Logistic Regression

Nipun Batra

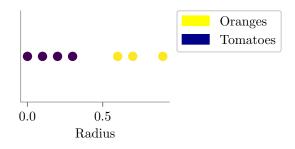
IIT Gandhinagar

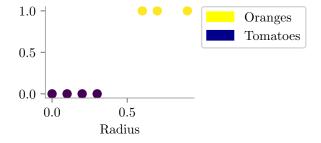
August 30, 2025

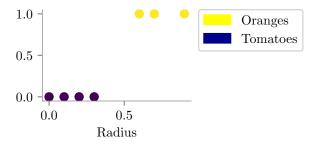
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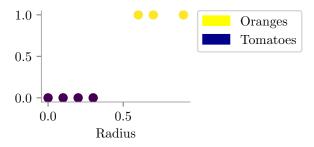
Problem Setup





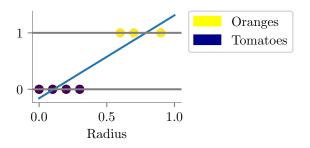


 $\label{eq:Aim: Probability (Tomatoes \mid Radius) ? or } Aim: Probability (Tomatoes \mid Radius) ? or \\$

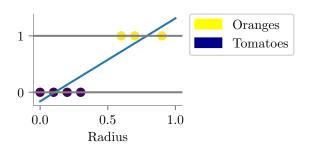


Aim: Probability(Tomatoes | Radius) ? or

More generally,
$$P(y = 1|X = x)$$
?



$$P(X = \textit{Orange} | \textit{Radius}) = \theta_0 + \theta_1 \times \textit{Radius}$$



$$P(X = Orange|Radius) = \theta_0 + \theta_1 \times Radius$$

Generally,

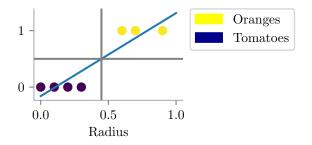
$$P(y=1|\mathbf{x}) = \mathbf{X}\boldsymbol{\theta}$$

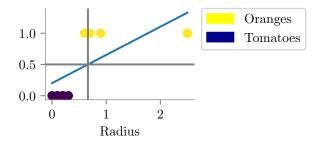
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Prediction: If \theta_0 + \theta_1 \times Radius > 0.5 \rightarrow \text{Orange}
Else \rightarrow \text{Tomato}
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Problem:

Range of $\mathbf{X}\boldsymbol{\theta}$ is $(-\infty,\infty)$

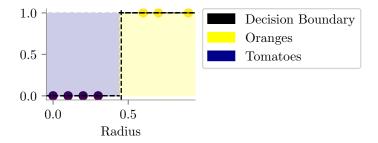
But $P(y=1|\ldots) \in [0,1]$





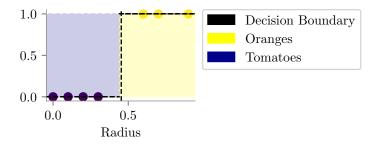
Linear regression for classification gives a poor prediction!

Ideal boundary

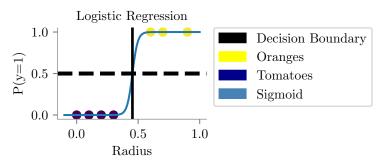


 Have a decision function similar to the above (but not so sharp and discontinuous)

Ideal boundary

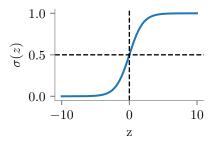


- Have a decision function similar to the above (but not so sharp and discontinuous)
- Aim: use linear regression still!



Question. Can we still use Linear Regression? Answer. Yes! Transform $\hat{y} \rightarrow [0,1]$

$$\begin{split} \hat{y} \in (-\infty, \infty) \\ \phi &= \mathsf{Sigmoid} \ / \ \mathsf{Logistic} \ \mathsf{Function} \ (\sigma) \\ \phi(\hat{y}) \in [0, 1] \\ \sigma(\mathbf{z}) &= \frac{1}{1 + \mathrm{e}^{-\mathbf{z}}} \end{split}$$



$Logistic \ / \ Sigmoid \ Function$



$$z \to \infty$$

 $\sigma(z) \to 1$

$$z \to \infty$$

$$\sigma(z) \to 1$$

$$z \to -\infty$$

$$z \to \infty$$

$$\sigma(z) \to 1$$

$$z \to -\infty$$

$$\sigma(z) \to 0$$

$$z \to \infty$$

$$\sigma(z) \to 1$$

$$z \to -\infty$$

$$\sigma(z) \to 0$$

$$z = 0$$

$$\begin{aligned} z &\to \infty \\ \sigma(z) &\to 1 \\ z &\to -\infty \\ \sigma(z) &\to 0 \\ z &= 0 \\ \sigma(z) &= 0.5 \end{aligned}$$

Question. Could you use some other transformation (ϕ) of \hat{y} s.t.

$$\phi(\hat{\mathbf{y}}) \in [0, 1]$$

Yes! But Logistic Regression works.

$$P(y = 1|\mathbf{X}) = \sigma(\mathbf{X}\boldsymbol{\theta}) = \frac{1}{1 + e^{-\mathbf{X}\boldsymbol{\theta}}}$$

Q. Write $\mathbf{X}\boldsymbol{\theta}$ in a more convenient form (as P(y=1|X), P(y=0|X))

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$$P(y=0|X) = 1 - P(y=1|X) = 1 - \frac{1}{1 + e^{-X\theta}} = \frac{e^{-X\theta}}{1 + e^{-X\theta}}$$

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$$P(y=0|X) = 1 - P(y=1|X) = 1 - \frac{1}{1 + e^{-X\theta}} = \frac{e^{-X\theta}}{1 + e^{-X\theta}}$$

$$\therefore \frac{P(y=1|X)}{1-P(y=1|X)} = e^{\mathbf{X}\boldsymbol{\theta}} \implies \mathbf{X}\boldsymbol{\theta} = \log \frac{P(y=1|X)}{1-P(y=1|X)}$$

Odds (Used in betting)

$$\frac{P(win)}{P(loss)}$$

Here,

$$Odds = \frac{P(y=1)}{P(y=0)}$$

$$log ext{-odds} = log rac{P(y=1)}{P(y=0)} = \mathbf{X}oldsymbol{ heta}$$

Logistic Regression

Q. What is decision boundary for Logistic Regression?

Logistic Regression

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Could we use cost function as:

$$J(\theta) = \sum_{i} (y_i - \hat{y}_i)^2$$
$$\hat{y}_i = \sigma(\mathbf{X}\boldsymbol{\theta})$$

Answer: No (Non-Convex)

Could we use cost function as:

$$J(\theta) = \sum (y_i - \hat{y}_i)^2$$
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Why? Squared loss + sigmoid creates non-convex surface:

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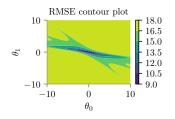
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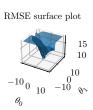
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- No guarantee gradient descent finds global optimum
- This is why we need cross-entropy loss instead!

Deriving Cost Function via Maximum Likelihood Estimation

Cost function convexity





Likelihood =
$$P(D|\theta)$$

 $P(y|X,\theta) = \prod_{i=1}^{n} P(y_i|x_i,\theta)$
where y = 0 or 1

 $\mathsf{Likelihood} = P(D|\theta)$

$$P(y|X,\theta) = \prod_{i=1}^{n} P(y_i|x_i,\theta) = \prod_{i=1}^{n} \left\{ \frac{1}{1 + e^{-x_i^T \theta}} \right\}^{y_i} \left\{ 1 - \frac{1}{1 + e^{-x_i^T \theta}} \right\}^{1 - y_i}$$

[Above: Similar to $P(D|\theta)$ for Linear Regression;

Difference Bernoulli instead of Gaussian]

 $-\log P(y|\mathbf{X}, oldsymbol{ heta}) = \mathsf{Negative\ Log\ Likelihood} = \mathsf{Cost\ function\ will\ be\ minimum}$

 Assume you have a coin and flip it ten times and get (H, H, T, T, T, H, H, T, T, T).

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- Answer 2: What is likelihood of seeing the above sequence when the p(Head)=θ?
- Idea find MLE estimate for θ

•
$$p(H) = \theta$$
 and $p(T) = 1 - \theta$

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- Log-likelihood = $\mathcal{LL}(\theta) = n_h \log(\theta) + n_t \log(1 \theta)$
- $\frac{\partial \mathcal{LL}(\theta)}{\partial \theta} = 0 \implies \frac{n_h}{\theta} + \frac{n_t}{1-\theta} = 0 \implies \theta_{MLE} = \frac{n_h}{n_h + n_t}$

Cross Entropy Cost Function

$$J(\theta) = -\log\left\{\prod_{i=1}^{n} \left\{\frac{1}{1 + e^{-x_i^T \theta}}\right\}^{y_i} \left\{1 - \frac{1}{1 + e^{-x_i^T \theta}}\right\}^{1 - y_i}\right\}$$

$$J(\theta) = -\left\{\sum_{i=1}^{N} y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i))\right\}$$

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This cost function is called cross-entropy.

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This cost function is called cross-entropy. Why?

What is the interpretation of the cost function?

What is the interpretation of the cost function? Let us try to write the cost function for a single example:

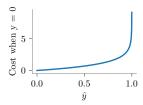
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What is the interpretation of the cost function? Let us try to write the cost function for a single example:

$$J(\theta) = -y_i \log \hat{y}_i - (1 - y_i) \log(1 - \hat{y}_i)$$

First, assume y_i is 0, then if \hat{y}_i is 0, the loss is 0; but, if \hat{y}_i is 1, the loss tends towards infinity!



Notebook: logits-usage

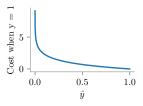
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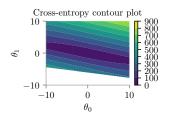
What is the interpretation of the cost function?

$$J(\theta) = -y_i \log \hat{y}_i - (1 - y_i) \log(1 - \hat{y}_i)$$

Now, assume y_i is 1, then if \hat{y}_i is 0, the loss is huge; but, if \hat{y}_i is 1, the loss is zero!



Cost function convexity



Cross-entropy surface plot



$$\begin{split} \frac{\partial J(\theta)}{\partial \theta_j} &= -\frac{\partial}{\partial \theta_j} \bigg\{ \sum_{i=1}^N y_i log(\sigma_{\theta}(x_i)) + (1 - y_i) log(1 - \sigma_{\theta}(x_i)) \bigg\} \\ &= -\sum_{i=1}^N \left[y_i \frac{\partial}{\partial \theta_j} \log(\sigma_{\theta}(x_i)) + (1 - y_i) \frac{\partial}{\partial \theta_j} log(1 - \sigma_{\theta}(x_i)) \right] \end{split}$$

$$\frac{\partial J(\theta)}{\partial \theta_j} = -\sum_{i=1}^{N} \left[y_i \frac{\partial}{\partial \theta_j} \log(\sigma_{\theta}(x_i)) + (1 - y_i) \frac{\partial}{\partial \theta_j} log(1 - \sigma_{\theta}(x_i)) \right]$$
$$= -\sum_{i=1}^{N} \left[\frac{y_i}{\sigma_{\theta}(x_i)} \frac{\partial}{\partial \theta_i} \sigma_{\theta}(x_i) + \frac{1 - y_i}{1 - \sigma_{\theta}(x_i)} \frac{\partial}{\partial \theta_i} (1 - \sigma_{\theta}(x_i)) \right]$$

Aside:

$$\begin{split} \frac{\partial}{\partial z} \sigma(z) &= \frac{\partial}{\partial z} \frac{1}{1 + e^{-z}} = -(1 + e^{-z})^{-2} \frac{\partial}{\partial z} (1 + e^{-z}) \\ &= \frac{e^{-z}}{(1 + e^{-z})^2} = \left(\frac{1}{1 + e^{-z}}\right) \left(\frac{e^{-z}}{1 + e^{-z}}\right) = \sigma(z) \left\{\frac{1 + e^{-z}}{1 + e^{-z}} - \frac{1}{1 + e^{-z}}\right\} \\ &= \sigma(z) (1 - \sigma(z)) \end{split}$$

Resuming from (1)

$$\frac{\partial J(\theta)}{\partial \theta_{j}} = -\sum_{i=1}^{N} \left[\frac{y_{i}}{\sigma_{\theta}(x_{i})} \frac{\partial}{\partial \theta_{j}} \sigma_{\theta}(x_{i}) + \frac{1 - y_{i}}{1 - \sigma_{\theta}(x_{i})} \frac{\partial}{\partial \theta_{j}} (1 - \sigma_{\theta}(x_{i})) \right]
= -\sum_{i=1}^{N} \left[\frac{y_{i}\sigma_{\theta}(x_{i})}{\sigma_{\theta}(x_{i})} (1 - \sigma_{\theta}(x_{i})) \frac{\partial}{\partial \theta_{j}} (x_{i}\theta) + \frac{1 - y_{i}}{1 - \sigma_{\theta}(x_{i})} (1 - \sigma_{\theta}(x_{i})) \frac{\partial}{\partial \theta_{j}} (1 - \sigma_{\theta}(x_{i})) \right]
= -\sum_{i=1}^{N} \left[y_{i} (1 - \sigma_{\theta}(x_{i})) x_{i}^{j} - (1 - y_{i}) \sigma_{\theta}(x_{i}) x_{i}^{j} \right]
= -\sum_{i=1}^{N} \left[(y_{i} - y_{i}\sigma_{\theta}(x_{i}) - \sigma_{\theta}(x_{i}) + y_{i}\sigma_{\theta}(x_{i})) x_{i}^{j} \right]
= \sum_{i=1}^{N} \left[\sigma_{\theta}(x_{i}) - y_{i} \right] x_{i}^{j}$$

Learning Parameters

$$\frac{\partial J(\theta)}{\theta_j} = \sum_{i=1}^{N} \left[\sigma_{\theta}(x_i) - y_i \right] x_i^j$$

Now, just use Gradient Descent!

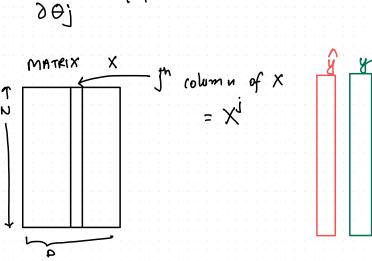
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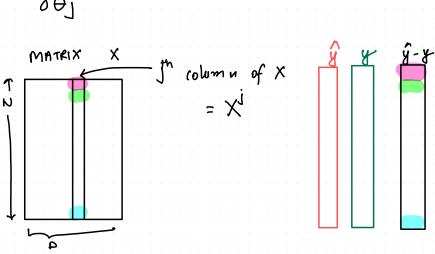
$$\frac{\partial J(\theta)}{\partial \theta j} = \sum_{i=1}^{N} (\hat{y_i} - \hat{y_i}) z_i^j$$
MATRIX X

The columns of X

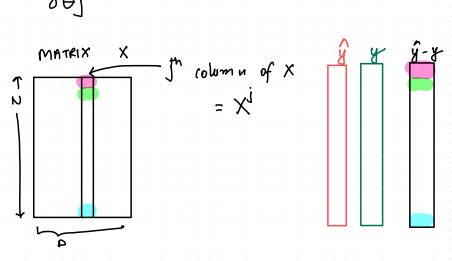


$$\frac{\partial J(\theta)}{\partial \theta_i} = \sum_{i=1}^{N} (\hat{y_i} - \hat{y_i}) z_i^j$$

$$\frac{\partial J(\theta)}{\partial \theta_i} = \sum_{i=1}^{N} (\hat{y_i} - y_i) z_i^j$$



$$\frac{\partial J(\theta)}{\partial x_i} = \sum_{i=1}^{N} (\hat{y_i} - \hat{y_i}) z_i^j = \sum_{i=1}^{N} (\hat{y_i} - \hat{y_i})$$



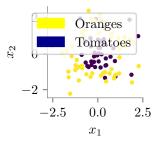
$$\frac{\partial J(\theta)}{\partial \Theta_{j}} = \sum_{i=1}^{N} (\hat{y_{i}} - \hat{y_{i}})^{2_{i}} = x_{1xN}^{T} (\hat{y_{i}} - \hat{y_{j}})$$

$$\begin{bmatrix} \frac{\partial J(\theta)}{\partial \Theta_{i}} \\ \frac{\partial J(\theta)}{\partial \Theta_{i}} \\ \vdots \\ \frac{\partial J(\theta)}{\partial \Theta_{i}} \end{bmatrix} = \begin{bmatrix} x_{1}^{T} (\hat{y_{i}} - \hat{y_{i}}) \\ x_{2}^{T} (\hat{y_{i}} - \hat{y_{i}}) \\ \vdots \\ \frac{\partial J(\theta)}{\partial \Theta_{i}} \end{bmatrix} = \begin{bmatrix} x_{1}^{T} (\hat{y_{i}} - \hat{y_{i}}) \\ \frac{\partial J(\theta)}{\partial \Theta_{i}} \\ \vdots \\ \frac{\partial J(\theta)}{\partial \Theta_{i}} \end{bmatrix}$$

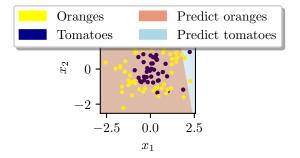
$$\frac{\partial J(\theta)}{\partial \Theta_{j}} = \sum_{i=1}^{N} (\hat{y_{i}} - y_{i}) z_{i}^{j} = x_{i}^{j} (\hat{y_{i}} - y_{j})$$

$$\begin{bmatrix}
\frac{\partial J(0)}{\partial B_{1}} \\
\frac{\partial J(0)}{\partial B_{2}} \\
\vdots \\
\frac{\partial J(0)}{\partial B_{D}}
\end{bmatrix} = \begin{bmatrix}
x^{1} (\hat{y} - \hat{y}) \\
x^{2} (\hat{y} - \hat{y})
\end{bmatrix}$$

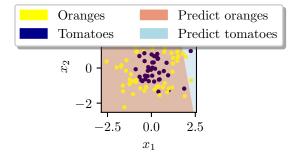
$$= \begin{bmatrix}
x^{1}(\hat{y} - \hat{y}) \\
\vdots \\
x^{D}(\hat{y} - \hat{y})
\end{bmatrix}$$



What happens if you apply logistic regression on the above data?

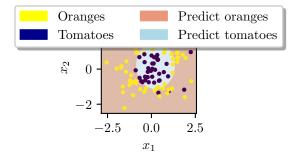


Linear boundary will not be accurate here. What is the technical name of the problem?



Linear boundary will not be accurate here. What is the technical name of the problem? Bias!

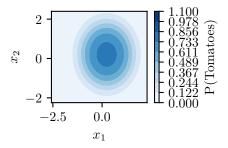
$$\phi(x) = \begin{bmatrix} \phi_0(x) \\ \phi_1(x) \\ \vdots \\ \phi_{K-1}(x) \end{bmatrix} = \begin{bmatrix} 1 \\ x \\ x^2 \\ x^3 \\ \vdots \\ x^{K-1} \end{bmatrix} \in \mathbb{R}^K$$

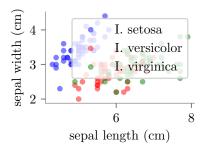


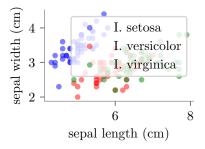
Using x_1^2, x_2^2 as additional features, we are able to learn a more accurate classifier.

How would you expect the probability contours look like?

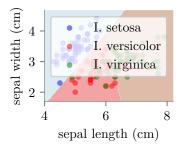
How would you expect the probability contours look like?

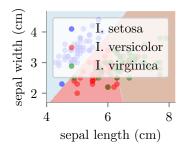




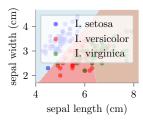


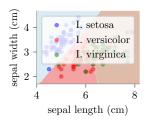
How would you learn a classifier? Or, how would you expect the classifier to learn decision boundaries?



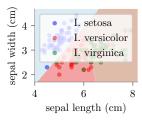


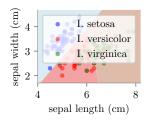
- 1. Use one-vs.-all on Binary Logistic Regression
- 2. Use one-vs.-one on Binary Logistic Regression
- 3. Extend Binary Logistic Regression to Multi-Class Logistic Regression





- 1. Learn P(setosa (class 1)) = $\mathcal{F}(\mathbf{X}\boldsymbol{\theta}_1)$
- 2. P(versicolor (class 2)) = $\mathcal{F}(\mathbf{X}\boldsymbol{\theta}_2)$
- 3. $P(\text{virginica (class 3)}) = \mathcal{F}(\mathbf{X}\boldsymbol{\theta}_3)$
- 4. Goal: Learn $\theta_i \forall i \in \{1, 2, 3\}$
- 5. Question: What could be an \mathcal{F} ?





- 1. Question: What could be an \mathcal{F} ?
- 2. Property: $\sum_{i=1}^{3} \mathcal{F}(\mathbf{X}\boldsymbol{\theta}_i) = 1$
- 3. Also $\mathcal{F}(z) \in [0,1]$
- 4. Also, $\mathcal{F}(\mathbf{z})$ has squashing proprties: $R\mapsto [0,1]$

Softmax

$$Z \in \mathbb{R}^d$$

$$\mathcal{F}(z_i) = \frac{e^{z_i}}{\sum_{i=1}^d e^{z_i}}$$

$$\therefore \sum \mathcal{F}(z_i) = 1$$

 $\mathcal{F}(z_i)$ refers to probability of class \underline{i}

Softmax for Multi-Class Logistic Regression

$$k = \{1, \dots, k\}$$
 classes
$$\theta = \begin{bmatrix} \vdots \vdots \vdots \\ \theta_1 \theta_2 \cdots \theta_k \\ \vdots \vdots \vdots \\ \vdots \vdots \vdots \end{bmatrix}$$

 $P(y = k|X, \theta) = \frac{e^{X\theta_k}}{\sum_{k=1}^{K} e^{X\theta_k}}$

Softmax for Multi-Class Logistic Regression

For K = 2 classes,

$$P(y = k|X, \theta) = \frac{e^{X\theta_k}}{\sum_{k=1}^{K} e^{X\theta_k}}$$

$$P(y = 0|X, \theta) = \frac{e^{X\theta_0}}{e^{X\theta_0} + e^{X\theta_1}}$$

$$P(y = 1|X, \theta) = \frac{e^{X\theta_1}}{e^{X\theta_0} + e^{X\theta_1}} = \frac{e^{X\theta_1}}{e^{X\theta_1}\{1 + e^{X(\theta_0 - \theta_1)}\}}$$

$$= \frac{1}{1 + e^{-X\theta'}}$$

$$= \text{Sigmoid!}$$

Assume our prediction and ground truth for the three classes for i^{th} point is:

$$\hat{y}_i = \begin{bmatrix} 0.1 \\ 0.8 \\ 0.1 \end{bmatrix} = \begin{bmatrix} \hat{y}_i^1 \\ \hat{y}_i^2 \\ \hat{y}_i^3 \end{bmatrix}$$

$$y_i = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} y_i^1 \\ y_i^2 \\ y_i^3 \end{bmatrix}$$

meaning the true class is Class #2

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Assume our prediction and ground truth for the three classes for i^{th} point is:

$$\hat{y}_i = \begin{bmatrix} 0.3 \\ 0.4 \\ 0.3 \end{bmatrix} = \begin{bmatrix} \hat{y}_i^1 \\ \hat{y}_i^2 \\ \hat{y}_i^3 \end{bmatrix}$$

$$y_i = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} y_i^1 \\ y_i^2 \\ y_i^3 \end{bmatrix}$$

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$$y_i = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} y_i^1 \\ y_i^2 \\ 3 \end{bmatrix}$$

meaning the true class is Class #2 Let us calculate $-\sum_{k=1}^3 y_i^k \log \hat{y}_i^k = -(0 \times \log(0.1) + 1 \times \log(0.4) + 0 \times \log(0.1))$ High number! Huge penalty for misclassification!

For 2 class we had:

$$J(\theta) = -\left\{ \sum_{i=1}^{N} y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i)) \right\}$$

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Extend to K-class:

$$J(\theta) = -\left\{ \sum_{i=1}^{N} \sum_{k=1}^{K} y_i^k \log(\hat{y}_i^k) \right\}$$

Now:

$$\frac{\partial J(\theta)}{\partial \theta_k} = \sum_{i=1}^{N} \left[x_i \left\{ I(y_i = k) - P(y_i = k | x_i, \theta) \right\} \right]$$

Hessian Matrix

The Hessian matrix of f(.) with respect to θ , written $\nabla^2_{\theta} f(\theta)$ or simply as \mathbb{H} , is the $d \times d$ matrix of partial derivatives,

$$\nabla_{\theta}^{2} f(\theta) = \begin{bmatrix} \frac{\partial^{2} f(\theta)}{\partial \theta_{1}^{2}} \frac{\partial^{2} f(\theta)}{\partial \theta_{1} \partial \theta_{2}} \cdots \frac{\partial^{2} f(\theta)}{\partial \theta_{1} \partial \theta_{n}} \\ \frac{\partial^{2} f(\theta)}{\partial \theta_{2} \partial \theta_{1}} \frac{\partial^{2} f(\theta)}{\partial \theta_{2}^{2}} \cdots \frac{\partial^{2} f(\theta)}{\partial \theta_{2} \partial \theta_{n}} \\ \vdots & \vdots & \vdots \\ \frac{\partial^{2} f(\theta)}{\partial \theta_{n} \partial \theta_{1}} \frac{\partial^{2} f(\theta)}{\partial \theta_{n} \partial \theta_{2}} \cdots \frac{\partial^{2} f(\theta)}{\partial \theta_{n}^{2}} \end{bmatrix}$$

Newton's Algorithm

The most basic second-order optimization algorithm is Newton's algorithm, which consists of updates of the form,

$$\theta_{k+1} = \theta_k - \mathbb{H}^1_k g_k$$

where g_k is the gradient at step k. This algorithm is derived by making a second-order Taylor series approximation of $f(\theta)$ around θ_k :

$$f_{quad}(\theta) = f(\theta_k) + g_k^T(\theta - \theta_k) + \frac{1}{2}(\theta - \theta_k)^T \mathbb{H}_k(\theta - \theta_k)$$

differentiating and equating to zero to solve for θ_{k+1} .

Learning Parameters

Now assume:

$$g(\theta) = \sum_{i=1}^{N} \left[\sigma_{\theta}(x_i) - y_i \right] x_i^j = \mathbf{X}^{\top} (\sigma_{\theta}(X) - y)$$
$$\pi_i = \sigma_{\theta}(x_i)$$

Let \mathbb{H} represent the Hessian of $J(\theta)$

$$\mathbb{H} = \frac{\partial}{\partial \theta} g(\theta) = \frac{\partial}{\partial \theta} \sum_{i=1}^{N} \left[\sigma_{\theta}(x_i) - y_i \right] x_i^j$$

$$= \sum_{i=1}^{N} \left[\frac{\partial}{\partial \theta} \sigma_{\theta}(x_i) x_i^j - \frac{\partial}{\partial \theta} y_i x_i^j \right] = \sum_{i=1}^{N} \sigma_{\theta}(x_i) (1 - \sigma_{\theta}(x_i)) x_i x_i^T$$

$$= \mathbf{X}^{\top} \operatorname{diag}(\sigma_{\theta}(x_i) (1 - \sigma_{\theta}(x_i))) \mathbf{X}$$

Iteratively reweighted least squares (IRLS)

For binary logistic regression, recall that the gradient and Hessian of the negative log-likelihood are given by:

$$g(\theta)_k = \mathbf{X}^{\top}(\pi_k - y)$$

$$\mathbf{H}_k = \mathbf{X}^{\top} S_k \mathbf{X}$$

$$\mathbf{S}_k = diag(\pi_{1k}(1 - \pi_{1k}), \dots, \pi_{nk}(1 - \pi_{nk}))$$

$$\pi_{ik} = sigm(\mathbf{x}_i \theta_k)$$

The Newton update at iteraion k + 1 for this model is as follows:

$$\theta_{k+1} = \theta_k - \mathbb{H}^{-1} g_k = \theta_k + (X^T S_k X)^{-1} X^T (y - \pi_k)$$
$$= (X^T S_k X)^{-1} [(X^T S_k X) \theta_k + X^T (y - \pi_k)] = (X^T S_k X)^{-1} X^T [S_k X \theta_k + y - \pi_k]$$

Regularized Logistic Regression

Unregularised:

$$J_1(\theta) = -\left\{ \sum_{i=1}^{N} y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i)) \right\}$$

L2 Regularization:

$$J(\theta) = J_1(\theta) + \lambda \theta^T \theta$$

L1 Regularization:

$$J(\theta) = J_1(\theta) + \lambda |\theta|$$

Class Imbalance Handling

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- Naive approach fails: Predicting all samples as majority class

With 99% class 0, 1% class 1:

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- Need: Better evaluation metrics and techniques

Modify the cost function to penalize minority class errors more:

$$J(\boldsymbol{\theta}) = -\sum_{i=1}^{N} w_i \left[y_i \log(\sigma(\boldsymbol{\theta}^{\top} \mathbf{x}_i)) + (1 - y_i) \log(1 - \sigma(\boldsymbol{\theta}^{\top} \mathbf{x}_i)) \right]$$

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- Implementation: Available in most ML libraries (sklearn: class_weight='balanced')

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- **Trade-off**: Lower threshold \rightarrow higher recall, lower precision

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- Undersampling: Remove samples from majority class
 - Pro: Faster training, balanced classes
 - Con: Loss of information, smaller dataset
- Oversampling: Duplicate samples from minority class
 - Pro: No information loss
 - Con: Risk of overfitting, larger dataset
- **SMOTE**: Generate synthetic minority examples
 - Creates new samples between existing minority samples
 - More sophisticated than simple duplication

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- PR-AUC: Area under precision-recall curve (better for imbalanced data)

Practice and Review

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- 3. Why do we use cross-entropy loss instead of squared error?
- 4. How does regularization help in logistic regression?

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- Regularization: L1/L2 help prevent overfitting