STEPS

1

Select Command Prompt - jupyter notebook Microsoft Windows [Version 10.0.19044.1766] (c) Microsoft Corporation. All rights reserved. C:\Users\ABID>D: cd ANPR D:\>cd ANPR D:\ANPR>.\anprsys\Scripts\Activate (anprsys) D:\ANPR>jupyter notebook

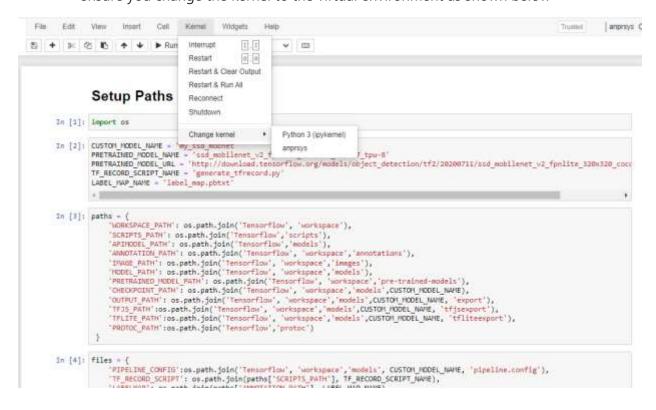
2.

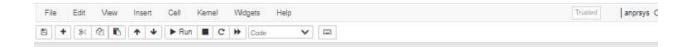
Install dependencies and add virtual environment to the Python Kernel pip install ipykernel

```
python -m pip install --upgrade pip
python -m ipykernel install --user --name=anprsys
```

3

ensure you change the kernel to the virtual environment as shown below

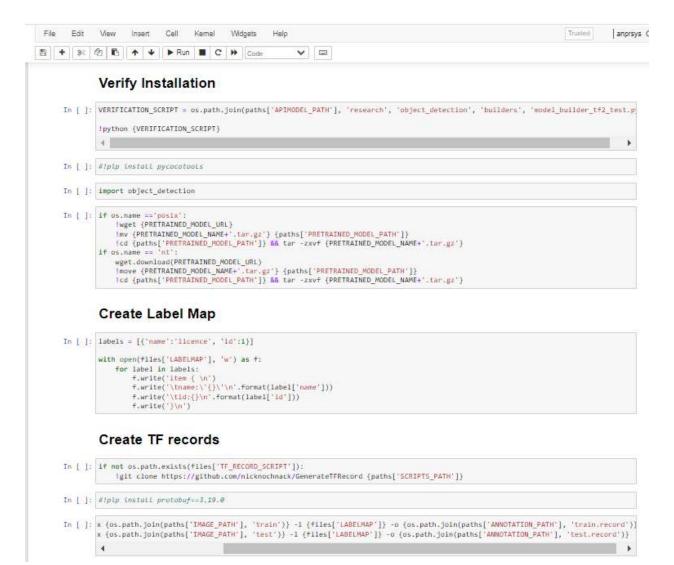


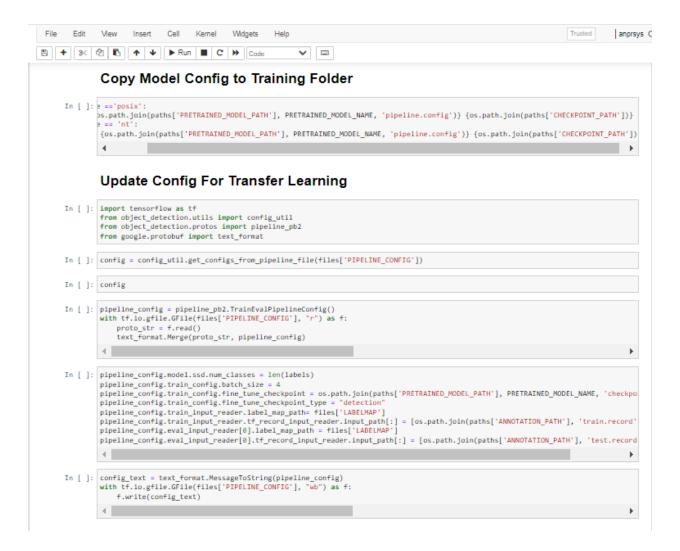


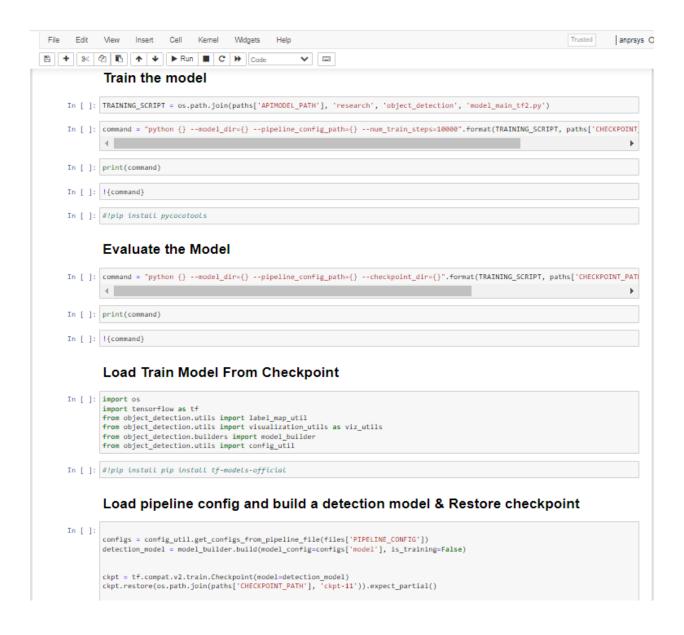
Setup Paths

```
In [1]: import os
In [2]: CUSTOM_MODEL_NAME = 'my_ssd_mobnet'
PRETRAINED_MODEL_NAME = 'ssd_mobilenet_v2_fpnlite_320x320_coco17_tpu-8'
PRETRAINED_MODEL_DRL = 'http://download.tensorfiow.org/models/object_detection/tf2/20200711/ssd_mobilenet_v2_fpnlite_320x320_coco17_tpu-8'
PRETORD_SCRIPT_NAME = 'generate_tfrecord.py'
LABEL_MAP_NAME = 'label_map.pbtxt'
In [3]: paths = {
                   In [4]: files = {
                    "FIPELINE_CONFIG':os.path.join('Tensorflow', 'workspace','models', CUSTOM_MODEL_NAME, 'pipeline.config'),
'TF_RECORD_SCRIPT': os.path.join(paths['SCRIPTS_PATH'], TF_RECORD_SCRIPT_NAME),
'LABELMAP': os.path.join(paths['ANNOTATION_PATH'], LABEL_MAP_NAME)
In [5]: for path in paths.values():
                    if not os.path.exists(path):
                        if os.name == 'posix'
  !mkdlr -p {path}
if os.name == 'nt':
  !mkdir {path}
In [ ]: #!pip install --upgrade pip
```

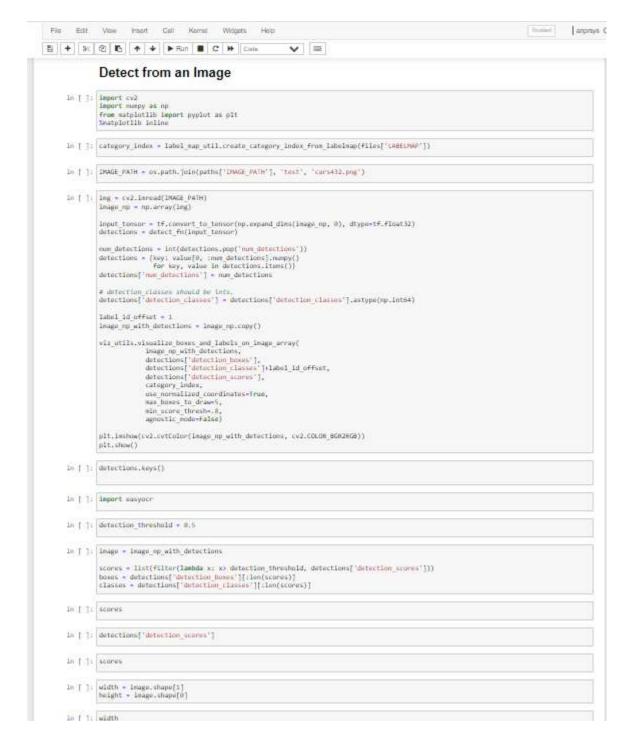
Download TF Models Pretrained Models from Tensorflow Model Zoo and Install TFOD







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In [ ]: # Apply ROI filtering and OCR
for idx, box in enumerate(boxes):
    print(box)
    roi = box*[height, width, height, width]
    region = image [int(roi[0]):int(roi[2]),int(roi[1]):int(roi[3])]
              print(roi)
              reader = easyocr.Reader(['bn'])
             ocr_result = reader.readtext(region)
print(ocr_result)
             plt.imshow(cv2.cvtColor(region,cv2.COLOR_BGR2RGB))
 In [ ]: ocr_result
In [ ]: for result in our result:
    print(np.sum(np.subtract(result[0][2],result[0][1])))
              print(result[1])
 In [ ]: region_threshold = 0.005
plate = []
             for result in ocr_result:
    length = np.sum(np.subtract(result[0][1],result[0][0]))
                  height = np.sum(np.subtract (result[0][2],result[0][1]))
                  if length*helght / rectangle_size > region_threshold:
   plate.append(result[1])
                  return plate
 In [ ]: filter_text(region, orr_result, region_threshold)
 In [ ]: region_threshold
width = image.shape[1]
             height = Image.shape[0]
              for idx, box in enumerate(boxes):
                 print(box)
rol = box*[height, width, height, width]
                  region = Image[int(roi[0]):int(roi[2]), int(roi[1]):int(roi[3])]
```

```
In [ ]: text,region = ocr_it(image_np_with_detections, detections, detection_threshold, region_threshold)
          Saving Files
In [ ]: import csv
In [ ]: import uuid
In [ ]: '{}.png'.format(uuid.uuid1())
In [ ]: def save_results(text, region, csv_filename, folder_path):
    img_name = '{}.png'.format(uuid.uuid1())
              cv2.imwrite(os.path.join(folder_path, img_name), region)
              with open( csv_filename, mode='a', newline='') as f:
    csv_writer = csv.writer ( f, delimiter = ',' , quotechar='"',quoting=csv.QUOTE_MINIMAL )
    csv_writer.writerow([(img_name, text)])
In [ ]: region
In [ ]: text
In [ ]: save_results(text, region, 'detection_results.csv', 'Detection_images')
          Real Time Detections from your Webcam
In [ ]: #!pip install opency-contrib-python
In [ ]: #!pip uninstall opencv-contrib-python-headless -y
#!pip uninstall opencv-python-headless -y
In [ ]: #!pip List opencv
In [ ]: #!pip install opencv-python==3.4.18.65
In [ ]: import cv2
         import numpy as np
from matplotlib import pyplot as plt
```

%matplotlib inline
In []: cap = cv2.VideoCapture(0)

Real Time Detections from your Webcam

```
In [ ]: #!pip install opency-contrib-python
In [ ]: #!pip uninstall opency-contrib-python-headless -y
#!pip uninstall opency-python -y
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In [ ]: #!pip List opency
In [ ]: #!pip install opency-python==3.4.18.65
In [ ]: import cv2
             import numpy as np
            from matplotlib import pyplot as plt
%matplotlib imline
In [ ]: cap = cv2.VideoCapture(0)
width = int(cap.get(cv2.CAP_PROP_FRAME_WIDTH))
            height = int(cap.get(cv2.CAP_PROP_FRAME_HEIGHT))
while cap.1sOpened():
                 ret, frame = cap.read()
image_np = np.array(frame)
                 input_tensor = tf.convert_to_tensor(np.expand_dims(image_np, 0), dtype=tf.float32) detections = detect_fn(input_tensor)
                 # detection_classes should be ints.
detections['detection_classes'] = detections['detection_classes'].astype(np.int64)
                 label_ld_offset = 1
                 image_np_with_detections = image_np.copy()
                 viz_utils.visualize_boxes_and_labels_on_image_array(
    image_np_with_detections,
    detections['detection_boxes'],
    detections['detection_classes']+label_id_offset,
    detections['detection_scores'],
                                   category_index,
                                  use_normalized_coordinates=True,
max_boxes_to_draw=5,
min_score_thresh=.8,
                                   agnostic_mode=False)
                    try:
```