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IIT Gandhinagar

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# **Setup**

• Output is continuous in nature.

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- Examples of linear systems:

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  - F = ma

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- Examples of linear systems:
  - F = ma
  - v = u + at

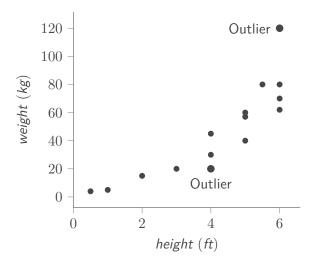
#### Task at hand

TASK: Predict Weight = f(height)

Height	Weight
3	29
4	35
5	39
2	20
6	41
7	?
8	?
1	?

The first part of the dataset is the training points. The latter ones are testing points.

### Scatter Plot



- $weight_1 pprox \theta_0 + \theta_1 \cdot height_1$
- $weight_2 \approx \theta_0 + \theta_1 \cdot height_2$
- $weight_N \approx \theta_0 + \theta_1 \cdot height_N$

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weight<sub>i</sub> 
$$\approx \theta_0 + \theta_1 \cdot height_i$$

$$\begin{bmatrix} weight_1 \\ weight_2 \\ \dots \\ weight_N \end{bmatrix} = \begin{bmatrix} 1 & height_1 \\ 1 & height_2 \\ \dots & \dots \\ 1 & height_N \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$$

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 $\hat{\mathbf{v}}_{n\times 1} = \mathbf{X}_{n\times d}\boldsymbol{\theta}_{d\times 1}$ 

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$$\hat{\mathbf{y}}_{n \times 1} = \mathbf{X}_{n \times d} \boldsymbol{\theta}_{d \times 1}$$

•  $\theta_0$  - Bias Term/Intercept Term

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$$\hat{\mathbf{y}}_{n\times 1} = \mathbf{X}_{n\times d}\boldsymbol{\theta}_{d\times 1}$$

- $\theta_0$  Bias Term/Intercept Term
- $\theta_1$  Slope

In the previous example y = f(x), where x is one-dimensional.

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Demand = f(# occupants, Temperature)

 $\mathsf{Demand} = \mathsf{Base} \ \mathsf{Demand} \ + \ \mathsf{K}_1 \ * \ \# \ \mathsf{occupants} \ + \ \mathsf{K}_2 \ * \ \mathsf{Temperature}$ 

#### Intuition

#### We hope to:

- Learn f: Demand = f(#occupants, Temperature)
- From training dataset
- To predict the condition for the testing set

• 
$$x_i = \begin{bmatrix} Temperature_i \\ \#Occupants_i \end{bmatrix}$$

#### We have

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• Estimated demand for  $i^{th}$  sample is  $demand_i = \theta_0 + \theta_1 Temperature_i + \theta_2 Occupants_i$ 

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 Notice the transpose in the equation! This is because x<sub>i</sub> is a column vector



### We can expect the following

- Demand increases, if # occupants increases, then  $\theta_2$  is likely to be positive

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- Demand increases, if # occupants increases, then  $\theta_2$  is likely to be positive
- Demand increases, if temperature increases, then  $\theta_1$  is likely to be positive
- Base demand is independent of the temperature and the # occupants, but, likely positive, thus  $\theta_0$  is likely positive.

# **Normal Equation**

Assuming N samples for training

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$$\begin{bmatrix} \hat{y_1} \\ \hat{y_2} \\ \vdots \\ \hat{y_N} \end{bmatrix}_{N \times 1} = \begin{bmatrix} 1 & x_{1,1} & x_{1,2} & \dots & x_{1,M} \\ 1 & x_{2,1} & x_{2,2} & \dots & x_{2,M} \\ \vdots & \vdots & \vdots & \dots & \vdots \\ 1 & x_{N,1} & x_{N,2} & \dots & x_{N,M} \end{bmatrix}_{N \times (M+1)} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_M \end{bmatrix}_{(M+1) \times 1}$$

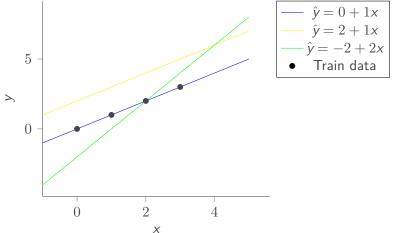
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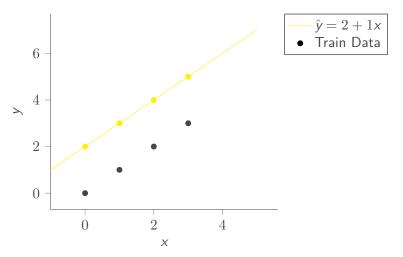
$$\hat{\mathbf{y}} = \mathbf{X}\boldsymbol{\theta}$$

- There could be different  $\theta_0, \theta_1 \dots \theta_M$ . Each of them can represents a relationship.
- Given multiples values of  $\theta_0, \theta_1 \dots \theta_M$  how to choose which is the best?
- · Let us consider an example in 2d

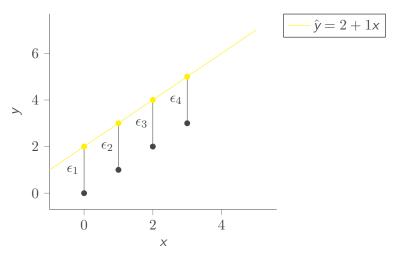
Out of the three fits, which one do we choose?



We have  $\hat{y} = 2 + 1x$  as one relationship.



How far is our estimated  $\hat{y}$  from ground truth y?



• 
$$y_i = \hat{y}_i + \epsilon_i$$
 where  $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$ 

- $y_i = \hat{y}_i + \epsilon_i$  where  $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
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- $\theta_0, \theta_1$ : The parameters of the linear regression
- $\epsilon_i = y_i \hat{y}_i$
- $\epsilon_i = y_i (\theta_0 + x_i \cdot \theta_1)$

### Good fit

•  $|\epsilon_1|$ ,  $|\epsilon_2|$ ,  $|\epsilon_3|$ , ... should be small.

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- minimize  $\epsilon_1^2 + \epsilon_2^2 + \cdots + \epsilon_N^2$   $L_2$  Norm
- minimize  $|\epsilon_1| + |\epsilon_2| + \cdots + |\epsilon_n|$   $L_1$  Norm

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To Learn:  $\theta$ 

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Objective: minimize  $\epsilon_1^2 + \epsilon_2^2 + \cdots + \epsilon_N^2$ 

$$oldsymbol{\epsilon} = egin{bmatrix} \epsilon_1 \ \epsilon_2 \ \vdots \ \epsilon_N \end{bmatrix}$$

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Objective: Minimize  $\epsilon^{\top}\epsilon$ 

## Derivation of Normal Equation

$$egin{aligned} oldsymbol{\epsilon} &= \mathbf{y} - \mathbf{X} oldsymbol{ heta} \\ oldsymbol{\epsilon}^{ op} oldsymbol{\epsilon} &= (\mathbf{y} - \mathbf{X} oldsymbol{ heta})^{ op} (\mathbf{y} - \mathbf{X} oldsymbol{ heta}) \\ &= \mathbf{y}^{ op} \mathbf{y} - 2 \mathbf{y}^{ op} \mathbf{X} oldsymbol{ heta} + oldsymbol{ heta}^{ op} \mathbf{X}^{ op} \mathbf{X} oldsymbol{ heta} \end{aligned}$$

This is what we wish to minimize

# Minimizing the objective function

$$\frac{\partial \boldsymbol{\epsilon}^{\top} \boldsymbol{\epsilon}}{\partial \boldsymbol{\theta}} = 0$$

- $\frac{\partial}{\partial \boldsymbol{\theta}} \mathbf{y}^{\top} \mathbf{y} = 0$
- $\frac{\partial}{\partial \boldsymbol{\theta}} (-2\mathbf{y}^{\top} \mathbf{X} \boldsymbol{\theta}) = -2\mathbf{X}^{\top} \mathbf{y}$
- $\frac{\partial}{\partial \boldsymbol{\theta}} (\boldsymbol{\theta}^{\top} \mathbf{X}^{\top} \mathbf{X} \boldsymbol{\theta}) = 2 \mathbf{X}^{\top} \mathbf{X} \boldsymbol{\theta}$

Substitute the values in the top equation

# Normal Equation derivation

$$0 = -2\mathbf{X}^{\top}\mathbf{y} + 2\mathbf{X}^{\top}\mathbf{X}\boldsymbol{\theta}$$

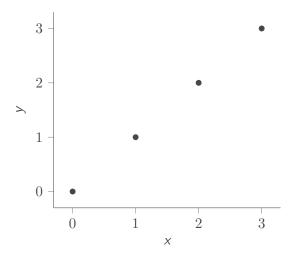
$$\mathbf{X}^{\top}\mathbf{y} = \mathbf{X}^{\top}\mathbf{X}\boldsymbol{\theta}$$

$$\hat{\boldsymbol{\theta}}_{\textit{OLS}} = (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{y}$$

	Х	У
П	0	0
	1	1
	2	2
	3	3

Given the data above, find  $\theta_0$  and  $\theta_1$ .

# Scatter Plot



$$\mathbf{X} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix}$$
$$\mathbf{X}^{\top} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{bmatrix}$$
$$\mathbf{X}^{\top} \mathbf{X} = \begin{bmatrix} 4 & 6 \\ 6 & 14 \end{bmatrix}$$

Given the data above, find  $\theta_0$  and  $\theta_1$ .

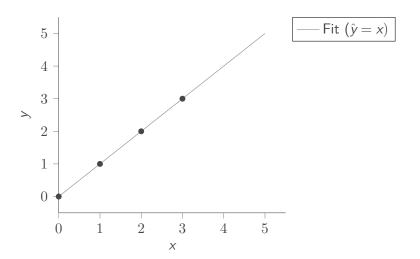
$$(\mathbf{X}^{\top}\mathbf{X})^{-1} = \frac{1}{20} \begin{bmatrix} 14 & -6 \\ -6 & 4 \end{bmatrix}$$

$$\mathbf{X}^{\top}\mathbf{y} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 6 \\ 14 \end{bmatrix}$$

$$\boldsymbol{\theta} = (\mathbf{X}^{\top}\mathbf{X})^{-1}(\mathbf{X}^{\top}\mathbf{y})$$

$$\begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} = \frac{1}{20} \begin{bmatrix} 14 & -6 \\ -6 & 4 \end{bmatrix} \begin{bmatrix} 6 \\ 14 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

### Scatter Plot

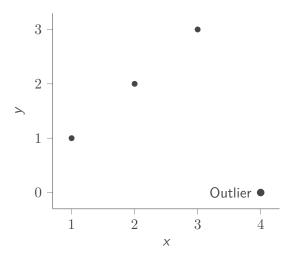


### Effect of outlier

X	У
1	1
2	2
3	3
4	0

Compute the  $\theta_0$  and  $\theta_1$ .

# Scatter Plot



$$\mathbf{X} = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{bmatrix}$$
$$\mathbf{X}^{\top} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \end{bmatrix}$$
$$\mathbf{X}^{\top} \mathbf{X} = \begin{bmatrix} 4 & 10 \\ 10 & 30 \end{bmatrix}$$

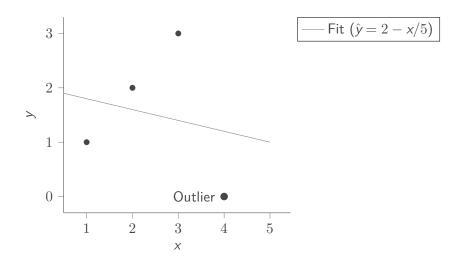
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$$(\mathbf{X}^{\top}\mathbf{X})^{-1} = \frac{1}{20} \begin{bmatrix} 30 & -10 \\ -10 & 4 \end{bmatrix}$$
$$\mathbf{X}^{\top}\mathbf{y} = \begin{bmatrix} 6 \\ 14 \end{bmatrix}$$

$$\boldsymbol{\theta} = (\mathbf{X}^{\top}\mathbf{X})^{-1}(\mathbf{X}^{\top}\mathbf{y})$$

$$\begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} = \begin{bmatrix} 2 \\ (-1/5) \end{bmatrix}$$

### Scatter Plot



# **Basis Expansion**

Transform the data, by including the higher power terms in the feature space.

t	S
0	0
1	6
3	24
4	36

The above table represents the data before transformation

Add the higher degree features to the previous table

t	$t^2$	S
0	0	0
1	1	6
3	9	24
4	16	36

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The above table represents the data after transformation Now, we can write  $\hat{s} = f(t, t^2)$ Other transformations:  $\log(x), x_1 \times x_2$ 

1. 
$$\hat{s} = \theta_0 + \theta_1 * t$$
 is linear

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$$\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2$$
 linear?

- 1.  $\hat{s} = \theta_0 + \theta_1 * t$  is linear
- 2. Is  $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2$  linear?
- 3. Is  $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2 + \theta_3 * \cos(t^3)$  linear?

¹https://stats.stackexchange.com/questions/8689/ what-does-linear-stand-for-in-linear-regression ⊕ → ⟨ ᢓ → ⟨ ᢓ → ⟨

- 1.  $\hat{s} = \theta_0 + \theta_1 * t$  is linear
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- 4. Is  $\hat{s} = \theta_0 + \theta_1 * t + e^{\theta_2} * t$  linear?

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- 4. Is  $\hat{s} = \theta_0 + \theta_1 * t + e^{\theta_2} * t$  linear?
- 5. All except #4 are linear models!

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# A big caveat: Linear in what?!<sup>1</sup>

- 1.  $\hat{s} = \theta_0 + \theta_1 * t$  is linear
- 2. Is  $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2$  linear?
- 3. Is  $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2 + \theta_3 * \cos(t^3)$  linear?
- 4. Is  $\hat{s} = \theta_0 + \theta_1 * t + e^{\theta_2} * t$  linear?
- 5. All except #4 are linear models!
- 6. Linear refers to the relationship between the parameters that you are estimating  $(\theta)$  and the outcome

¹https://stats.stackexchange.com/questions/8689/ what-does-linear-stand-for-in-linear-regression ♂ → ⟨ ② → ⟨ ○ →

#### **Basis Functions**

- Linear regression only refers to linear in the parameters
- We can perform an arbitrary nonlinear transformation  $\phi(x)$  of the inputs x and then linearly combine the components of this transformation.
- $\phi: \mathbb{R}^D \to \mathbb{R}^K$  is called the basis function

#### **Basis Functions**

#### Some examples of basis functions:

- Polynomial basis:  $\phi(x) = \{1, x, x^2, x^3, \dots\}$
- Fourier basis:  $\phi(x) = \{1, \sin(x), \cos(x), \sin(2x), \cos(2x), \dots\}$
- Gaussian basis:

$$\phi(x) = \{1, \exp(-\frac{(x-\mu_1)^2}{2\sigma^2}), \exp(-\frac{(x-\mu_2)^2}{2\sigma^2}), \dots\}$$

• Sigmoid basis:  $\phi(x)=\{1,\sigma(x-\mu_1),\sigma(x-\mu_2),\dots\}$  where  $\sigma(x)=\frac{1}{1+e^{-x}}$ 

#### Linear Combination of Vectors

Let  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_i$  be vectors in  $\mathbb{R}^D$ , where D denotes the dimensions.

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A linear combination of  $v_1, v_2, v_3, \ldots, v_i$  is of the following form

$$\alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2 + \alpha_3 \mathbf{v}_3 + \cdots + \alpha_i \mathbf{v}_i$$

where  $\alpha_1, \alpha_2, \alpha_3, \dots, \alpha_i \in \mathbb{R}$ 

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Let  $v_1, v_2, \ldots, v_i$  be vectors in  $\mathbb{R}^D$ , with D dimensions. The span of  $v_1, v_2, \ldots, v_i$  is denoted by  $\mathsf{SPAN}\{v_1, v_2, \ldots, v_i\}$ 

$$\{\alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2 + \dots + \alpha_i \mathbf{v}_i \mid \alpha_1, \alpha_2, \dots, \alpha_i \in \mathbb{R}\}$$

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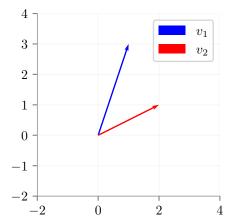
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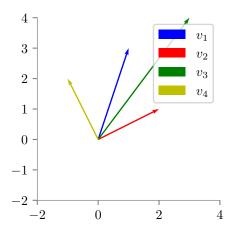
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If we stack the vectors  $v_1, v_2, \ldots, v_i$  as columns of a matrix V, then the span of  $v_1, v_2, \ldots, v_i$  is given as  $V\alpha$  where  $\alpha \in \mathbb{R}^i$ 

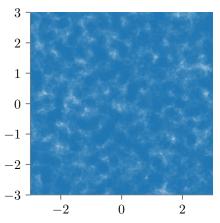
Find the span of  $(\begin{bmatrix}1\\3\end{bmatrix},\begin{bmatrix}2\\1\end{bmatrix})$ 





We have  $v_3 = v_1 + v_2$ We have  $v_4 = v_1 - v_2$ 

Simulating the above example in python using different values of  $\alpha_1$  and  $\alpha_2$ 



$$\mathsf{Span}((\mathit{v}_1,\mathit{v}_2)) \in \mathcal{R}^2$$



Find the span of  $(\begin{bmatrix}1\\2\end{bmatrix},\begin{bmatrix}2\\4\end{bmatrix})$ 

Find the span of  $\begin{bmatrix}1\\2\end{bmatrix},\begin{bmatrix}2\\4\end{bmatrix}$ ) Can we obtain a point (x, y) s.t. x = 3y?

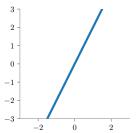
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Find the span of \left(\begin{bmatrix}1\\2\end{bmatrix},\begin{bmatrix}2\\4\end{bmatrix}\right) Can we obtain a point (x, y) s.t. x = 3y? No
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Find the span of  $\begin{pmatrix} 1\\2 \end{pmatrix}, \begin{pmatrix} 2\\4 \end{pmatrix}$ )

Can we obtain a point (x, y) s.t. x = 3y?

No

Span of the above set is along the line y=2x



Find the span of ( 
$$\begin{bmatrix} 1\\1\\1 \end{bmatrix}$$
 ,  $\begin{bmatrix} 2\\-2\\2 \end{bmatrix}$  )

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• Origin

•  $X_1 = [1,1,1]$ 
•  $X_2 = [2,-2,2]$ 

•  $X_3 = [2,-2,2]$ 
•  $X_4 = [2,-2]$ 
•  $X_4 =$ 

1.5 x

2.0

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The span is the plane z = x or  $x_3 = x_1$ 

1.5 2.0

Consider X and y as follows.

$$\mathbf{X} = \begin{pmatrix} 1 & 2 \\ 1 & -2 \\ 1 & 2 \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} 8.8957 \\ 0.6130 \\ 1.7761 \end{pmatrix}$$

• We are trying to learn  $m{ heta}$  for  $\hat{\mathbf{y}}=\mathbf{X}m{ heta}$  such that  $||\mathbf{y}-\hat{\mathbf{y}}||_2$  is minimised

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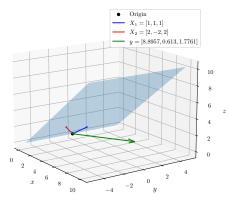
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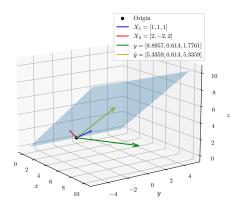
• We wish to find  $\hat{y}$  such that

$$\mathop{\arg\min}_{\hat{\mathbf{y}} \in \textit{SPAN}\{\bar{x_1}, \bar{x_2}, \dots, \bar{x_D}\}} ||\mathbf{y} - \hat{\mathbf{y}}||_2$$

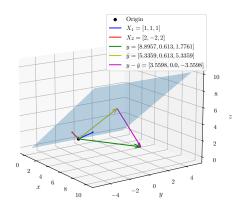


Span of 
$$\left(\begin{bmatrix}1\\1\\1\end{bmatrix},\begin{bmatrix}2\\-2\\2\end{bmatrix}\right)$$

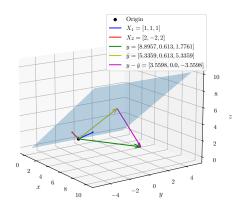




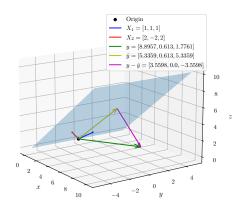
- We seek a  $\hat{\boldsymbol{y}}$  in the span of the columns of  $\boldsymbol{X}$  such that it is closest to  $\boldsymbol{y}$ 



• This happens when  $\mathbf{y} - \hat{\mathbf{y}} \perp \mathbf{x}_j \forall j$  or  $\mathbf{x}_i^{\top} (\mathbf{y} - \hat{\mathbf{y}}) = 0$ 



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- $\mathbf{X}^{\top}\mathbf{y} = \mathbf{X}^{\top}\mathbf{X}\boldsymbol{\theta}$  or  $\hat{\boldsymbol{\theta}} = (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{y}$



# Dummy Variables and Multicollinearity

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The matrix X is not full rank.

It arises when one or more predictor variables/features in  $\boldsymbol{X}$  can be expressed as a linear combination of others

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- Avoid dummy variable trap

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Can we use the direct encoding? Then this implies that S>W>E>N

N-1 Variable encoding

	Is it N?	Is it E?	Is it W?
N	1	0	0
Е	0	1	0
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N Variable encoding

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Is it S = 1 - (Is it N + Is it W + Is it E)

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Е	01
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This introduces dependencies between them, and this can cause confusion in classifiers.

Gender	height
F	
F	
F	
M	
M	

Gender	height
F	
F	
F	
Μ	
М	

Encoding

Gender	height
F	
F	
F	
M	
M	

#### Encoding

Is Female	height
1	
1	
1	
0	
0	

Is Female	height
1	5
1	5.2
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Now,  $\theta_0$  can be interpreted as average person height.  $\theta_1$  as the amount that female height is above average and male height is below average.

# **Practice and Review**

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