**TASI-VRU Data Storage:**

* **Raw data**
  + Stored at: /10.234.5.7/TASI-VRU Data Storage/Reordered\_drive/Raw\_Data
  + **192** Folders present. Checked Timestamps for **184** of them. The rest of them did not have timestamp data. The average time between frames is recorded in a csv file. The ideal value is 100ms since recording is at 10fps.
  + Folder Structure for each raw data file A screenshot of a computer

    Description automatically generated
  + Lidar Recording bags are present.
  + Camera Recording bags are not stored. Videos are present instead.
  + GPS Recording bags are present and the extracted folders are also present
  + Joystick click file present.
  + JSON file containing some metadata present.(Includes length of recording and number of frames, clicks)A screen shot of a computer

    Description automatically generated
  + Below is a brief view of average frame gap.(ideal is 100ms)
* A screenshot of a calendar

  Description automatically generated
  + Around 10 datasets(first 10 above) have very large frame gaps, hence large number of missing frames. More details in the csv.
* **Problematic Dataset:** 
  + Stored at: 10.234.5.7/TASI-VRU Data Storage/Problematic\_Datasets
  + 22 Folders present. Checked Timestamps for 7 folders. Rest has no timestamp info. The average time between frames is recorded. The ideal value is 100ms since recording is at 10fps. Below is the average time between frames of the 6 cameras. Since the value is 30 percent higher than 100ms, there is a large amount of missing frames in these datasets. More info in the excel.A table with numbers and text

    Description automatically generated
* **Processed Data**
  + Stored at: /10.234.5.7/TASI-VRU Data Storage/Reordered\_drive/processed\_final
  + 703 folders present
  + High level sub-folder structure for each Processed Data folder A screenshot of a computer program

    Description automatically generated