

Autograd

What AutoDiff Is Not

* Finite differences

→ One sided:

$$\frac{\partial}{\partial x_i} f(x_1, \dots, x_N) \approx \frac{f(x_1, \dots, \cancel{x_i+h}, \dots) - f(x_1, \dots, \cancel{x_i}, \dots)}{h}$$

→ Or two sided

$$\frac{\partial}{\partial x_i} f(x_1, \dots, x_N) \approx \frac{f(x_1, \dots, \cancel{x_i+h}, \dots) - f(x_1, \dots, \cancel{x_i-h}, \dots)}{2h}$$

- Challenges with finite differences
 - Expensive: compute forward pass for each variable
 - Numerically unstable

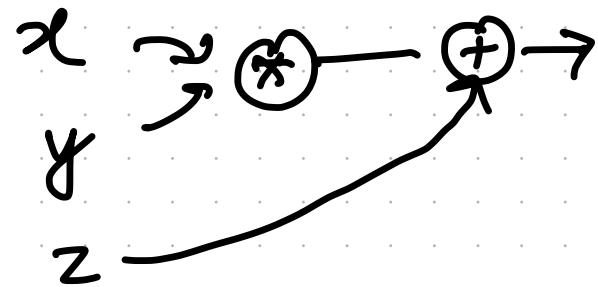
Computational Graphs

- * Nodes : operations (+, *, ...)
- * Edges : variables / Tensors

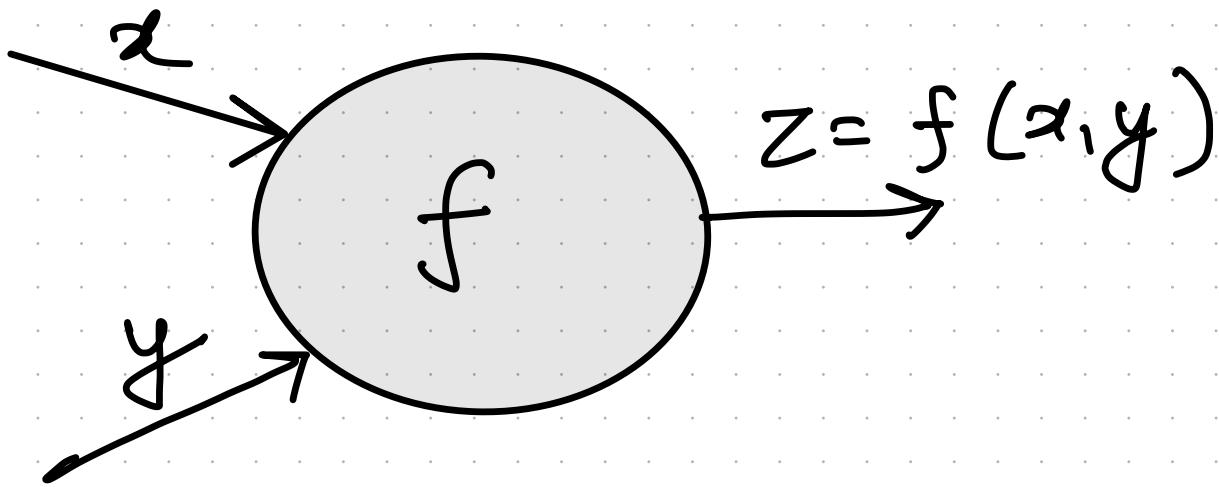
Computational Graphs

- * Nodes : operations (+, *, ...)
- * Edges : variables / Tensors
(and data dependencies)

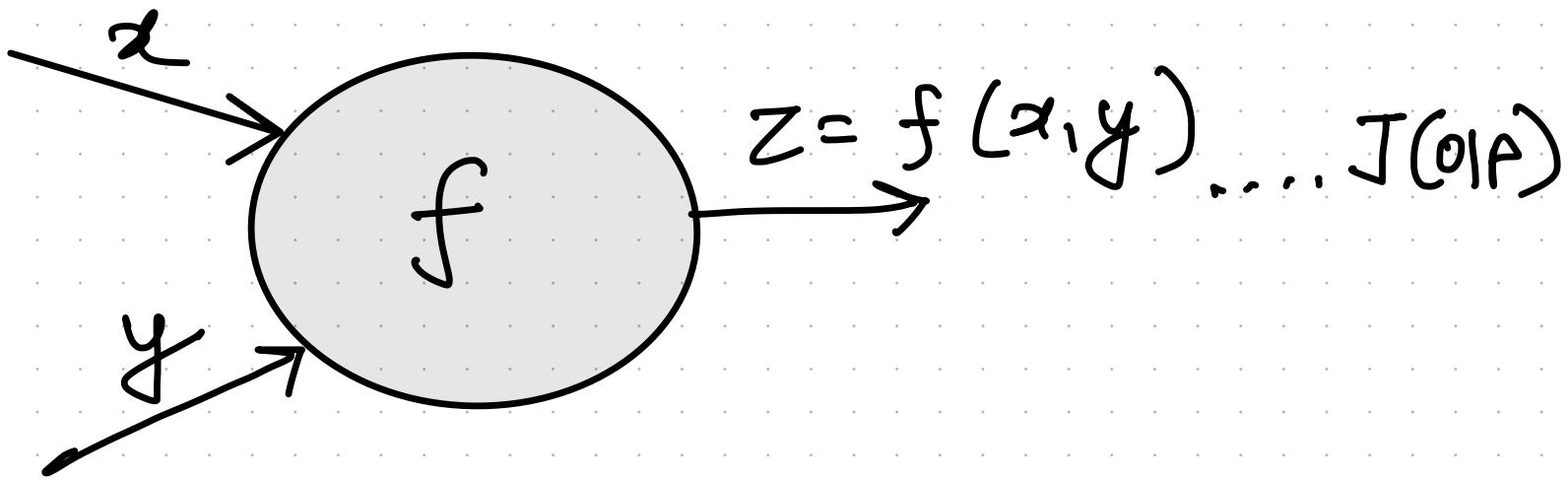
Example : $(x * y) + z$



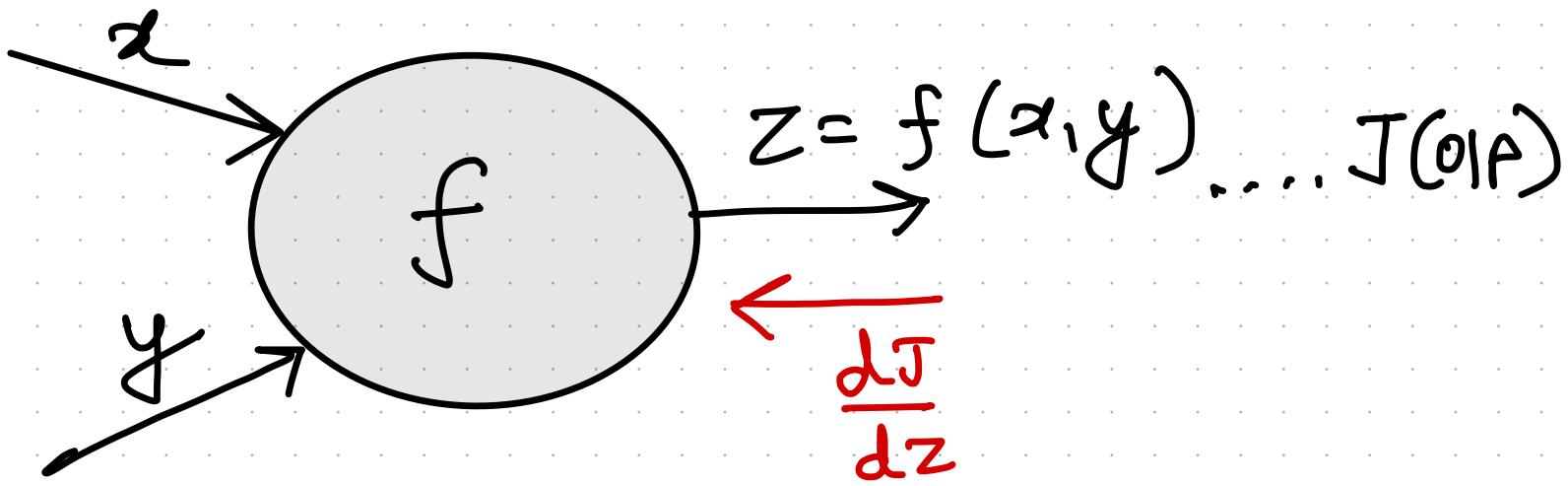
Back Prop Through Computational Graph



Back Prop Through Computational Graph

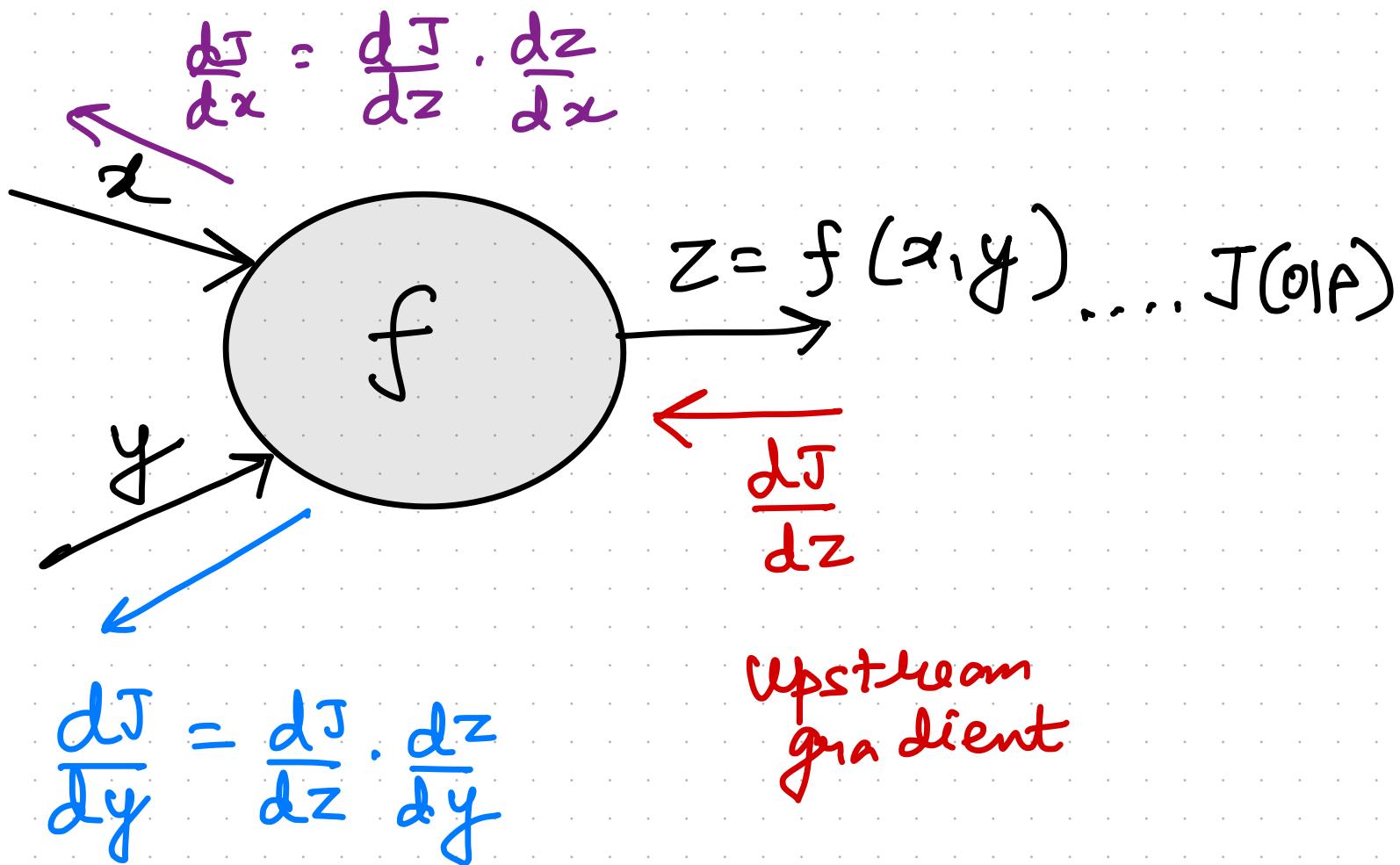


Back Prop Through Computational Graph

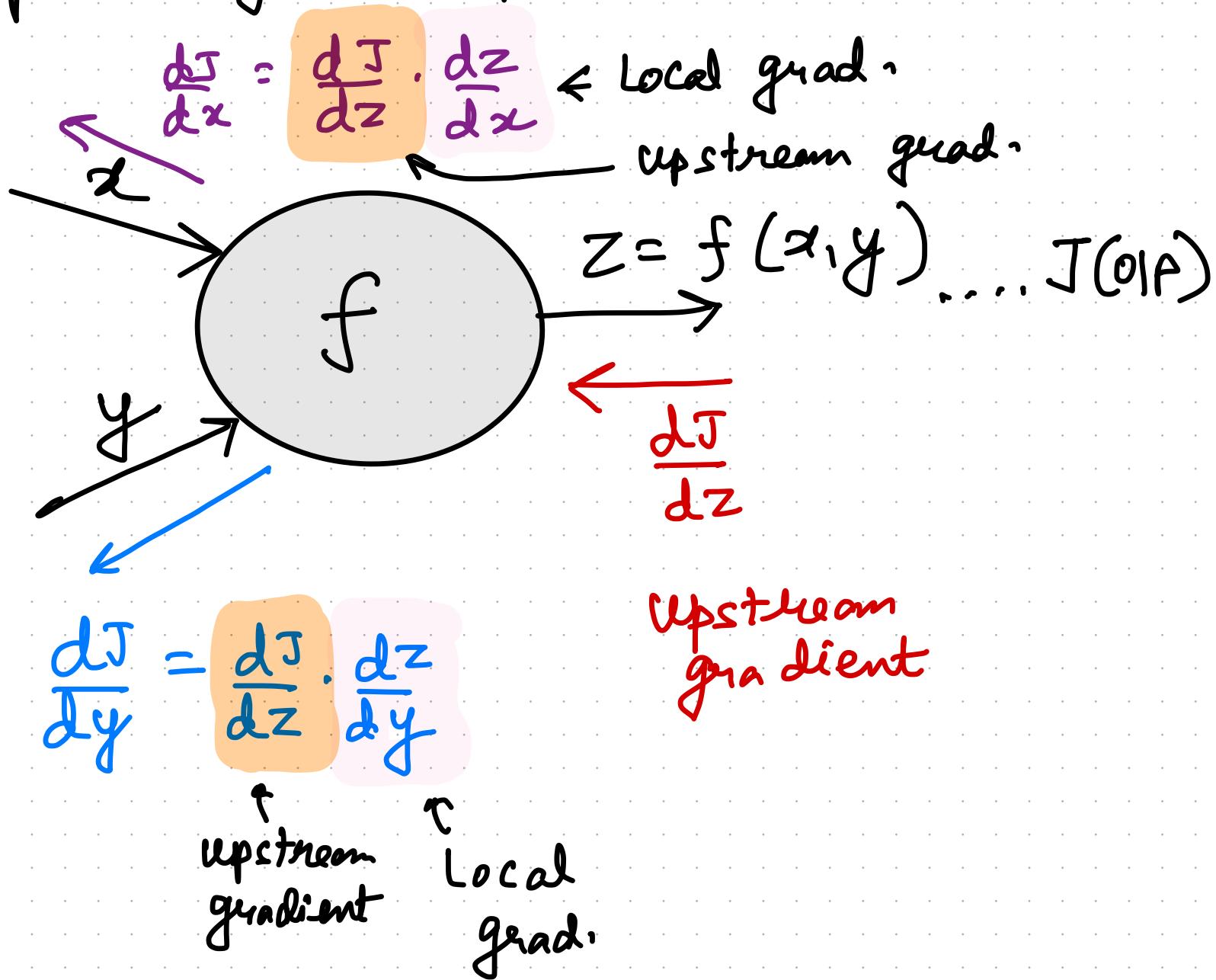


Upstream
gradient

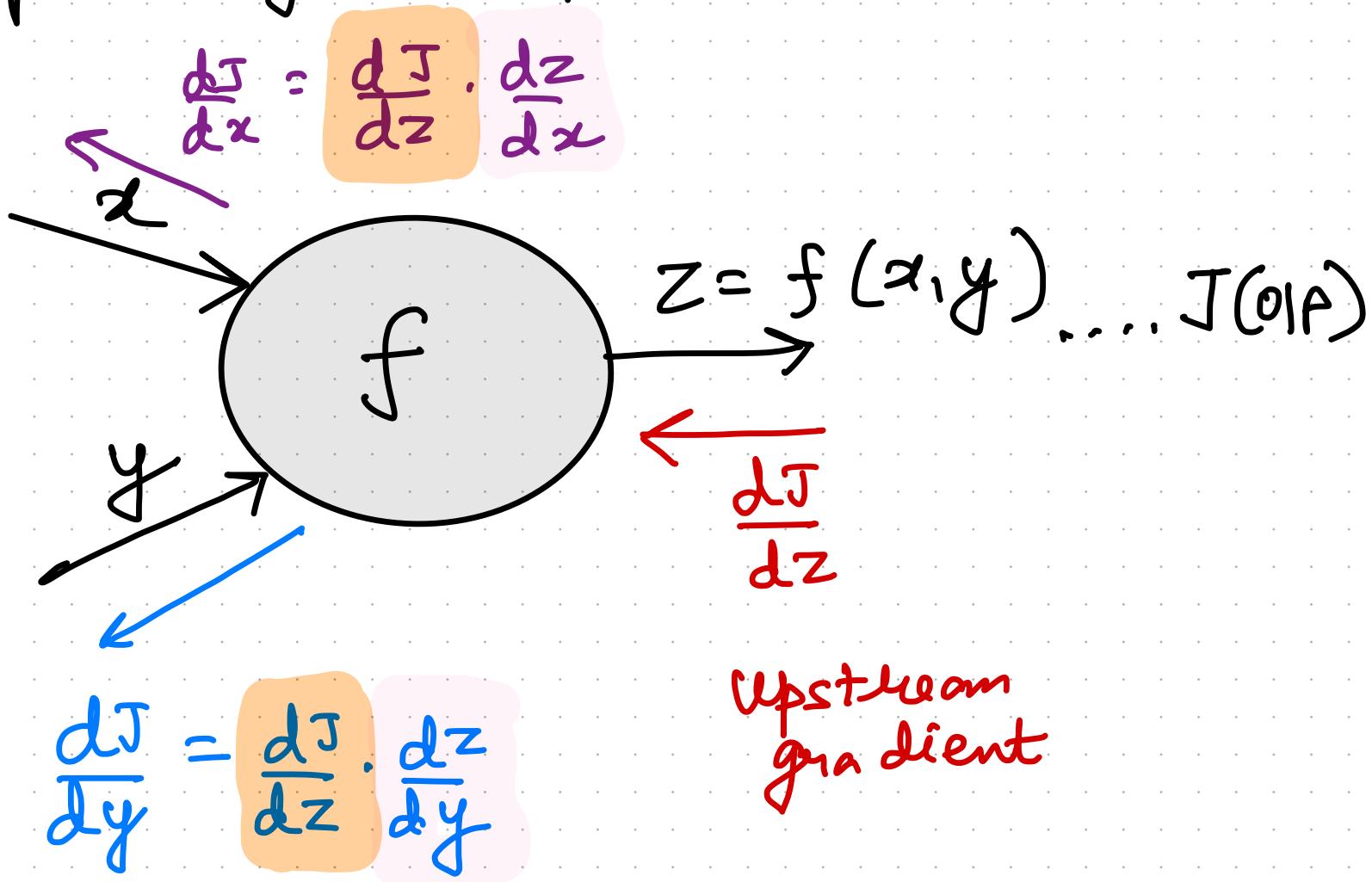
Back Prop Through Computational Graph



Back Prop Through Computational Graph



Back Prop Through Computational Graph



DOWNSTRREAM GRADIENT

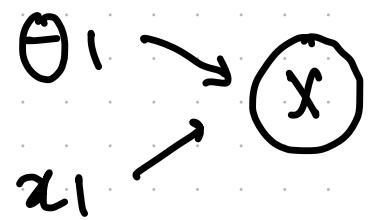
= UPSTREAM GRADIENT \times LOCAL GRADIENT

$$\hat{y} = \frac{1}{1 + e^{-(\theta_0 + \theta_1 x_1 + \theta_2 x_2)}}$$

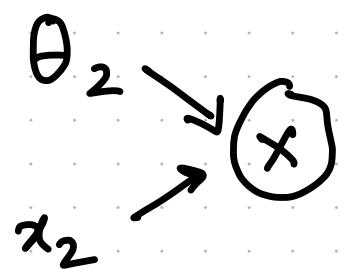
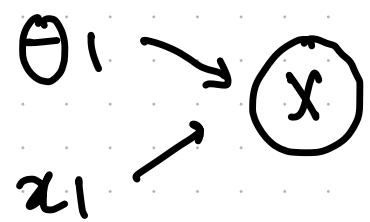
$$y = 1$$

$$\begin{aligned}\text{Loss} &= -y \log \hat{y} - (1-y) \log (1-\hat{y}) \\ &= -\log \left(\frac{1}{1 + e^{-(\theta_0 + \theta_1 x_1 + \theta_2 x_2)}} \right)\end{aligned}$$

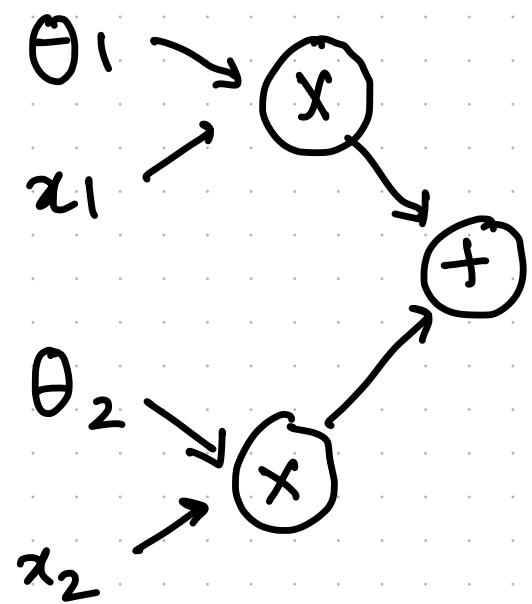
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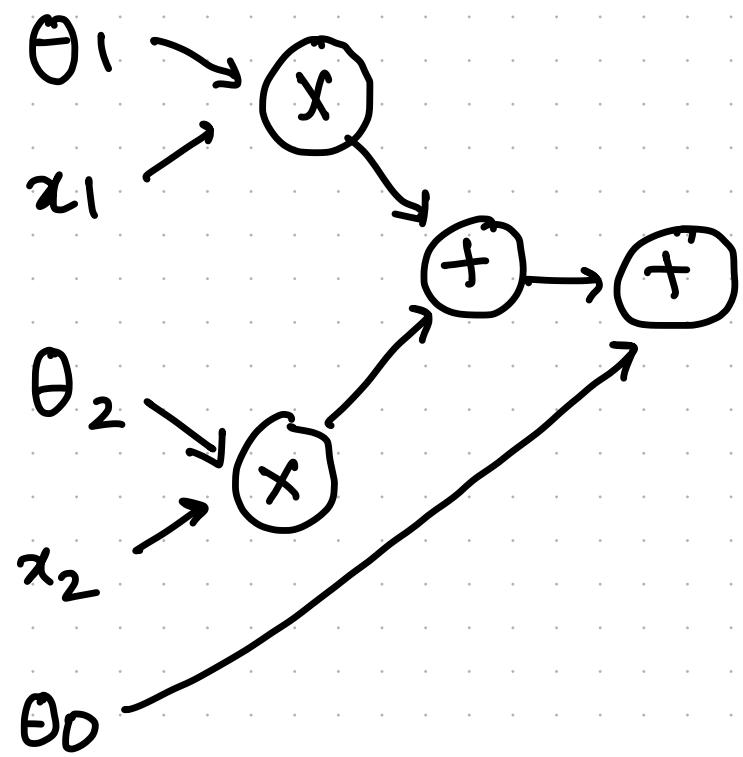
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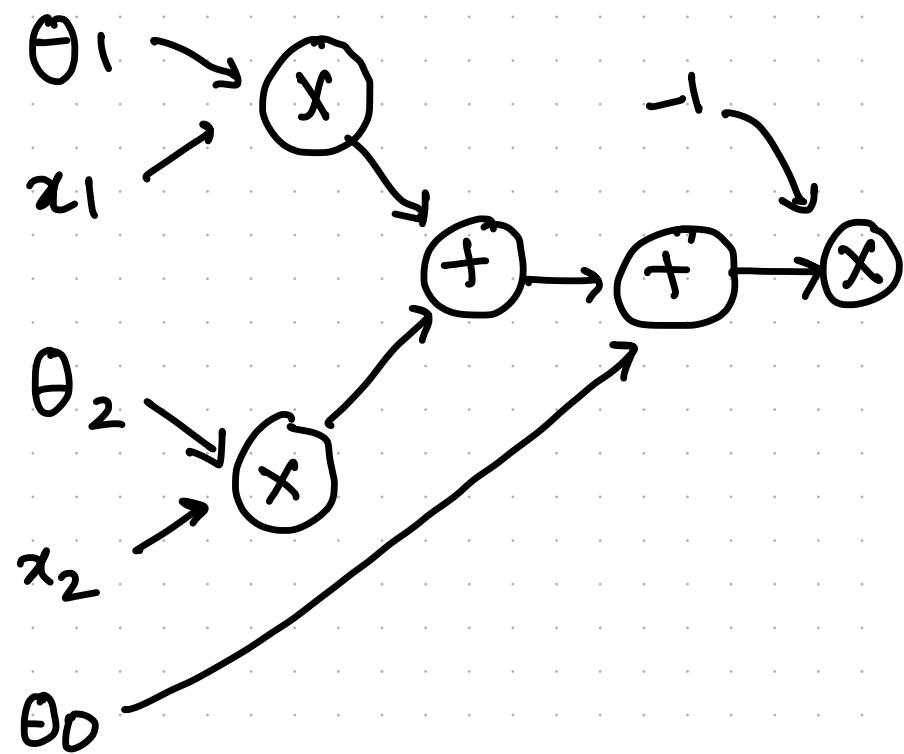
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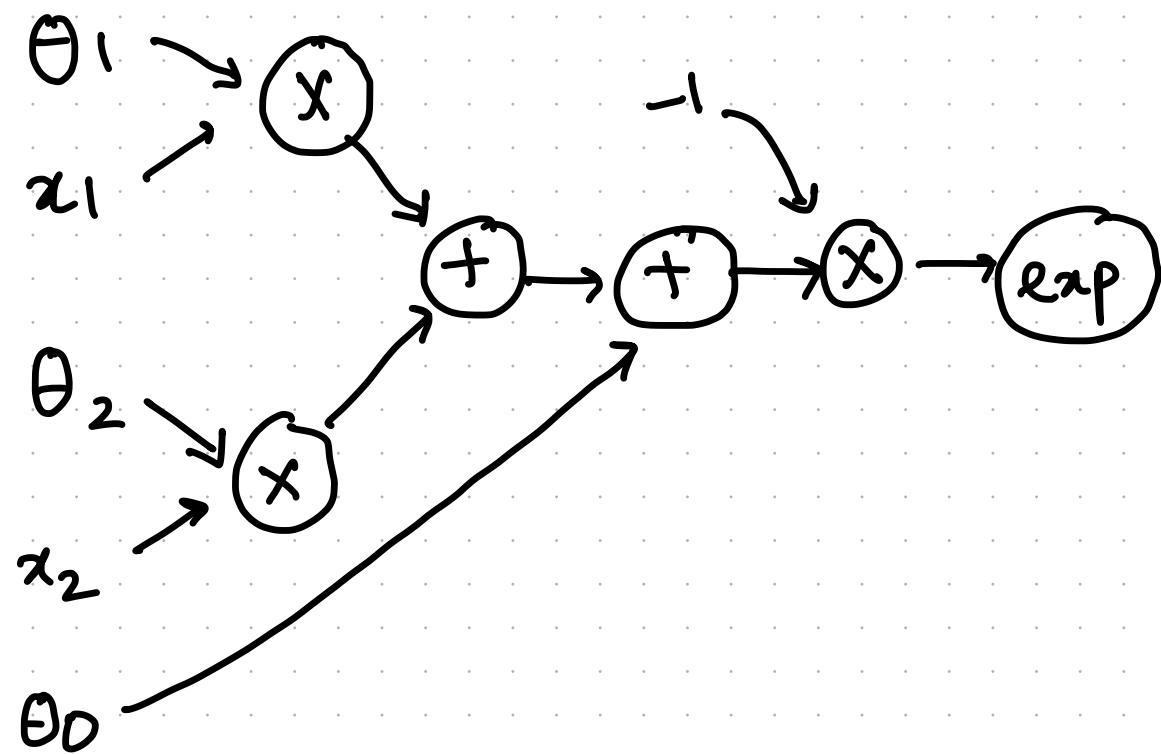
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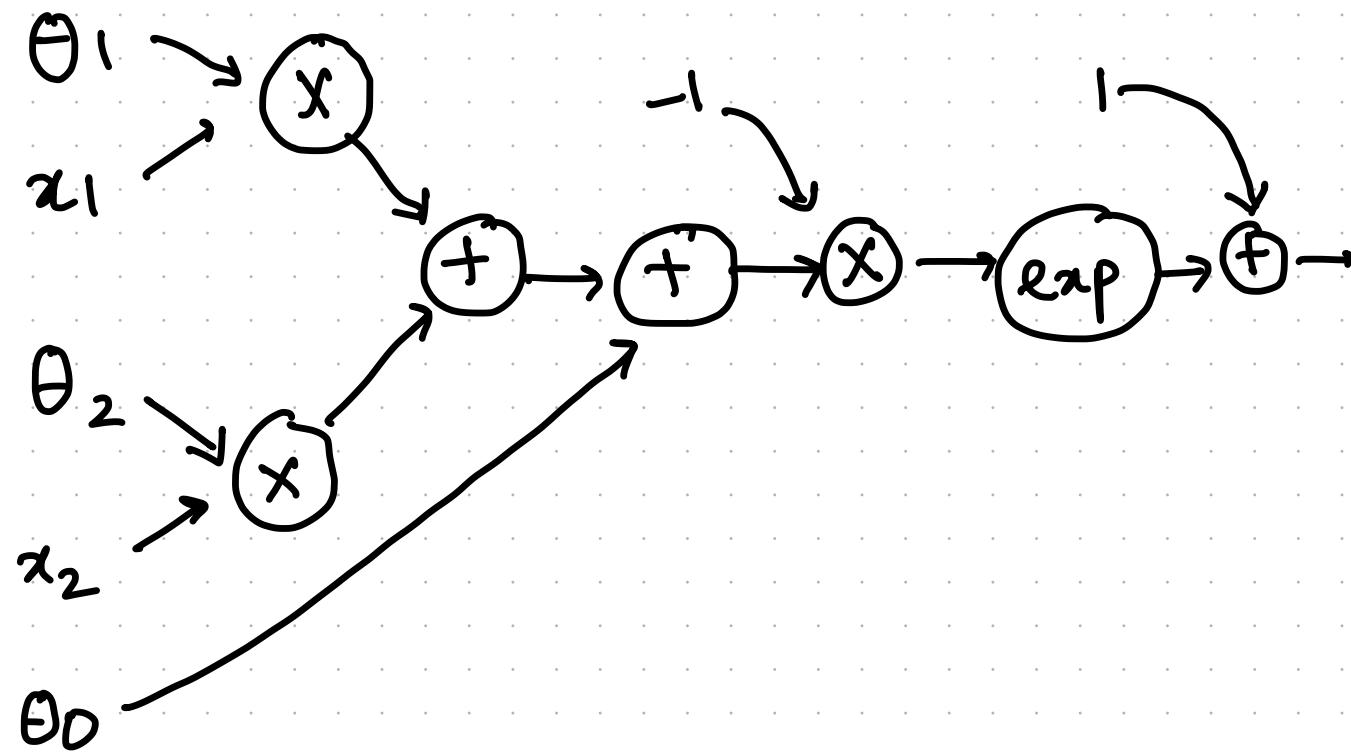
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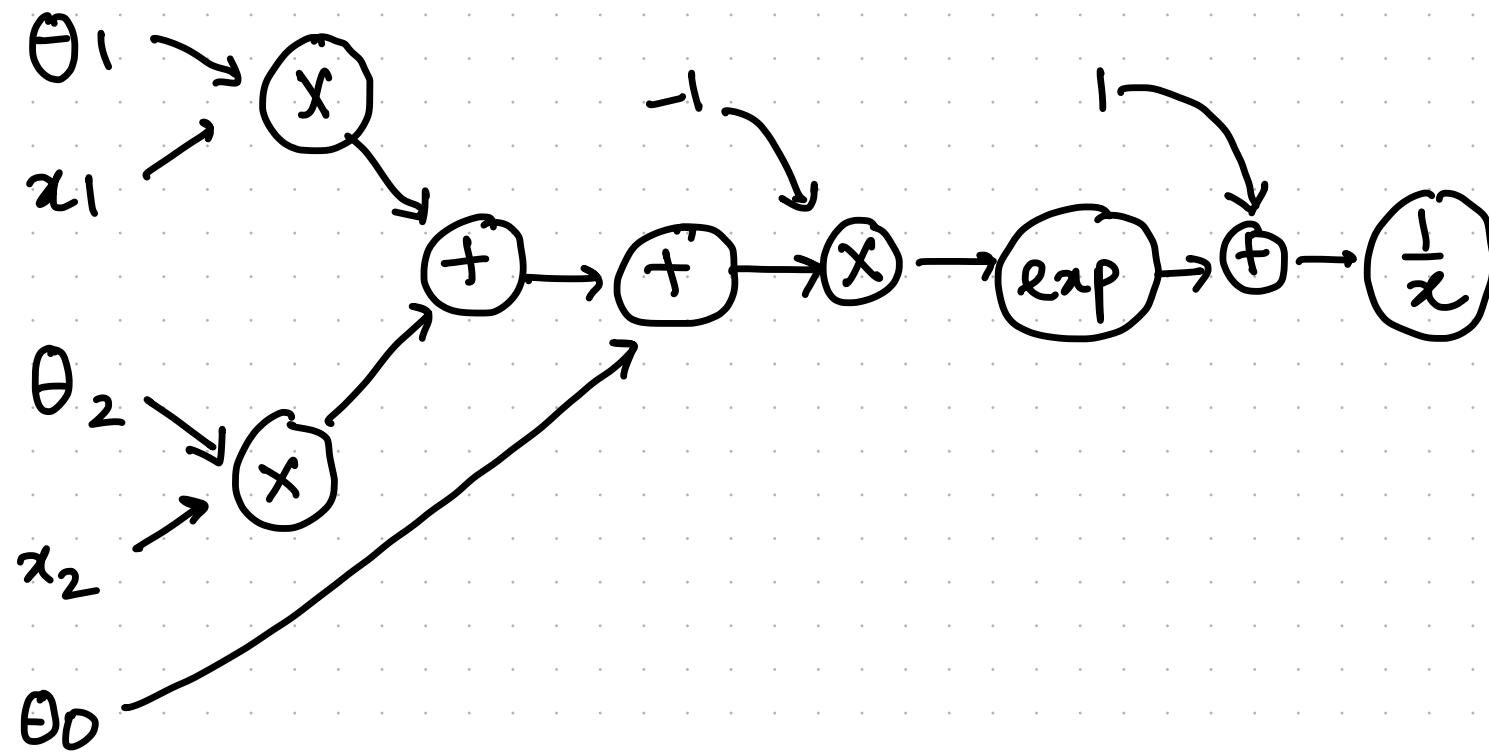
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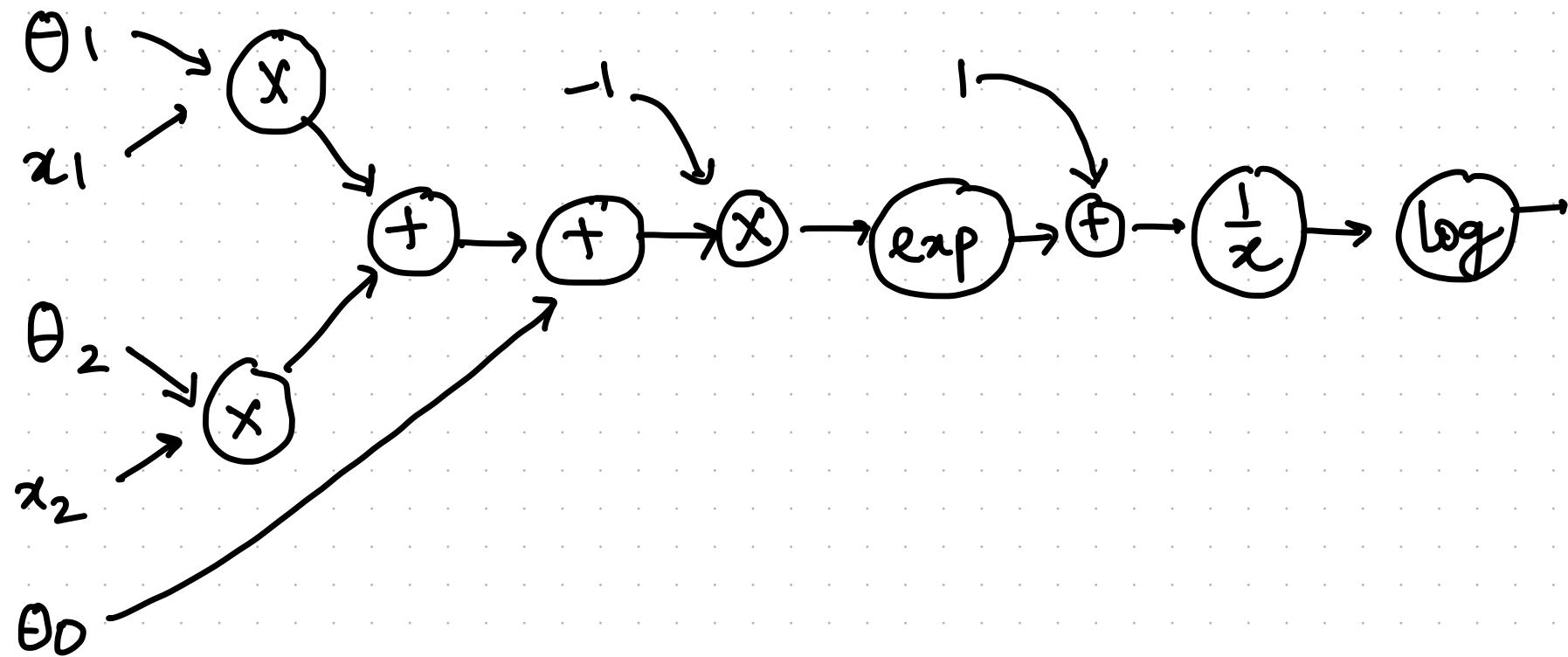
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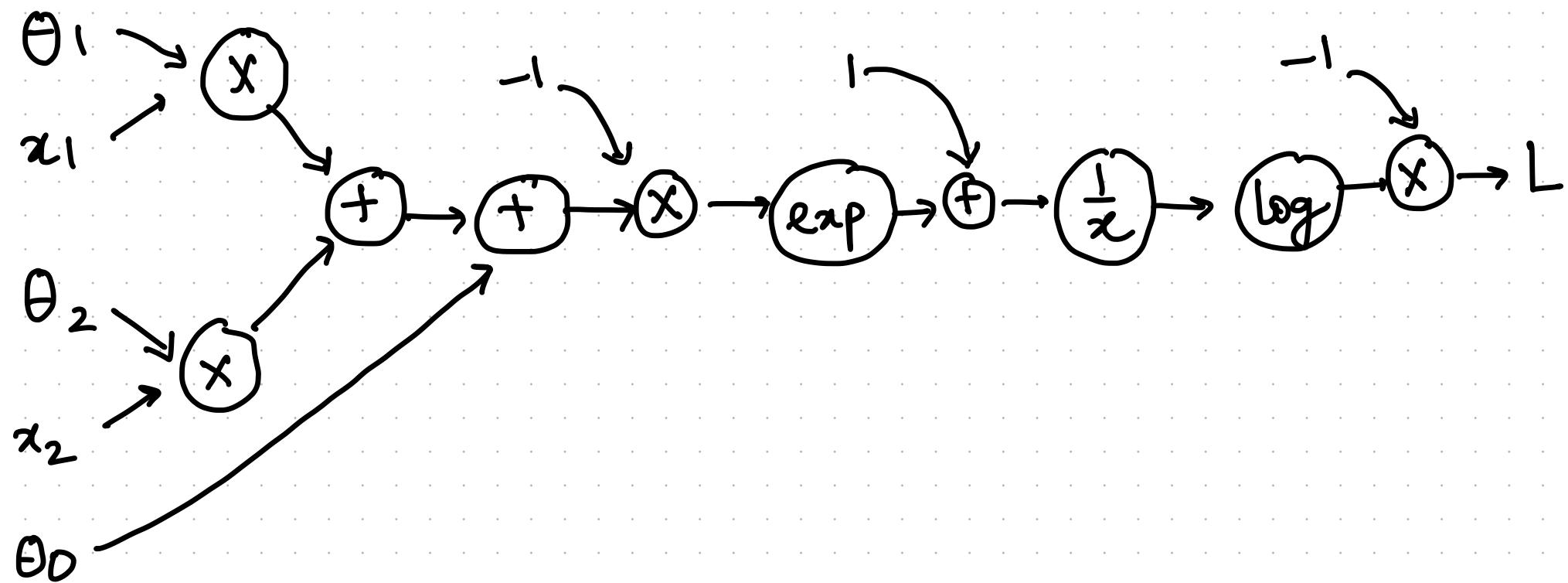
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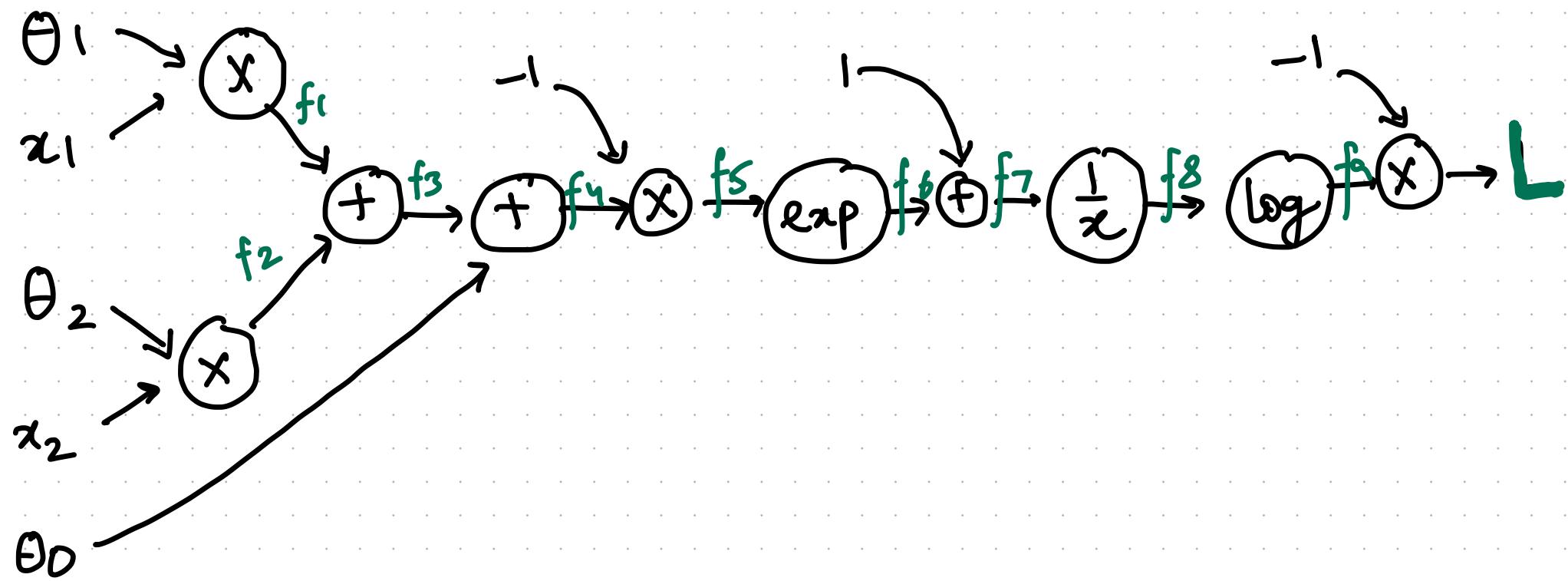
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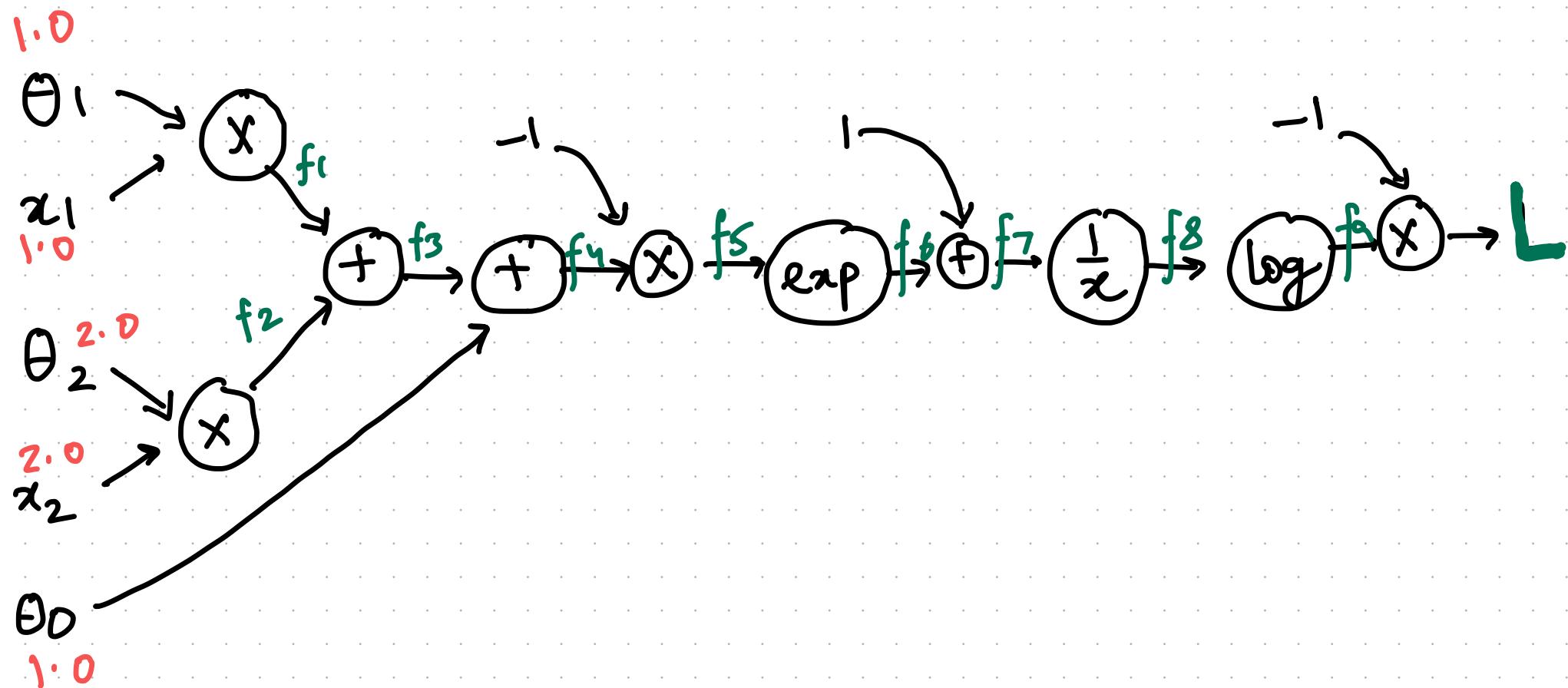
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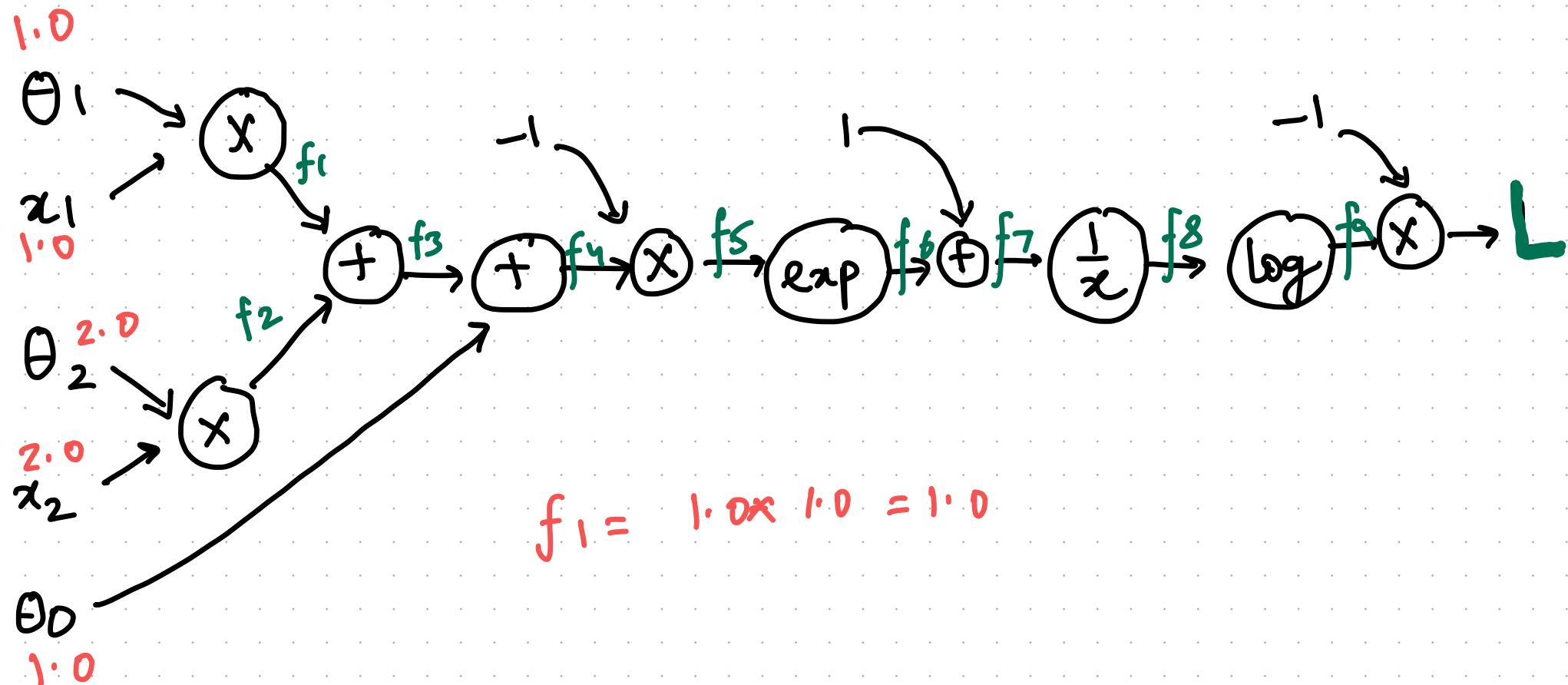
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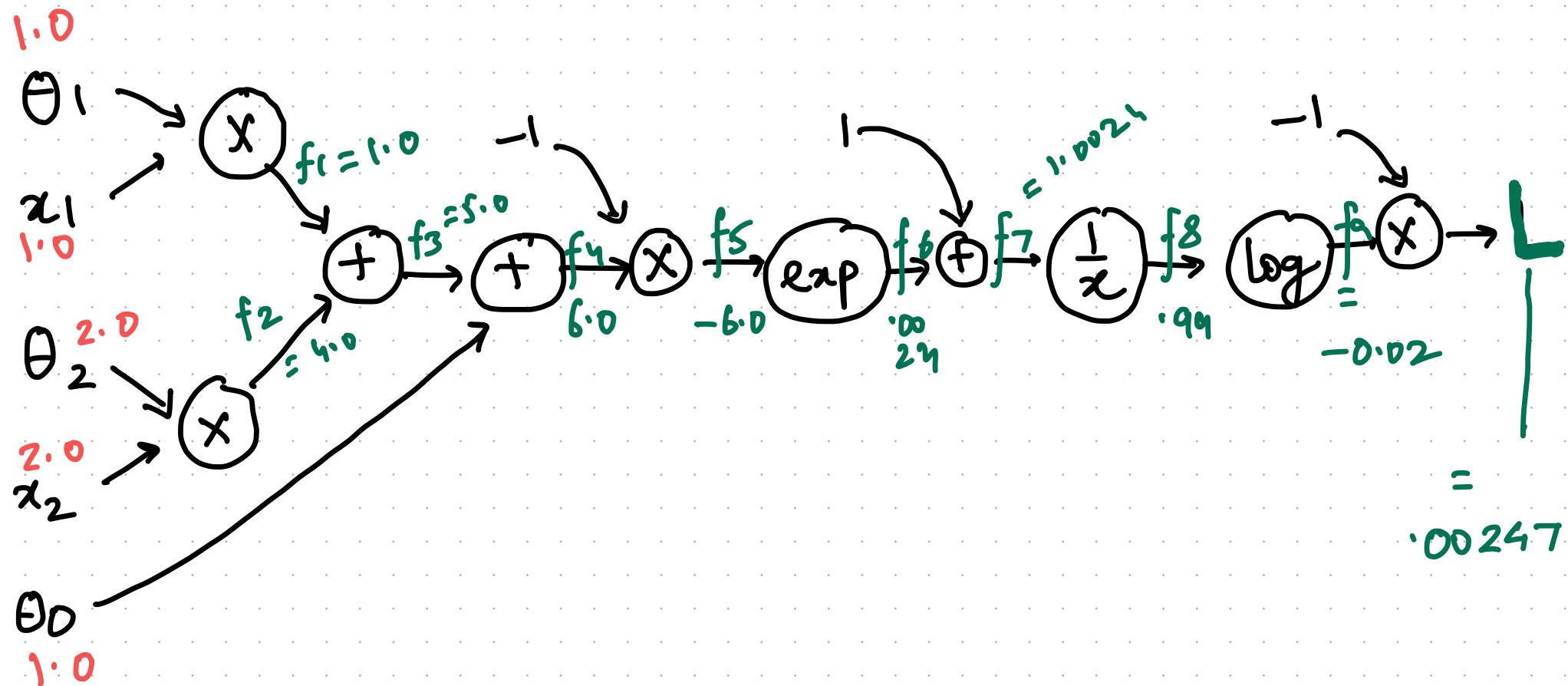
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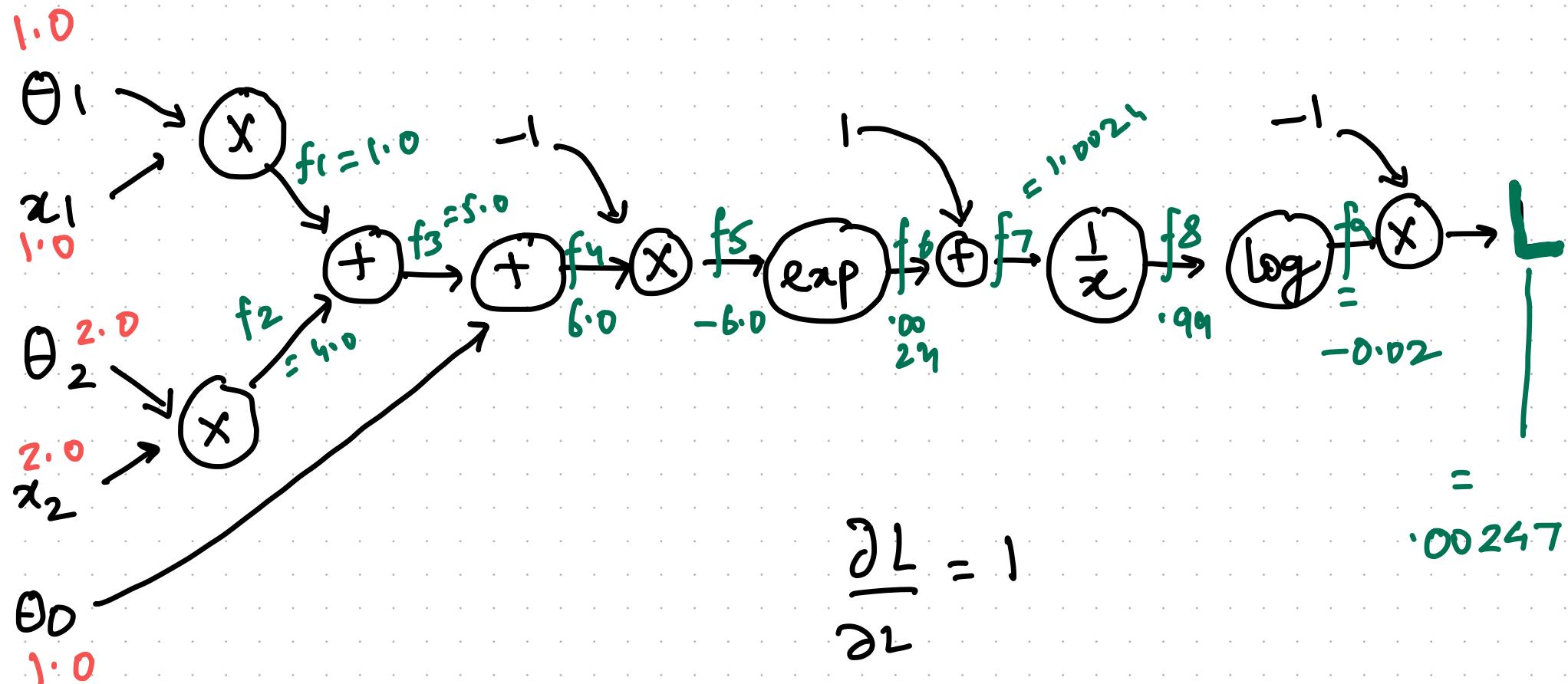
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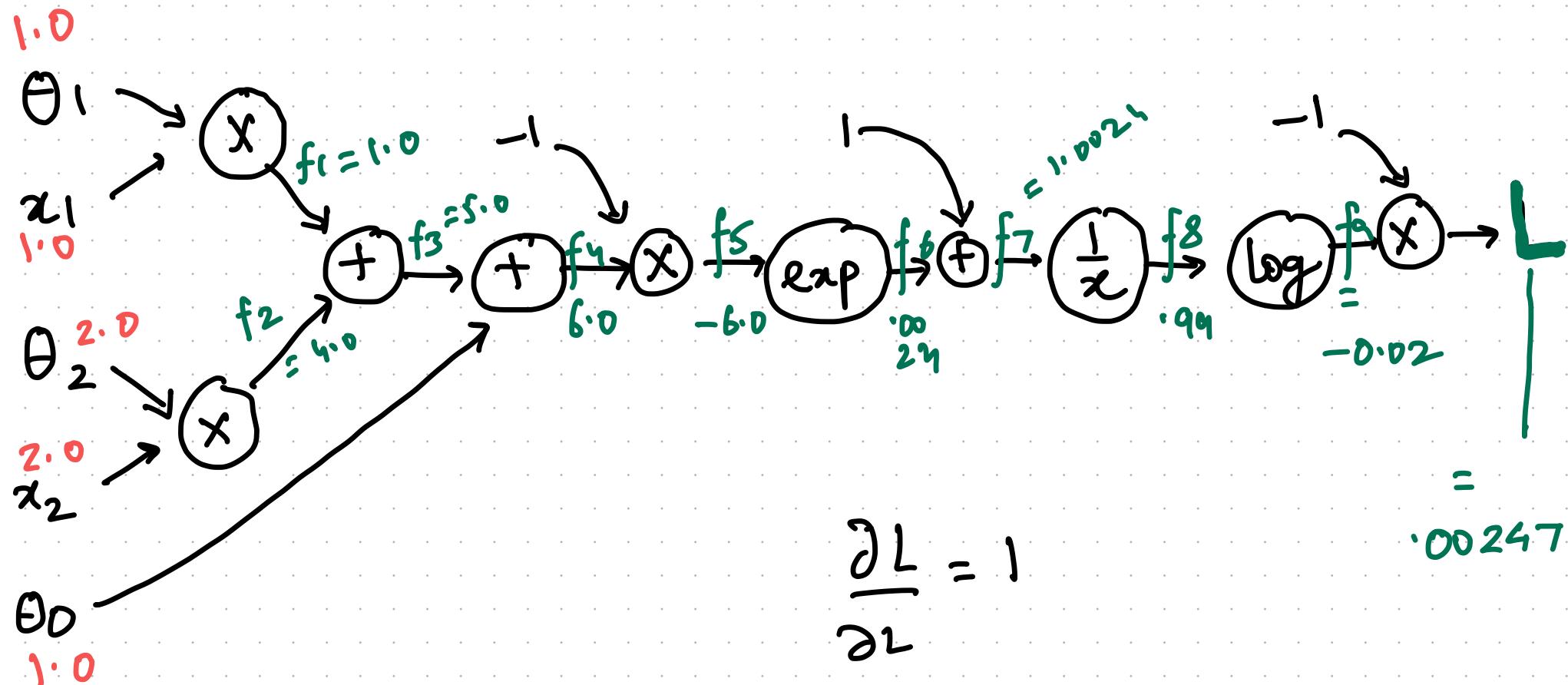
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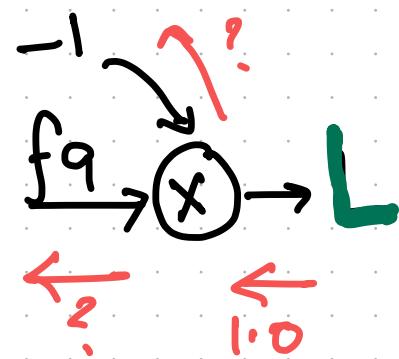
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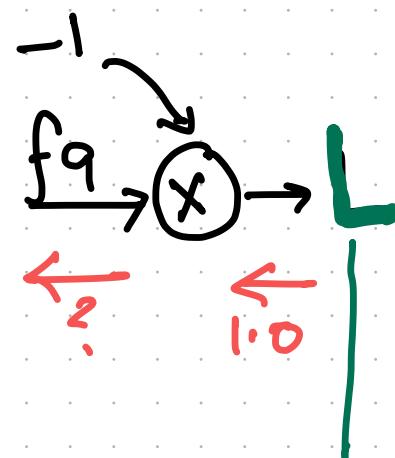


$$\text{LOSS} = -1 * \log \left(\frac{1}{1 + e^{-(\theta_0 + \theta_1 x_1 + \theta_2 x_2)}} \right)$$



$$\frac{\partial L}{\partial L} = 1$$

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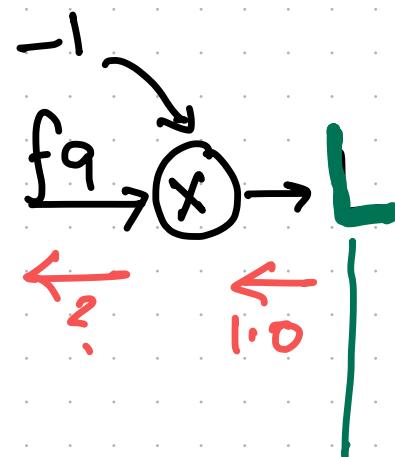


$$= \\ \cdot 00247$$

$$\frac{\partial L}{\partial z} = 1$$

Upstream gradient = 1.0

$$\text{LOSS} = -1 * \log\left(\frac{1}{1 + e^{-(\theta_0 + \theta_1 x_1 + \theta_2 x_2)}}\right)$$



$$\frac{\partial L}{\partial f_q} = 1$$

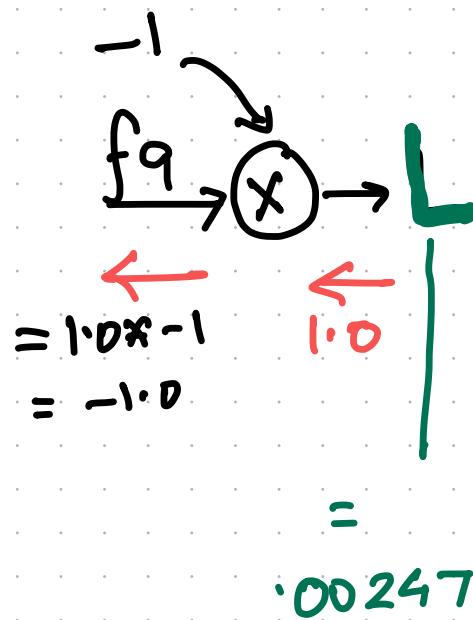
Upstream gradient = 1.0

$$= \\ \cdot 00247$$

$$L = f_q * -1$$

$$\frac{\partial L}{\partial f_q} = -1 \quad \text{LOCAL GRADIENT} = -1$$

$$\text{LOSS} = -1 * \log\left(\frac{1}{1 + e^{-(\theta_0 + \theta_1 x_1 + \theta_2 x_2)}}\right)$$



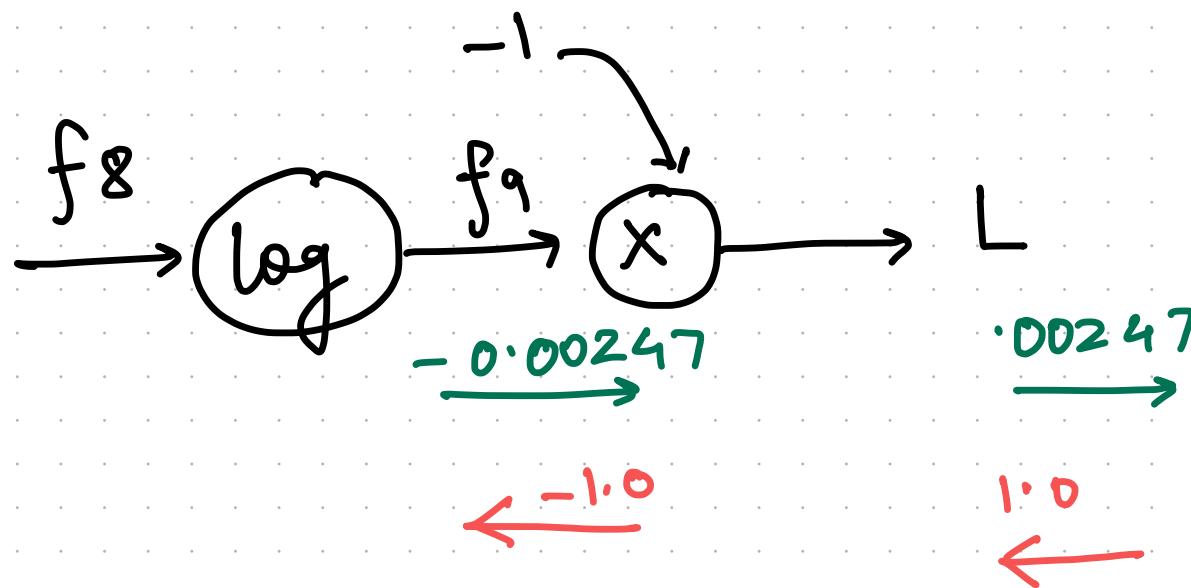
$$\frac{\partial L}{\partial f9} = 1$$

Upstream gradient = $1 \cdot 0$

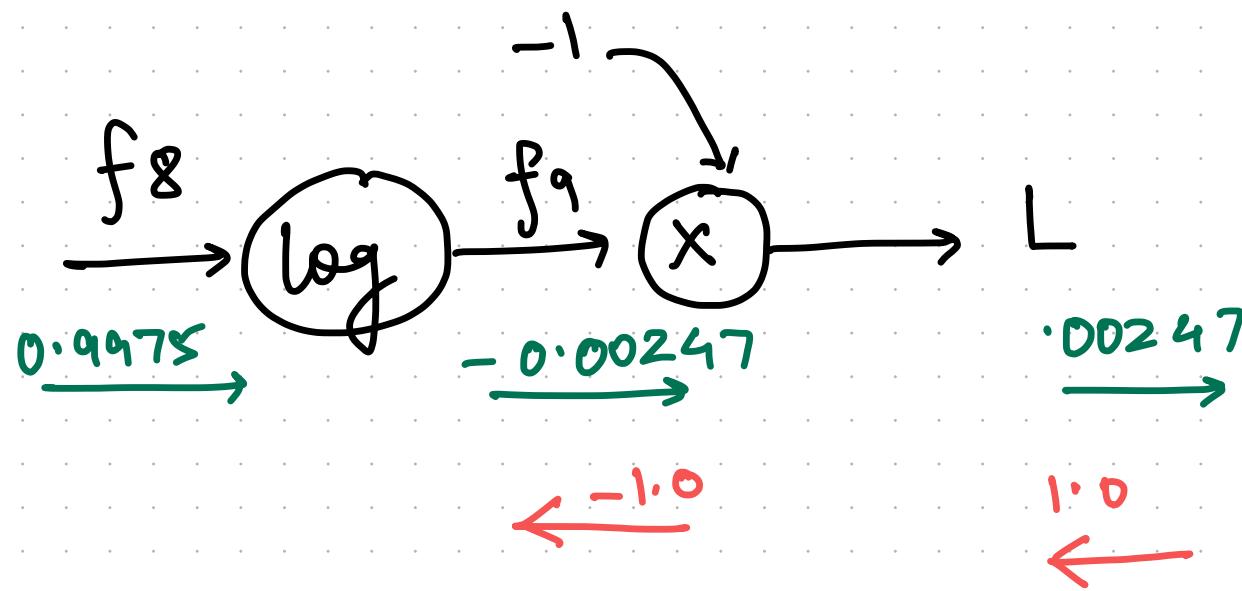
$$L = f9 * -1$$

$$\frac{\partial L}{\partial f9} = -1 \quad \text{LOCAL GRADIENT} = -1$$

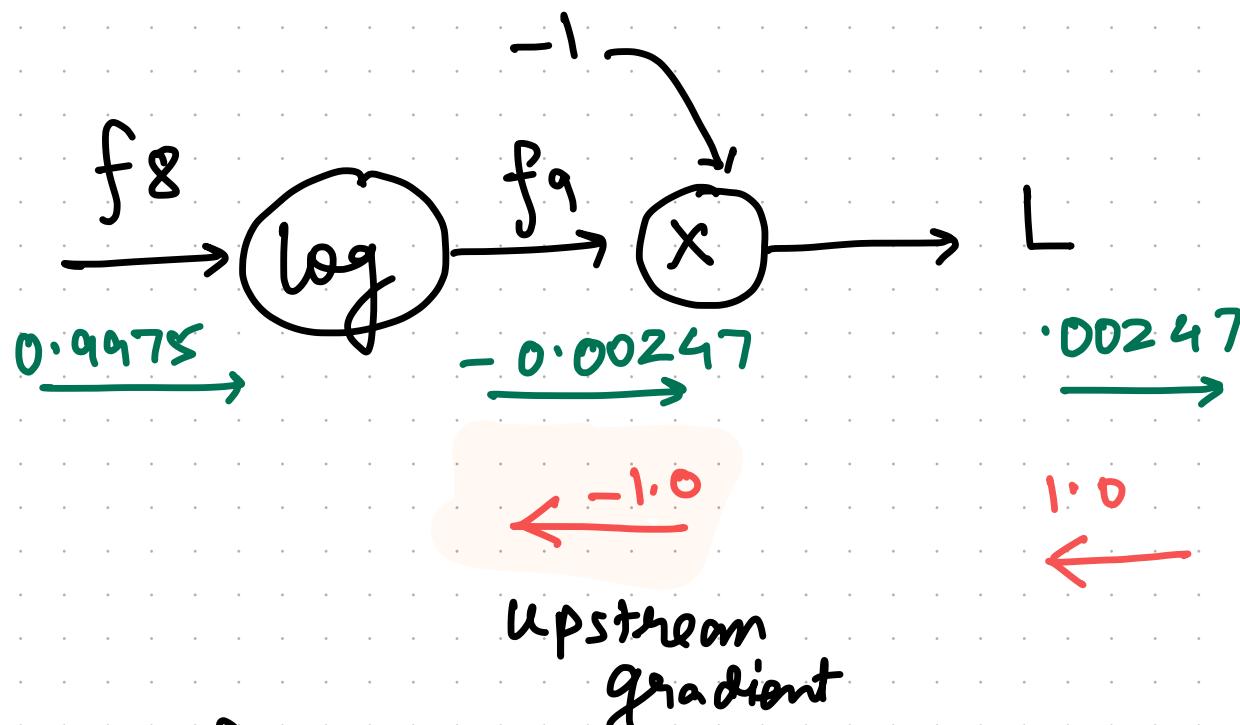
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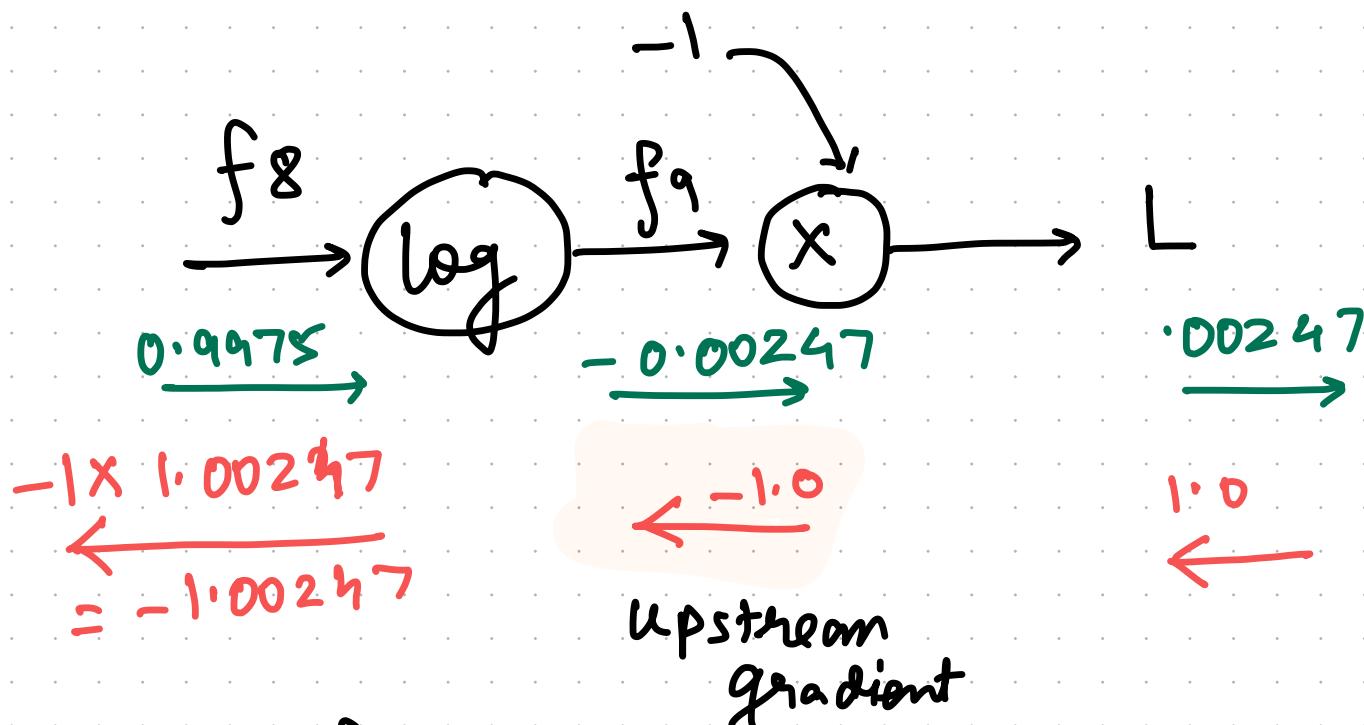
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$$f_9 = \log f_8$$

$$\frac{\partial f_9}{\partial f_8} = \frac{1}{f_8} = \frac{1}{0.9975} = 1.00247 = \text{local gradient}$$

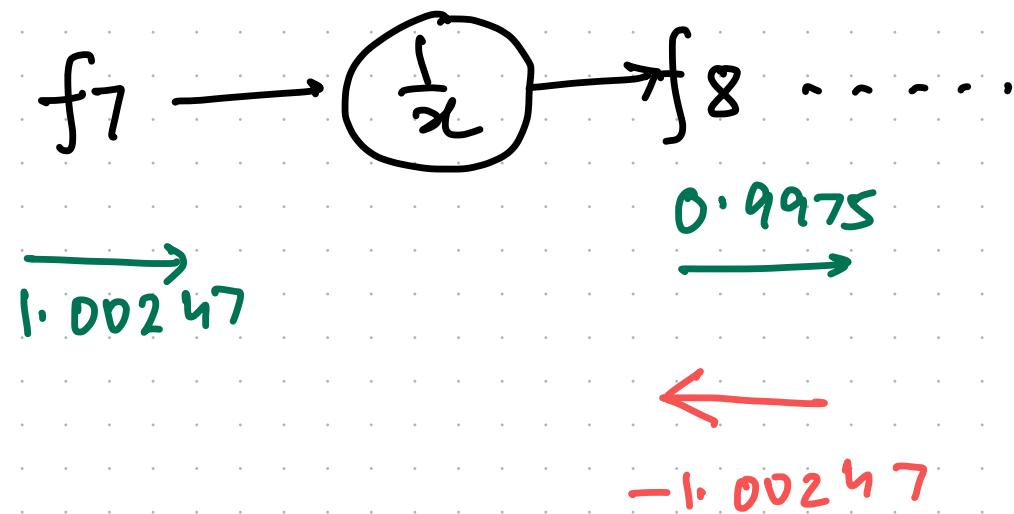
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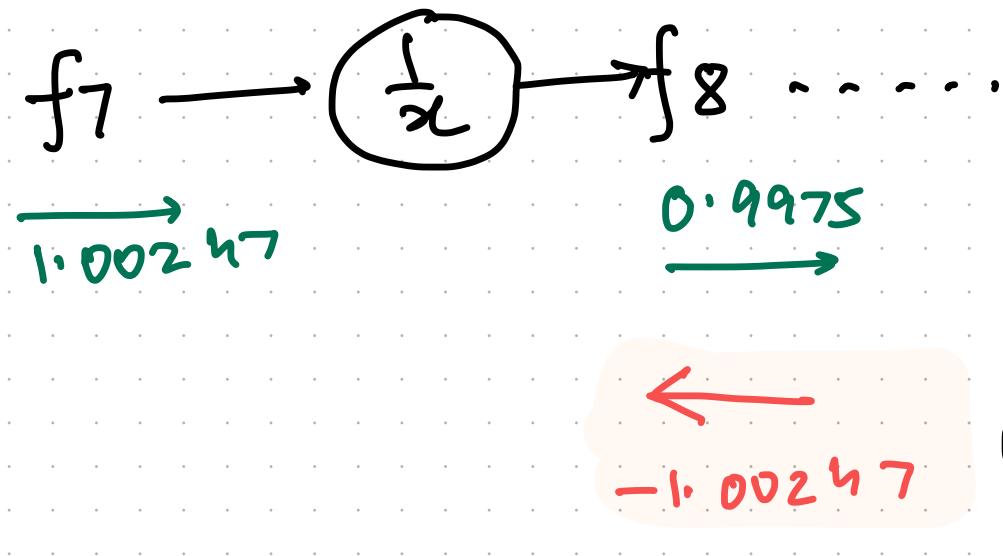
$$f_9 = \log f_8$$

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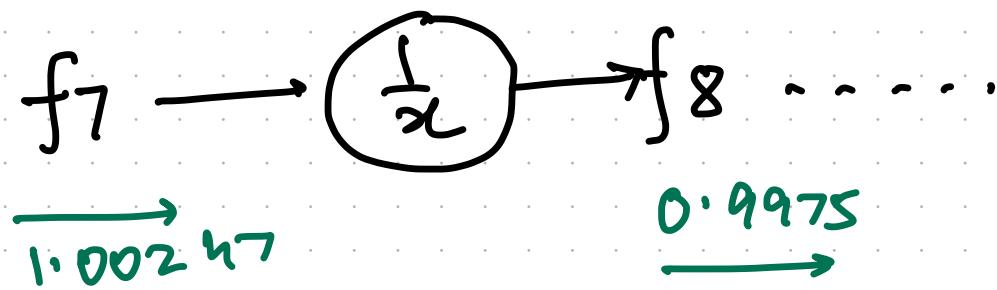
upstream
gradient

$$f_8 = \frac{1}{f_7}$$

$$\frac{\partial f_8}{\partial f_7} = \frac{-1}{f_7^2} = -0.9951$$

= Local gradient

$$\text{LOSS} = -1 * \log\left(\frac{1}{1 + e^{-(\theta_0 + \theta_1 x_1 + \theta_2 x_2)}}\right)$$



$$\begin{aligned} & -0.9951 * -1.00247 \\ & = 0.9975 \end{aligned}$$

$$\begin{aligned} & \leftarrow \\ & -1.00247 \end{aligned}$$

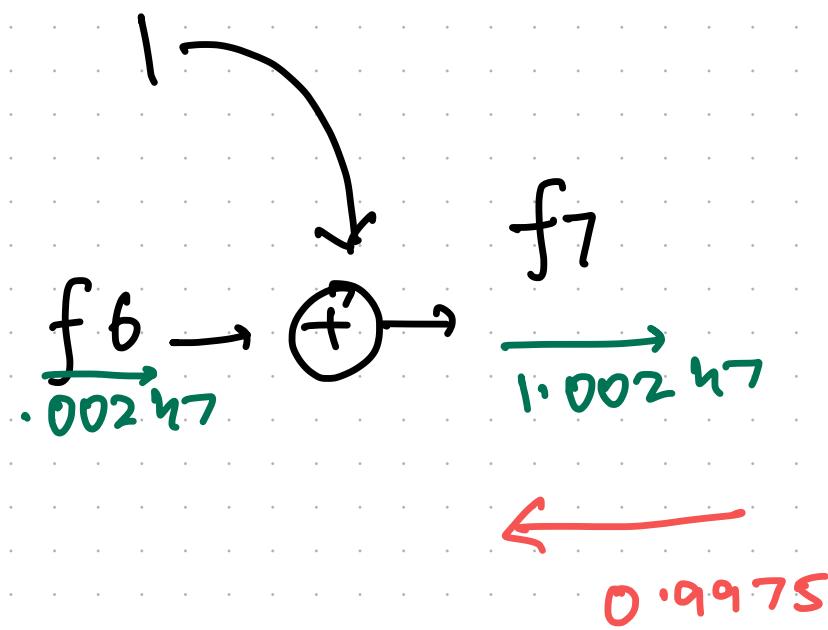
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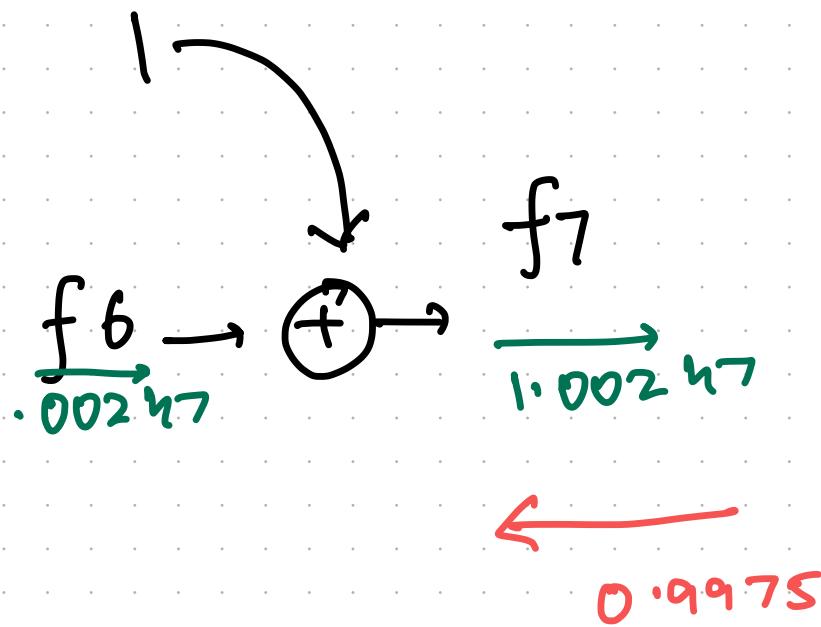
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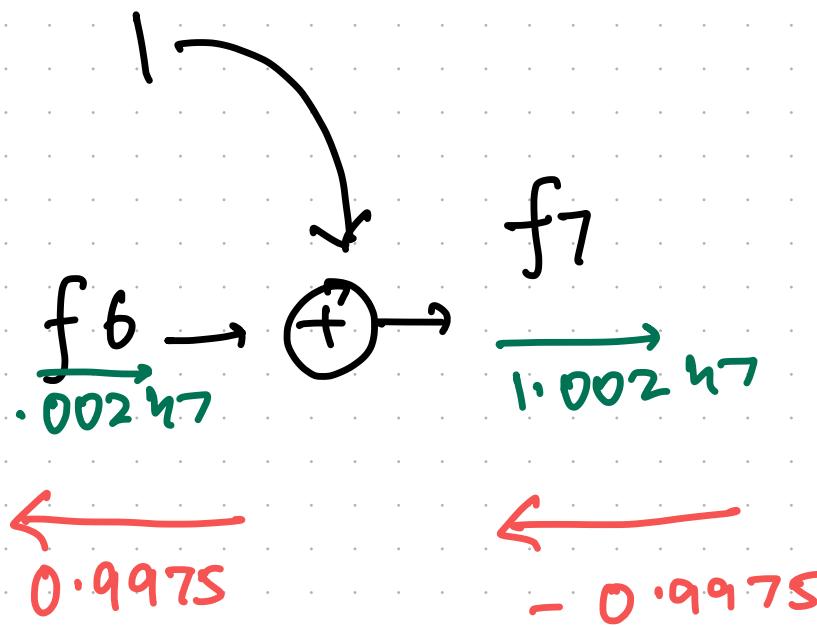
$$\text{LOSS} = -1 * \log \left(\frac{1}{1 + e^{-(\theta_0 + \theta_1 x_1 + \theta_2 x_2)}} \right)$$



$$\text{Upstream grad.} = 0.9975$$

$$\text{local grad.} = 1$$

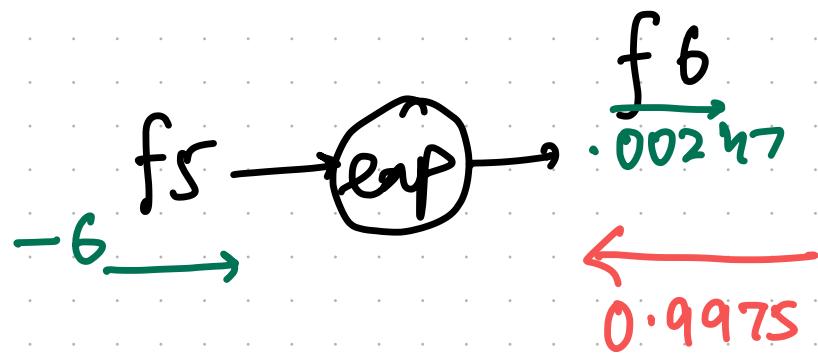
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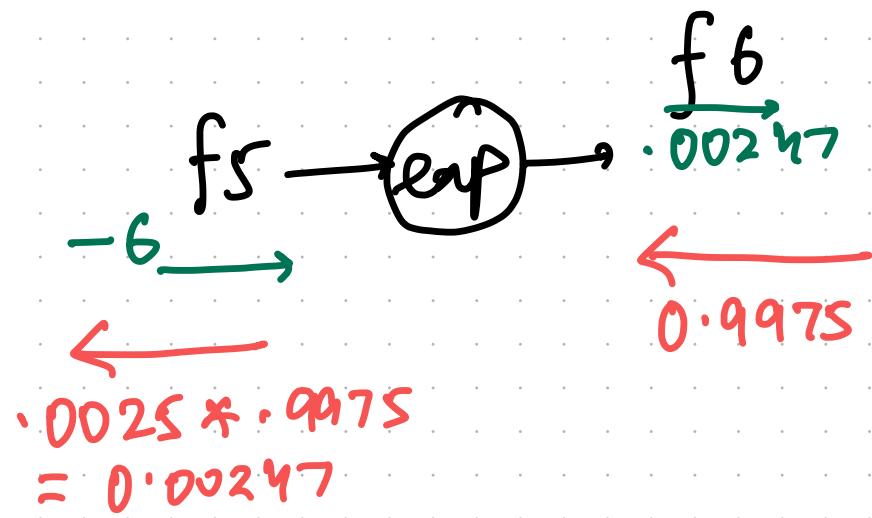
$$\text{LOSS} = -1 * \log \left(\frac{1}{1 + e^{-(\theta_0 + \theta_1 x_1 + \theta_2 x_2)}} \right)$$



$$\text{Upstream grad.} = 0.9975$$

$$\text{local grad.} = \frac{\partial f_6}{\partial f_5} = \frac{\partial e^{f_5}}{\partial f_5} = e^{-6} = e^{-6} = 0.0025$$

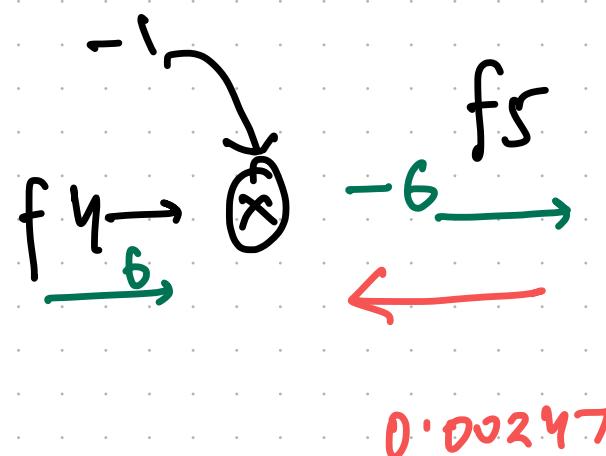
$$\text{LOSS} = -1 * \log \left(\frac{1}{1 + e^{-(\theta_0 + \theta_1 x_1 + \theta_2 x_2)}} \right)$$



$$\text{Upstream grad.} = 0.9975$$

$$\text{local grad.} = \frac{\partial f_b}{\partial f_s} = \frac{\partial e^{f_s}}{\partial f_s} = e^{-f_s} = e^{-b} = 0.0025$$

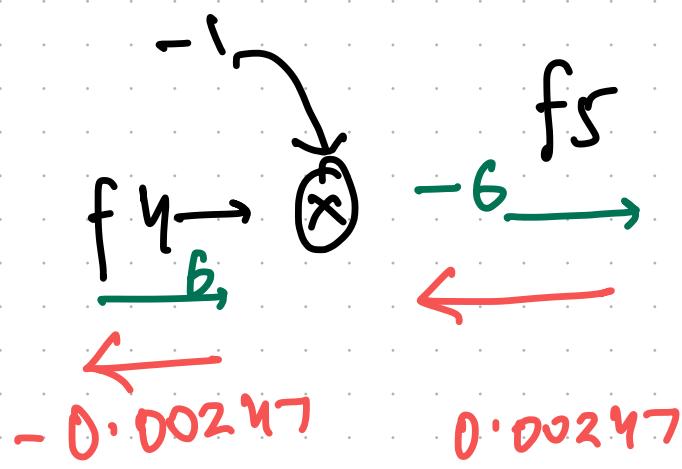
$$\text{LOSS} = -1 * \log \left(\frac{1}{1 + e^{-(\theta_0 + \theta_1 x_1 + \theta_2 x_2)}} \right)$$



Upstream grad. = 0.00247

local grad. = -1

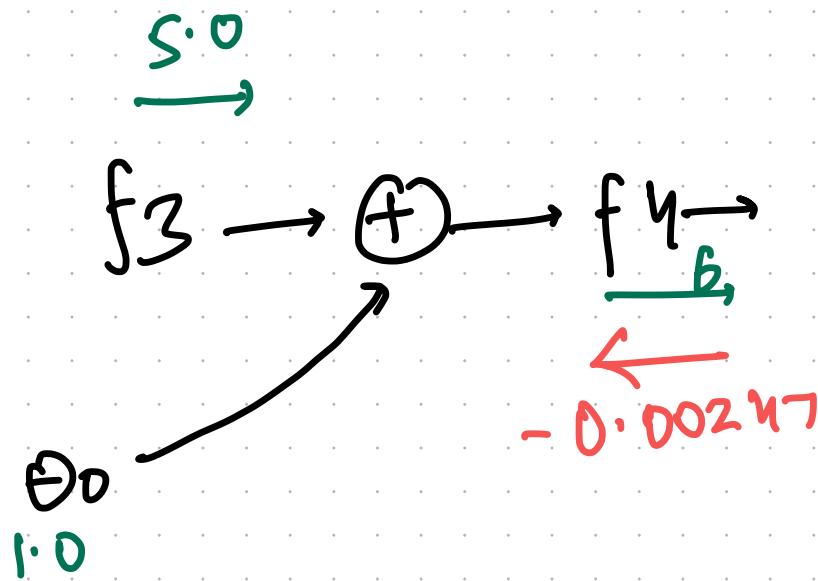
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Upstream grad. = 0.00247

local grad. = -1

$$\text{LOSS} = -1 * \log \left(\frac{1}{1 + e^{-(\theta_0 + \theta_1 x_1 + \theta_2 x_2)}} \right)$$



Upstream grad. = -0.00247

local grad. (θ_0) = $\frac{\partial f_4}{\partial \theta_0} = 1$; local grad for $f_3 = 1$

$$\text{LOSS} = -1 * \log \left(\frac{1}{1 + e^{-(\theta_0 + \theta_1 x_1 + \theta_2 x_2)}} \right)$$

$\overset{-0.00247}{\leftarrow}$

$\underset{\longrightarrow}{5.0}$

$$f_3 \rightarrow \oplus \rightarrow f_4 \rightarrow$$

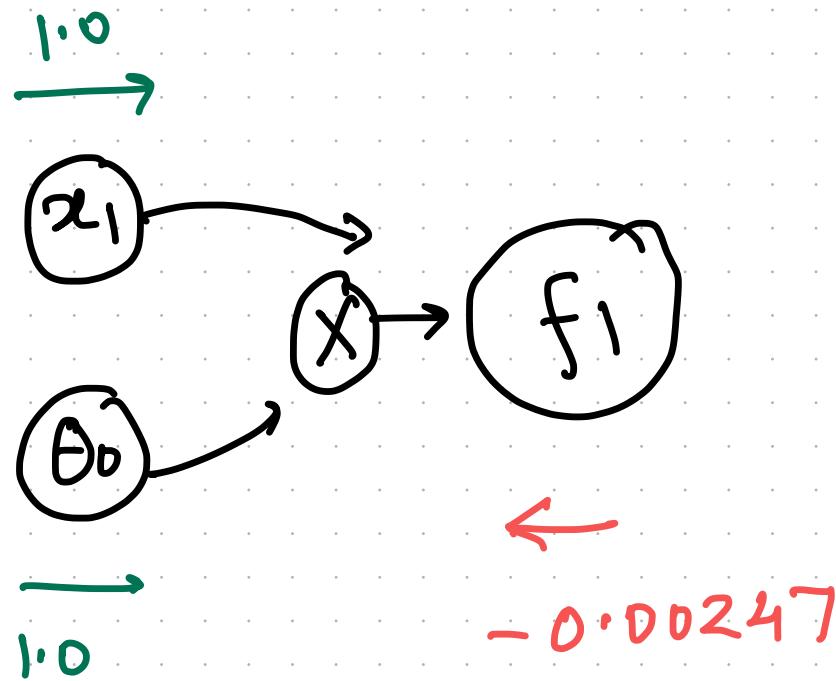
$\overset{-0.00247}{\leftarrow}$

θ_0
 $\underset{\longleftarrow}{1.0}$
 $\overset{-0.00247}{\leftarrow}$

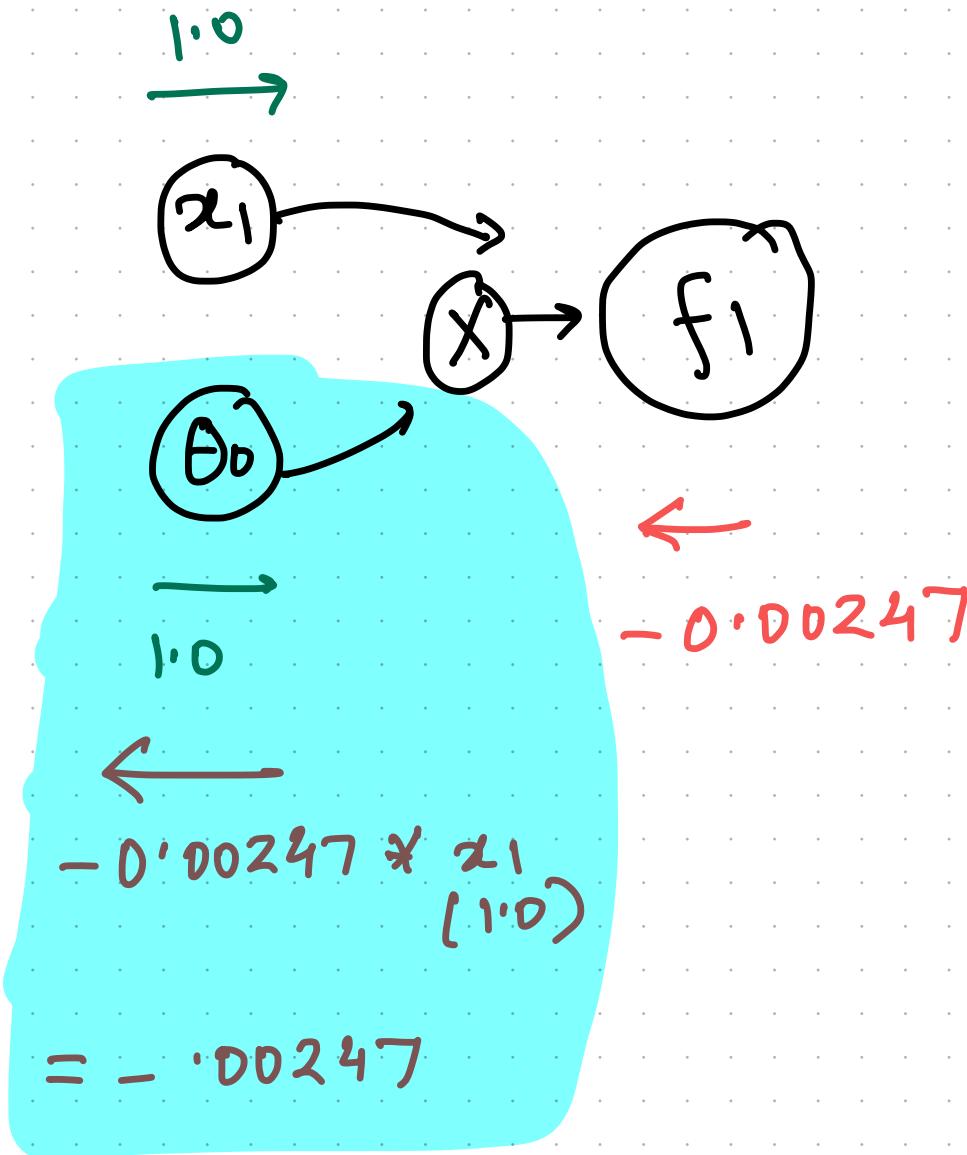
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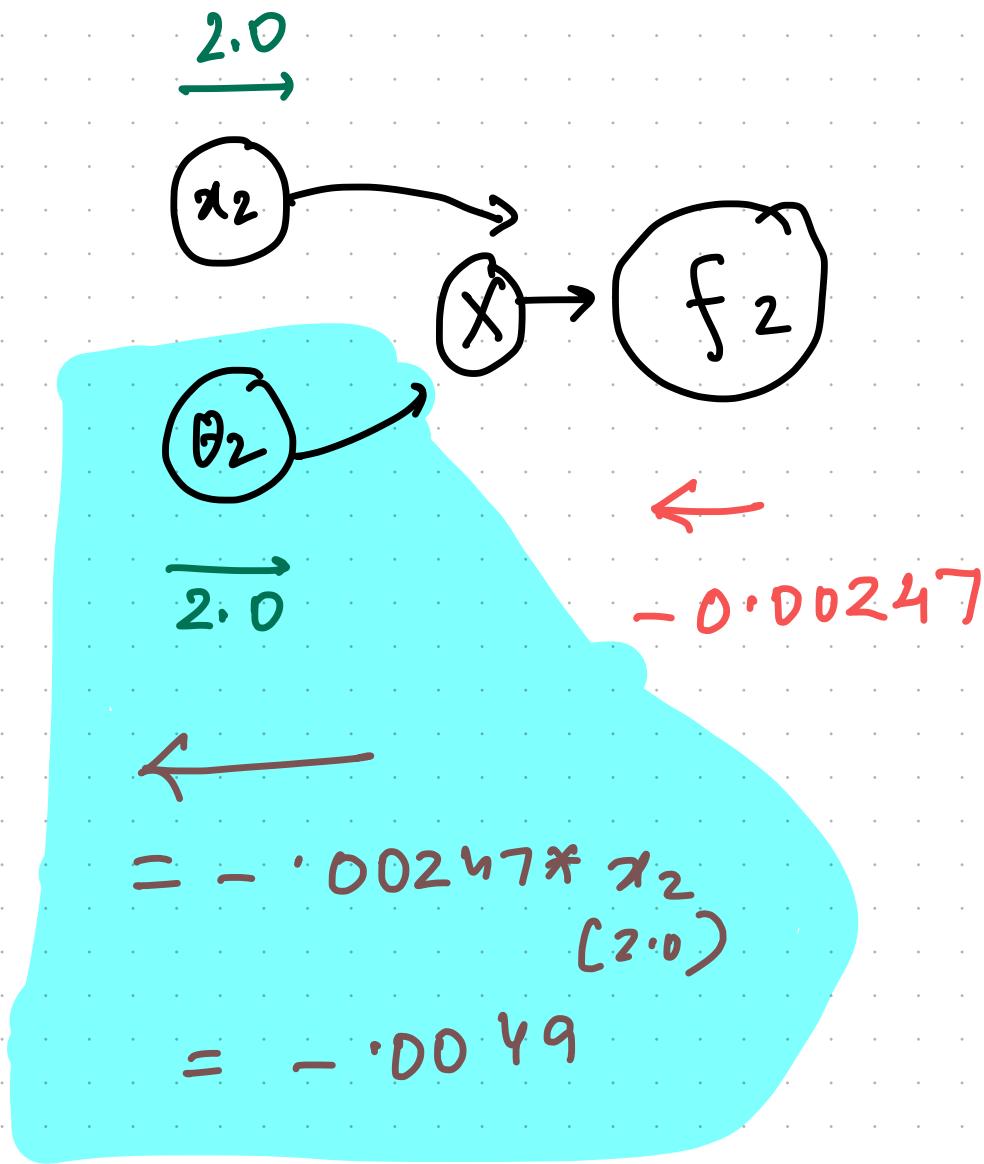
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What autodiff library needs to know

(i) $f = a * b ; \frac{\partial f}{\partial a} = b ; \frac{\partial f}{\partial b} = a$

(ii) $f = a + b ; \frac{\partial f}{\partial a} = \frac{\partial f}{\partial b} = 1$

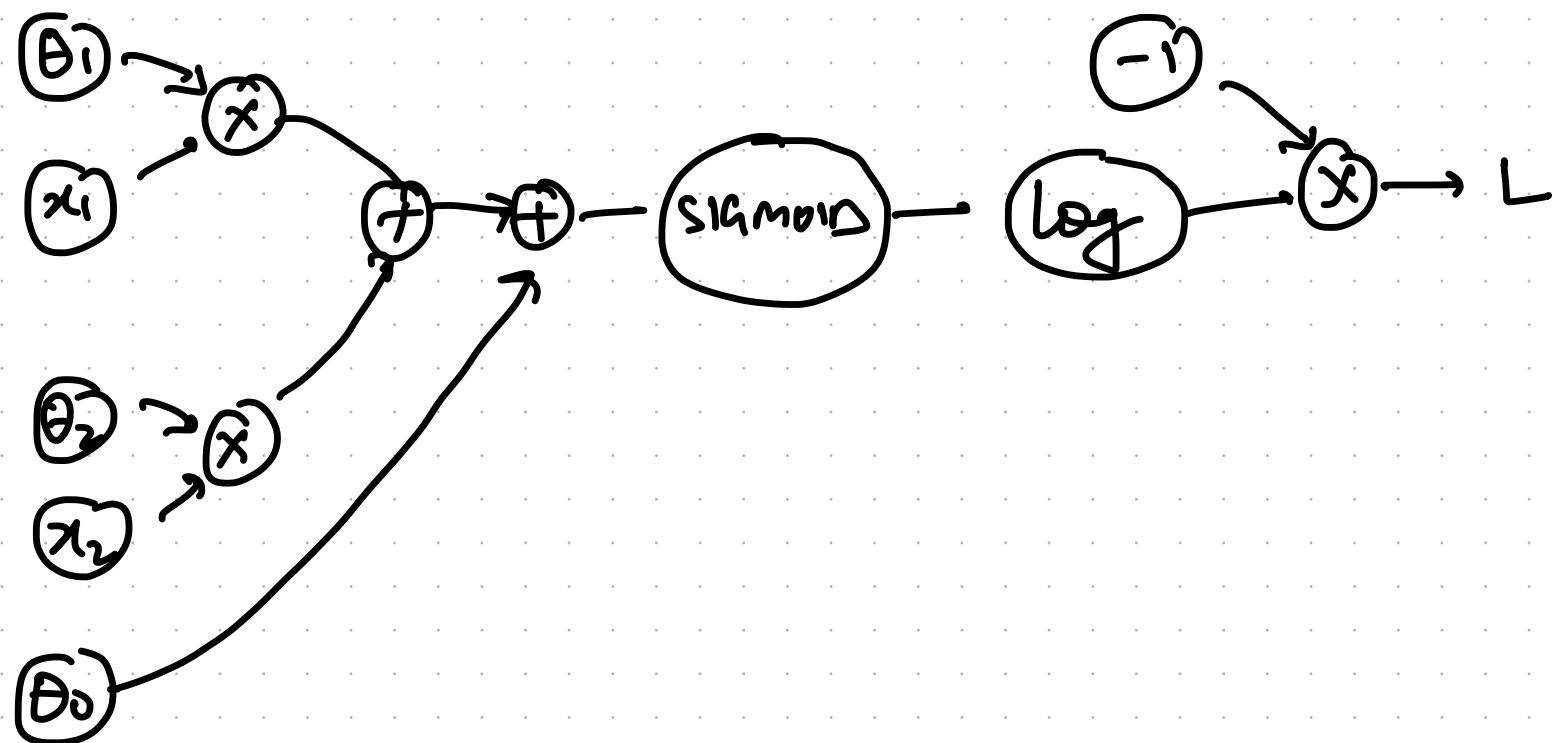
(iii) $f = e^a ; \frac{\partial f}{\partial a} = e^a$

(iv) $f = \frac{1}{a} ; \frac{\partial f}{\partial a} = -1/a^2$

:

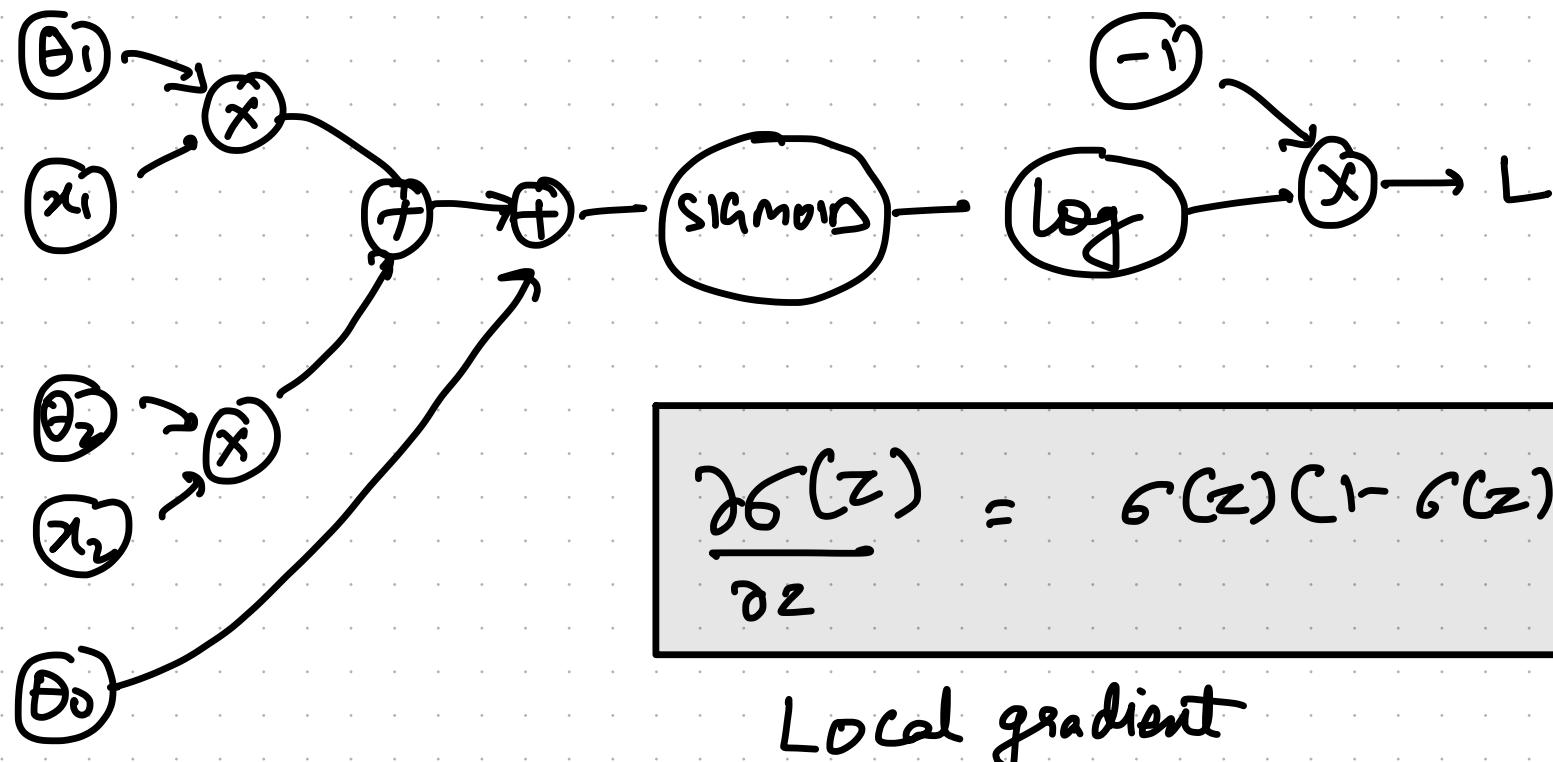
Simplifying Computational graph

$$L = -1 \times \log (\text{SIGMOID}(\theta_0 + \theta_1 x_1 + \theta_2 x_2))$$



* Simplifying computational graph

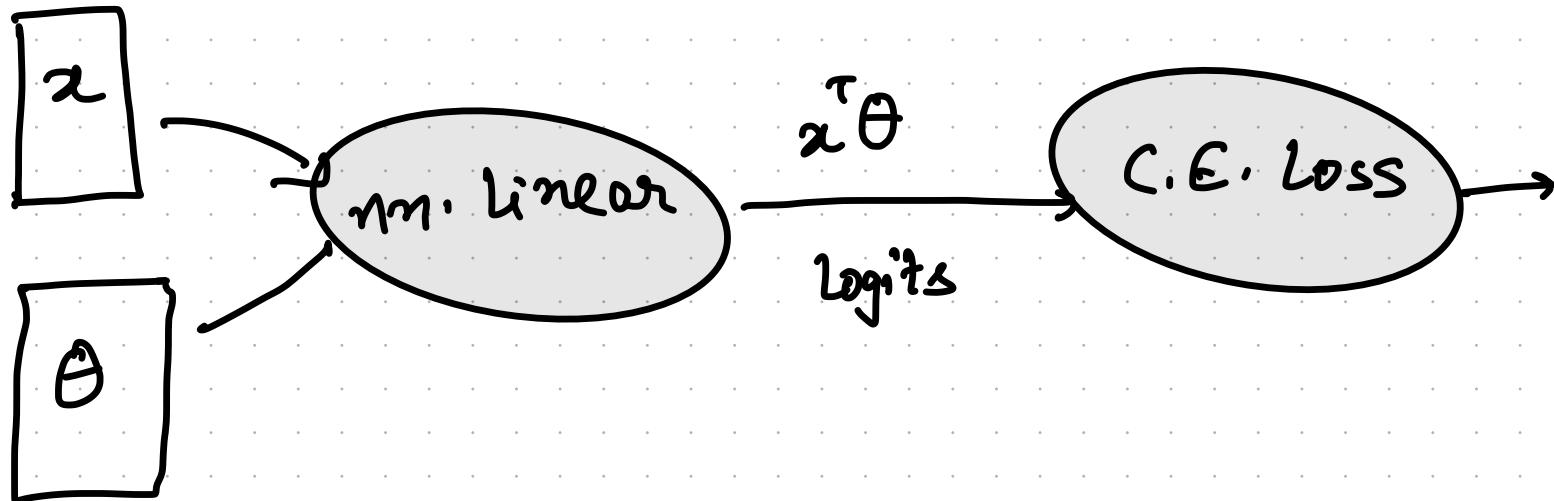
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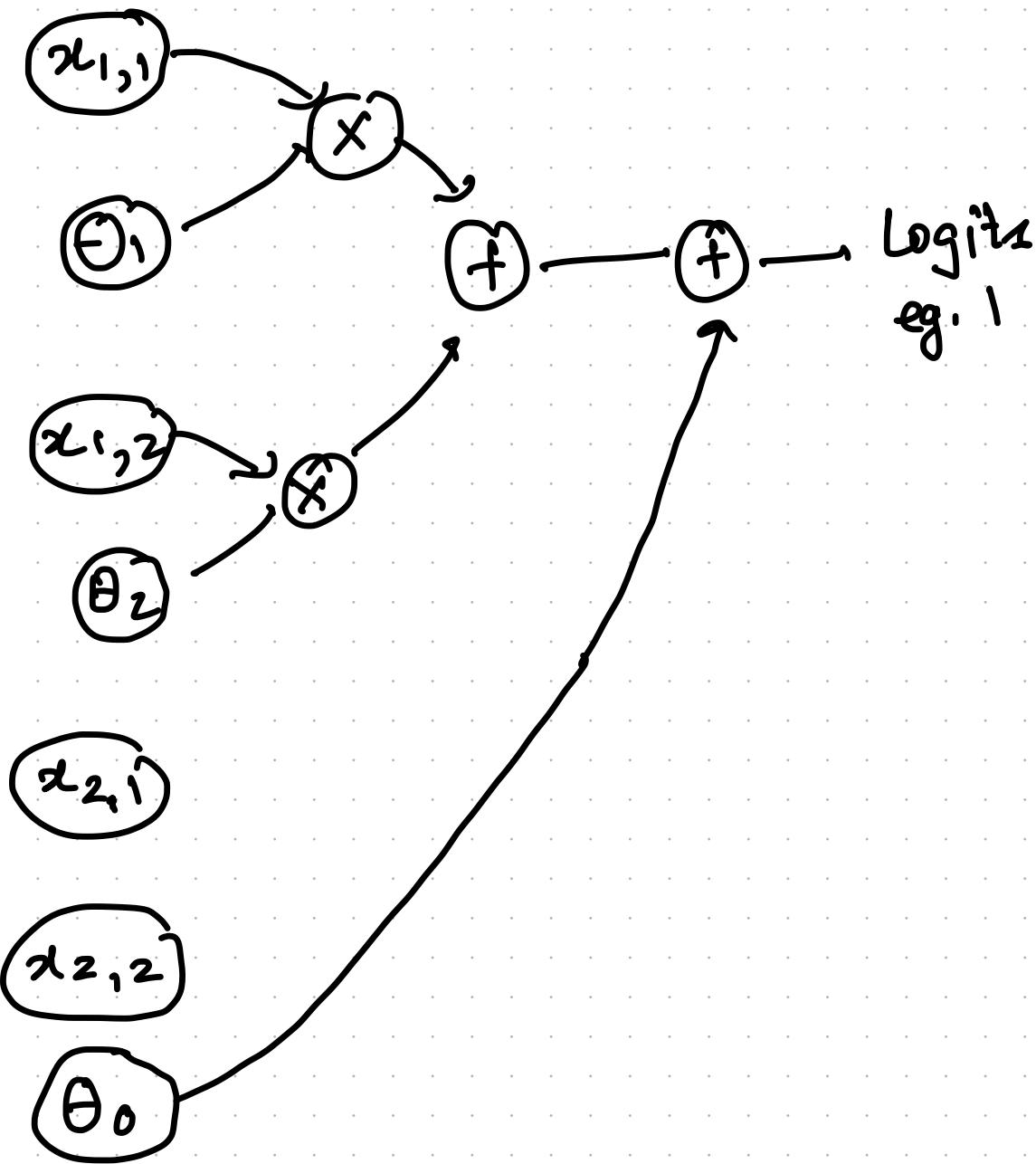
Exercise: Show you get same answer
as before

* Simplifying computational graph

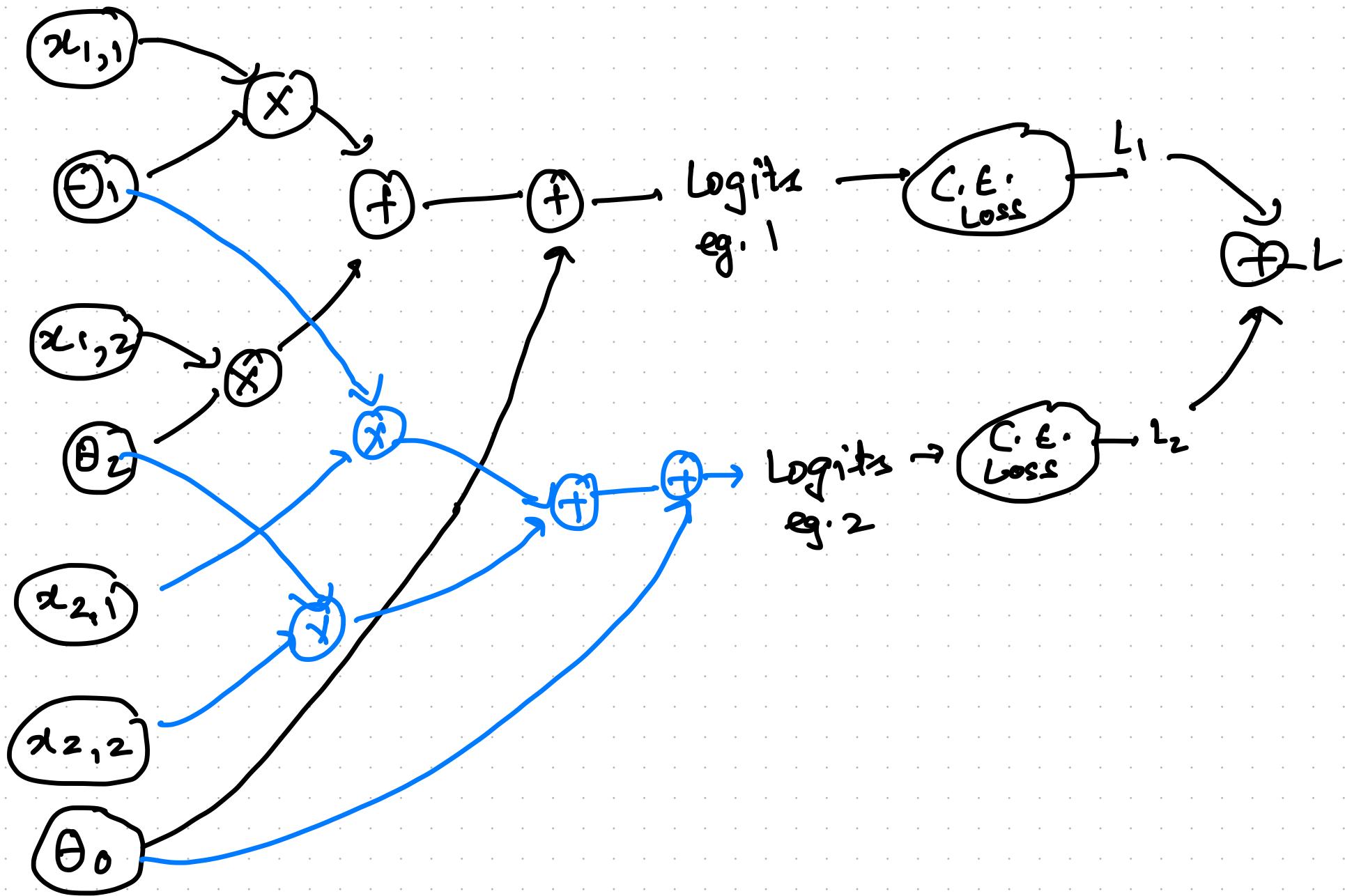
$$L = -1 \times \log (\text{SIGMOID}(\theta_0 + \theta_1 x_1 + \theta_2 x_2))$$



* Training over N examples



* Training over N examples



* Training over Nr examples

Chain Rule for One Independent Variable

Suppose that $x = g(t)$ and $y = h(t)$ are differentiable functions of t and $z = f(x, y)$ is a differentiable function of x and y . Then $z = f(x(t), y(t))$ is a differentiable function of t and

$$\frac{dz}{dt} = \frac{\partial z}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial z}{\partial y} \cdot \frac{dy}{dt},$$

where the ordinary derivatives are evaluated at t and the partial derivatives are evaluated at (x, y) .

* Training over Nr examples

Chain Rule for One Independent Variable

Suppose that $x = g(t)$ and $y = h(t)$ are differentiable functions of t and $z = f(x, y)$ is a differentiable function of x and y . Then $z = f(x(t), y(t))$ is a differentiable function of t and

$$\frac{dz}{dt} = \frac{\partial z}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial z}{\partial y} \cdot \frac{dy}{dt},$$

where the ordinary derivatives are evaluated at t and the partial derivatives are evaluated at (x, y) .

$$L = L_1 + L_2$$

$$L_1 = x_1 \theta$$

$$L_2 = x_2 \theta$$

* Training over Nr examples

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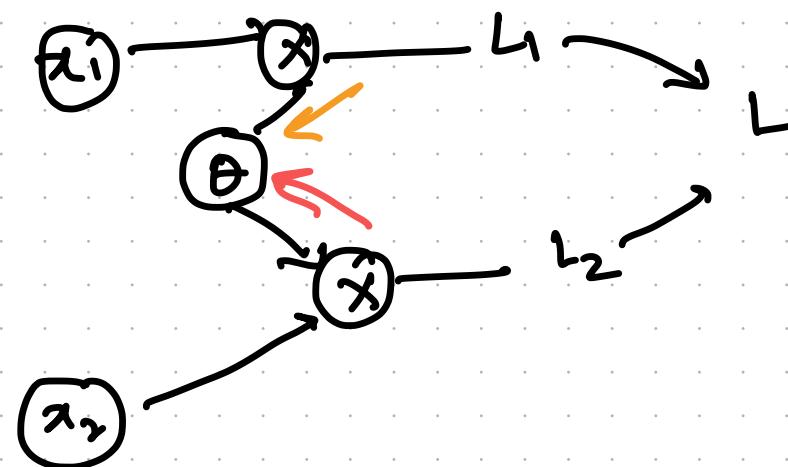
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$$\frac{\partial L}{\partial \theta} = \text{orange arrow} + \text{red arrow}$$

Addition of all incoming gradients