



Missing data considerations

R implementation of imputation approaches



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#### Objectives

- ► Throughout the course we have been sub-setting our data such that we are only including rows of data with non-missing outcomes and exposures.
- ► Today we will start to explore the possible implications of this practice and think about the underlying assumptions we are making when we do this.
- ▶ Upon completion of this session, you will be able to do the following:
  - Define mechanisms that generate missing data
  - Describe the impact of conducting analyses on complete cases or available data under the different missing data mechanisms
  - ▶ Describe imputation procedures to account for missing data
  - ► Implement several imputation procedures using R mice package

multiple
imputation
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equations

# Missing data mechanisms

Y-f(M(X), 62(X)) YO, R		
Missing data mechanism	Definition	Ignorable?
Constate dependent  missimness  Park(x)  4 ((10, ym)	Whether or not a value is missing does not depend on observed data OR the missing value we would have observed.  - Think a value is missing based a coin toss with some probability of a head that does not depend on anything else	Yes Complete cases represent a random sample of original sample -> analysis of complete case will loss precision but will be unbiased
At random	. // /	
Not at random		

# Missing data mechanisms

Missing data mechanism	Definition	Ignorable?
Completely at random	Whether or not a value is missing does not depend on observed data OR the missing value we would have observed.	Yes
At random $f(R Y^{o},X)$	Whether or not a value is missing depends on observed covariates - Think a value is missing is based on a coin toss with probability based on observed characteristics	Yes'  Complete cases are NOT representative of the original sample. Analysis of complete cases may be biased unless you correctly specify the model, could lose precision
Not at random		

# Missing data mechanisms

Missing data mechanism	Definition	Ignorable?
Completely at random	Whether or not a value is missing does not depend on observed data OR the missing value we would have observed.	Yes
At random	Whether or not a value is missing depends on observed covariates	Yes
Not at random $f(R/Y^n)$	Whether or not a value is missing depend on the value of the variable you would observe had it not been missing	No Complete cases are a specific selection of the original sample Bias!
\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	missing	Bias!

## Imputation algorithms

Single conditional mean imputation Y = Bot Pix, + .. + PPXp+Z Single predicted value imputation

You Bot 6, X, + ... + Box + E, E~ N(0, 59) Matching methods (Trave shorts of subjects based on X:

#### Chained equation approach

#### mice

The idea here is anchored in the desire to estimate the joint distribution of a set of random variables (some values of which are missing). We may be able to derive the exact joint distribution OR we can approximate the joint distribution by deriving the set of full conditional distributions.

E.g.  $Y = (y_1, y_2)$  follows a multivariate normal distribution with mean  $\mu = (\mu_1, \mu_2)$  and variances  $\sigma_1^2$ ,  $\sigma_2^2$  and covariance  $\rho \sigma_1 \sigma_2$ .

Then we can write out the two conditional distributions:

- $f(y_1|y_2) \sim N(\mu_1 + \rho \sigma_1 \frac{y_2 \mu_2}{\sigma_2}, \sigma_1^2(1 \rho^2))$   $f(y_2|y_1) \sim N(\mu_2 + \rho \sigma_2 \frac{y_1 \mu_1}{\sigma_1}, \sigma_2^2(1 \rho^2))$

We can use the MCMC algorithm to generate values from each of these two conditional distributions with the end goal of approximating the joint distribution of Y.

### Chained equation approach

Let  $X_1, X_2, ..., X_p$  be the target imputation variables ordered from most to least observed values. Z defines a set of prognostic variables that have no missing data. Here I am being generic, the set of target imputation variables may include the outcome variable or not and Z may include the outcome variable or not, plus any potentially predictive variables for the target imputation variables.

1. Step 1: Setting  $t = 0, X_i^{(0)}$  for i = 1, ..., p are simulated from

$$f_{i}(X_{i}|X_{1}^{(0)},X_{2}^{(0)},...,X_{i-1}^{(0)}Z,\theta_{i})$$

$$X_{1}^{(0)} = f_{1}(X_{1}|Z,\theta_{1}) \qquad \text{(eyessian parameters)}$$

$$X_{2}^{(0)} = f_{2}(X_{2}|X_{1}^{(0)},Z,\theta_{2})$$

$$X_{2}^{(0)} = f_{3}(X_{3}|X_{2}^{(0)},X_{1}^{(0)}Z,\theta_{3})$$

## Chained equation approach

2. Step 2: For t = 1: obtain simulated values  $X_i^{(1)}$  for i = 1, ..., p from

$$X_{0}^{(1)} = g_{1}(X_{1}|X_{2}^{(0)},...,X_{p}^{(0)},Z,\phi_{1})$$

$$X_{0}^{(1)} = g_{2}(X_{2}|X_{1}^{(1)},X_{3}^{(0)},...,X_{p}^{(0)},Z,\phi_{2})$$

through

$$g_p(X_p|X_1^{(1)}, X_2^{(1)}, ..., X_{p-1}^{(1)}, Z, \phi_p)$$

Then repeat this process for t = 2, ..., b.

# Now, let's implement some of these approaches!