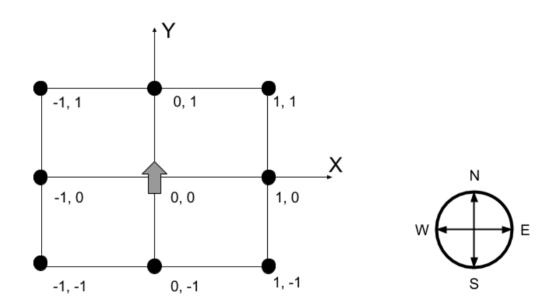
Walking Robot

Diggy is a robot that can walk on a 2D plane (x, y coordinates). It can only perform following operations:

- 1. **R**: Turn 90 degree on right (clockwise).
- 2. L: Turn 90 degree on left (counterclockwise).
- 3. **WN**: Walk forward **N** units in the direction robot is facing. For example, **W2** means robot walks 2 unit point forward

Your need to create a command-line based script in any programming language of your choice. The script accepts a command line argument as an input string of the current position, direction and walking code and print out the result of the last position of the robot.



Input Format

XYDS

X = Current X position

Y = Current Y position

D = Current direction robot is facing (North, East, South or West)

S = Walk string

Output Format

XYD

X = Current X position

Y = Current Y position

D = Current direction robot is facing (North, East, South or West) Your script must take these inputs from command line.

Example

\$ php diggyWalkingRobot.php 5 2 SOUTH RW2LW4R \$ 3 -2 East