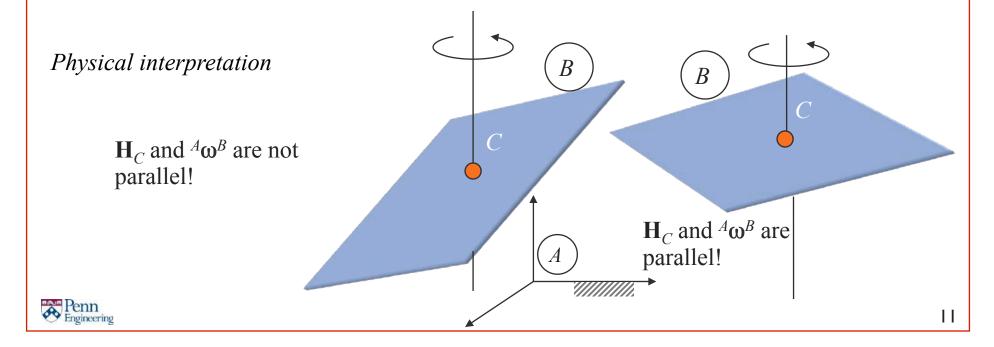
Principal Axes and Principal Moments

Principal axis of inertia

u is a unit vector along a principal axis if **I** . **u** is parallel to **u** There are 3 independent principal axes!

Principal moment of inertia

The moment of inertia with respect to a principal axis, **u** . **I** . **u**, is called a principal moment of inertia.



Euler's Equations

$$\frac{{}^{A}d\mathbf{H}_{C}}{dt} = \mathbf{M}_{C}$$

$$\begin{bmatrix} I_{11} & 0 & 0 \\ 0 & I_{22} & 0 \\ 0 & 0 & I_{33} \end{bmatrix} \begin{bmatrix} \dot{\omega}_1 \\ \dot{\omega}_2 \\ \dot{\omega}_3 \end{bmatrix} + \begin{bmatrix} 0 & -\omega_3 & \omega_2 \\ \omega_3 & 0 & -\omega_1 \\ -\omega_2 & \omega_1 & 0 \end{bmatrix} \begin{bmatrix} I_{11} & 0 & 0 \\ 0 & I_{22} & 0 \\ 0 & 0 & I_{33} \end{bmatrix} \begin{bmatrix} \omega_1 \\ \omega_2^2 \\ \omega_3 \end{bmatrix} = \begin{bmatrix} M_{C,1} \\ M_{C,2} \\ M_{C,3} \end{bmatrix}$$

2

differentiating

Let \mathbf{b}_1 , \mathbf{b}_2 , \mathbf{b}_3 , be along principal axes and

$$^{A}\omega^{B} = \omega_{1} \mathbf{b}_{1} + \omega_{2} \mathbf{b}_{2} + \omega_{3} \mathbf{b}_{3}$$

$$\frac{{}^{B}d\mathbf{H}_{C}}{dt} + {}^{A}\omega^{B} \times \mathbf{H}_{C} = \mathbf{M}_{C} \blacktriangleleft$$

$$\frac{{}^{B}d\mathbf{H}_{C}}{dt} = I_{11}\dot{\boldsymbol{\omega}}_{1}\mathbf{b}_{1} + I_{22}\dot{\boldsymbol{\omega}}_{2}\mathbf{b}_{2} + I_{33}\dot{\boldsymbol{\omega}}_{3}\mathbf{b}_{3}$$

