

## Neural Networks

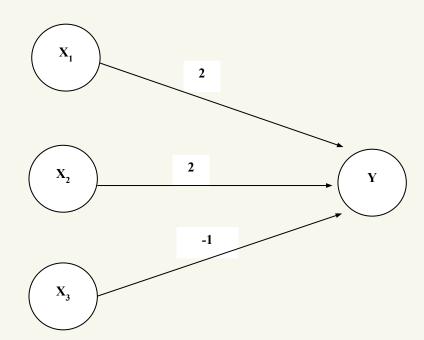
Moin Mostakim



## McCulloch and Pitts produced the first neural network in 1943

Many of the principles can still be seen in neural networks of today

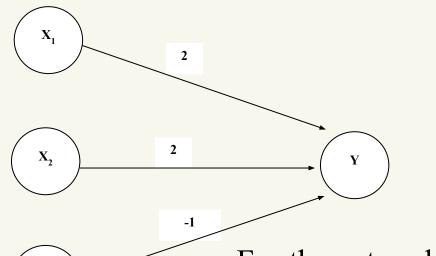




The activation of a neuron is binary. That is, the neuron either fires (activation of one) or does not fire (activation of zero).

 $X_3$ 



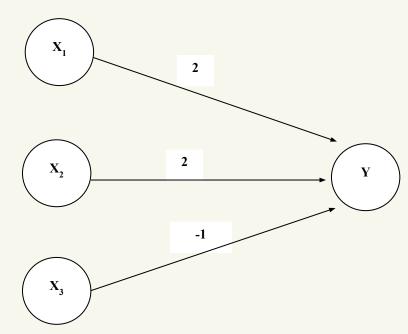


For the network shown here the activation function for unit *Y* is

$$f(y_in) = 1$$
, if  $y_in \ge \theta$  else 0

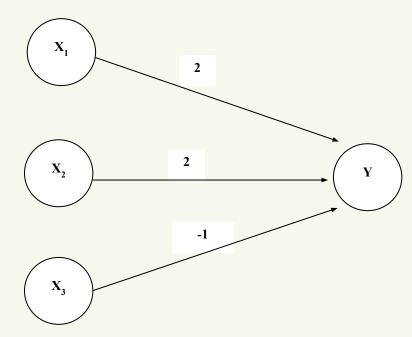
where y\_in is the total input signal received  $\theta$  is the threshold for Y





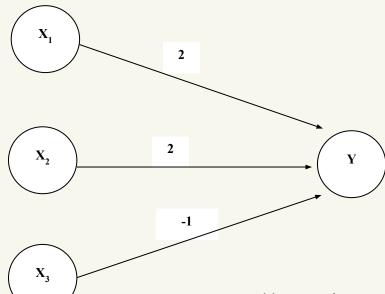
Neurons in a McCulloch-Pitts network are connected by directed, weighted paths





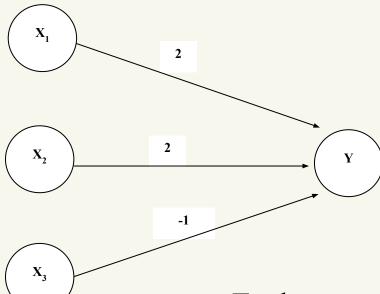
If the weight on a path is positive the path is excitatory, otherwise it is inhibitory





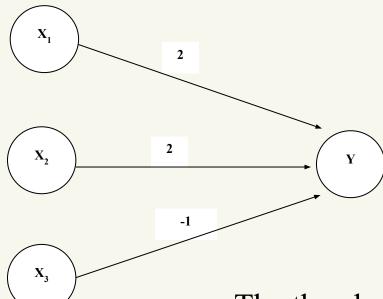
All excitatory connections into a particular neuron have the same weight, although different weighted connections can be input to different neurons





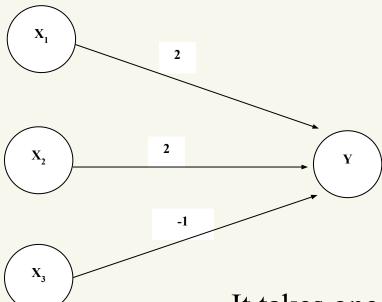
Each neuron has a fixed threshold. If the net input into the neuron is greater than the threshold, the neuron fires





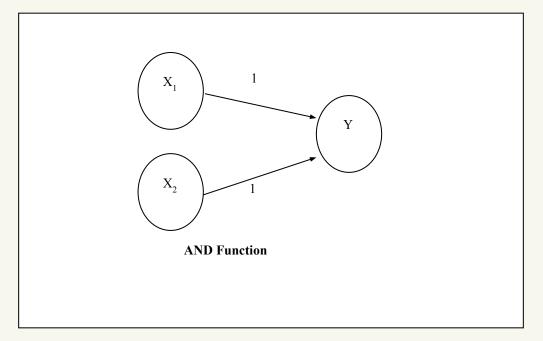
The threshold is set such that any non-zero inhibitory input will prevent the neuron from firing





It takes one time step for a signal to pass over one connection.

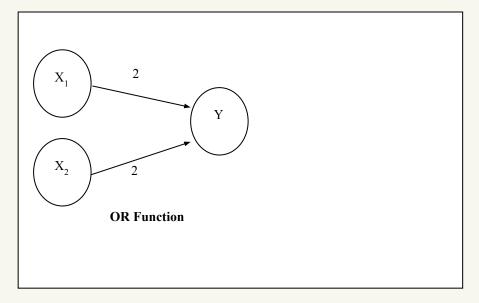


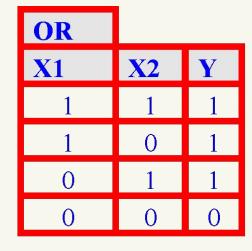


AND		
<b>X</b> 1	<b>X2</b>	Y
1	1	1
1	0	0
0	1	0
0	0	0

Threshold(Y) = 2

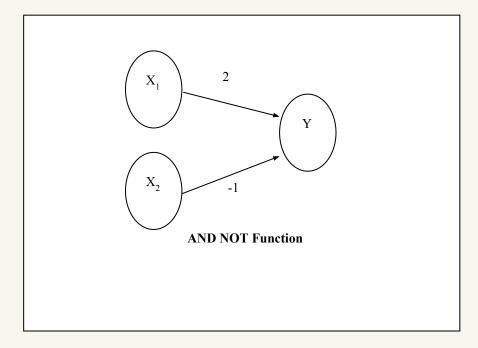




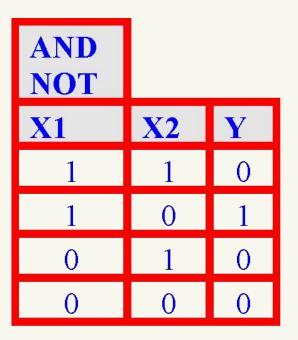


Threshold(Y) = 2





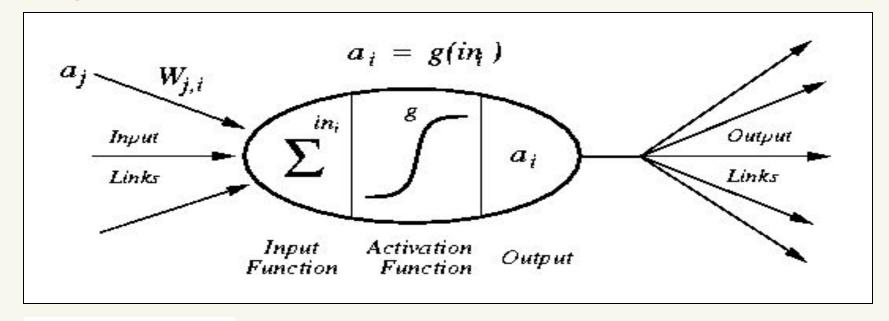
Threshold(Y) = 2





## Modelling a Neuron





$$in_i = \sum_j W_j, _ia_j$$

 $in_i = \sum_j W_j, ia_j$  •  $\mathbf{a_j}$  :Activation value of unit j

• w<sub>i,I</sub>: Weight on the link from unit j to unit i

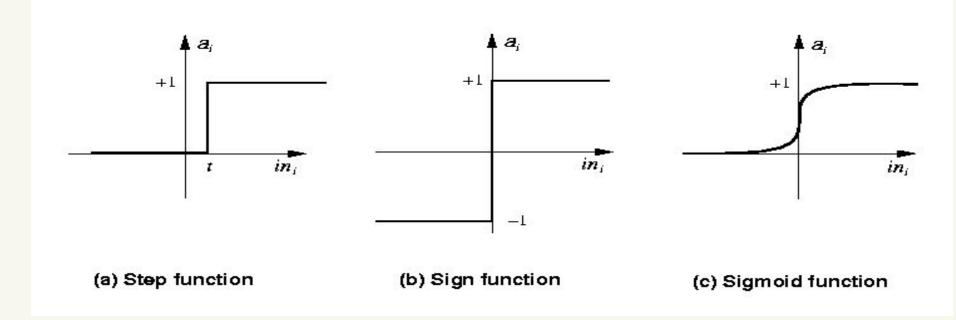
• in, :Weighted sum of inputs to unit i

:Activation value of unit i

• g :Activation function

## Activation Functions





- Step<sub>t</sub>(x) = 1 if x >= t, else 0
- Sign(x) = +1 if  $x \ge 0$ , else -1
- Sigmoid(x)=  $1/(1+e^{-x})$
- Identity Function

## Simple Networks

Output



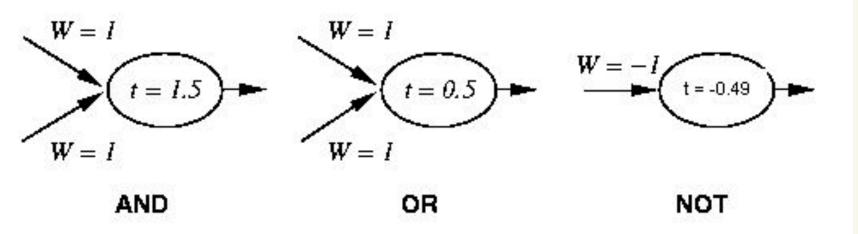
	AND
Input 1	0
Input 2	0

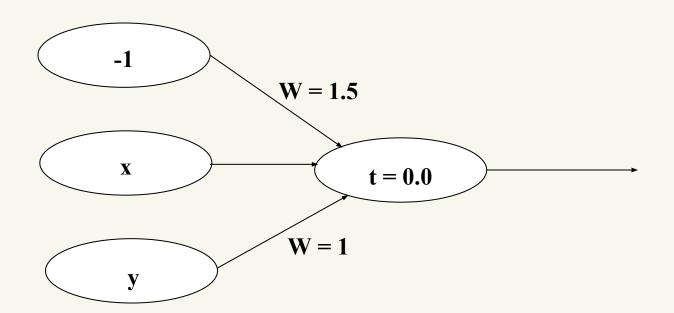
1	
1	
1	

OR

NOT	
0	1
1	0

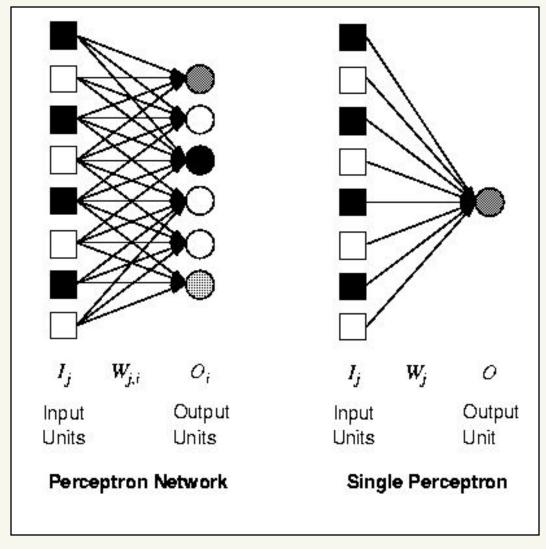
## Simple Networks







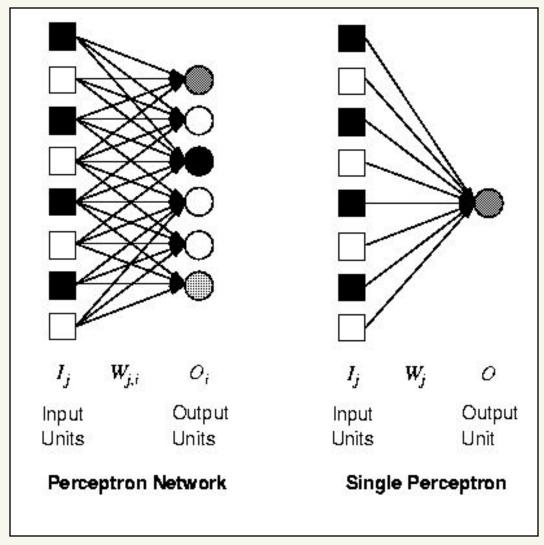
## Perceptron





- Synonym for Single-Layer, Feed-Forward Network
- First Studied in the 50's
- Other networks were known about but the perceptron was the only one capable of learning and thus all research was concentrated in this area

## Perceptron





- A single weight only affects one output so we can restrict our investigations to a model as shown on the right
- Notation can be simpler, i.e.

$$O = Step_0 \sum_{j} WjIj$$





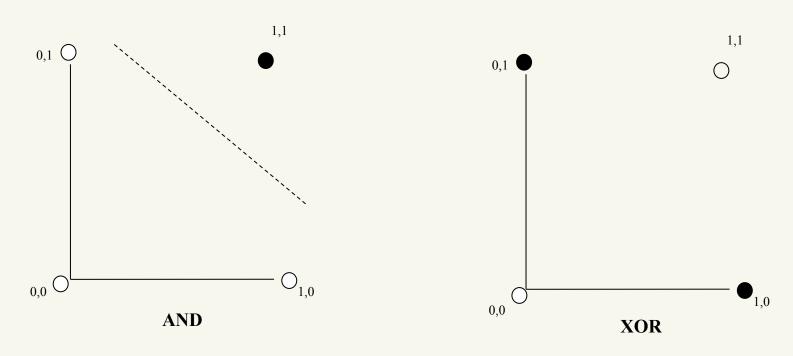
Input	1
Input	2
Outpu	ıt

AND			
0	0	1	1
0	1	0	1
0	0	0	1

XOR				
0	0	1	1	
0	1	0	1	
0	1	1	0	

## What can perceptrons represent?

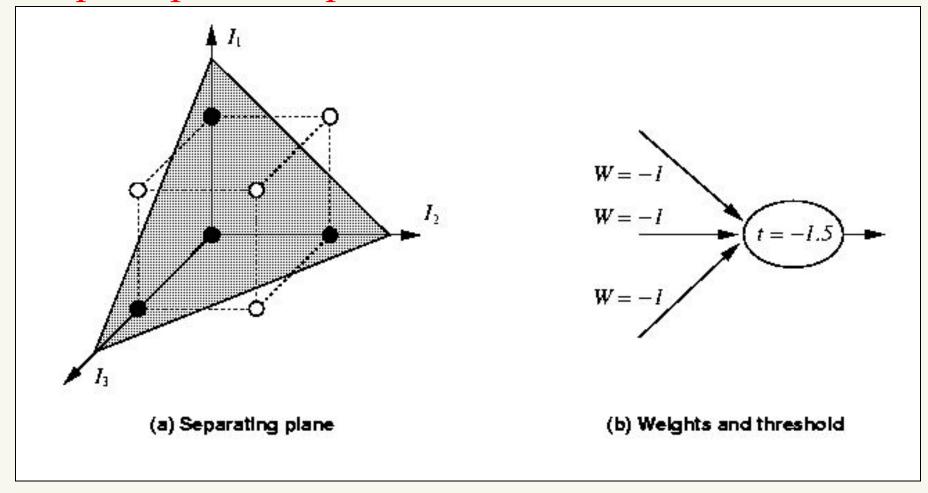




- Functions which can be separated in this way are called Linearly Separable
- Only linearly Separable functions can be represented by a perceptron

## What can perceptrons represent?





Linear Separability is also possible in more than 3 dimensions — but it is harder to visualise





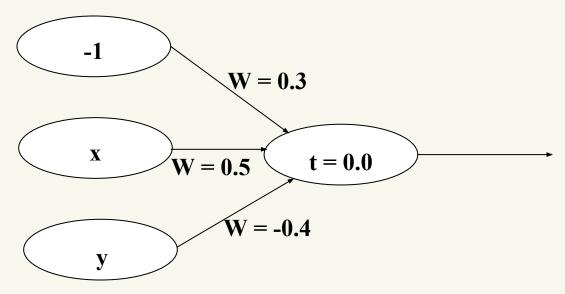
## Aim

Input 1
Input 2
Output

AND			
0	0	1	1
0	1	0	1
0	0	0	1

## Training a perceptrons





$I_1$	I <sub>2</sub>	$I_3$	Summation	Output
-1	0	0	(-1*0.3) + (0*0.5) + (0*-0.4) = -0.3	0
-1	0	1	(-1*0.3) + (0*0.5) + (1*-0.4) = -0.7	0
-1	1	0	(-1*0.3) + (1*0.5) + (0*-0.4) = 0.2	1
-1	1	1	(-1*0.3) + (1*0.5) + (1*-0.4) = -0.2	0

## Learning



## While epoch produces an error

Present network with next inputs from epoch

$$Err = T - O$$

If Err <> 0 then

$$\mathbf{W_j} = \mathbf{W_j} + \mathbf{LR} * \mathbf{I_j} * \mathbf{Err}$$

**End If** 

**End While** 



**End While** 



```
While epoch produces an error  \begin{array}{c} \text{Present network with next inputs from epoch} \\ \text{Err} = T - O \\ \text{If Err} &> 0 \text{ then} \\ \text{W}_j = \text{W}_j + \text{LR} * \text{I}_j * \text{Err} \\ \text{End If} \end{array}
```

**Epoch**: Presentation of the entire training set to the neural network.

In the case of the AND function an epoch consists of four sets of inputs being presented to the network (i.e. [0,0], [0,1], [1,0], [1,1])





```
While epoch produces an error  \begin{array}{c} \text{Present network with next inputs from epoch} \\ \text{Err} = T - O \\ \text{If Err} &> 0 \text{ then} \\ \text{W}_j = \text{W}_j + \text{LR} * \text{I}_j * \text{Err} \\ \text{End If} \\ \end{array}
```

Training Value, T: When we are training a network we not only present it with the input but also with a value that we require the network to produce. For example, if we present the network with [1,1] for the AND function the training value will be 1





```
While epoch produces an error
```

**End While** 

```
Present network with next inputs from epoch Err = T - O
If Err \Leftrightarrow 0 then W_j = W_j + LR * I_j * Err
End If
```

Error, Err: The error value is the amount by which the value output by the network differs from the training value. For example, if we required the network to output 0 and it output a 1, then Err = -1





```
While epoch produces an error
```

```
Present network with next inputs from epoch Err = T - O If Err >> 0 \text{ then} W_j = W_j + LR * I_j * Err End If End While
```

Output from Neuron, O: The output value from the neuron

**<u>Ii</u>**: Inputs being presented to the neuron

 $\underline{\mathbf{W}}$ : Weight from input neuron ( $I_i$ ) to the output neuron

**LR**: The learning rate. This dictates how quickly the network converges. It is set by a matter of experimentation. It is typically 0.1



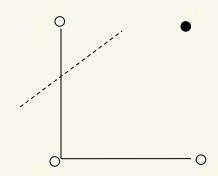


#### After First Epoch

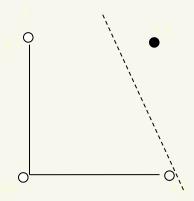
#### **Note**

$$\overline{I_1 \text{ point}} = W_0/W_1$$

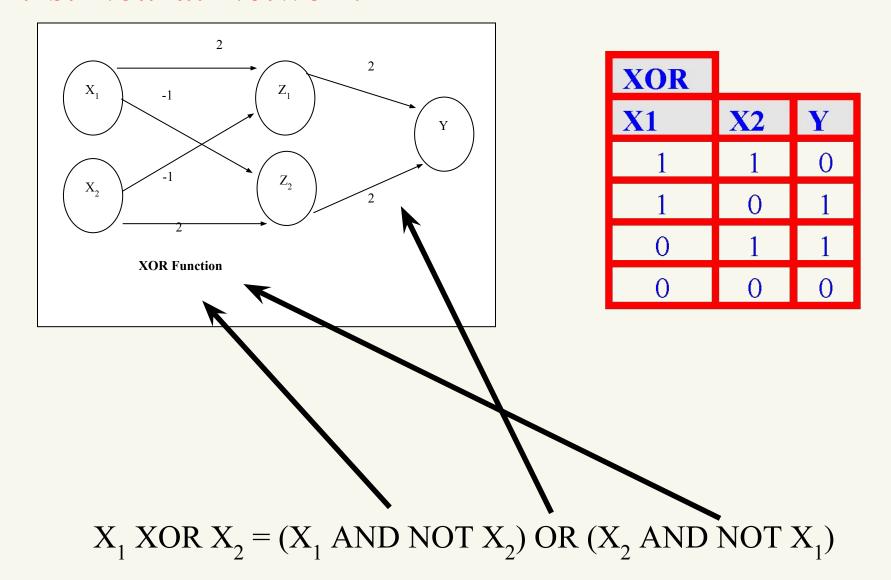
$$I_2 \text{ point} = W_0/W_2$$



At Convergence











If we touch something cold we perceive heat

If we keep touching something cold we will perceive cold

If we touch something hot we will perceive heat



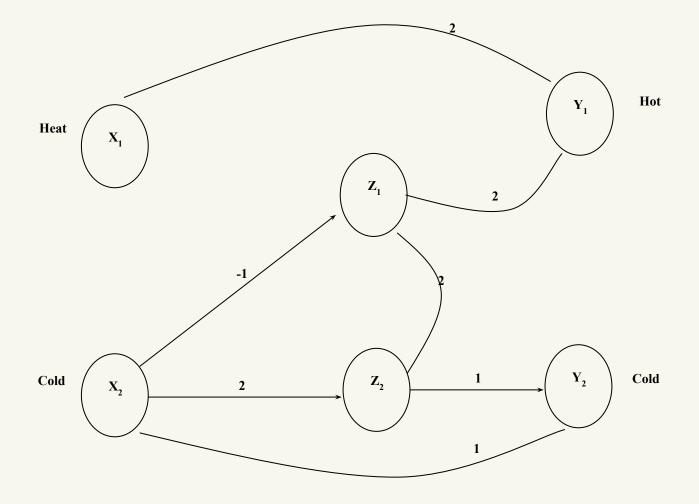


To model this we will assume that time is discrete

If cold is applied for one time step then heat will be perceived

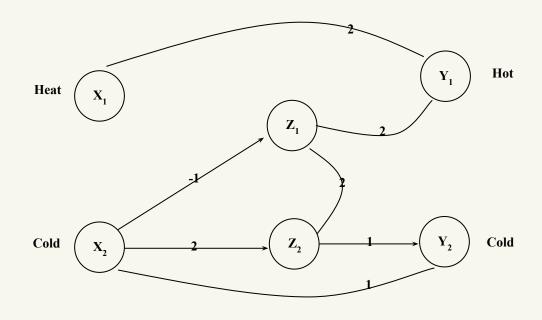
If a cold stimulus is applied for two time steps then cold will be perceived

If heat is applied then we should perceive heat









• It takes time for the stimulus (applied at  $X_1$  and  $X_2$ ) to make its way to  $Y_1$  and  $Y_2$  where we perceive either heat or cold

- At t(0), we apply a stimulus to  $X_1$  and  $X_2$
- At t(1) we can update  $Z_1$ ,  $Z_2$  and  $Y_1$
- At t(2) we can perceive a stimulus at Y<sub>2</sub>
- At t(2+n) the network is fully functional





We want the system to perceive cold if a cold stimulus is applied for two time steps

$$Y_2(t) = X_2(t-2) AND X_2(t-1)$$

$X_2(t-2)$	$X_2(t-1)$	<b>Y</b> <sub>2</sub> (t)
1	1	1
1	0	0
0	1	0
0	0	0



We want the system to perceive heat if either a hot stimulus is applied or a cold stimulus is applied (for one time step) and then removed

$$Y_1(t) = [X_1(t-1)] \text{ OR } [X_2(t-3)] \text{ AND NOT } X_2(t-2)]$$

X2(t-3)	X2(t-2)	AND NOT	X1(t-1)	OR
1	1	0	1	1
1	0	1	1	1
0	1	0	1	1
0	0	0	1	1
1	1	0	0	0
1	0	1	0	1
0	1	0	0	0
0	0	0	0	0

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#### The network shows

$$Y_1(t) = X_1(t-1) \text{ OR } Z_1(t-1)$$

$$Z_1(t-1) = Z_2(t-2) \text{ AND NOT } X_2(t-2)$$

$$Z_2(t-2) = X_2(t-3)$$

Substituting, we get

$$Y_1(t) = [X_1(t-1)] \text{ OR } [X_2(t-3)] \text{ AND NOT } X_2(t-2)]$$

which is the same as our original requirements



# You can confirm that Y<sub>2</sub> works correctly

You can also check it works on the spreadsheet

