Towards scalable subspace iteration algorithms: Spectrum slicing

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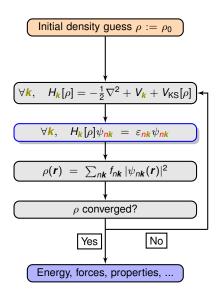
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Abinit Developer Workshop 2024

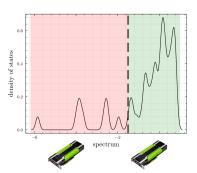




Exploiting parallelism over bands



- all states are labeled by 1 ≤ n ≤ nband band index and k Bloch vector
- parallelism over k-points [OK]
- fixed k, parallelism over npw [OK]
- fixed k, parallelism over nband





Building blocks of any diagonalisation scheme

 $A \in \mathbb{C}^{npw \times npw}$ Hermitian matrix, seek the lowest nband \ll npw eigenpairs

What all methods have in common: Subspace Iteration

- **1** Initialise vector space generated by starting vectors $X_0 \in \mathbb{C}^{npw \times nband}$, j = 0;
- ② Update vectors X_{j+1} by diagonalisation in subspace, j = j + 1;
- **3** Iterate until $||AX_i \Lambda_i X_i|| < tol.$

How methods differ:

- Cost of projecting columns of *H* on subspace.
- Size of diagonalisation problem on subspace.

Hamiltonian application

AX

batch processing on GPU

Rayleigh-Ritz

Input: matrix *A*, initial guess *X*Output: approximate eigenpairs of *A*

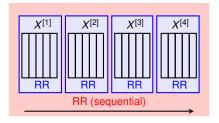
- Orthogonalize X:
- 2 Project to subspace $B = X^{T}AX$;
- 3 Diagonalize $BY = \Lambda Y$ (**dense**);
- 4 Return rotated subspace $X' = Y^{\top}X$.

 $\mathcal{O}(n^3)$



What we wish to avoid: global Rayleigh-Ritz

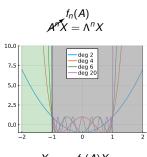
Method 1: Locally Optimal Block Conjugate
Gradient = approximate eigenvectors based on
energy minimisation over vectors. Example for
nblock= 4:



$$X_{i+1} = RR(X_{i-1}, X_i, AX_i - \Lambda_i X_i)$$

$$\mathsf{nblock} \times \left(\frac{3 \times \mathsf{nband}}{ P \times \mathsf{nblock}} + \frac{(3 \times \mathsf{nband})^3}{\mathsf{nblock}^3} \right) + \frac{\mathsf{nband}^3}{\mathsf{nblock}^3}$$

<u>Method 2</u>: **Chebyshev filtering** = polynomial filtering based on *scalars* instead of RR per block.



$$X_{j+1} = f_n(A)X_j$$

$$deg \times \frac{nband}{P} + \frac{nband^3}{P}$$



What we wish to achieve: divide and conquer

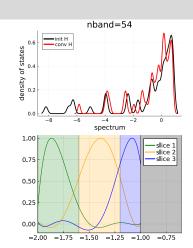
- Partition the spectrum into subintervals (=slices), for evolving matrices (i SCF iter):
 - First few SCF iterations Chebyshev filtering;
 - Compute spectrum bounds: use Ritz values

$$\boldsymbol{\mu}_{\mathrm{0}}^{(i)} = \mathrm{diag}(\langle X_{\mathrm{tol}}^{(i-1)}, \boldsymbol{A}^{(i)} X_{\mathrm{tol}}^{(i-1)} \rangle),$$

$$egin{aligned} m{U} &= \max_{\mathsf{nband}} (\mu_0^{(i)} + \| A X_{\mathsf{tol}}^{(i-1)} - \mu_0^{(i)} X_{\mathsf{tol}}^{(i-1)} \|); \end{aligned}$$

- Cut [L, U) into **nsli** "balanced" slices: bounds $[\ell_k^{(i)}, u_k^{(i)})$ and vectors $m_k^{(i)}$ per slice.
- **3** Build subspace $X_{\text{tol}}^{(i,k)} \in \mathbb{C}^{\text{npw} \times m_k^{(i)}}$ per slice separately (filter + RR);
- Ombine occupied states

$$\mu_{\text{tol}}^{(i)} = \bigcup_{\substack{1 \leq k \leq \text{nsli} \\ 1 < j < m_k^{(i)}}} \{ \ \mu_{\text{tol},j}^{(i,k)} \ \in [\ell_k^{(i)}, u_k^{(i)}) \}$$



$$\boxed{\frac{\text{nslice}}{\textit{P}} \times \left(\text{deg} \times \frac{\text{nband}}{\text{nslice}} + \frac{\text{nband}^3}{\text{nslice}^3}\right)}$$



Challenge of spectrum slicing

Assume we have nproc processing units.

Problem: how to assign

- vectors (and subspace dimension) to slices,
- processing units to slices,
- interval bounds to slices,

while assuring that each processor has the same amount of work.

slice 1
$$\mapsto$$
 X_1 , nproc₁, ℓ_1 , u_1
slice 2 \mapsto X_2 , nproc₂, ℓ_2 , u_2
slice 3 \mapsto X_3 , nproc₃, ℓ_3 , u_3

. .



Issue 1: Missing eigenpairs



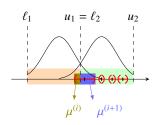
Building the subspace (Saad 2016):

$$\dim(\underbrace{\sum_{j=1}^{m} \psi_{j} \psi_{j}^{\top}}_{\text{projector}} A^{n} \underbrace{\text{Span}(X_{0})}_{\text{initial guess}}) = m$$

Difficulties:

- poorly chosen starting iteration
- number of true vectors m per slice is not known a priori
- eigenvalue "jump": a Ritz value outside a slice may be approximating a value inside the slice

$$(\mu - r, \mu + r), \quad r := ||Av - \mu v||$$



Solution:

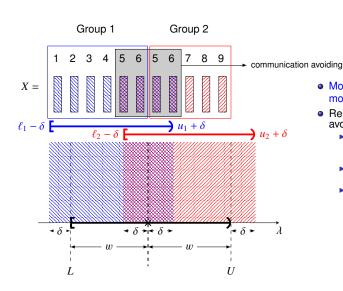
• remove duplicates by overlapping slices (Liou et al. 2020)

$$[\ell_i - \delta, u_i + \delta), \quad \delta = \frac{u_i - \ell_i}{10}, \quad 1 \le i \le \text{nsli}$$

• require full slices using condition $\langle v, Av \rangle > u + \delta$ (Schofield et al. 2012)



Issue 2: Processor groups



- More vectors in slice ⇒ more procs in slice.
- Remove duplicates while avoiding:
 - communication of converged vectors near interval boundaries
 - re-orthonormalisation near interval boundary
 - redefinition of MPI communicators?



Issue 3: Load balancing

• Optimize slices (ℓ_i, u_i, m_i) : minimise

$$\max(m_i \times \deg_i, m_i^3)$$

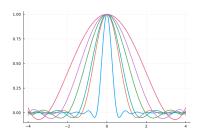
- Convergence rate:
 - ▶ Optimize m: choose dimension p of the subspace larger than m

$$\frac{|\lambda_m|}{|\lambda_{p+1}|} \ll \frac{|\lambda_m|}{|\lambda_{m+1}|}$$

Optimize deg: $\alpha > 0$ amplification factor, choose n (Schofield et al. 2012)

$$\min\left(\frac{f_n(\ell_i)}{f_n(\ell_i-\delta)},\frac{f_n(u_i)}{f_n(u_i+\delta)}\right) \geq \alpha$$

Work imbalance: lock converged vectors as lower eigenvalues converge faster

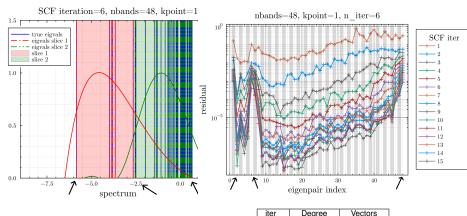


W	0.6	1.6	2.6	3.6	4.6
deg	39	15	9	7	5



Numerical illustration on a toy system

FeNiF6, 48 occupied states, 76 electrons, 1 k-point.



	LOBPCG	Cheby	Slicing
SCF iter	20	19	85
Degree	-	10	8,20
Vectors	48	48	6,42

iter	Degree		Vectors	
	s1	s2	s1	s2
1	7	17	8	40
2	8	19	8	40
3-6	8	20	5	43
7-85	8	20	6	42



Sum up: key points of spectrum slicing algorithm

```
Input: matrix A at current SCF iteration, slice bounds and number of vectors per slice,
             starting guess X
    Output: approximation of N lowest eigenpairs
   for k = 1, \ldots, nslice:
                                                                               // parallel nslice/P
     do
        Initialize J_k \in \mathbb{N}^{m_k} and Y := X[:, J_k];
  3
        Center filter on slice [\ell_k, u_k);
        for m = 2, \ldots, maxit do
  5
            Apply filter Ynew = f_n(A)Y;
  6
           Orthonormalise Ynew:
           Apply Rayleigh-Ritz to Ynew for m_k eigenpairs;
                                                                         // Rayleight-Ritz size m<sub>k</sub>
         Y = Ynew:
     X[:,J_k]=Y;
 11 return X:
Difficulty: subspace dimension is less obvious than scalars
                                        Spectrum slicing =
          "slice → interval"
                                    "slice → dimension" careful ortho
                                                                              evolving matrix
     parallelism over scalars | + | parallelism over subspace dimension | + |
```

To be implemented in ABINIT.