# **Communication & Detection**

# **Theory Summary**

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# 1. Introduction

### **Functions & Signals**

Real-valued signal:  $\mathbb{R} \mapsto \mathbb{R}$ Complex-valued signal:  $\mathbb{R} \mapsto \mathbb{C}$ 

Integrable: integral  $\int_{-\infty}^{\infty} u(t) \; dt$  exists if

- "Lebesgue-measurable" (not jumping around)
- $\|u\|_1 = \int_{-\infty}^{\infty} |u(t)| dt < \infty$

 $\mathcal{L}_1$  : set of all integrable functions

$$\int_{-\infty}^{\infty} u(t) dt = \int_{-\infty}^{\infty} Re\{u(t)\} dt + i * \int_{-\infty}^{\infty} Im\{u(t)\} dt$$

**Lebesgue measure zero:** We say that a set of points is a of  $\mathcal{L}_2$  if the integral doesn't change if we add it (e.g. by only changing any finite or countable infinite number of points):

A set  $N \subseteq \mathbb{R}$  is a set of *Lebesgue measure zero*, if  $\forall \ \varepsilon > 0$  we can find a sequence of intervals  $[a_1,b_1],[a_2,b_2],...$ 

- total length is smaller than  $\varepsilon: \sum_{j=1}^{\infty} \left(b_j a_j\right) < \varepsilon$
- union of all intervals covers N :  $N \subseteq \bigcup_{j=1}^{\infty} [a_j, b_j]$

**Indistinguishable:** u, v are indistinguishable

$$\underline{u} \equiv \underline{v}$$

if they only differ on a set of Lebesgue measure zero

$$\underline{u} \equiv \underline{v} \iff \int_{-\infty}^{\infty} |u(t) - v(t)| \ dt = 0$$
$$\iff \int_{-\infty}^{\infty} |u(t) - v(t)|^2 \ dt = 0$$

$$\underline{u} \equiv \underline{v} \implies \int_{-\infty}^{\infty} u(t) dt = \int_{-\infty}^{\infty} v(t) dt$$

### **Operations on Signals**

Time shift:  $t \mapsto x(t-t_0)$ 

Time reflection:  $\bar{x}: t \mapsto x(-t)$ 

**Convolution:**  $x * h : t \mapsto \int_{-\infty}^{\infty} x(\tau)h(t-\tau) d\tau$ 

Inner product:

$$\langle u, v \rangle = \int_{-\infty}^{\infty} u(t) v^*(t) dt$$

Orthogonal:  $\langle u, v \rangle = 0$ 

$$< u, v> = < v, u>^* \\ < \alpha u, v> = \alpha < u, v> \quad \alpha \in \mathbb{C} \\ < u, \alpha v> = \alpha^* < u, v> \quad \alpha \in \mathbb{C} \\ < u_1 + u_2, v> = < u_1, v> + < u_2, v> \\ < u, v_1 + v_2> = < u, v_1> + < u, v_2>$$

### **Energy**

 $\mathcal{L}_2$ : set of energy-limited signals; if  $||u||_2 < \infty$ 

$$||u||_2^2 = \langle u, u \rangle = \int_{-\infty}^{\infty} |u(t)|^2 dt$$
$$||u||_2 = \sqrt{\int_{-\infty}^{\infty} |u(t)|^2 dt}$$

### **Fourier transform**

$$\hat{x}: f \mapsto \int_{-\infty}^{\infty} x(t) e^{-i2\pi f t} dt$$
,  $x \in \mathcal{L}_1$ 

IFT: 
$$\check{g}: t \mapsto \int_{-\infty}^{\infty} g(f) \, e^{i2\pi f t} \, dt$$
 ,  $g \in \mathcal{L}_1$ 

Table: 
$$t \mapsto x(t - t_0)$$
  $f \mapsto e^{-i 2\pi f t_0} \hat{x}(f)$   $x * y$   $\hat{x} \cdot \hat{y}$   $\hat{x} \cdot \hat{y}$   $\hat{x} \cdot \hat{y}$   $\hat{x}$ 

For **real signals**:  $\hat{x}(-f) = \hat{x}^*(f)$  (conjugate symmetric)

### **Useful theorems**

### **Cauchy-Schwarz Inequality**

$$|\langle u, v \rangle| \leq ||u||_2 \cdot ||v||_2$$

$$\left| \int_{-\infty}^{\infty} u(t) v^*(t) dt \right|^2 \le \int_{-\infty}^{\infty} |u(t)|^2 dt \cdot \int_{-\infty}^{\infty} |v(t)|^2 dt$$

#### Triangle Inequality for $\mathcal{L}_2$

$$\begin{aligned} |||u||_2 - ||v||_2| & \leq ||u + v||_2 \leq ||u||_2 + ||v||_2 \\ ||u + v||_2^2 & = ||u||_2^2 + ||v||_2^2 + 2 \Re\{\langle u, v \rangle\} \\ ||u - v||_2^2 & = ||u||_2^2 + ||v||_2^2 - 2 \Re\{\langle u, v \rangle\} \end{aligned}$$

#### **Parseval Theorem**

FT preserves inner product and therefore the energy

$$\langle u, v \rangle = \langle \hat{u}, \hat{v} \rangle \quad \Leftrightarrow \quad \|u\|_2 = \|\hat{u}\|_2$$

### Filters & Bandwidth

**Filter** with impulse response h: input  $x \mapsto \text{output } x * h$ 

$$y(t) = \int_{-\infty}^{\infty} h(\tau) x(t-\tau)$$

Stable: if h is integrable

 $\hat{h}$  : frequency response of the filter

**Bandwidth:** x is bandlimited to W Hz, if W smallest nr. S.t.

$$\hat{x}(f) = 0 \quad , \qquad |f| > W$$

A signal is said to be bandlimited to W Hz, if it is unchanged when lowpassfiltered by ideal lowpass  $F_W$ :

$$x(t) = (x * LPF_W)(t)$$
,  $t \in \mathbb{R}$ 

$$LPF_W = 2W \ sinc \ (Wt)$$
 ,  $\widehat{LPF_W} = I\{ |f| \le W \}$ 

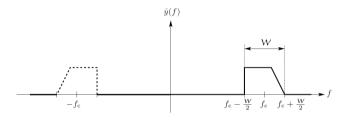
Indistinguishable functions have the same FT

# 2. Passband Signals

x is a passband signal that is bandlimited to W Hz around the carrier frequency  $f_c$  if:

$$- f_c > \frac{w}{2} > 0$$

$$-\hat{x}_{PB}(f) = 0 \quad \forall \ \left| |f| - f_c \right| > \frac{W}{2}$$



A signal is bandlimited around a carrier frequency, if it stays the same after filtering with the bandpass BPF:

$$x_{PB}(t) = (x_{PB} * BPF_{W,f_c})(t)$$
,  $t \in \Re$ 

$$BPF_{W,f_c} = 2W \ sinc(Wt) \cos(2\pi f_c t)$$

The bandwidth W is influenced by the carrier frequency  $f_c$ 

### Multiplication by a carrier

Multiplying by a carrier frequency doubles the bandwidth (now, entire signal, i.e. also parts previously on the negative side of the axis, count towards the bandwidth)

x: bandlimited to W Hz

$$y: t \mapsto x(t)\cos(2\pi f_c t)$$

$$\hat{y}(f) = \frac{1}{2} \,\hat{x}(f - f_c) + \frac{1}{2} \,\hat{x}(f + f_c)$$

### **Analytic representation**

For a real, bandlimited signal  $x_{PB}$  around  $f_c$ :

$$x_{PB}(t) = x_A(t) + x_A^*(t) = 2 \Re\{x_A(t)\}\$$
  
 $\hat{x}_{PB}(f) = \hat{x}_A(f) + \hat{x}_A^*(-f)$ 

$$\hat{x}_{\scriptscriptstyle A}(f) = \hat{x}_{\scriptscriptstyle DR}(f) \ I\{ f \ge 0 \}$$

If  $x_{PB}$  real  $\Rightarrow$   $|x_A|$  is symmetric

Energy:  $||x_{PB}||_2^2 = 2 ||x_A||_2^2$ 

Inner product:  $\langle x_{PB}, y_{PB} \rangle = 2 \Re \{ \langle x_A, y_A \rangle \}$ 

### Baseband representation of a real signal

The baseband representation of a *real* passband signal is the analytic representation shifted by  $f_c$ :

$$\hat{x}_{BB}(f) = \hat{x}_{A}(f + f_{c}) = \hat{x}_{PB}(f + f_{c}) \ I\{|f| \le W/2\}$$

$$x_{BB}(t) = e^{-i 2\pi f_{c}t} x_{A}(t)$$

The same can be achieved directly with the passband signal:

$$x_{BB} = (e^{-i 2\pi f_C t} x_{PB}(t)) * LPF_{W_C}, \qquad W_C = \frac{W}{2}$$

Recovering  $x_{PB}$  from  $x_{BB}$  and  $f_c$ 

(TD) 
$$x_{PB} = 2 \Re \{ x_{BB} e^{i 2\pi f_C t} \}$$

$$(FD) \qquad \hat{x}_{PB}(f) = \hat{x}_{BB}(f - f_c) + \hat{x}_{BB}^*(-f - f_c)$$

$$\langle x_{PB}, y_{PB} \rangle = 2 \Re \{ \langle x_{BB}, y_{BB} \rangle \}$$

$$||x_{PB}||_2^2 = 2 ||x_{BB}||_2^2$$

i)  $x_{PB}$ ,  $y_{PB}$  orthogonal iff  $\langle x_{BB}, y_{BB} \rangle$  is purely imaginary

ii) 
$$z_{PB} = x_{PB} * y_{PB} \implies z_{BB} = x_{BB} * y_{BB}$$

### **In-Phase & Quadrature Components**

In reality, we calculate  $x_{BB}$  by splitting it up into its inphase and its quadrature part, which we calculate separately:

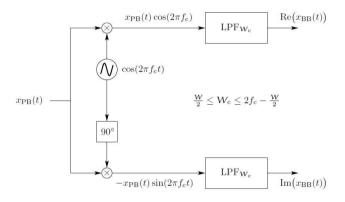
$$x_{BB} = (t \mapsto e^{-i 2\pi f_C t} x_{PB}(t)) * LPF_{W_C}$$

$$= (t \mapsto x_{PB}(t) \cos(2\pi f_C t)) * LPF_{W_C}$$

$$-i (t \mapsto x_{PB}(t) \sin(2\pi f_C t)) * LPF_{W_C}$$

 $In-Phase \triangleq Re(x_{BB}(t))$ 

Quadrature  $\triangleq Im(x_{BB}(t))$ 



### Baseband representation of filtered signal

BB representation of  $x_{PB}*h$  is of FT

$$f \mapsto \hat{x}_{BB}(f) \hat{h}(f + f_c)$$

# 3. Complete Orthonormal Systems & the Sampling Theorem

**Vector space:** set of vectors with two operations:

 $- \forall v \in V$ ,  $\forall \alpha \in \mathbb{C}$ :  $\alpha \cdot v \in V$  (scaling)

 $- \forall v, w \in V : v + w \in V$  (addition)

**Linear subspace:**  $U \subseteq \mathcal{L}_2$  is a linear subspace of  $\mathcal{L}_2$ , if:

- not empty
- closed under amplification:  $\alpha \cdot v \in U$  ,  $v \in U$
- closed under superposition:  $u_1 + u_2 \in U$  ,  $u_1, u_2 \in U$

**Linear combination:**  $v = \alpha_1 u_1 + \dots + \alpha_n u_n = \sum_v \alpha_v u_v$  $span(u_1, \dots, u_n)$  = set of all lin. combinations of  $(u_1, \dots u_n)$ 

**Linear independence:** the n-tuple  $(u_1, ..., u_n)$  is lin. indep. :

$$\sum_{v=1}^{n} \alpha_v u_v = 0 \quad \Leftrightarrow \quad \alpha_v = 0 \quad \forall \ v = 1 \dots n$$

Finite dimensional: counts for subspace  $U \subseteq \mathcal{L}_2$  if there exists an n-tuple  $(u_1, ..., u_n)$  s.t.  $U = span(u_1, ..., u_n)$ 

**Basis:**  $(u_1, ..., u_n)$  is a basis for U with *dimension* n, if

- $(u_1, \dots, u_n)$  are linearly independent
- $-U = span(u_1, ..., u_n)$

**Projection:** projection of v onto u points in direction of u:

$$w = \frac{\langle v, u \rangle}{\|u\|_2^2} \cdot u \qquad , \qquad \langle v - w, u \rangle = 0$$

**Orthogonality:** n-tuple  $(\phi_1, ..., \phi_n)$  is orthogonal if

$$\langle \phi_i, \phi_j \rangle = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$$

### **Projection onto linear subspace**

Let  $U \subseteq \mathcal{L}_2$  have the orthonormal basis  $(\phi_1, ..., \phi_n)$ 

$$u = \sum_{l=1}^{d} \alpha_l \, \phi_l = \sum_{l=1}^{d} \langle u, \phi_l \rangle \, \phi_l$$
 ,  $u \in U$ 

Energy:  $||u||_2^2 = \sum_{l=1}^d |\langle u, \phi_l \rangle|^2$ 

Inner Product:  $\langle v, u \rangle = \sum_{l=1}^{d} \langle v, \phi_l \rangle \langle u, \phi_l \rangle^*$ 

U has orthonormal basis  $\Leftrightarrow$  only element of U with zero energy is the all-zero signal

Closest element: projection w of v onto U is the element of U closest to v:  $||v - u||_2 \ge ||v - w||_2 \quad \forall u \in U$ 

### **Gram-Schmidt Procedure**

Creates an orthonormal basis from any given basis

Given: basis  $u_1, \dots, u_d$ 

$$\phi_{1} = \frac{u_{1}}{\|u_{1}\|_{2}}, \qquad \phi_{i} = \frac{u_{i} - \sum_{l=1}^{i-1} \langle u_{i}, \phi_{l} \rangle \phi_{l}}{\|u_{i} - \sum_{l=1}^{i-1} \langle u_{i}, \phi_{l} \rangle \phi_{l}\|}, i = 2 \dots d$$

### Complete Orthonormal System (CONS)

Orthonormal basis for an infinite-dimensional vector space

A sequence ...,  $\phi_{-1}$ ,  $\phi_0$ ,  $\phi_1$ ,  $\phi_2$ , ... is a CONS for U if

- i)  $\phi_l \subseteq U$
- ii)  $\langle \phi_l, \phi_{l'} \rangle = I\{ l = l' \}$  ,  $l, l' \in \mathbb{Z}$
- iii)  $||u||_2^2 = \sum_{l=-\infty}^{\infty} |\langle u, \phi_l \rangle|^2$ ,  $u \in U$

The following equations are equivalent:

- a)  $\forall u, \varepsilon > 0$ ,  $\exists L_{\varepsilon}, \alpha_i : \| u \sum_{l=-L_{\varepsilon}}^{L_{\varepsilon}} \alpha_l \phi_l \|_2 < \varepsilon$
- b)  $\forall u \in U$ :  $\lim_{l \to \infty} ||u \sum_{l=-L}^{L} \langle u, \phi_l \rangle \phi_l ||_2 = 0$
- c)  $\forall u, v \in U$ :  $\langle u, v \rangle = \sum_{l=-\infty}^{\infty} \langle u, \phi_l \rangle \langle v, \phi_l \rangle^*$
- d) iii) :  $\forall u \in U$  :  $||u||_2^2 = \sum_{l=-\infty}^{\infty} |\langle u, \phi_l \rangle|^2$

#### Example of CONS: Fourier Series

The functions  $\{ \phi_l \}$  define a CONS for the subspace  $\{ u \in \mathcal{L}_2 : u(z) = 0 \ \forall \ |z| > Z \}$  of energy-limited signals

$$\phi_l: z \mapsto \frac{1}{\sqrt{2Z}} e^{i\pi l z/Z} I\{ |z| < Z \}$$

$$\langle u, \phi_l \rangle = \frac{1}{\sqrt{2Z}} \int_{-Z}^{Z} u(z) e^{-i\pi l z/Z} dz$$

### **Sampling Theorem**

x is an energy-limited signal bandlimited to W Hz iff:

$$x = \check{g}$$
  $\exists g: g(f) = 0$ ,  $|f| > W$  
$$\int_{-W}^{W} |g(f)|^2 df < \infty$$

$$U = \{ g \in \mathcal{L}_2 : g(f) = 0, |f| > W \}$$
  
 
$$U' = \{ x : x = \check{g} \text{ for some } g \in U \}$$

*Lemma:* If  $\{\psi_l\}$  is a CONS for U, then  $\{\check{\psi}_l\}$  is a CONS for U'

$$\langle x, \check{\psi} \rangle = \langle \check{g}, \check{\psi} \rangle = \langle g, \psi \rangle$$

### $\mathcal{L}_2$ – Sampling Theorem

$$x,y \in \widecheck{U}$$
,  $T = \frac{1}{2W}$  or simply  $0 < T \le \frac{1}{2W}$ 

i) reconstruct signal from samples ..., x(-T), x(0), x(T), ...:

$$\lim_{L \to \infty} \int_{-\infty}^{\infty} \left| x(t) - \sum_{l=-L}^{L} x(-lT) \operatorname{sinc} \left( \frac{t}{T} + l \right) \right|^{2} dt = 0$$

ii) reconstruct signal's energy by

$$\int_{-\infty}^{\infty} |x(t)|^2 dt = T \sum_{l=-\infty}^{\infty} |x(lT)|^2$$

iii) For another bandlimited signal y we can calculate

$$\langle x, y \rangle = T \sum_{l=-\infty}^{\infty} x(l T) y^*(l T)$$

### **Pointwise Sampling Theorem**

If a signal can be written as

$$x(t) = \int_{-W}^{W} g(t) \, e^{i2\pi f t} \, df \ , \qquad g \in \, \mathcal{L}_2$$

We can write for every  $0 < T \le 1/2W$ 

$$x(t) = \lim_{L \to \infty} \sum_{l=-L}^{L} x(-lT) \operatorname{sinc}\left(\frac{t}{T} + l\right)$$

If  $\{\alpha_l\}_{l=-\infty}^{\infty}$  is square summable, there exists an energy-limited bandlimited signal u s.t.

$$u(lT) = \alpha_l$$
 ,  $l \in \mathbb{Z}, T = \frac{1}{2W}$ 

### **Complex sampling**

If we sample the passband directly, we need  $2\left(f_c + \frac{W}{2}\right)$  real samples / second, which is huge (and depends on  $f_c$ )

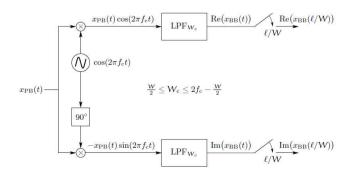
Complex sampling: taking a real passband signal  $x_{PB}$  and sampling its baseband representation to obtain samples

$$2 x (BW \text{ of } x_{BB}) = 2 x \frac{W}{2} = W \frac{complex \text{ samples}}{s}$$

$$x_{BB}\left(\frac{l}{W}\right) = \left(\left(t \mapsto e^{-i2\pi f_c t} x_{PB}(t)\right) * LPF_{W_c}\right) \left(\frac{l}{W}\right)$$

$$= \left(\left(t \mapsto x_{PB}(t)\cos(2\pi f_c t)\right) * LPF_{W_c}\right) \left(\frac{l}{W}\right)$$

$$-i\left(\left(t \mapsto x_{PB}(t)\sin(2\pi f_c t)\right) * LPF_{W_c}\right) \left(\frac{l}{W}\right)$$



$$x_{BB}(t) = \sum_{l=-\infty}^{\infty} x_{BB}\left(\frac{l}{W}\right) sinc(Wt-l)$$

$$x_{PB} = 2 \Re \left\{ e^{i2\pi f_C t} \sum_{l=-\infty}^{\infty} x_{BB} \left( \frac{l}{W} \right) \operatorname{sinc}(Wt - l) \right\}$$

$$= 2 \sum_{l=-\infty}^{\infty} \Re \left\{ x_{BB} \left( \frac{l}{W} \right) \right\} \operatorname{sinc}(Wt - l) \cos(2\pi f_C t)$$

$$-2 \sum_{l=-\infty}^{\infty} \Im \left\{ x_{BB} \left( \frac{l}{W} \right) \right\} \operatorname{sinc}(Wt - l) \sin(2\pi f_C t)$$

### Sampling theorem for real passband signals

i)  $x_{PB}$  can be reconstructed from samples of  $x_{BB}$ :

$$\lim_{L\to\infty}\int\limits_{-\infty}^{\infty}\left(x_{PB}(t)-2\,\Re\left\{e^{i2\pi f_ct}\,\sum_{l=-L}^{L}x_{BB}\left(\frac{l}{W}\right)\,sinc(Wt-l)\right\}\right)^2dt=0$$

ii) reconstruct signal's energy by

$$||x_{PB}||_2^2 = \frac{2}{W} \sum_{l=-\infty}^{\infty} \left| x_{BB} \left( \frac{l}{W} \right) \right|^2$$

iii) For another bandlimited signal  $y_{BB}(l/W)$  we can write

$$\langle x_{PB}, y_{PB} \rangle = \frac{2}{W} \Re \left\{ \sum_{l=-\infty}^{\infty} x_{BB} \left( \frac{l}{W} \right) y_{BB}^* \left( \frac{l}{W} \right) \right\}$$

## 4. Linear Modulation

Modulation system: map data to physical (real) waveform

$$X(t) = \begin{cases} x_0(t) & \text{if } D = 0 \\ x_1(t) & \text{if } D = 1 \end{cases}$$

### Probability space $(\Omega, \mathcal{F}, P(\cdot))$

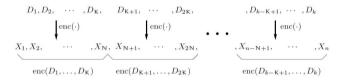
- $\Omega$  : sample space = set of possible outcomes
- $\mathcal{F}$  : set of events
- $P(\cdot)$ : assigns probabilities to events

Stochastic process is a function of time and "luck"

- fix luck: it becomes a function of time
- fix time: it becomes a RV (random variable)

### **Block-Mode Mapping**

(K,N) binary-to-real block encoder of rate  $\frac{K}{N} \left[ \frac{bits}{real \, symbol} \right]$ 



### **Linear Modulation**

$$X(t) = A \sum_{l=1}^{n} X_l g_l(t)$$

The transmitted energy is a RV given by:

$$||X||_2^2 = A^2 \sum_{l} \sum_{l'} X_l X_{l'} \langle g_l, g_{l'} \rangle$$

If the signals are orthogonal, this simplifies to:

$$||X||_2^2 = A^2 \sum_{l=1}^n X_l^2$$

### **Recovering with Matched Filter**

$$X(t) = A \sum_{l=1}^{n} X_l \, \phi_l(t)$$

Where  $\phi_1, \dots, \phi_n$  are orthonormal and  $X_l$  is given by

$$X_l = \frac{1}{A} \langle X, \, \phi_l \rangle$$

**Matched filter:** for a signal  $\phi$ , the matched filter is

$$t \mapsto \overline{\phi^*}(t) = \phi^*(-t)$$

With this matched filter, we can directly calculate

$$\langle u, \phi(t-t_0) \rangle = (u * \overleftarrow{\phi^*}) (t_0)$$

By using  $\phi_l = \phi(t - lT_s)$  we can now calculate

$$X_l = \frac{1}{A} \left( X * \overleftarrow{\phi^*} \right) (lT_s)$$

This leads us to Pulse Amplitude Modulation

### Constellation

Map  $D_1, \ldots, D_k$  to  $X_1, \ldots, X_n$  using a one-to-one mapping

$$\varphi: \{0,1\}^k \rightarrow \mathbb{R}^n$$

The set of all values  $\chi$  which can be created with  $\varphi$  is called a *constellation*, where the **number of points** is  $\#\chi = |\chi|$ 

Minimum distance:  $\delta = \min_{x,x' \in \chi} |x - x'|$ 

Second moment:  $\frac{1}{|\chi|} \sum_{x \in \chi} x^2$ 

### 5. Pulse Amplitude Modulation (PAM)

The bits  $D_1, \dots, D_l$  are mapped to  $X_1, \dots, X_n$  by

$$X(t) = A \sum_{l=1}^{n} X_l \, \phi_l(t - l \, T_s)$$

 $T_s > 0$ : baud period ;  $\frac{1}{T_s}$ : baud rate  $\left[\frac{real\ symbols}{s}\right]$ 

We want the signals  $\phi_1, \dots, \phi_n$  to be orthogonal:

$$\int_{-\infty}^{\infty} \phi(t - l T_s) \phi^*(t - l' T_s) dt = \begin{cases} 1 & \text{if } l' = l \\ 0 & \text{if } l' \neq l \end{cases}$$

Taking a signal with duration less than  $T_s$  would work; however, this would imply an infinite bandwidth

### **Self-similarity function**

$$R_{v,v}(\tau) = \int_{-\infty}^{\infty} v(t+\tau) v^*(t) dt , \qquad v: \mathbb{R} \mapsto \mathbb{C}$$

#### **Properties**

- 1)  $R_{v,v}(0) = ||v||_2^2$
- 2)  $|R_{v,v}(\tau)| \le R_{v,v}(0)$  (maximum at origin)
- 3)  $R_{v,v}(-\tau) = R_{v,v}^*(\tau)$
- 4)  $R_{v,v}(\tau) = \int_{-\infty}^{\infty} |\hat{v}(f)|^2 e^{i2\pi f \tau} df$
- 5)  $R_{v,v}$  is uniformly continuous
- 6)  $R_{v,v}(\tau) = (v * \bar{v}^*)(\tau)$

We will often need it with a filter:

$$R_{g,g}(\tau) = \int_{-\infty}^{\infty} |\hat{g}(f)|^2 \ e^{i2\pi f \tau} \ df$$

### Nyquist pulse & criteria

 $v: \mathbb{R} \mapsto \mathbb{C}$  is a Nyquist pulse of parameter  $T_s$  if

$$v(l T_s) = I\{l = 0\} \qquad \forall l \in \mathbb{Z}$$

#### **Nyquist criterion**

For  $T_s > 0$  ,  $v = \check{g} : v$  is a Nyquist pulse if and only if

$$\lim_{J \to \infty} \int_{-\frac{1}{2T_s}}^{\frac{1}{2T_s}} \left| T_s - \sum_{j=-J}^{J} g\left(f + \frac{j}{T_s}\right) \right| df = 0 \quad \Leftrightarrow \quad$$

$$\sum_{j=-\infty}^{\infty} g\left(f + \frac{j}{T_s}\right) \equiv T_s \quad \forall f \in \mathbb{R}$$

With this, we can conclude that  $R_{\phi,\phi}$  is a Nyquist pulse:

$$\int_{-\infty}^{\infty} \phi(t - l T_s) \phi^*(t - l' T_s) dt = I\{l = l'\}$$

if and only if: 
$$\sum_{j=-\infty}^{\infty} \left| \hat{\phi} \left( f - \frac{j}{T_s} \right) \right|^2 \equiv T_s$$

Corollary: If  $\phi$  are orthonormal and bandlimited to W Hz, then  $W \geq \frac{1}{2T_c}$ 

Sinc: most efficient, but very slow decay in time-domain

$$\phi(t) = \frac{1}{\sqrt{T_s}} \operatorname{sinc}\left(\frac{t}{T_s}\right), \quad t \in \mathbb{R}$$

**Raised-cosine:** roll-off factor  $\beta \in [0,1]$ 

$$\left|\hat{\phi}(f)\right|^{2} = \begin{cases} T_{s} & 0 \leq |f| \leq \frac{1-\beta}{2T_{s}} \\ \frac{T_{s}}{2} \left(1 + \cos\left(\frac{\pi T_{s}}{\beta} \left(|f| - \frac{1-\beta}{2T_{s}}\right)\right) \\ 0 & |f| > \frac{1-\beta}{2T_{s}} \end{cases}$$

# 6. PAM: Energy, Power & Power Spectral Density (PSD)

### **Energy in Pam**

Effective energy is random:

$$E_s = \int_{-\infty}^{\infty} X^2(t) dt$$

#### **Expected energy**

$$\varepsilon = E[E_s] = A^2 \sum_{l=1}^{N} \sum_{l'=1}^{N} E[X_l X_{l'}] R_{g,g}((l-l') T_s)$$

$$= A^{2} \int_{-\infty}^{\infty} \sum_{l} \sum_{l'} E[X_{l} X_{l'}] e^{i2\pi f(l-l')T_{S}} |\hat{g}(f)|^{2} df$$

Energy per bit:  $\varepsilon_b = \frac{\varepsilon}{\kappa} \iff$  Energy per symbol:  $\varepsilon_s = \frac{\varepsilon}{\kappa}$ 

If g's are orthogonal, or if zero-mean & uncorrelated:

$$\varepsilon = A^2 \|g\|_2^2 \sum_{l=1}^N E[X_l^2]$$

### **Power in PAM**

$$P = \lim_{T \to \infty} \frac{1}{2T} E \left[ \int_{-T}^{T} X^{2}(t) dt \right]$$

a) We need a converging sum:

$$|g(t)| \le \frac{\beta}{1 + \left| \frac{t}{T_s} \right|^{1+\alpha}}, \quad \alpha, \beta > 0$$

b) How to generate  $(X_I)$ :

- i)  $(X_I)$  is WSS & zero-mean
- ii) bi-infinte block encoding
- iii)  $g = \phi$  (orthogonal signals)

With zero-mean, we use the least power for the same info, as  $E[(W-c)^2] \ge Var[W]$  with equality iff c = E[W]

i)  $(X_I)$  is WSS & zero-mean (additive noise)

$$E[X_l] = 0$$
,  $E[X_l X_{l+m}] = K_{xx}(m)$ 

$$P = \frac{A^2}{T_s} \sum_{m=-\infty}^{\infty} K_{xx}(m) R_{g,g}(m T_s)$$

$$= \frac{A^2}{T_s} \int_{-\infty}^{\infty} \sum_{m} K_{x,x}(m) e^{i2\pi f m T_s} |\hat{g}(f)|^2 df$$

$$(X_l)$$
 uncorrelated:  $P = \frac{A^2}{T_S} \sigma_x^2 ||g||_2^2$ 

ii) Bi-infinite Block Mode

$$D_v = (D_{v_{K+1}}, \dots, D_{v_{K+k}}), \qquad X_v = enc(D_v)$$

$$P = \frac{1}{N T_s} E \left[ \int_{-\infty}^{\infty} \left( A \sum_{l=1}^{N} X_l g(t - l T_s) \right)^2 dt \right] = \frac{\varepsilon}{T_s}$$

iii) Pulse Shape is orthogonal

$$X(t) = A \sum_{l=-\infty}^{\infty} X_l \, \phi(t - l \, T_s)$$

$$P = \frac{A^2}{T_s} \lim_{L \to \infty} \frac{1}{2L+1} \sum_{l=-L}^{L} E[X_l^2]$$

A large variance leads to a large power consumption

### Power Spectral Density (PSD)

See "Various" for computation

PSD = (Autocorr. fct.)Usually:

$$S_{xx} = \widehat{K}_{xx}$$

However, we want to calculate the PSD for non-WSS signals, which leads us to Operational PSD (OPSD)

### Operational PSD (OPSD)

We search a function  $S_{xx}$  which fulfils:

Power of 
$$X = \int_D S_{xx}(f) df = \int_{-\infty}^{\infty} I\{f \in D\} S_{xx}(f) df$$

We can write this as the power filtered by  $h \in \mathcal{L}_1$ :

Power of 
$$X * h = \int_{-\infty}^{\infty} |\hat{h}(f)|^2 S_{xx}(f) df$$

For uniqueness, we further want:  $S_{xx}(f) = S_{xx}(-f)$ 

 $S_{xx}$  is measurable, integrable and symmetric as well as non-negative except on a set of Lebesgue measure zero

$$(X*h)(t) = A \sum_{l} X_{l} (g*h)(t-lT_{s})$$

i) Case 1:  $(X_I)$  WSS & zero-mean

$$S_{xx}(f) = \frac{A^2}{T_c} \sum_{m} K_{xx}(m) e^{i2\pi f m T_s} |\hat{g}(f)|^2$$

ii) Case 2: Infinite Block Mode

$$S_{xx}(f) = \frac{A^2}{NT_s} \sum_{l=1}^{N} \sum_{l'=1}^{N} E[X_l X_{l'}] e^{i2\pi f(l-l')T_s} |\hat{g}(f)|^2$$

iii) Case 3: Orthogonal Pulse shape: doesn't work, as pulses are not orthogonal after filtering

We say a SP(X(f)) of OPSD  $S_{xx}$  is **bandlimited to W Hz**:

$$S_{rr}(f) = 0$$
 ,  $|f| > W$ 

bandwidth of  $PAM \leq bandwidth$  of gi) Case 1:

bandwidth of PAM = bandwidth of aii) Case 2:

# 7. Quadrature Amp. Mod. (QAM)

QAM signal is a passband signal whose baseband representation is given by a complex PAM signal:

$$X_{PB}(t) = 2 \Re \left\{ A \sum_{l=1}^{N} C_{l} \ g(t - l T_{s}) \ e^{i2\pi f_{c}t} \right\}$$

Splitting it up into the in-phase & quadrature component:

$$\begin{split} X_{PB}(t) &= \sqrt{2}\,A\,\sum\nolimits_{l=1}^{n} \Re\{C_{l}\}\,2\,\Re\left\{\frac{1}{\sqrt{2}}\,g(t-lT_{s})\,e^{i2\pi f_{c}t}\right\} \\ &+ \sqrt{2}\,A\,\sum\nolimits_{l=1}^{n} \Im\{C_{l}\}\,2\,\Re\left\{\frac{i}{\sqrt{2}}\,g(t-lT_{s})\,e^{i2\pi f_{c}t}\right\} \end{split}$$

In-phase component (with corresponding baseband rep.)

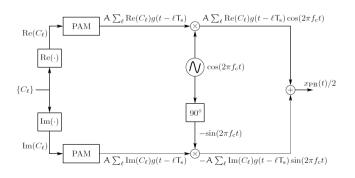
$$g_{I,l} = 2 \Re \left\{ \frac{1}{\sqrt{2}} g(t - lT_s) e^{i2\pi f_c t} \right\}$$

$$g_{I,l,BB} = \frac{1}{\sqrt{2}} g(t - lT_s)$$

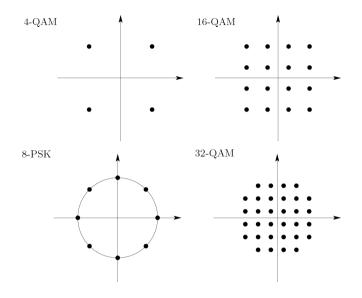
Quadrature component (with corresponding BB rep.)

$$g_{Q,l} = 2 \Re \left\{ \frac{i}{\sqrt{2}} g(t - lT_s) e^{i2\pi f_c t} \right\}$$
$$g_{Q,l,BB} = \frac{i}{\sqrt{2}} g(t - lT_s)$$

For real pulse shapes g, we can draw this as:



#### **QAM Constellations**



Minimum distance:

$$\delta = \min_{c \neq c'} |c - c'|$$

Second moment:

$$\frac{1}{|X|}\sum_{c\in X}|c|^2$$

### **Recovering Complex Symbols via Inner Product**

$$X_{PB} = \sqrt{2} A \sum_{l=1}^{n} \Re\{C_{l}\} \phi_{I,l} + \sqrt{2} A \sum_{l=1}^{n} \Im\{C_{l}\} \phi_{Q,l}$$

$$\Re\{C_{l}\} = \frac{1}{\sqrt{2} A} \langle X_{PB}, \phi_{I,l} \rangle$$

$$\Im\{C_{l}\} = \frac{1}{\sqrt{2} A} \langle X_{PB}, \phi_{Q,l} \rangle$$

where  $\phi$  signals are orthogonal

### **Energy in QAM**

$$E = E \left[ \int_{-\infty}^{\infty} X^{2}(t) dt \right] = 2 E \left[ \int_{-\infty}^{\infty} |X_{BB}(t)|^{2} dt \right]$$
$$= 2 A^{2} \sum_{l=1}^{N} \sum_{l'=1}^{N} E \left[ C_{l} C_{l'}^{*} \right] R_{gg}((l-l') T_{s})$$

### **Power in QAM**

Power in QAM is twice the power in its BB representation

### i) Bi-infinite block mode

$$P_{BB} = \frac{A^2}{N T_S} \int_{-\infty}^{\infty} \sum_{l=1}^{N} \sum_{l'=1}^{N} E[C_l C_{l'}^*] e^{i2\pi f(l'-l)T_S} |\hat{g}(f)|^2 df$$

$$P = \frac{E_S}{T_S} = \frac{E}{T_S N} = 2 P_{BB}$$

### ii) Orthogonal signals

$$\langle g(\cdot -lT_s), g(\cdot -l'T_s) \rangle = I\{l' = l\}$$

$$P = \frac{2A^2}{T_s} \lim_{L \to \infty} \frac{1}{2L+1} \sum_{l=-L}^{L} E[|C_l|^2]$$

### **Operational PSD**

 $S_{zz}$  integrable, must not be symmetric (!)

Power in 
$$Z * h = \int_{-\infty}^{\infty} S_{ZZ}(f) |\hat{h}(f)|^2 df$$

If  $X_{BB}$  has OPSD  $S_{BB}$ , then the OPSD of the QAM signal X is

$$S_{XX}(f) = S_{BB}(|f| - f_c) \quad \forall f_c \in \mathbb{R}$$

For the different cases, look at PAM and adapt the formulae correspondingly

# 8. Hypothesis Testing

### Standard (univariate) Gaussian RV

$$f_W(\omega) = \frac{1}{\sqrt{2\pi}} e^{-\frac{\omega^2}{2}}, \qquad \omega \in \mathbb{R}$$

Standard Gaussian  $X \sim \mathcal{N}(0,1)$ 

Centered Gaussian: X = aW,  $W \sim \mathcal{N}(0,1)$ 

Gaussian:  $X = \sigma W + \mu \sim \mathcal{N}(\mu, \sigma^2)$ 

- $\frac{X-\mu}{\sigma} = W \sim \mathcal{N}(0,1)$  has a standard distribution
- $E[X] = \mu$  ,  $Var[X] = \sigma^2$

$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

 $\mu$  : standard deviation ;  $\sigma^2$  : variance

Affine transformation:  $\alpha X + \beta = X'$ 

### **Q-function**

$$Q(\alpha) = \frac{1}{\sqrt{2\pi}} \int_{\alpha}^{\infty} e^{-\frac{\eta^2}{2}} d\eta$$

### **Properties**

- 1)  $P[W > \alpha] = Q(\alpha)$  $P[W < \alpha] = 1 Q(\alpha)$
- 2)  $P[\alpha \le W \le \beta] = Q(\alpha) Q(\beta)$
- 3)  $Q(-\alpha) = 1 Q(+\alpha)$
- 4)  $X \sim \mathcal{N}(\mu, \sigma^2)$   $P[X > \alpha] = Q\left(\frac{\alpha \mu}{\sigma}\right)$
- $\sum_{i} \alpha_{i} Z_{i} \sim \mathcal{N}(\mu, \sigma^{2}) , Z_{i} \sim \mathcal{N}(\mu_{i}, \sigma_{i}^{2})$   $\mu = \sum_{i} \alpha_{i} \mu_{i} , \sigma^{2} = \sum_{i} \alpha_{i}^{2} \sigma_{i}^{2}$

### **Binary Hypothesis Testing**

Prior: 
$$\pi_0 = P[H = 0]$$
 ,  $\pi_1 = P[H = 1]$    
  $\pi_0, \pi_1 \ge 0$  ,  $\pi_0 + \pi_1 = 1$ 

**Observation:**  $Y \in \mathbb{R}$ 

Guessing rule:  $\varphi_{Guess}: \mathbb{R}^d \mapsto \{0,1\}$ 

Interpretation:  $\varphi_{Guess}(y_{obs}) = 0 \Leftrightarrow "Guess H = 0"$ 

 $\varphi_{Guess}(y_{obs}) = 1 \Leftrightarrow "Guess H = 1"$ 

#### **Probability of error**

$$P[error] = P[\varphi_{Guess}(Y) \neq H]$$

$$= \pi_0 P[\varphi_{Guess}(Y) = 1 \mid H = 0] + \pi_1 P[\varphi_{Guess}(Y) = 0 \mid H = 1]$$

### **Optimal Guessing rule**

Optimal rule is the one which minimizes P[error]

Optimal probability of error:  $p^*(error)$ 

#### No observation/observable

$$\varphi_{Guess}^* = \left\{ \begin{array}{ll} 0 & \pi_0 > \pi_1 \\ 1 & \pi_0 < \pi_1 \end{array} \right.$$

$$p_{Guess}^*(error) = \min\{\pi_0, \pi_1\}$$

With observable:  $Y = y_{obs}$ 

$$f_Y(y_{obs}) = \pi_0 f_{Y|H}(y_{obs} | H = 0) + \pi_1 f_{Y|H}(y_{obs} | H = 1)$$

"A posteriori" probability:

$$P[H = 0 | Y = y_{obs}] = \frac{\pi_0 f_{Y|H=0}(y_{obs} | H = 0)}{f_Y(y_{obs})}$$

$$P[H = 1 | Y = y_{obs}] = \frac{\pi_1 f_{Y|H=1}(y_{obs} | H = 1)}{f_Y(y_{obs})}$$

$$\varphi_{Guess}^*(y_{obs}) = \begin{cases} 0 & \pi_0 f_{Y|H=0}(y_{obs}) > \pi_1 f_{Y|H=1}(y_{obs}) \\ 1 & \pi_0 f_{Y|H=0}(y_{obs}) \le \pi_1 f_{Y|H=1}(y_{obs}) \end{cases}$$

$$p^*(error) = \int_{\mathbb{R}^d} \min \big\{ \, \pi_0 \, f_{Y|H=0}(y), \pi_1 \, f_{Y|H=1}(y) \, \big\} \, \, dy$$

### Randomized Guessing rule

$$\theta \sim Unif[0,1]$$
 ; bias  $b(y_{obs}) \in [0,1]$   
 $\theta \leq b(y_{obs})$   $\Rightarrow$  Guess "H=0"  
 $\theta > b(y_{obs})$   $\Rightarrow$  Guess "H=1"

#### Likelihood ratio

$$LR(y) = \frac{f_{Y|H=0}(y)}{f_{Y|H=1}(y)} \begin{cases} > \frac{\pi_1}{\pi_0} & \to \text{"}H = 0\text{"} \\ < \frac{\pi_1}{\pi_0} & \to \text{"}H = 1\text{"} \end{cases}$$
$$\frac{\alpha}{0} = \infty \ (\alpha > 0) \ , \qquad \frac{0}{0} = 1$$

MAP (Maximum a posteriori): see optimal rule

### ML (Maximum likelihood)

Equal to MAP for a uniform prior, as it ignores priors

$$\varphi_{ML}(y_{obs}) = \begin{cases} 0 & LR(y_{obs}) > 1\\ 1 & LR(y_{obs}) < 1 \end{cases}$$

Randomized if equal ( $LR(y_{obs}) = 1$ )

### **Bhattacharyya Bound**

$$p^*(error) \le \frac{1}{2} \int_{\mathbb{R}^d} \sqrt{f_{Y|H=0}(y) f_{Y|H=1}(y)} dy$$

### **Processing Y**

No rule based on the processed data can outperform the optimal rule

### Sufficient statistics

A sufficient statistics is a processed version Z of Y s.t. basing our guess on Y only via Z, there still exists an optimal guessing rule that depends only on Z

This means that we can calculate the likelihood ratio by only regarding  $\boldsymbol{Z}$ 

### Multi-dimensional Gaussian hypothesis testing

Given:  $Y \in \mathbb{R}^j$ 

"H=0": 
$$Y^{(j)} = s_0^{(j)} + Z_j$$
,  $j = 1 ... J$ 

"H=1": 
$$Y^{(j)} = s_1^{(j)} + Z_j$$
,  $j = 1 ... J$ 

where  $Z_1, ..., Z_J$  are  $IID \mathcal{N}(0, \sigma^2)$ ;  $s_0, s_1 \in \mathbb{R}^J$ 

Euclidean product:  $\langle u, v \rangle_{\epsilon} = \sum_{j=1}^{J} u^{(j)} v^{(j)}$ 

Norm:  $||u|| = \sqrt{\langle u, u \rangle_{\epsilon}}$ 

#### Likelihood function

$$LR(y) = \exp\left\{\frac{1}{2\sigma^2} \left[ \|y - s_1\|^2 - \|y - s_0\|^2 \right] \right\}$$

We can rewrite those rules by defining

$$\varphi = \frac{s_0 - s_1}{\|s_0 - s_1\|_{\epsilon}}, \quad \|\varphi\| = 1$$

Guessing Y based on  $T(Y) = \langle Y, \varphi \rangle$  is also optimal

$$LR(t) = \exp\left\{\frac{(t - \langle s_1, \varphi \rangle_{\epsilon})^2 - (t - \langle s_0, \varphi \rangle_{\epsilon})^2}{2\sigma^2}\right\}$$

$$\varphi_{MAP}(y) = \begin{cases} 0 & \langle y, \varphi \rangle \geq \frac{\langle s_0, \varphi \rangle + \langle s_1, \varphi \rangle}{2} + \underbrace{\frac{\sigma^2}{\|s_0 - s_1\|} \ln \frac{\pi_1}{\pi_0}}_{bias} \end{cases}$$

$$1 & otherwise$$

**Nearest neighbour rule:** chose the one which is nearer to the point, whereby you include the bias from the prior

For  $\pi_0=\pi_1=rac{1}{2}$  , we get the error probability

$$p^*(error) = Q\left(\frac{\|s_0 - s_1\|}{2\sigma}\right)$$

For the general formula, see p.395

# 9. Multi-hypothesis Testing

$$\begin{split} M \in \ \mathcal{M} &= \{\,1,\ldots,|\mathcal{M}|\,\} \\ \pi_m &= \Pr[\,M = m] \ \geq 0 \;, \qquad \sum_{m \in \mathcal{M}} \pi_m = 1 \\ f_Y(y) &= \sum_{m \in \mathcal{M}} \pi_m \, f_{Y|M = m}(y) \end{split}$$

#### Without observation

$$\phi^*=\widetilde{m}$$
 , where  $\pi_{\widetilde{m}}=\max_{m\in\mathcal{M}}\pi_m$  
$$p^*(error)=1-p^*(correct)=1-\max_{m\in\mathcal{M}}\pi_m$$

#### With observation

$$\Pr[\ M = \widetilde{m} \mid Y = y_{obs}\ ] = \max_{m \in \mathcal{M}} \Pr[\ M = m \mid Y = y_{obs}]$$

$$p^*(error) = 1 - \int f_Y(y) \max_{m \in \mathcal{M}} \Pr[M = m \mid Y = y] dy$$

$$\phi^*(y_{obs}) \in \widetilde{\mathcal{M}}(y_{obs})$$

$$\widetilde{\mathcal{M}}(y_{obs}) = \left\{ \widetilde{m} : \pi_{\widetilde{m}} f_{Y|M=\widetilde{m}}(y_{obs}) = \max_{m \in \mathcal{M}} \pi_m f_{Y|M=m}(y_{obs}) \right\}$$

**MAP:** pick uniformly from  $\widetilde{\mathcal{M}}(y_{obs})$ 

ML: ignores priors, just take one with maximal density

#### **Union-Bound**

$$Pr(A \cup B) = Pr(A) + Pr(B) - Pr(A \cap B)$$
  
 $Pr(A \cup B) \le Pr(A) + Pr(B)$ 

In general:

$$\Pr\left(\bigcup_{j} U_{j}\right) \leq \sum_{j} \Pr(U_{j})$$

For hypothesis testing:

$$\Pr(\phi \neq m) \leq \sum_{m' \neq m} P\left[\frac{\pi_{m'}}{\pi_{m'} + \pi_m} f_{Y|M=m'}(y) \geq \frac{\pi_m}{\pi_{m'} + \pi_m} f_{Y|M=m}(y)\right]$$

### **General M-ary Gaussian Hypothesis Testing**

For equi-norm vectors:  $||s_1|| = ||s_2|| = \cdots = ||s_m||$ 

$$\widetilde{\mathcal{M}}(y) = \arg\max_{m} \{ \langle y, s_m \rangle_{\epsilon} \}$$

$$p^*(err) \leq \sum_{m \in \mathcal{M}} \pi_m \sum_{m' \neq m} Q\left(\frac{\|s_m - s_{m'}\|}{2\sigma} + \frac{\sigma}{\|s_m - s_{m'}\|} \ln \frac{\pi_m}{\pi_{m'}}\right)$$

We choose symbols such that the minimal distance is large

$$p^*(error) \ge \max_{m' \ne m} Q\left(\frac{\|s_m - s_{m'}\|}{2\sigma}\right) = Q\left(\frac{d_{min}}{2\sigma}\right)$$

### **Gaussian Vectors**

Orthogonal:  $U^{-1} = U^T (UU^T = I_n)$ 

Symmetric:  $U^T = U$ 

Eigenvectors:  $A v_i = \lambda_i v_i$ 

If A is symmetric, it has n eigenvalues and orthogonal EVs

$$U = [v_1, \dots, v_n], \qquad \Lambda = diag(\lambda_1, \dots, \lambda_n)$$
 
$$A = U \Lambda U^T$$

### Positive (semi)definite matrix: $K \ge 0$

- K is symmetric
- $\alpha^T K \alpha \ge 0$  ,  $\alpha \in \mathbb{R}^n$

$$K = S^T S \iff K \text{ is symmetric, } \lambda_i \geq 0$$

Autocovariance matrix (are all positive semidefinite)

$$K_{XX} = E[(X - E[X])(X - E[X])^{T}] = \begin{cases} Var(X^{(1)}) & Cov(X^{(1)}, X^{(2)}) & \cdots & Cov(X^{(1)}, X^{(n)}) \\ \vdots & \ddots & \vdots \\ & \cdots & Var(X^{(n)}) \end{cases}$$

$$Y = AX : K_{YY} = A K_{XX} A^T \ge 0$$

Characteristic function:  $\Phi_{Y}(\omega) = E[e^{i\omega^{T}X}] = \int f_{Y} e^{i\omega^{T}X}$ 

#### Standard Gaussian n-vector

$$W = \left(\omega^{(1)}, \dots, \omega^{(n)}\right)^T, \qquad \omega^{(i)} \ IID \sim \mathcal{N}(0,1)$$

$$f_W(\omega) = \prod_{l=1}^n \left( \frac{1}{\sqrt{2\pi}} e^{-\frac{(\omega^{(l)})^2}{2}} \right) = \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2}||w||^2}$$

$$E[W] = 0$$
,  $K_{WW} = I_n$ ,  $\Phi_W(\omega) = e^{-\frac{1}{2}\omega^T\omega}$ 

General Gaussian:  $X = A W + \mu \sim \mathcal{N}(\mu, K)$ 

$$A = U \sqrt{\Lambda}$$
 of  $K$ ,  $K \ge 0$ 

$$E[X] = \mu$$
,  $K_{XX} = AA^T$ ,  $\Phi_X(\omega) = e^{-\frac{1}{2}\omega^T K_{XX}\omega + i\omega^T \mu}$  
$$f_X(x) = \frac{1}{\sqrt{2\pi \det(K)}} e^{-\frac{1}{2}(x-\mu)^T K^{-1}(x-\mu)}$$

**Jointly Gaussian:**  $X_1, \dots, X_n$  are jointly Gaussian if the vector  $(X_1, \dots, X_n)^T$  is Gaussian

For  $X_1, X_2$  which are jointly Gaussian:

$$X_1 \perp \!\!\! \perp X_2 = independent \quad \Leftrightarrow \quad Cov(X_1, X_2) = 0$$

# 10. Continuous-time SP

$$X: \Omega \times \mathbb{R} \to \mathbb{R} \qquad (\omega, t) \mapsto X(\omega, t)$$

t fixed:  $X(\omega) \rightarrow RV$ 

 $\omega$  fixed:  $X(t) \rightarrow function of time$ 

### Finite-dimensional Distribution (FDD)

FDDs of a c.-t. SP (X(t)) is the collection of all the joint distributions of  $(X(t_1), ..., X(t_n))$ ,  $n \in \mathbb{N}$ 

#### **Gaussian SP**

(X(t)) is a Gaussian SP if  $(X(t_1), ..., X(t_n))$  are Gaussian

FDD is specified by:

- mean function:  $t \mapsto E[X(t)]$ 

- covariance function:  $(t_1, t_2) \mapsto Cov[X(t_1), X(t_2)]$ 

(X(t)), (Y(t)) are **independent**, if

$$(X(t_1), \dots, X(t_n)) \perp (Y(t_1), \dots, Y(t_n))$$

(X(t)) is **stationary** if all time-shifts have identical FDDs:

$$\big(X(t_1+\tau),\ldots,X(t_n+\tau)\big)=\big(X(t_1),\ldots,X(t_n)\big)$$

### (X(t)) is WSS (wide-sense stationary) if

- a) it is of finite variance
- b) constant mean:  $E[X(t)] = E[X(0)] \ \forall t$
- c)  $Cov[X(t_1), X(t_2)] = Cov[X(t_1 + \tau), X(t_2 + \tau)]$

Autocovariance function:  $K_{XX}(\tau) = Cov[X(t+\tau), X(t)]$ 

PSD 
$$S_{XX}$$
:  $K_{XX}(\tau) = \int_{-\infty}^{\infty} S_{XX}(t) e^{i2\pi f \tau} df$ 

Power of 
$$X * h = \int_{-\infty}^{\infty} S_{XX}(f) |\hat{h}(f)|^2 df$$

### Gaussian SP is stationary if and only if it is WSS

#### Average power

Power in 
$$X = \int_{-\infty}^{\infty} S_{XX}(x) df = K_{XX}(0)$$

### **Linear functionals**

WSS, measurable:

$$\omega \mapsto \int_{-\infty}^{\infty} X(\omega, t) s(t) dt$$

#### Mean of a linear functional

$$E\left[\int_{-\infty}^{\infty} X(t)s(t) dt\right] = E[X(0)] \int_{-\infty}^{\infty} s(t) dt$$

#### Variance of a linear functional

$$Var\left[\int_{-\infty}^{\infty} X(t) \, s(t) \, dt\right] = \int_{-\infty}^{\infty} K_{XX}(\sigma) \, R_{SS}(\sigma) \, d\sigma$$
$$= \int_{-\infty}^{\infty} S_{XX}(f) \, |\hat{s}(f)|^2 \, df$$

#### Sets of Gaussian RVs

If (X(t)) is a stationary Gaussian, then also a Gaussian RV

$$\int_{-\infty}^{\infty} X(t) \, s(t) \, dt \, + \, \sum_{i=1}^{n} \alpha_i \, X(t_i)$$

Mean

$$E[X(0)] \left( \int_{-\infty}^{\infty} s(t) dt + \sum_{i} \alpha_{i} \right)$$

#### <u>Variance</u>

$$\int K_{XX}(\sigma)R_{SS}(\sigma) d\sigma + \sum_{i} \sum_{j} \alpha_{i} \alpha_{j} K_{XX}(t_{i} - t_{j})$$

$$+ 2 \sum_{i} \alpha_{i} \int K_{XX}(t - t_{i}) s(t) dt$$

For multiple sets:

$$Cov\left[\int X s_j dt, \int X s_k dt\right] = \int S_{XX}(f) \hat{s}_j(f) \hat{s}_k^*(f) df$$

### **White Gaussian Noise**

 $\left(N(t)\right)$  is white Gaussian noise of double-sided PSD  $\frac{N_0}{2}$  with respect to the bandwidth W if it is a Gaussian with

$$S_{NN}(f) = \frac{N_0}{2} , \qquad f \in [-W, W]$$

**Properties** 

$$\langle N, s \rangle = \int_{-\infty}^{\infty} N(t) s(t) dt \sim \mathcal{N}\left(0, \frac{N_0}{2} \|s\|_2^2\right)$$

 $\int N(t) s_1(t) dt$ , ...,  $\int N(t) s_m(t) dt$  are jointly Gaussians:

$$Cov. matrix: \begin{array}{lll} \frac{N_0}{2} \begin{pmatrix} \langle s_1, s_1 \rangle & \cdots & \langle s_1, s_m \rangle \\ \vdots & \ddots & \vdots \\ \langle s_m, s_1 \rangle & \cdots & \langle s_m, s_m \rangle \end{array} \right)$$

For  $\phi_1, ..., \phi_m$  orthonormal, noise is independent of signal

$$\int X(t) \, \phi_1(t) \, dt \, , \dots, \int X(t) \, \phi_m(t) \, dt \, \sim IID \, \mathcal{N}\left(0, \frac{N_0}{2}\right)$$

$$K_{NN} * s = \frac{N_0}{2} s$$
  $\left( K_{NN} \approx \frac{N_0}{2} \delta \right)$ 

$$Cov\left[\int N(\sigma) s(\sigma) d\sigma, N(t)\right] = \frac{N_0}{2} s(t)$$

### **Projection of Noise**

 $\left(N(t)
ight)$  WGN of PSD  $rac{N_0}{2}$  ;  $\phi_1,\ldots,\phi_d$  orthonormal signals

$$t \mapsto \sum_{l=1}^{d} \langle N, \phi_l \rangle \, \phi_l(t)$$
 and

$$t \mapsto N(t) - \sum_{l=1}^{d} \langle N, \phi_l \rangle \, \phi_l(t)$$

are independent (as uncorrelated) Gaussian SPs

### 11. Detection in White Gaussian Noise

$$M \in \{1, ..., |d|\}$$
 ,  $\pi_m = \Pr[M = m]$  
$$Y(t) = s_m(t) + N(t)$$

 $s_1, \dots, s_d$ : real, deterministic, integrable, bandlimited to W

$$(N(t))$$
 If  $M$  :  $(N(t))$  WGN of PSD  $\frac{N_0}{2}$ 

If  $(\phi_1,\ldots,\phi_d)$  is an orthonormal basis for  $span(s_1,\ldots,s_d)$ , for every decision rule based on (Y(t)) there exists one with identical performance which is only based on

$$T = (\langle Y, \phi_1 \rangle, \dots, \langle Y, \phi_d \rangle)^T$$

Conditional on = m:

$$T = (\langle s_m, \phi_1 \rangle, \dots, \langle s_m, \phi_d \rangle)^T + \frac{N_0}{2} \sim IID \mathcal{N}\left(\langle s_m, \phi_i \rangle, \frac{N_0}{2}\right)$$

### **Optimal rules**

$$\varphi^* = \arg\max_{m'} \left\{ \ln \pi_{m'} - \frac{\sum_{l=1}^d (\langle y, \phi_l \rangle - \langle s_{m'}, \phi_l \rangle)^2}{N_0} \right\}$$

For a uniform prior:

$$\varphi^* = \arg\min_{m'} \left\{ \sum_{l=1}^d (\langle y, \phi_l \rangle - \langle s_{m'}, \phi_l \rangle)^2 \right\}$$

For a uniform prior & equal energy:

$$\varphi^* = \arg\max_{m'} \left\{ \sum_{l=1}^d \langle s_{m'}, \phi_l \rangle \langle Y, \phi_l \rangle \right\}$$

#### Performance

$$P_{MAP}(error|M=m) \leq \sum_{m' \neq m} Q\left(\frac{\|s_m - s_{m'}\|_2}{\sqrt{2 N_0}} + \frac{\sqrt{N_0/2}}{\|s_m - s_{m'}\|_2} \ln \frac{\pi_m}{\pi_{m'}}\right)$$

$$P_{MAP}(error|M=m) \geq \max_{m' \neq m} Q\left(\frac{\|s_m - s_{m'}\|_2}{\sqrt{2 \; N_0}} + \frac{\sqrt{N_0/2}}{\|s_m - s_{m'}\|_2} ln \frac{\pi_m}{\pi_{m'}}\right)$$

### Examples (p.586ff)

### **Antipodal Signalling**

$$s_0 = -s_1 = s$$
,  $E_s = ||s||_2^2$ 

$$T = \langle Y, \phi \rangle, \qquad \phi = \frac{s}{\|s\|_2}$$

#### General binary signalling

$$\tilde{Y}(t) = Y(t) - \frac{s_0(t) + s_1(t)}{2}$$

#### |M| - ary Orthogonal Keying

Use orthogonal signals:  $\langle s_{m'}, s_{m''} \rangle = E_s I\{ m' = m'' \}$ 

$$\varphi^* = \arg\max_{m'} \langle Y, s_{m'} \rangle$$

#### |M| - ary Simplex

Like orthogonal keying, but subtract mean, which makes it more power-efficient

$$\bar{\phi}(t) = \frac{1}{|M|} \sum_{m=1}^{|M|} \phi_m(t)$$

$$s_m(t) = \sqrt{E_s} \sqrt{\frac{|M|}{|M|-1}} \left( \phi_m - \bar{\phi} \right)$$

To decode: search for unit-length vector  $\psi$  which is orthogonal to all  $s_1, \dots, s_M$ 

$$\phi = \left\{ s_m + \sqrt{\frac{E_s}{|M| - 1}} \, \psi \right\}$$

### **Bi-Orthogonal Keying**

Always take two signals that are opposite to each other on the unit circle

# 12. Various

### **Discrete-Time SP**

(Strict-sense) stationary (SSS):  $(X_v)$  is stationary if  $\forall \eta, n$ 

$$(X_1, \dots, X_n) = (X_{1+\eta}, \dots, X_{n+\eta})$$
$$X_1 = X_{\eta}$$

Every strict-sense stationary SP is also wide-sense stat.

#### Wide-sense stationary (WSS):

- 1)  $Var(X_v) < \infty$
- 2)  $E[X_{1}] = E[X_{1}]$
- 3)  $E[X_{v'} X_{v}] = E[X_{v'+\eta} X_{v+\eta}]$   $E[Z_{v'} Z_{v}^{*}] = E[Z_{v'+\eta} Z_{v+\eta}^{*}], \quad Z \text{ is } CRV$

Autocovariance function: for a WSS SP  $(X_v)$ 

$$K_{x,x}(\eta) = Cov[X_{v+\eta}, X_v]$$

- i)  $K_{xx}(\eta) = K_{xx}(-\eta)$
- i)  $\sum_{v=1}^{n} \sum_{v'=1}^{n} \alpha_v \alpha_{v'} K_{rr}(v-v') \geq 0 \quad \forall \alpha_i \in \mathbb{R}$

### Power Spectral Density (PSD)

The DT WSS SP  $(X_v)$  is of the PSD  $S_{xx}: \left[-\frac{1}{2}, \frac{1}{2}\right] \mapsto \mathbb{R}$  if  $S_{xx}$  is nonnegative, symmetric, integrable and

$$K_{xx}(\eta) = \int_{-\frac{1}{2}}^{\frac{1}{2}} S_{xx}(\theta) e^{-i2\pi\eta\theta} d\theta$$

### **Complex Random Variables**

$$Z = X + i Y, z = {x \choose y}$$
$$f_Z(z) = f_{X,Y}(x, y)$$

$$E[Z] = E[X] + i * E[Y], E[Z^*] = (E[Z])^*$$

Variance

$$Var[Z] = E[|Z - E[Z]|^2]$$

Covariance

$$Cov[Z, W] = E[(Z - E[Z]) (W - E[W])^*]$$
  
=  $(Cov[W, Z])^*$ 

Proper: a CRV is called proper if

- i) E[Z] = 0 (zero mean)
- ii)  $Var[Z] < \infty$  (finite variance)
- iii)  $E[Z^2] = 0$

$$\Leftrightarrow E[X^2] = E[Y^2], E[X \cdot Y] = 0$$

### **Gaussian RV**

For a Gaussian X = g(Y), we get:

$$f_X(x) = \frac{1}{|g'(y)|} f_W(y)$$
,  $x = g(y)$ 

$$X \sim \mathcal{N}(\mu, \sigma^2) \quad \Leftrightarrow \quad \frac{X - \mu}{\sigma} \sim \mathcal{N}(0, 1)$$

$$Z = X_1 + X_2 \rightarrow f_Z(z) = (f_{x_1} * f_{x_2}) = f_{x_1} \cdot f_{x_2}$$

**Cumulative Function** 

$$F_X(x) = \int_{-\infty}^x f_X(\tau) d\tau$$

### **Integrals**

$$\left| \int_{-\infty}^{\infty} u(t) \, dt \right| \le \int_{-\infty}^{\infty} |u(t)| \, dt$$
$$\int_{-\infty}^{\infty} u^*(t) \, dt = \left( \int_{-\infty}^{\infty} u(t) \, dt \right)^*$$

#### Excess bandwidth

$$\left(\frac{bandwidth\ of\ \phi}{\frac{1}{2T_s}}-1\right)*100\%$$
 ,  $W_{min}=\frac{1}{2T_s}$ 

### **Sandwich Theorem**

$$b_n \leq a_n \leq c_n$$

If  $\{b_n\}$  and  $\{c_n\}$  converge to same limit, then so does  $\{a_n\}$ 

# 13. Tables

$$i = \sqrt{1} = e^{i\frac{\pi}{2}}$$

$$\tan' x = 1 + \tan^2 x$$

$$\sin^2 x + \cos^2 x = 1$$

$$\cosh^2 x - \sinh^2 x = 1$$

$$\cos(z) = \cos(x)\cosh(y) - i\sin(x)\sinh(y)$$

$$\sin(z) = \sin(x)\cosh(y) + i\cos(x)\sinh(y)$$

Grad	Rad	$\sin \varphi$	$\cos \varphi$	$\tan \varphi$
0°	0	0	1	0
30°	$\frac{1}{6}\pi$	$\frac{1}{2}$	$\frac{\sqrt{3}}{2}$	$\frac{\sqrt{3}}{3}$
45°	$\frac{1}{4}\pi$	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{2}}{2}$	1
60°	$\frac{1}{3}\pi$	$\frac{\sqrt{3}}{2}$	$\frac{1}{2}$	$\sqrt{3}$
90°	$\frac{1}{2}\pi$	1	0	
120°	$\frac{2}{3}\pi$	$\frac{\sqrt{3}}{2}$	$-\frac{1}{2}$	$-\sqrt{3}$
135°	$\frac{3}{4}\pi$	$\frac{\sqrt{2}}{2}$	$-\frac{\sqrt{2}}{2}$	-1
150°	$\frac{5}{6}\pi$	$\frac{1}{2}$	$-\frac{\sqrt{3}}{2}$	$-\frac{\sqrt{3}}{3}$
180°	$\pi$	0	-1	0

### **Additionstheoreme**

$$\sin(\alpha \pm \beta) = \sin\alpha\cos\beta \pm \cos\alpha\sin\beta$$
$$\cos(\alpha \pm \beta) = \cos\alpha\cos\beta \mp \sin\alpha\sin\beta$$
$$\tan(\alpha \pm \beta) = \frac{\tan\alpha \pm \tan\beta}{1 \mp \tan\alpha\tan\beta}$$

### **Doppelter und halber Winkel**

$$\sin 2\varphi = 2\sin\varphi\cos\varphi \qquad \qquad \sin^2\frac{\varphi}{2} = \frac{1}{2}(1-\cos\varphi)$$

$$\cos 2\varphi = \cos^2\varphi - \sin^2\varphi \qquad \cos^2\frac{\varphi}{2} = \frac{1}{2}(1-\cos\varphi)$$

$$\tan 2\varphi = \frac{2\tan\varphi}{1-\tan^2\varphi} \qquad \tan^2\frac{\varphi}{2} = \frac{1-\cos\varphi}{1+\cos\varphi}$$

### **Umformung einer Summe in ein Produkt**

$$\sin \alpha + \sin \beta = 2 \sin \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2}$$
$$\sin \alpha - \sin \beta = 2 \cos \frac{\alpha + \beta}{2} \sin \frac{\alpha - \beta}{2}$$
$$\cos \alpha + \cos \beta = 2 \cos \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2}$$
$$\cos \alpha - \cos \beta = -2 \sin \frac{\alpha + \beta}{2} \sin \frac{\alpha - \beta}{2}$$

### <u>Umformung eines Produkts in eine Summe</u>

$$2\sin\alpha\sin\beta = \cos(\alpha - \beta) - \cos(\alpha + \beta)$$
$$2\cos\alpha\cos\beta = \cos(\alpha - \beta) + \cos(\alpha + \beta)$$
$$2\sin\alpha\cos\beta = \sin(\alpha - \beta) + \sin(\alpha + \beta)$$

### Reihenentwicklungen

$$e^{x} = 1 + x + \cdots = \sum_{k=0}^{\infty} \frac{x^{k}}{k!}$$

$$\log(1+x) = x - \frac{x^{2}}{2} + \cdots = \sum_{k=1}^{\infty} (-1)^{k-1} \frac{x^{k}}{k}$$

$$(1+x)^{n} = 1 + \binom{n}{1}x + \cdots = \sum_{k=0}^{\infty} \binom{n}{k}x^{k}$$

$$\sin x = x - \frac{x^{3}}{3!} + \cdots = \sum_{k=0}^{\infty} (-1)^{k} \frac{x^{2k+1}}{(2k+1)!}$$

$$\cos x = 1 - \frac{x^{2}}{2!} + \cdots = \sum_{k=0}^{\infty} (-1)^{k} \frac{x^{2k}}{(2k)!}$$

$$\arctan x = x - \frac{x^{3}}{3} + \cdots = \sum_{k=0}^{\infty} (-1)^{k} \frac{x^{2k+1}}{(2k+1)!}$$

$$\sinh x = x + \frac{x^{3}}{3!} + \cdots = \sum_{k=0}^{\infty} \frac{x^{2k+1}}{(2k+1)!}$$

$$\cosh x = 1 + \frac{x^{2}}{2!} + \cdots = \sum_{k=0}^{\infty} \frac{x^{2k+1}}{(2k)!}$$

$$\operatorname{artanh} x = x + \frac{x^{3}}{3} + \cdots = \sum_{k=0}^{\infty} \frac{x^{2k+1}}{(2k+1)!}$$

### Summe der ersten n-Zahlen

$$\sum_{k=1}^{n} k = 1 + 2 + \dots + n = \frac{n(n+1)}{2}$$

#### Geometrische Reihe

$$\sum_{k=0}^{n} x^{k} = 1 + x + \dots + x^{n} = \frac{1 - x^{n+1}}{1 - x}$$

### **Fourier-Korrespondenzen**

f(t)	$\widehat{f}(\omega)$
$e^{-at^2}$	$\sqrt{\frac{\pi}{a}}e^{\frac{-\omega^2}{4a}}$
$e^{-a t }$	$\frac{2a}{a^2 + \omega^2}$

### **Eigenschaften der Fourier-Transformation**

Eigenschaft	f(t)	$\widehat{f}(\omega)$	
Linearität	$\lambda f(t) + \mu g(t)$	$\lambda \widehat{f}(\omega) + \mu \widehat{g}(\omega)$	
Ähnlichkeit	f(at) $a > 0$	$\frac{1}{ a }\widehat{f}(\frac{\omega}{a})$	
Verschiebung	f(t-a)	$e^{-ai\omega}\widehat{f}(\omega)$	
versementing	$e^{ait}f(t)$	$\widehat{f}(\omega - a)$	
Ableitung	$f^{(n)}(t)$	$(\mathrm{i}\omega)^n\widehat{f}(\omega)$	
Trotestung	$t^n f(t)$	$\mathrm{i}^n\widehat{f}^{(n)}(\omega)$	
Faltung	f(t) * g(t)	$\widehat{f}(\omega) \cdot \widehat{g}(\omega)$	

### Partialbruchzerlegung (PBZ)

Reelle Nullstellen n-ter Ordnung:

$$\frac{A_1}{(x-a_k)} + \frac{A_2}{(x-a_k)^2} + \dots + \frac{A_n}{(x-a_k)^n}$$

Paar komplexer Nullstellen n-ter Ordnung:

$$\frac{B_1x + C_1}{(x - a_k)(x - \overline{a_k})} + \dots + \frac{B_nx + C_n}{[(x - a_k)(x - \overline{a_k})]^n} +$$
$$(x - a_k)(x - \overline{a_k}) = (x - Re)^2 + Im^2$$

### **Laplace- Korrespondenz**

f(t)	F(s)	f(t)	F(s)
$\sigma(t)$	1	H(t-a)	$\frac{1}{s}e^{-as}$
1	$\frac{1}{s}$	$e^{at}$	$\frac{1}{s-a}$
t	$\frac{1}{s^2}$	$te^{at}$	$\frac{1}{(s-a)^2}$
$t^n$	$\frac{n!}{s^{n+1}}$	$t^n e^{at}$	$\frac{n!}{(s-a)^{n+1}}$
$\sin\left(at\right)$	$\frac{a}{s^2 + a^2}$	$\sinh\left(at\right)$	$\frac{a}{s^2 - a^2}$
$\cos\left(at\right)$	$\frac{s}{s^2+a^2}$	$\cosh\left(at\right)$	$\frac{s}{s^2 - a^2}$

### **Eigenschaften der Laplace-Transformation**

Eigenschaft	f(t)	F(s)
Linearität	$\lambda f(t) + \mu g(t)$	$\lambda F(s) + \mu G(s)$
Ähnlichkeit	f(at) $a>0$	$\frac{1}{a}F(\frac{s}{a})$
Verschiebung im Zeitbereich	$f(t-t_0)$	$e^{-st_0}F(s)$
Verschiebung im Bildbereich	$e^{-at}f(t)$	F(s+a)
	f'(t)	sF(s) - f(0)
Ableitung im Zeitbereich	f''(t)	$s^2F(s) - sf(0) - f'(0)$
	$f^{(n)}$	$s^{n}F(s) - \sum_{k=0}^{n-1} f^{(k)}(0)s^{n-k-1}$
	-tf(t)	F'(s)
Ableitung im Bildbereich	$t^2 f(t)$	F''(s)
	$(-t)^n f(t)$	$F^{(n)}(s)$
Integration im Zeitbereich	$\int_0^t f(u)  \mathrm{d} u$	$\frac{1}{s}F(s)$
Integration im Bildbereich	$\frac{1}{t}f(t)$	$\int_{s}^{\infty} F(u)  \mathrm{d}u$
Faltung	f(t) * g(t)	$F(s) \cdot G(s)$
Periodische Funktion	f(t) = f(t+T)	$\frac{1}{1 - e^{-sT}} \int_0^T f(t) e^{-st} dt$

# <u>Ableitungen</u>

Potenz- und Exponentialfunktionen			Trigonometrische Funktionen		Hyperbolische Funktionen	
f(x)	f'(x)	Bedingung	f(x) $f'(x)$		f(x)	f'(x)
$x^n$	$nx^{n-1}$	$n \in \mathbb{Z}_{\geq 0}$	$\sin x$	$\cos x$	$\sinh x$	$\cosh x$
$x^n$	$nx^{n-1}$	$n \in \mathbb{Z}_{<0},  x \neq 0$	$\cos x$	$-\sin x$	$\cosh x$	$\sinh x$
$x^a$	$ax^{a-1}$	$a \in \mathbb{R}, \ x > 0$	$\tan x$	$\frac{1}{\cos^2 x}$	$\tanh x$	$\frac{1}{\cosh^2 x}$
$\log x$	$\frac{1}{x}$	x > 0	$\arcsin x$	$\frac{1}{\sqrt{1-x^2}}$	arsinh x	$\frac{1}{\sqrt{x^2+1}}$
$e^x$	$e^x$		$\arccos x$	$-\frac{1}{\sqrt{1-x^2}}$	$\operatorname{arcosh} x$	$\frac{1}{\sqrt{x^2-1}}$
$a^x$	$a^x \cdot \log a$	a > 0	$\arctan x$	$\frac{1}{1+x^2}$	$\operatorname{artanh} x$	$\frac{1}{1-x^2}$

# **Stammfunktionen**

f(x)	F(x)	Bedingung	f(x)	F(x)	f(x)	F(x)
$x^n$	$\frac{1}{n+1}x^{n+1}$	$n \in \mathbb{Z}_{\geq 0}$	$\frac{1}{x}$	$\log  x $	$\sin(\omega t)\sin(\omega t)$	$\frac{t}{2} - \frac{\sin{(2\omega t)}}{4\omega}$
$x^n$	$\frac{1}{n+1}x^{n+1}$	$n \in \mathbb{Z}_{\leq -2},  x \neq 0$	$\tan x$	$-\log \cos x $	$\sin(\omega t)\cos(\omega t)$	$-rac{\cos{(2\omega t)}}{4\omega}$
$x^a$	$\frac{1}{a+1}x^{a+1}$	$a \in \mathbb{R}, a \neq -1, x > 0$	$\tanh x$	$\log\left(\cosh x\right)$	$\sin\left(\omega t\right)\sin\left(n\omega t\right)$	$\frac{n\cos\left(\omega t\right)\sin\left(n\omega t\right)-\sin\left(\omega t\right)\cos\left(n\omega t\right)}{\omega(n^2-1)}$
$\log x$	$x \log x - x$	x > 0	$\sin^2 x$	$\frac{1}{2}(x - \sin x \cos x)$	$\sin\left(\omega t\right)\cos\left(n\omega t\right)$	$\frac{n\sin{(\omega t)}\sin{(n\omega t)} + \cos{(\omega t)}\cos{(n\omega t)}}{\omega(n^2 - 1)}$
$e^{ax}$	$\frac{1}{a}e^{ax}$	$a \neq 0$	$\cos^2 x$	$\frac{1}{2}(x+\sin x\cos x)$	$\cos\left(\omega t\right)\sin\left(n\omega t\right)$	$\frac{\sin(\omega t)\sin(n\omega t) + n\cos(\omega t)\cos(n\omega t)}{\omega(1-n^2)}$
$a^x$	$\frac{a^x}{\log a}$	$a > 0, a \neq 1$	$\tan^2 x$	$\tan x - x$	$\cos\left(\omega t\right)\cos\left(n\omega t\right)$	$\frac{\sin{(\omega t)}\cos{(n\omega t)} + n\cos{(\omega t)}\sin{(n\omega t)}}{\omega(1-n^2)}$

### **Standard-Substitutionen**

Integral	Substitution	Ableitung	Bemerkung
$\int f(x, x^2 + 1)  \mathrm{d}x$	$x = \tan t$	$\mathrm{d}x = \tan^2 t + 1\mathrm{d}t$	$t \in \bigcup_{k \in \mathbb{Z}} \left( k\pi - \frac{\pi}{2}, k\pi + \frac{\pi}{2} \right)$
$\int f(x, \sqrt{ax+b})  \mathrm{d}x$	$x = \frac{t^2 - b}{a}$	$\mathrm{d}x = \frac{2}{a}t\mathrm{d}t$	$t \ge 0$
$\int f(x, \sqrt{ax^2 + bx + c})  \mathrm{d}x$	$x + \frac{b}{2a} = t$	$\mathrm{d}x = \mathrm{d}t$	$t \in \mathbb{R},$ quadratische Ergänzung
$\int f(x, \sqrt{a^2 - x^2})  \mathrm{d}x$	$x = a \sin t$	$\mathrm{d}x = a\cos t\mathrm{d}t$	$-\frac{\pi}{2} < t < \frac{\pi}{2}, 1 - \sin^2 x = \cos^2 x$
$\int f(x, \sqrt{a^2 + x^2})  \mathrm{d}x$	$x = a \sinh t$	$\mathrm{d}x = a\cosh t\mathrm{d}t$	$t \in \mathbb{R},  1 + \sinh^2 x = \cosh^2 x$
$\int f(x, \sqrt{x^2 - a^2})  \mathrm{d}x$	$x = a \cosh t$	$\mathrm{d}x = a\sinh t\mathrm{d}t$	$t \ge 0, \cosh^2 x - 1 = \sinh^2 x$
$\int f(e^x, \sinh x, \cosh x) dx$	$e^x = t$	$\mathrm{d}x = \frac{1}{t}\mathrm{d}t$	$t > 0$ , $\sinh x = \frac{t^2 - 1}{2t}$ , $\cosh x = \frac{t^2 + 1}{2t}$
$\int f(\sin x,  \cos x)  \mathrm{d}x$	$\tan \frac{x}{2} = t$	$\mathrm{d}x = \frac{2}{1+t^2}  \mathrm{d}t$	$-\frac{\pi}{2} < t < \frac{\pi}{2}$ , $\sin x = \frac{2t}{1+t^2}$ , $\cos x = \frac{1-t^2}{1+t^2}$