

Lecture 5 - INFERENCE AND STATISTICAL PHYSICS

1. Notions from Statistical Physics

Stat. Physics: How can complex behavior emerge from the interaction of a large number of identical particles (e.g. water)

- probabilistic descriptions of the physical system in terms of elementary particles
- extract macroscopic/deterministic facts about the system through moments/expectations under this probabilistic model. → qualitative behavior

The Boltzmann distribution

- N particles x_i , each belong to a configuration space X
 $x = (x_1, \dots, x_n) \in \underbrace{X \times \dots \times X}_n =: X_N$
e.g. $x_i \in X = \{+1, -1\}$ a spin \uparrow or \downarrow
 $|X| = 2$, $|X_N| = 2^N$!

- Observable: a function $x \mapsto O(x)$ on the configurations space
- Energy: $E(x)$, a fundamental observable

$$E(x) = \sum_{i=1}^n E_i(x_i) : \text{non-interacting system}$$

$$\bar{E}(x) = \sum_{i_1, \dots, i_K} \bar{E}_{i_1, \dots, i_K}(x_{i_1}, \dots, x_{i_K}) : K\text{-body interaction system -}$$

Usually, K is small ($K=2$ or 3) in real physical systems $\Rightarrow K \ll N$, source of structure.

Def: (Boltzmann distribution)

Distribution $p_\beta(x)$ on the (joint) configuration space

$$p_\beta(x) = \frac{1}{Z(\beta)} e^{-\beta E(x)}$$

• $\beta = \frac{1}{T}$ is the inverse temperature

• $Z(\beta) = \sum_{x \in X} e^{-\beta E(x)}$ is the partition function

Remarks: • This is a Gibbs distribution! (Lec. 4)

• A maximum entropy distr. :

$$\max_P H(p) \quad \text{s.r.} \quad \mathbb{E}_p[\epsilon] = y$$

note: expectations typically written as

$$\langle O \rangle_p = \mathbb{E}_{p_\beta}[O(x)]$$

• For continuous x , p_β is a density w.r.t. Lebesgue measure -

Role of the inverse temperature β

- Just a parameter : would change E and set $\beta=1$
- Yet, $\beta = \frac{1}{T}$ carries physical meaning

$\rightarrow \beta \rightarrow 0$ (high-temperature limit)

$$p_\beta(x) \xrightarrow{\beta \rightarrow 0} \frac{1}{|\mathcal{X}|} \quad \text{uniform distribution}$$

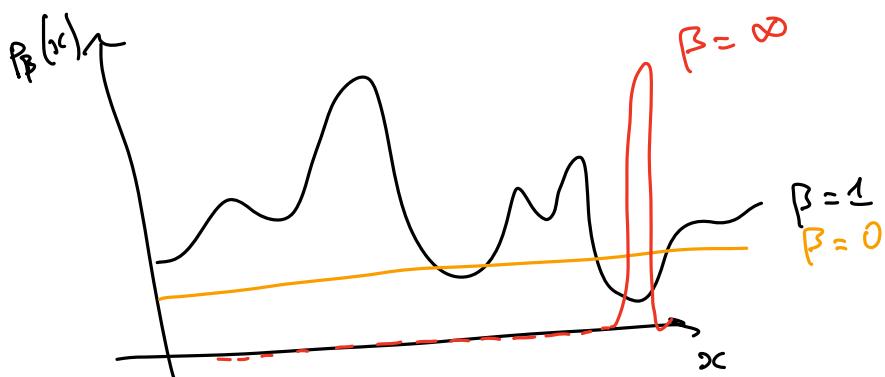
$\rightarrow \beta \rightarrow \infty$ (low-temperature limit)

$$p_\beta(x) \xrightarrow{\beta \rightarrow \infty} \frac{1}{|\mathcal{X}_0|} \mathbb{I}\{x \in \mathcal{X}_0\}$$

$$\mathcal{X}_0 = \arg \min E = \{x_0 : E(x_0) \leq E(x) \forall x \in \mathcal{X}\}$$

\uparrow set of Ground States (global minima)

(p_β is uniform over ground states)



Thermodynamic potentials

Quantities that summarize properties of Boltzmann dist p_x

- Free Energy: $F(\beta) = -\frac{1}{\beta} \log Z(\beta)$

(also, "free entropy" $\phi(\beta) = -\beta F(\beta) = \log Z(\beta)$)

- Internal Energy: $U(\beta) = \frac{\partial}{\partial \beta} (F(\beta))$

- Canonical Entropy: $S(\beta) = \beta^2 \frac{\partial}{\partial \beta} F(\beta)$

Fact: $U(\beta) = \langle E(x) \rangle = \bar{E}_{pp} [E(x)]$

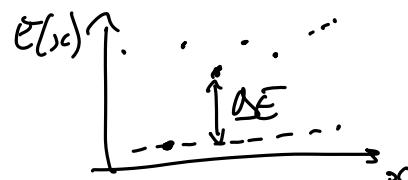
$$S(\beta) = - \sum_x p_F(x) \log p_F(x)$$

$$F(\beta) = U(\beta) - \frac{1}{\beta} S(\beta)$$

Limits: $\beta \rightarrow 0$:

$$F(\beta) = -\frac{1}{\beta} \log |x| + \langle E(x) \rangle_0 + O(\beta)$$

$\beta \rightarrow \infty$: let $\Delta E = \min \{E(x) - \bar{E}_0, x \notin X_0\}$
(energy gap)



$$U(\beta) = E_0 + \Theta(e^{-\beta \Delta E})$$

$$S(\beta) = \log |X_0| + \Theta(e^{-\beta \Delta E})$$

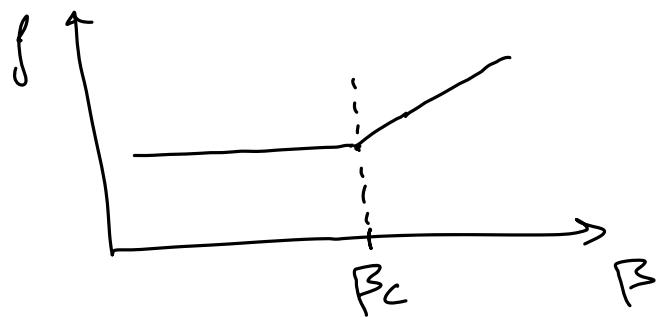
$$\left[F(\beta) = E_0 - \frac{1}{\beta} \log |X_0| + \Theta(e^{-\beta \Delta E}) \right. \\ \left. = \quad \text{("Laplace method")} \right]$$

- Thermodynamic limit

$N \rightarrow \infty$ limit, describes macroscopic properties of the system.

- Thermodynamic potentials are often proportional to N

(free energy density) $f(\beta) = \lim_{N \rightarrow \infty} \frac{F_N(\beta)}{N}$



singularities in $f(\beta)$ are called
phase transitions

often correspond to qualitative changes in the system
(e.g. boiling Temp of water)

Example: Ising model

- model of magnetic materials
- molecules tend to align with magnetic field
- also interact with each other
- Ising model represents molecules as "Ising spins" on a lattice $\mathcal{L} = \{1 \dots L\}^d$

$$\textcircled{0} - \textcircled{0} - \textcircled{0} - \textcircled{0} \quad (d=1)$$

$$\begin{array}{c} \uparrow - \uparrow - \uparrow \\ | \quad | \quad | \\ \uparrow - \uparrow - \uparrow \end{array}$$

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spins $\sigma_i \in \{+1, -1\}$

Configuration $\sigma = (\sigma_1, \dots, \sigma_N)$ $(X_N = \{\pm 1\}^N$
 $N = L^d)$
 has energy

$$E(\sigma) = - \sum_{i \sim j} \underbrace{\sigma_i \sigma_j}_{\substack{\uparrow \\ \text{edges}}} - B \sum_i \sigma_i$$

↳ external magnetic field
 pairwise interactions

Typical quantity of interest: average magnetization

$$M_N(\beta, B) = \frac{1}{N} \sum_i \langle \sigma_i \rangle_B$$

and its limits.

- $\rightarrow d=1$ (Ising 1924): no phase tr.
- $\rightarrow d=2$ (1948, Debye): phase tr.
- $\rightarrow d > 2$: open

Ex: Ising-Spin-glass

different types of interactions:

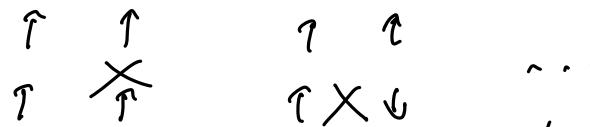
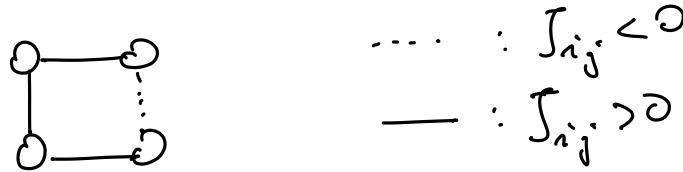
$$E(\sigma) = - \sum_{i \sim j} J_{ij} \sigma_i \sigma_j - \beta \sum_i \sigma_i$$

↑

$J_{ij} > 0$: ferromagnetic

$J_{ij} < 0$: anti-ferromagnetic

→ this can lead to "frustration"



no configuration can satisfy all constraints!

→ much less understood than Ising models

→ Giorgio Parisi (Nobel prize today!)

"Statistical Field Theory" (1987)

2. Inference in graphical models

$$p(x_1, \dots, x_N) = \frac{1}{Z} \prod_{c \in C} \phi_c(x_c) \quad C: \text{cliques of graph } G.$$

→ We are interested in queries of the form

$$p(x_S) = \sum_{x_{V \setminus S}} p(x_1, \dots, x_N) \quad (\text{marginalization})$$

→ this will also allow computing conditional probabilities
(by Bayes rule)

→ (reminder) This is intractable without structure
(at least for $|S| \ll N$)
⇒ need to exploit graph structure

→ Algorithms based on message passing
Belief propagation / Sum-Product / Junction Tree
(BP)

■ BP on Ising chains (1D Ising model)



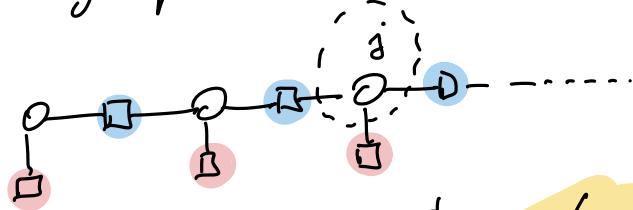
$$\sigma = (\sigma_1, \dots, \sigma_N)$$

$$\sigma_i \in \{\pm 1\}$$

$$E(\sigma) = - \sum_{i=1}^{N-1} \sigma_i \cdot \sigma_{i+1} - B \sum_{i=1}^N \sigma_i$$

$$p_B(\sigma) \propto e^{-B E(\sigma)}$$

- Factor graph:



● : external field
● : pairwise interactions

→ want to compute $p(\sigma_j)$, marginal over spin σ_j

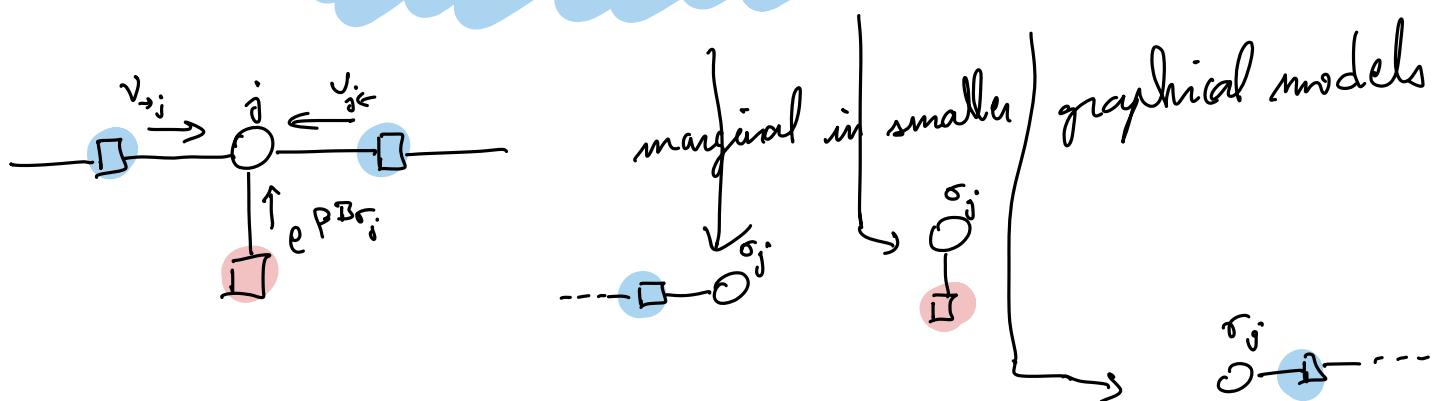
- Introduce messages $v_{\rightarrow j}$ and $v_{\leftarrow j}$

$$v_{\rightarrow j}(\sigma_j) = \frac{1}{Z_{\rightarrow j}} \sum_{\sigma_1, \dots, \sigma_{j-1}} \exp \left\{ \beta \sum_{i=1}^{j-1} \sigma_i \sigma_{i+1} + \beta \sum_{i=1}^{j-1} \sigma_i \right\}$$

$$v_{\leftarrow j}(\sigma_j) = \frac{1}{Z_{\leftarrow j}} \sum_{\sigma_{j+1}, \dots, \sigma_N} \exp \left\{ \beta \sum_{i=j}^N \sigma_i \sigma_{i+1} + \beta \sum_{i=j}^N \sigma_i \right\}$$

We then have (check!)

$$p(\sigma_j) \propto v_{\rightarrow j}(\sigma_j) e^{\beta \sum_{i=1}^{j-1} \sigma_i} v_{\leftarrow j}(\sigma_j) \quad (*)$$



- Computing messages :

Key observation:

$$v_{\rightarrow j}(\sigma_j) \propto \sum_{\sigma_{j-1}} v_{\rightarrow j-1}(\sigma_{j-1}) \exp \left(\beta \sigma_{j-1} \sigma_j + \beta \sum_{i=1}^{j-1} \sigma_i \right) \quad (***)$$

\Rightarrow only need sum over a single spin!

An instance of Dynamic Programming:

Algorithm for computing $p(\sigma_f)$

(i) initialize $v_{\rightarrow 1}, v_{\leftarrow N}$ to uniform

(ii) Compute all messages $v_{\rightarrow j}, v_{\leftarrow j}$ using
Dynamic Programming (**)

($v_{\rightarrow j}$: forward, $v_{\leftarrow j}$: backward)

(iii) Compute desired marginals using (*)

Remark: . $O(N)$ time complexity, $O(1)$ space

. if we had K states $\forall i \in \{1, \dots, K\}$, $O(NK^2)$ time

. What about marginals $p(\sigma_j, \sigma_k) \quad j < k$?

Γ \rightarrow sufficient to compute $p(\sigma_k | \sigma_j)$

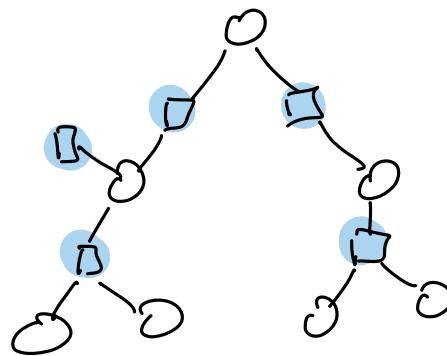
\rightarrow note that $p(\sigma_{j+1}, \dots, \sigma_N | \sigma_j)$ takes a similar
form $\propto \exp \left\{ \beta \sum_{i=j}^{N-1} \sigma_i \sigma_{i+1} + \gamma \sum_{i=j}^N \sigma_i \right\}$.

\rightarrow computing $p(\sigma_k | \sigma_j) \Leftrightarrow$ computing marginal over σ_k
in this modified model, with \neq initial conditions

• BP on trees (preview)

- Consider graphical models that are trees (no cycles)

$$p(x) = \frac{1}{Z} \prod_c \phi_c(x_c)$$



- In this case, BP is also exact.

Messages $\nabla_{i \rightarrow a}$ (node \rightarrow factor)

$\nabla_{a \rightarrow i}$ (factor \rightarrow node)

Updates : $\nabla_{j \rightarrow a}^{(t+1)}(x_j) \propto \prod_{b \in M(j) \setminus \{a\}} \nabla_{b \rightarrow j}^{(t)}(x_j)$

$\nabla_{a \rightarrow j}^{(t)}(x_j) \propto \sum_{i \in M(a) \setminus \{j\}} \phi_a(x_{M(a)}) \prod_{k \in M(a) \setminus \{i\}} \nabla_{i \rightarrow a}^{(t)}(x_k)$

Marginals : $\nabla_i^{(t)}(x_i) \propto \prod_{a \in M(i)} \nabla_{a \rightarrow i}^{(t-1)}(x_i)$

(Thus) : After some $t > t^*$, we have $\nabla_i^{(t)}(x_i) = p(x_i)$