# Efficient ab-initio geometry optimization guided by force field

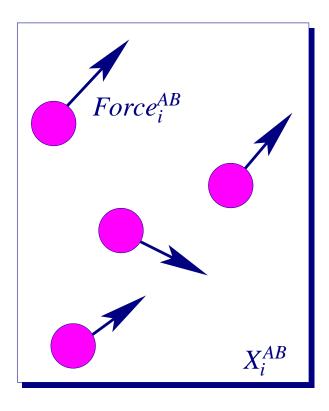
T. Deutsch, S. Goedecker

DRFMC, CEA Grenoble
tdeutsch@cea.fr

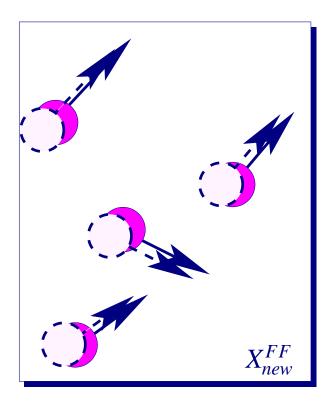
#### Goal

- Ab-initio geometry optimization: 100–200 steps
- Reduce the number of ab-initio calculation using a force field:
  - force field iteration very low cost compared to an ab initio iteration

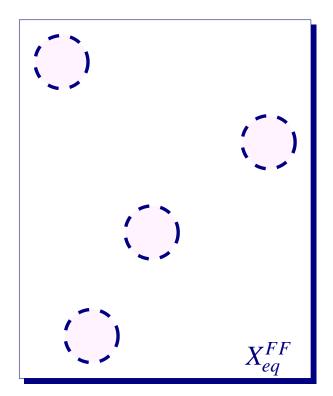
1. Ab initio (AB) positions  $X_i^{AB}$  and  $Force_i^{AB}$ 



- 1. Ab initio (AB) positions  $X_i^{AB}$  and  $Force_i^{AB}$
- 2. Force Field (FF)
  Looking for  $X_{new}^{FF}$  so that  $Force^{FF}\left(X_{new}^{FF}\right) == Force_{i}^{AB}$ using SD or CG.

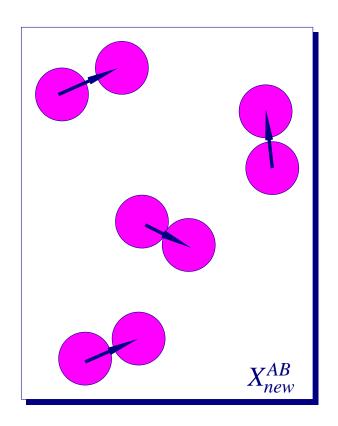


- 1. Ab initio (AB) positions  $X_i^{AB}$  and  $Force_i^{AB}$
- 2. Force Field (FF)
  Looking for  $X_{new}^{FF}$  so that  $Force^{FF}\left(X_{new}^{FF}\right) == Force_{i}^{AB}$ using SD or CG.
- 3. Force Field (FF) Looking for  $X_{eq}^{FF}$  with SD of CG



- 1. Ab initio (AB) positions  $X_i^{AB}$  and  $Force_i^{AB}$
- 2. Force Field (FF)
  Looking for  $X_{new}^{FF}$  so that  $Force^{FF}\left(X_{new}^{FF}\right) == Force_{i}^{AB}$ using SD or CG.
- 3. Force Field (FF) Looking for  $X_{eq}^{FF}$  with SD of CG
- 4. New position (AB) using SD or DIIS

$$\delta X^{AB} = X_{eq}^{FF} - X_{new}^{FF}$$
$$X_{i+1}^{AB} = X_i^{AB} + \alpha \delta X^{AB}$$



# **Advantages**

- In contrast to BFGS, valid also outside of a quadratic region
- If Force Field identical to Ab initio: only 1 step
- Applicable also for the search of saddle points

# **Advantages**

- In contrast to BFGS, valid also outside of a quadratic region
- If Force Field identical to Ab initio: only 1 step
- Applicable also for the search of saddle points

#### **Drawbacks**

Need an accurate Force Field

# (Preliminary) Results

Silicon HGH pp ecut 7.5 Hartree tolmxf 2.57e-6 Hartree/bohr (1.e-4 eV/angström)

Type	bfgs	lenosky	bazant
Cluster(5)	18	20	45
<b>Si-64</b>	31	11	13
<b>Si-63</b>	123	15	16
Surface			143

# Comparison in parallel ABINIT – CPMD

#### **Methods**

#### **ABINIT** or **CPMD** (diagonalisation scheme):

$$\frac{\partial}{\partial \Psi} \left( \frac{1}{2} \Psi^T H[\rho] \Psi \right) = H[\rho] \Psi$$

Si 64 atoms:

**ABINIT 370 s, CPMD 415 s** 

#### **Methods**

#### **ABINIT** or **CPMD** (diagonalisation scheme):

$$\frac{\partial}{\partial \Psi} \left( \frac{1}{2} \Psi^T H[\rho] \Psi \right) = H[\rho] \Psi$$

Si 64 atoms:

**ABINIT 370 s, CPMD 415 s** 

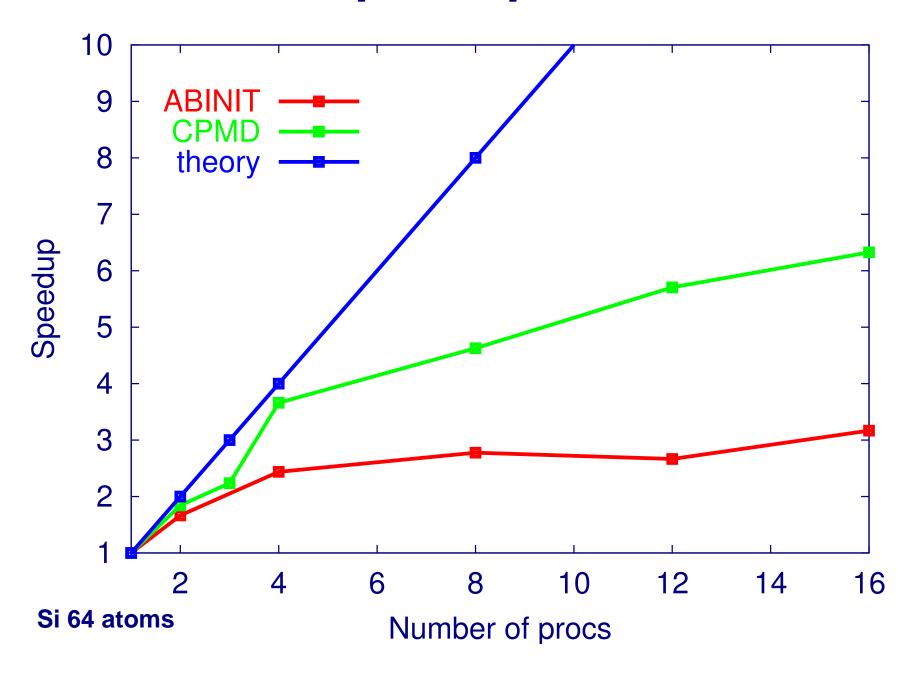
#### Variational principle (CPMD):

$$\frac{\partial}{\partial \Psi} E_{tot}^{DFT} (\Psi_1, \Psi_2, \dots, \Psi_N) = H[\rho] \Psi_i$$

Need a gap

**CPMD 280s** 

# **Speedup**



## A 3-dim FFT

Stefan Goedecker

DRFMC, CEA Grenoble
SGoedecker@cea.fr

## **Basic problems**

- Low ratio between floating point operations and data (load/store's)
   3-dim FFT:
  - $N^3$  data points
  - $15N^3\log_2(N)$  floating point operations
- Large data sets that do not fit into cache
- Highly nonlocal data access pattern

#### **Serial optimization discussed in:**

S. Goedecker, A. Hoisie: "Performance Optimization of Numerically Intensive Codes", SIAM, 2001 (ISBN 0-89871-484-2)

# Rotation technique for 3-dim FFT

#### **Convention:**

```
i1, i2, i3 untransformed dimensions
I1, I2, I3 transformed dimensions
i3 = (j3, jp3)
I3 = (J3, Jp3)
```

```
Input: i1, i2, j3, jp3
where i1 = 1, n1
i2 = 1,n2
j3 = 1, n3/nproc
jp3 = 1, nproc
```

# Rotation technique for 3-dim FFT

multiple 1-dim FFT: i1, I2, j3, jp3

Rotation and removal: I2, i1, j3, jp3

multiple 1-dim FFT: I2, I1, j3, jp3

Rotation and removal: I1, I2, j3, jp3

#### **Convention:**

i1, i2, i3 untransf. dim.

11, 12, 13 transf. dim.

i3 = (j3, jp3)

13 = (J3, Jp3)

Previous data set reformatted: I1, J2, Jp2, j3, jp3

Copy: I1, J2, j3, Jp2, jp3

MPI\_ALLTOALL: I1, J2, j3, jp3, Jp2

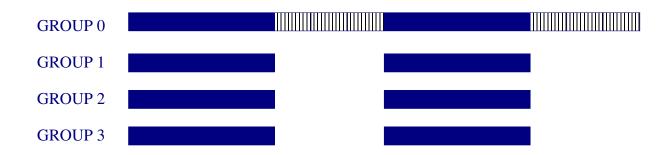
Previous data set reformatted: I1, J2, i3, Jp2

FFT: I1, J2, I3, Jp2

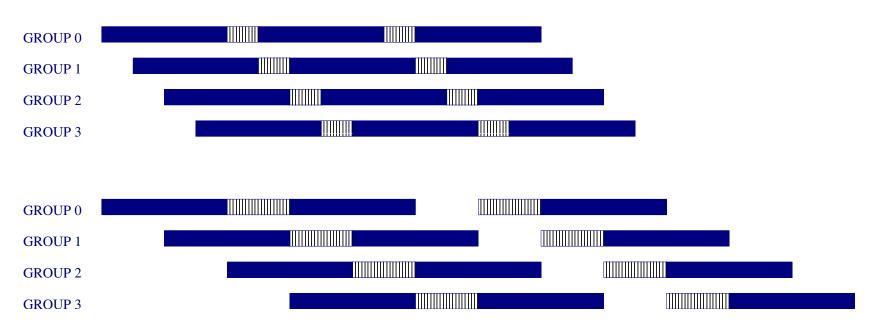
Copy: I1, I3, J2, Jp2

# **Communication traffic patterns**

#### In a conventional MPI/OpenMP implementation



#### In this MPI/OpenMP implementation



#### Results obtained so far

OpenMP/MPI approach gives 2 times higher speed than pure MPI approach

60 Gflops for a  $128^3$  FFT on 64 nodes (256 processors) Speedup of more than 100 compared to serial FFT

Speedup of 3.3 for the pure OpenMP version on the 4 processors of one node