

# Communication Networks in Modern Vehicles



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**1. Relationship between car crashes and the lack of ADAS integration in modern vehicles**

**2. Ensuring accuracy when displaying the real-time changes in the vehicular surroundings on driver-assistance systems**

**3. Comprehensive testing of ADAS functionalities in simulators**

**4. Reduction in crash potential with the incorporation of ADAS technology**

# Introduction to ADAS Technology

## Evolution

- Closely linked to advancements in sensor technology, computer vision

## Benefits

- 17% reduction in collision rates compared to those without these features <sup>[1]</sup>
- 27% reduction in rear-end collisions<sup>[1]</sup>

## Challenges

- Sensor reliability in adverse weather
- False positives



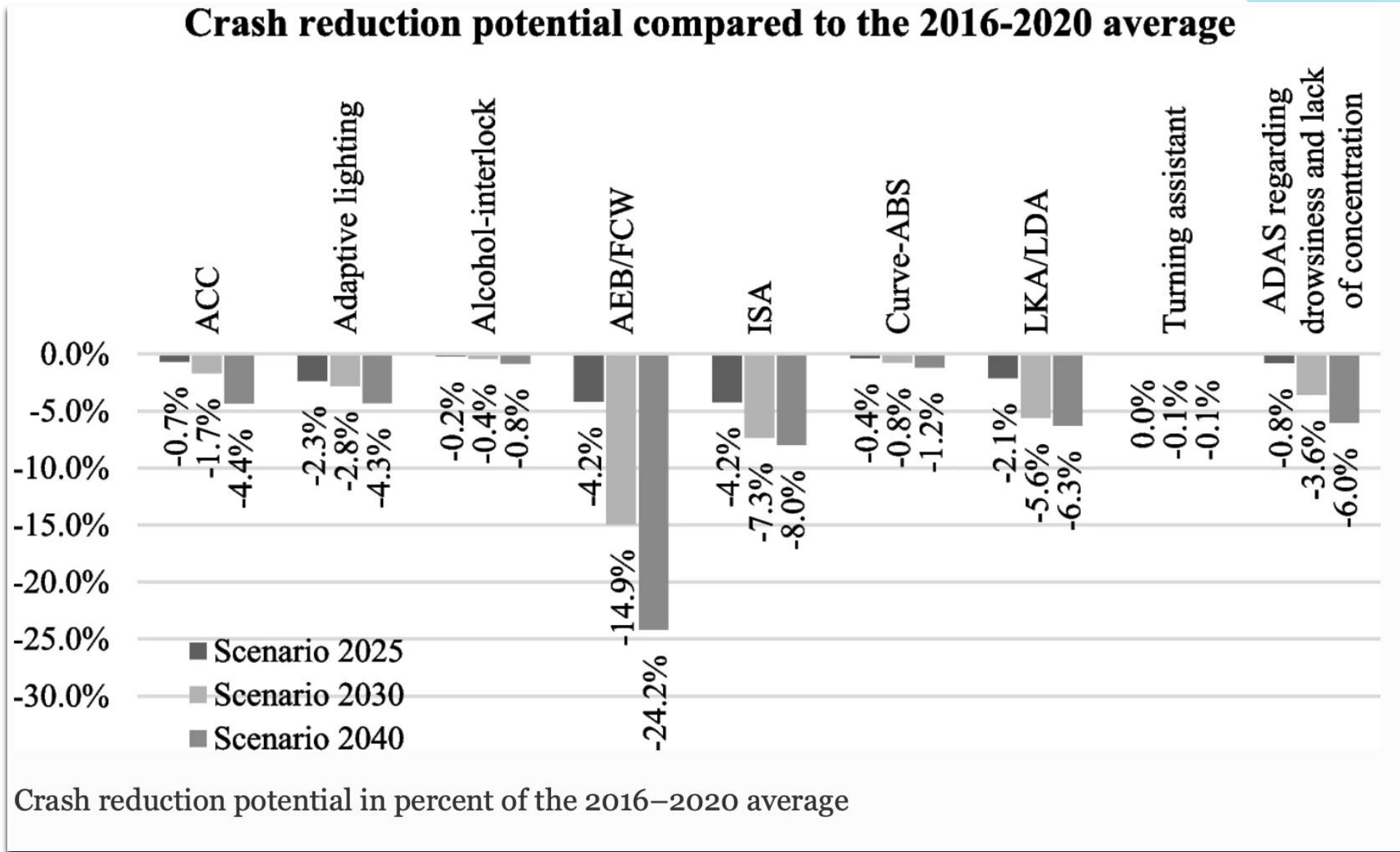


Figure 1: Crash Reduction Potential Compared to 2016-2020 Average <sup>[1]</sup>

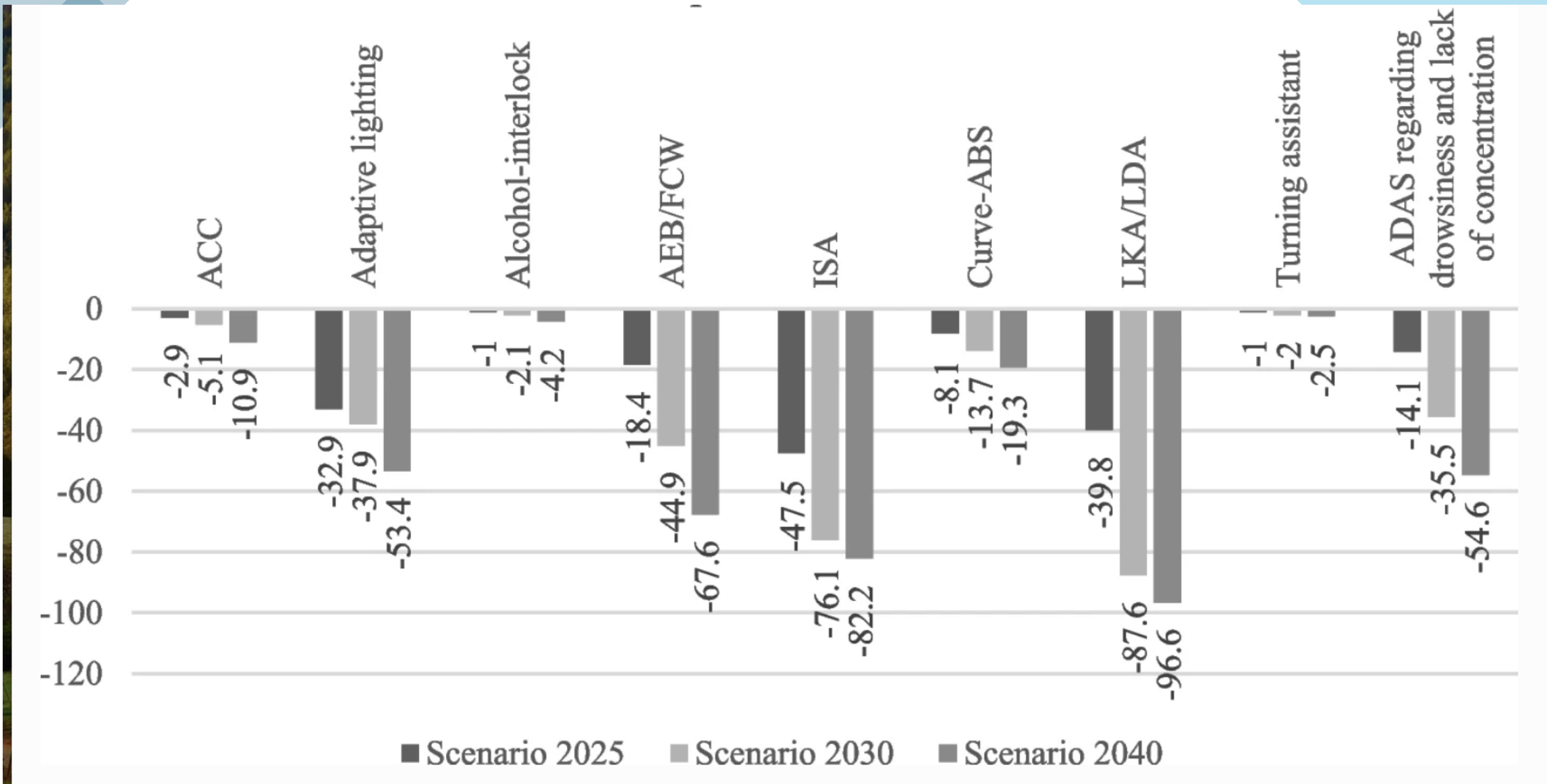


Figure 2: Reduction Potential in Fatalities<sup>[1]</sup>

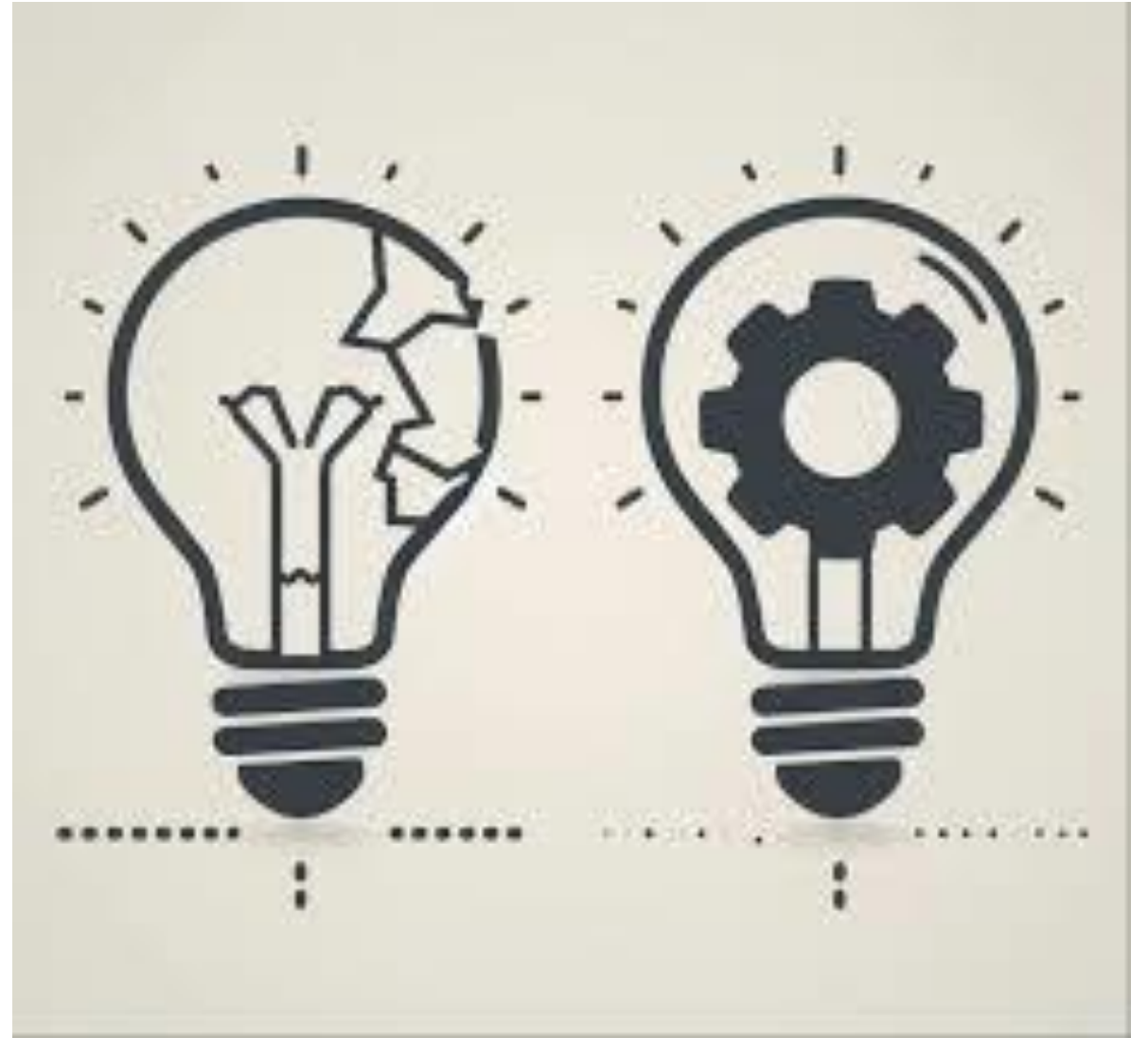
# Introduction to ADAS Technology: Important Finding

## Role of Sensor Fusion in Enhancing Accuracy

- Combines data from LiDAR, radar, cameras for enhanced accuracy
- Improves spatial awareness, reducing false positives

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With growing ADAS integration and increasing traffic complexity, there's a clear need for precise real-world rendering in vehicles to improve spatial awareness.

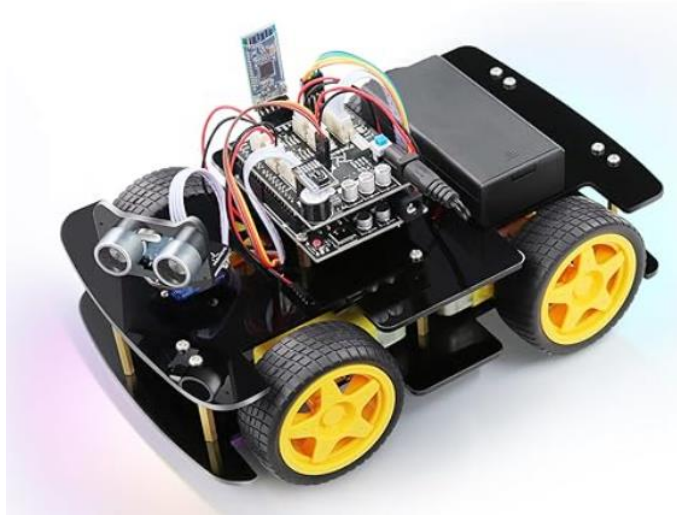


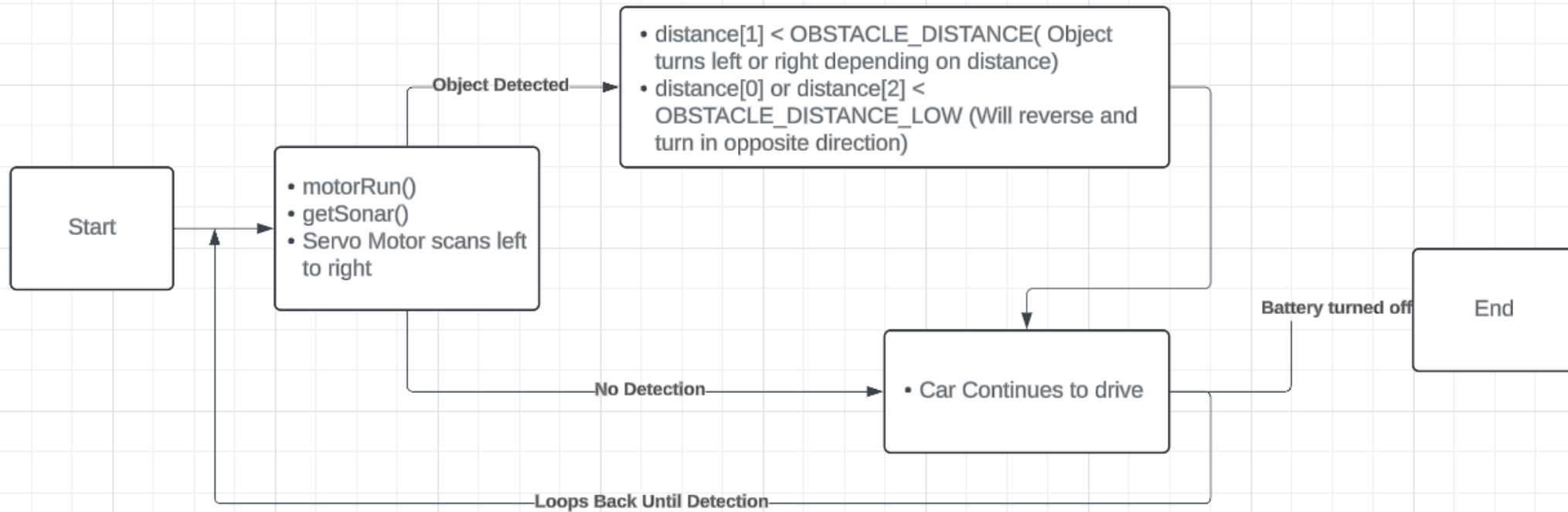


# Stakeholders and Targeted Audience

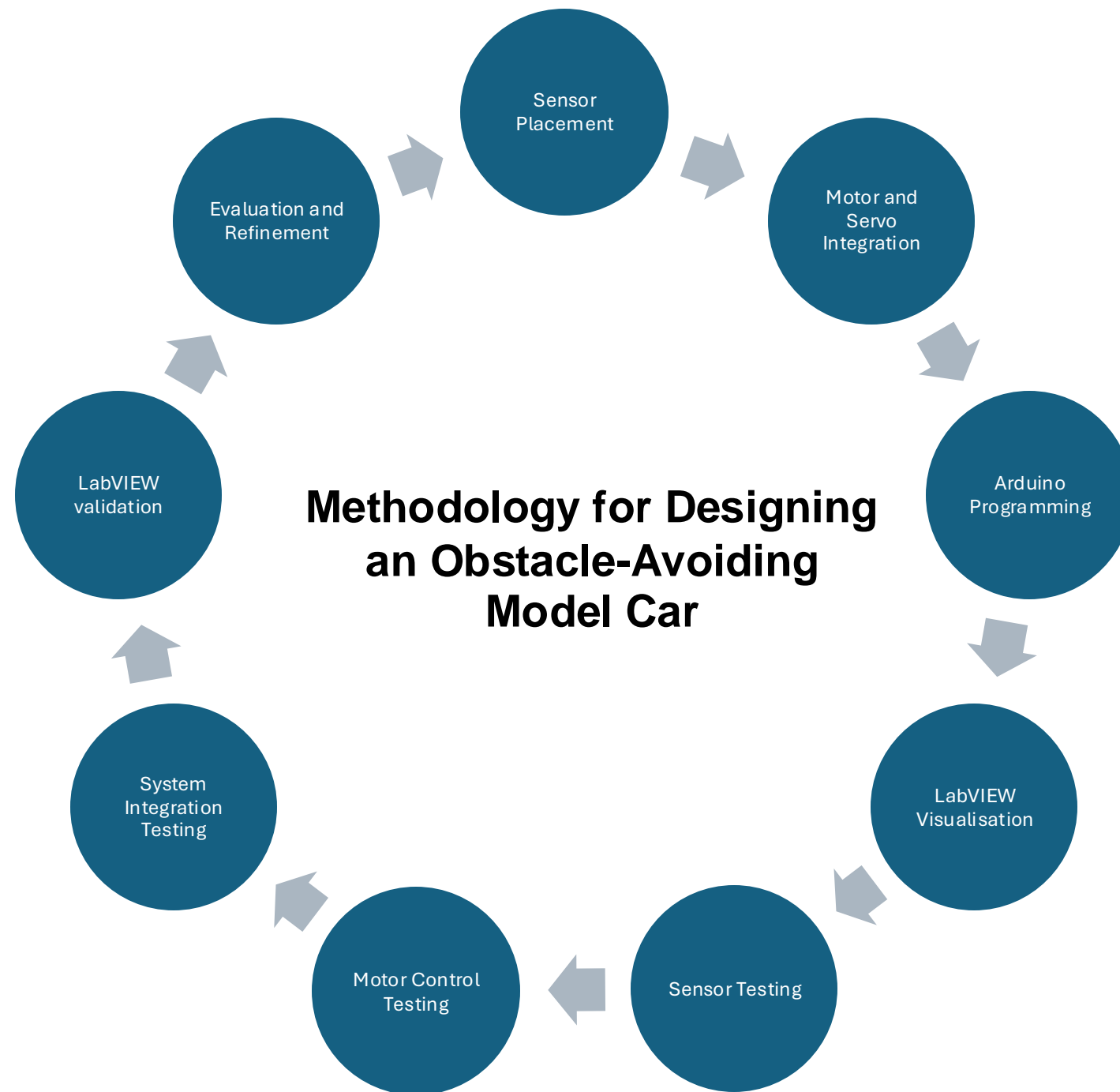


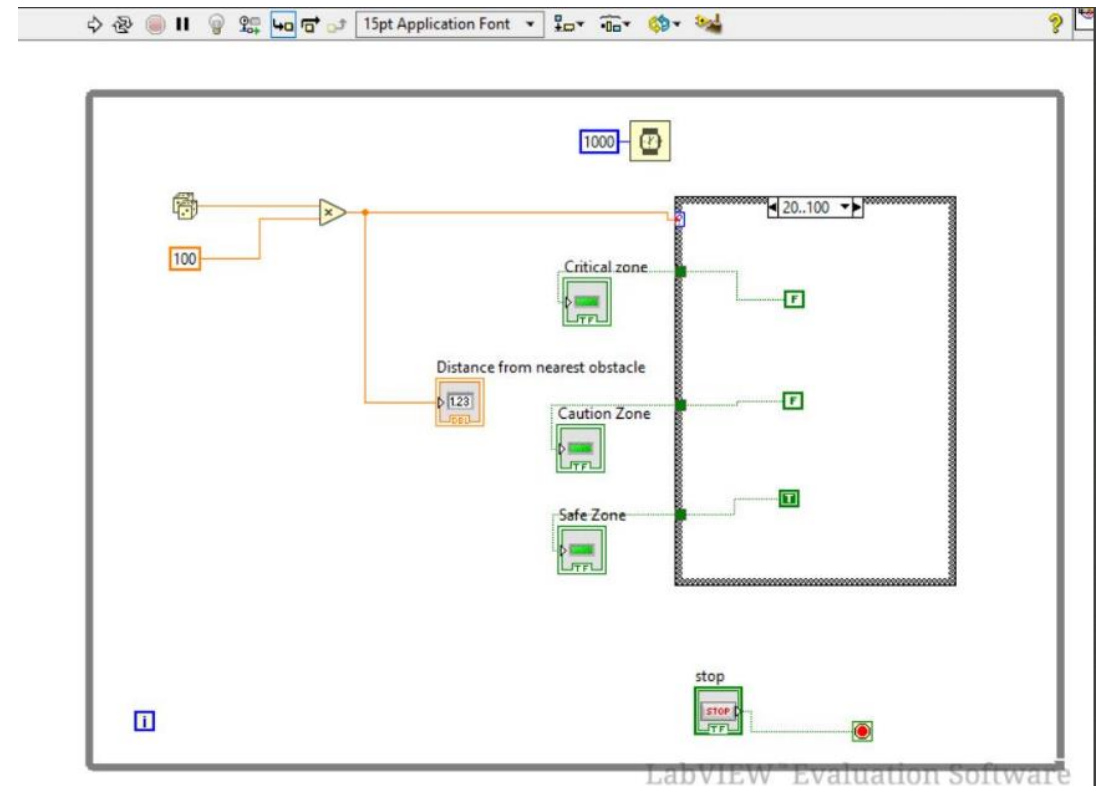
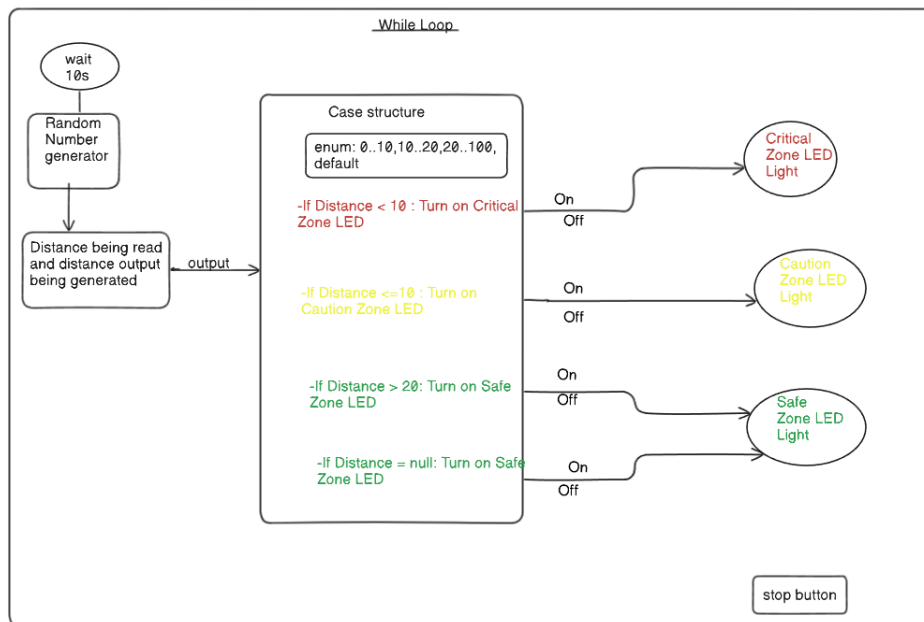
## Resources Required





**Figure 3:** Sensor Integration and Data Collection Logic [2]







	Assigned To	Week 1	Week 2	Week 3	Week 4	Week 5	Week 6	Week 7	Week 8	Week 9	Week 10	Week 11	Week 12
<b>Planning</b>													
Defining Project Goals and deliverables	All Members												
Making project plan and timeline	All Members												
Resources allocation and responsibilities assignment	All Members												
<b>Concept Development</b>													
Research and conceptualize	All Members												
Develop initial prototypes	Jordan, Lomi												
Gather feedbacks and refine concepts	All Members												
<b>System Level Design</b>													
Design sensor detection system	Jordan, Lomi												
Plan head unit display and data flow	Alisha, Abid												
Define component interaction	All Members												
<b>Detailed Design</b>													
Detailed schematics and documents	Jordan, Lomi												
Develop algorithms for data processing	Alisha												
Finalize material and component selections	Jordan, Lomi												
<b>Testing</b>													
Conduct unit testing	Jordan, Lomi												
Perform integration testing	Alisha, Abid, Mark												
validating and feedback	Alisha, Abid												
<b>Refinement</b>													
<b>Project completion</b>													

## Deliverable Outcomes

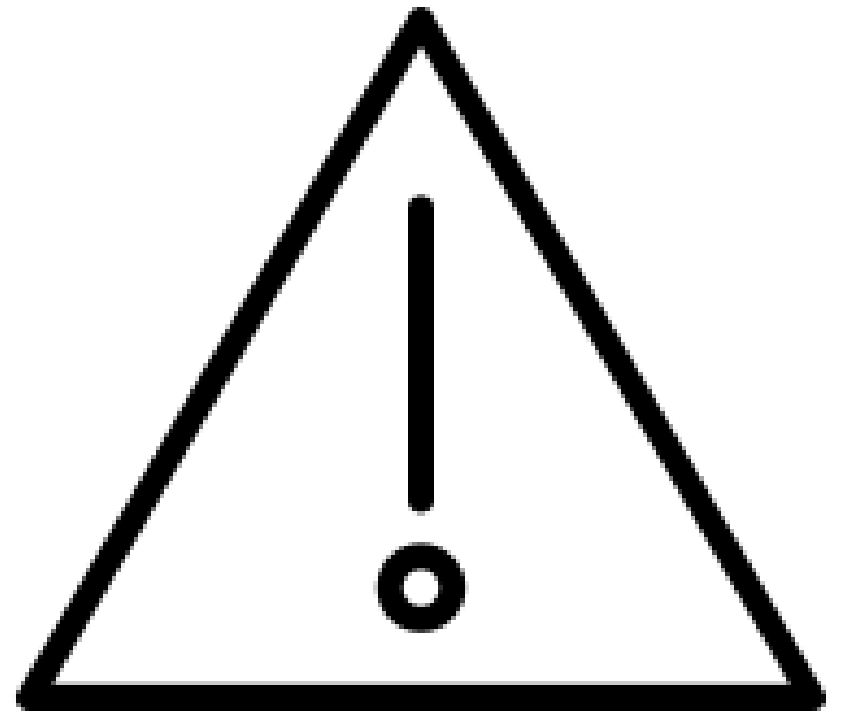
Figure 4: Deliverable Outcomes <sup>[3]</sup>

# Comparison with Existing Approaches

Feature	Other Approaches	Our Approach
Single-Feature Implementations	Focus on individual features (i.e. braking)	Integration of multiple features for synergy
Reliance on Basic Sensor Technologies	Basic sensors with limited accuracy	Advanced sensor fusion using LiDAR, cameras, and ultrasonic sensors
Limited Testing Environments	Limited testing	Use of advanced simulators to replicate diverse real-world conditions

## **Lacking Comprehensive Integration of ADAS Functionalities**

- Adaptive Cruise Control
- Lane Departure Warning (LDW) and Lane Keeping Assist (LKA)
- Automatic Emergency Braking (AEB)





Any  
questions?

# References

[1] Aleksa, M. et al. (2024) *Impact analysis of advanced driver assistance systems (ADAS) regarding road safety – computing reduction potentials - European Transport Research Review, SpringerOpen*. Available at: <https://etr.springeropen.com/articles/10.1186/s12544-024-00654-0#:~:text=For%20the%20Forward%20Collision%20Prevention,could%20reduce%209%25%20of%20crashes>. (Accessed: 13 September 2024).

[2] Created by Jordan Armstrong

[3] Created by Alisha