

Electronic Circuits Summary

Andreas Biri, D-ITET

16.06.14

Constants (@300K)

$$\epsilon_0 = 8.854 \cdot 10^{-12} \text{ F/m} \quad m_0 = 9.11 \cdot 10^{-31} \text{ kg}$$

$$k = 1.38 \cdot 10^{-23} \text{ J/K} = 8.617 \cdot 10^{-5} \text{ eV/K}$$

$$\frac{kT}{q} = 0.0259 \text{ V}, \quad \frac{q}{kT} = 38.61 \frac{1}{\text{V}}, \quad kT = 25.9 \text{ meV}$$

$$1 \text{ eV} = 1.602 \cdot 10^{-19} \text{ J} \quad q = 1.602 \cdot 10^{-19} \text{ A s}$$

1. Transistor Characteristics

Resistor: $V_R = R \cdot I_R$

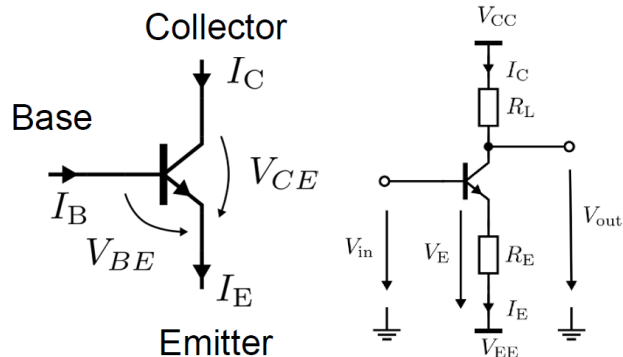
Capacitor: $I_C = C \cdot \frac{d}{dt} V_C$

Inductor: $V_L = L \cdot \frac{d}{dt} I_L$

Bipolar Junction Transistor (BJT)

$$I_C = I_S \cdot e^{\frac{V_{BE}}{V_T}} \left(1 + \frac{V_{CE}}{V_A} \right), \quad V_T = \frac{kT}{q} \approx 26 \text{ mV}$$

$$I_B = \frac{I_C}{\beta}, \quad I_E = (1 + \beta) I_B, \quad V_A : \text{Early voltage}$$



Small Signal Equivalent Circuit BJT

Consider only small oscillations around operation point

→ Linearize as approximation, $V_{CC} = 0 = V_{EE}$ as const.

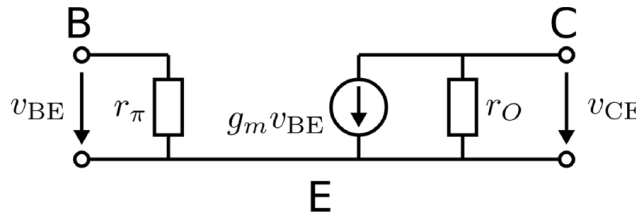
$$i_c = \frac{\beta}{\beta + 1} \frac{v_E}{R_E} = \frac{d I_C}{d V_{BE}} (v_{in} - v_E) = g_m \cdot \Delta V_{BE} \approx \frac{v_E}{R_E}$$

$$v_{out} \approx - \frac{g_m R_L}{1 + g_m R_E} v_{in}$$

$$g_m = \frac{d I_C}{d V_{BE}} = \frac{I_C}{V_T}, \quad g_\pi = \frac{d I_B}{d V_{BE}} = \frac{g_m}{\beta}$$

$$g_0 = \frac{d I_C}{d V_{CE}} = \frac{I_C}{V_A + V_{CE}} \approx \frac{I_C}{V_A}$$

$$r_\pi = \frac{1}{g_\pi} = \frac{\beta}{g_m}, \quad r_0 = \frac{1}{g_0} = \frac{V_A + V_{CE}}{I_C} \approx \frac{V_A}{I_C}$$



Biasing of a BJT (Setting the operation point)

Voltage divider R_{B1}, R_{B2} sets the bias voltage

Transistor in active region : $V_{BE} \approx 0.7 \text{ V}$

MOSFET

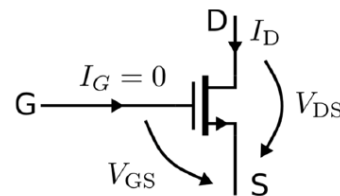
$$I_D = \frac{K' W}{2 L} (V_{GS} - V_t)^2 (1 + \lambda V_{DS}), \quad V_{DS} > V_{GS} - V_t$$

K' : Intrinsic transconduct. coeff.

V_t : Threshold voltage

W / L : Gate width / Gate length

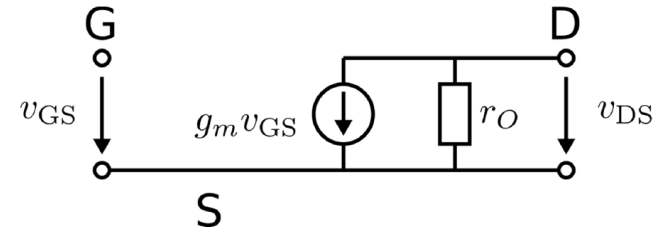
λ : Characteristic length



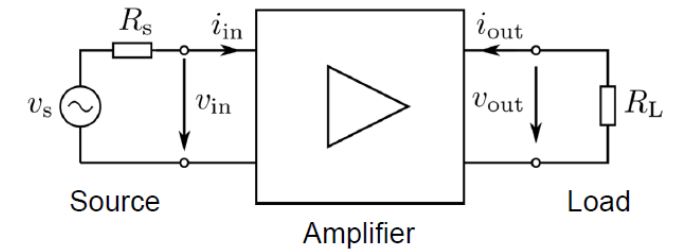
Small Signal Equivalent Circuit MOSFET

$$g_m = \frac{d I_D}{d V_{GS}} \approx \sqrt{\frac{2 K' W}{L}} I_D$$

$$g_0 = \frac{d I_D}{d V_{DS}} = I_D \frac{\lambda}{1 + \lambda V_{DS}} \approx \lambda I_D, \quad r_0 = \frac{1}{g_0} \approx \frac{1}{\lambda I_D}$$



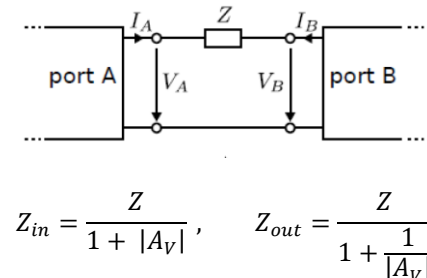
2. Single-Transistor Amplifiers



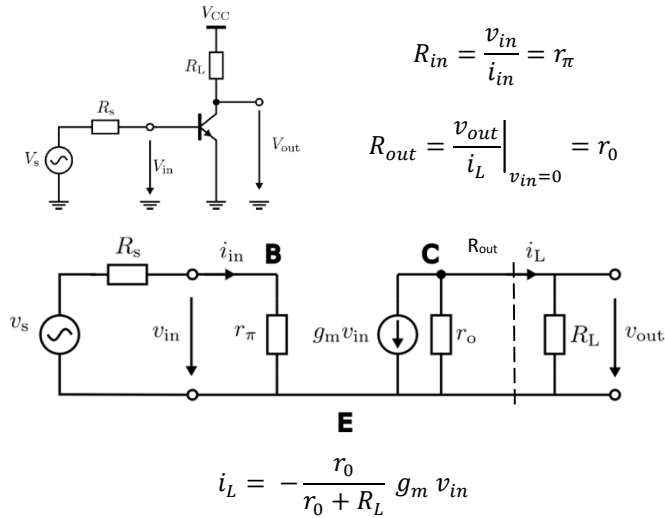
Impedances: $Z_{in} = \frac{v_{in}}{i_{in}}, \quad Z_{out} = \frac{v_{out}}{i_{out}} (v_s = 0)$

Gains: $A_V = \frac{v_{out}}{v_s}, \quad A_I = \frac{i_{out}}{i_s} (R_L = 0)$

Millers theorem



Common-Emitter / Source Amplifier

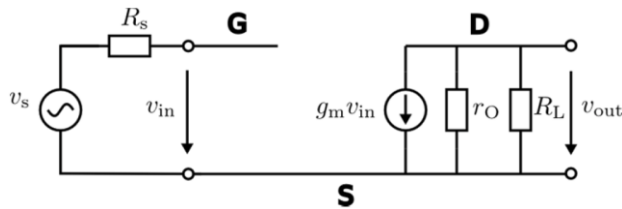


$$A_V = \frac{v_{out}}{v_S} \approx -\frac{r_{\pi}}{r_{\pi} + R_S} g_m R_L, \quad \frac{v_{out}}{v_{in}} = \frac{i_L R_L}{v_{in}} \approx -g_m R_L$$

Inverting Amplifier $\rightarrow 180^\circ$ phase shift

$$A_I = \left. \frac{i_{out}}{i_S} \right|_{v_{out}=0} = \frac{R_S}{R_S + r_{\pi}} \beta, \quad \left. \frac{i_{out}}{i_{in}} \right|_{v_{out}=0} = g_m r_{\pi} = \beta$$

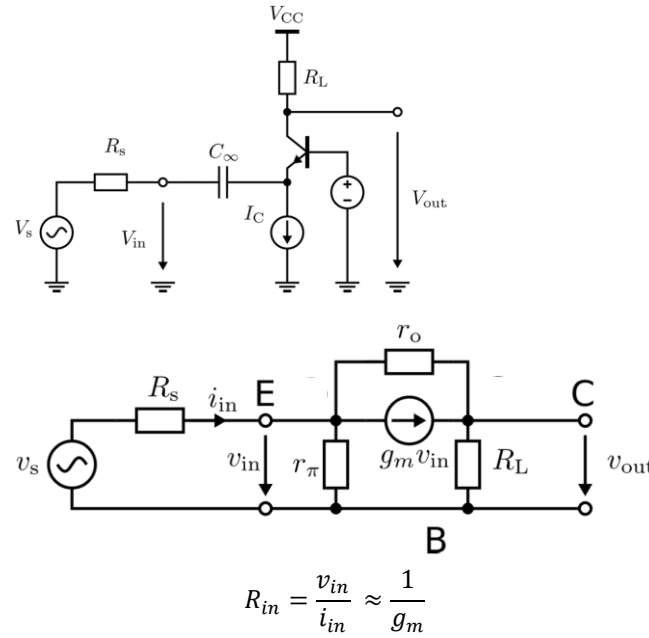
MOSFET: instead of BJT, no current into the gate



No current flow into the gate: $R_{out} \rightarrow \infty, v_{in} = v_S$

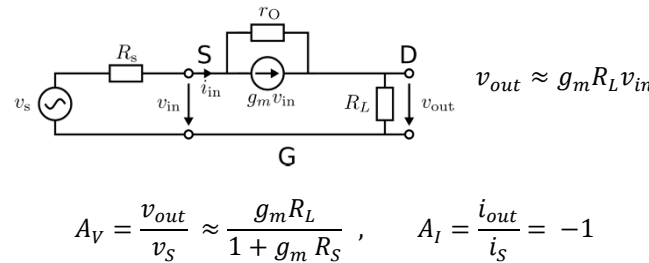
$$R_{out} = r_o, \quad A_V \approx -g_m R_L$$

Common-Base / Gate Amplifier



$$A_I = \left. \frac{i_{out}}{i_{in}} \right|_{v_{out}=0} = -\frac{g_m}{\frac{1}{R_S || r_{\pi}} + g_m} \approx -1 \quad \text{for } R_S \gg r_{\pi}$$

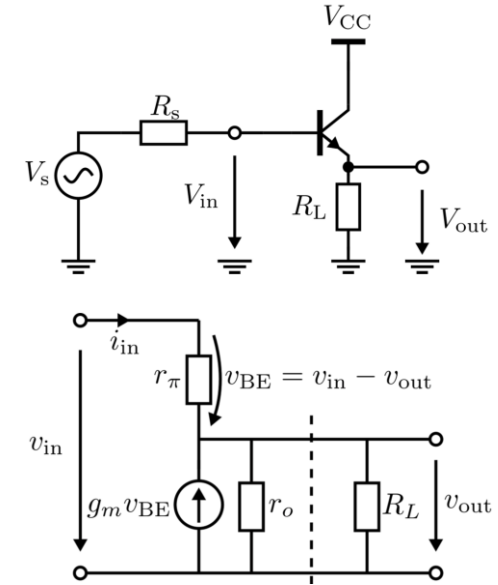
MOSFET: $R_S = 0$: voltage source ; $R_S = \infty$: current source



$$R_{in} = \frac{v_{in}}{i_{in}} \approx \frac{1}{g_m}, \quad R_{out} \approx (1 + g_m R_S) r_o$$

Common-Collector / Drain Amplifier

Also known as emitter / source follower

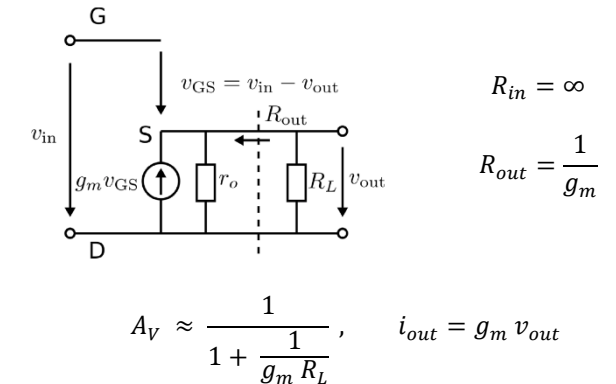


Usually: $R_L \ll r_o \rightarrow R_L || r_o \approx R_L$

$$R_{in} = \frac{v_{in}}{i_{in}} = r_{\pi} + (1 + \beta) R_L, \quad R_{out} = \frac{1}{g_m + \frac{1}{r_{\pi}}} \approx \frac{1}{g_m}$$

$$A_V = \frac{v_{out}}{v_{in}} \approx \frac{1}{1 + \frac{1}{g_m R_L}} \approx 1, \quad A_I = 1 + \beta$$

MOSFET: no current flowing into the gate ($A_I = \infty$)



Comparison of the three basic amplifiers

	CE/CS Amplifier	CC/CD Amplifier (Voltage Buffer)	CB/CG Amplifier (Current Buffer)
Voltage Gain $ A_V $	High	~ 1	High
Current Gain $ A_I $	High	Moderate	~ 1
Input Resistance R_{in}	High	High	Low
Output Resistance R_{out}	High	Low	High

After voltage buffer: lower output resistance (better V-source)

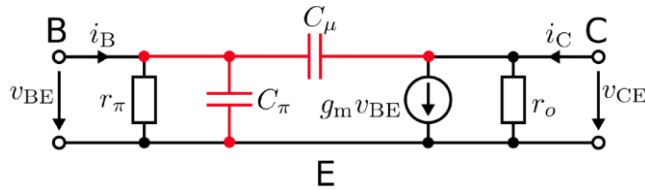
After current buffer: larger output resistance (better C-source)

Impedance Matching

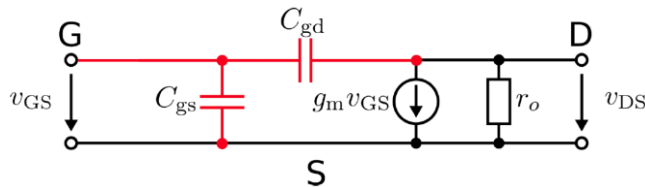
P_L is maximized when $R_L = R_S$

3. Frequency Response of Amplifiers

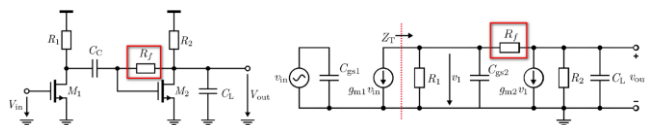
Change of charge vs. voltage across pn-junctions between BJTs can be represented by a parasitic capacitance



C_π : capacitance between B and E , $\triangleq C_{gs}$
 C_μ : capacitance between B and C , $\triangleq C_{gd}$

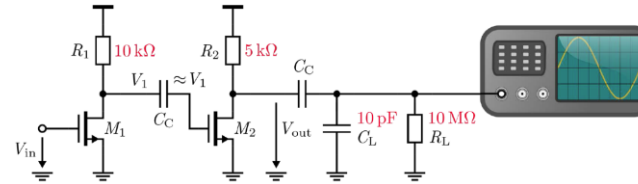


Bandwidth-Broadening



Additional shunt/feedback resistor R_f up to doubles bandwidth!

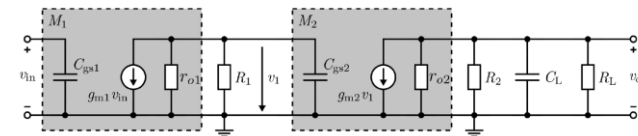
Multi-Stage Amplifier



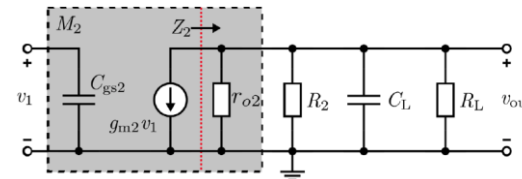
Small signal model: all constant voltage supplies become ground

C_C : large, \approx shorts , C_{gd} : often negligible

Stage 1:



Stage 2:

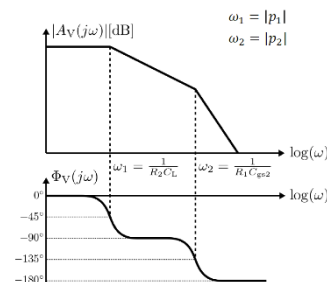


$$v_{out} = -g_{m2} v_1 Z_2 \approx \frac{-g_{m2} R_2}{1 + s C_L R_2} v_1, \quad Z_2 \approx \frac{R_2}{1 + s C_L R_2}$$

$$A_{V2}(s) = \frac{v_{out}(s)}{v_1(s)} = -\frac{g_{m2} R_2}{1 + s C_L R_2}$$

Cut-off frequencies: defined by poles

$$A_V(s) = \frac{v_{out}(s)}{v_{in}(s)} = \frac{g_{m1} R_1 * g_{m2} R_2}{(1 + s R_1 C_{gs2})(1 + s R_2 C_L)}$$



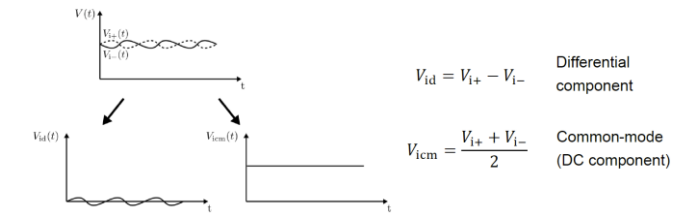
$$\omega_1 = |p_1| = \frac{1}{R_2 C_L}, \quad \omega_2 = |p_2| = \frac{1}{R_1 C_{gs2}}$$

Time Domain representation:

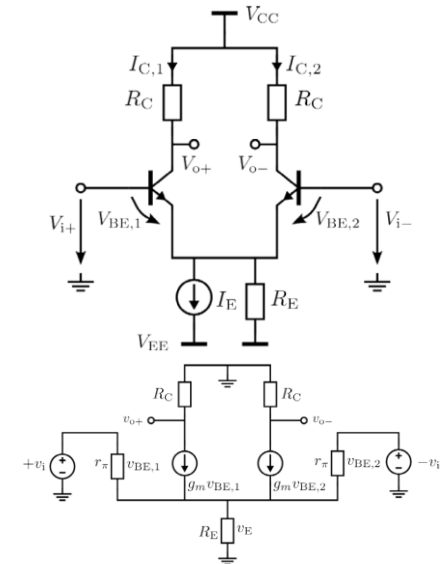
$$v_{out}(t) = A * e^{p_1 t} + B * e^{p_2 t} + C$$

4. Differential Amplifiers

Transmitting information with two complementary signals
 Information is contained in the difference, same DC value



Differential amplifier: In order to filter out DC component before the amplification, we use a fixed tail current I_E , which also enables DC coupling of stages (current splitted)



V_E (emitter-node potential) remains constant $\rightarrow v_E = 0$
 Symmetry between left and right branch \rightarrow split circuit into two independent parts and analyze separately (once)

Differential amplification: $A_{vd} = \frac{v_{od}}{v_{id}} = -g_m R_C$

Common-mode amplification: $A_{vcm} = \frac{v_o}{v_i} = \frac{v_{ocm}}{v_{icm}} = -\frac{R_C}{2R_E}$

Common Mode Rejection Ratio

Indicates how strong a common mode signal is attenuated compared to a differential signal

$$G = \frac{A_{vd}}{A_{vcm}} = \frac{-g_m R_C}{-R_C/2R_E} = 2 g_m R_E$$

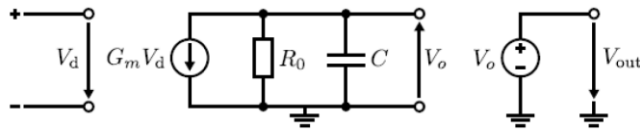
$$CMRR = G_{dB} = 20 * \log_{10} G$$

$$GBP = A_0 * \omega_c$$

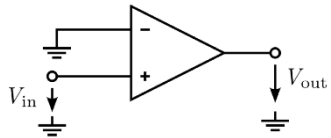
Operational amplifiers

Ideal: $Z_{in} \rightarrow \infty$, $Z_{out} \rightarrow 0$, $A_{vd} \rightarrow \infty$, $CMMR \rightarrow \infty$

Non-ideal Small Signal Equivalent

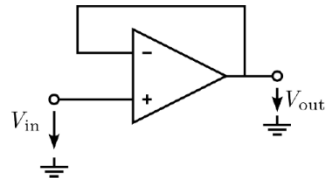


Voltage Comparator



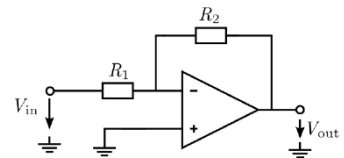
$$V_{out} = \text{sign}(V_{in}) * V_{CC}$$

Voltage follower (Buffer)



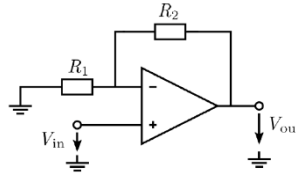
$$V_{out} = V_{in}$$

Inverting amplifier



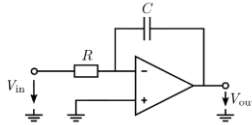
$$V_{out} = -\frac{R_2}{R_1} V_{in}$$

Non-inverting amplifier



$$V_{out} = \left(1 + \frac{R_2}{R_1}\right) V_{in}$$

Integrator

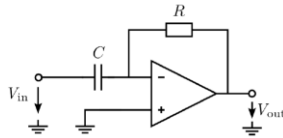


$$V_{out}(s) = -\frac{V_{in}(s)}{sRC}$$

$$V_{out}(t) = V_{out}(0) - \frac{1}{RC} \int_0^t V_{in}(t) dt$$

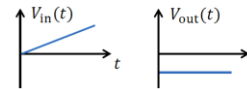


Differentiator



$$V_{out}(s) = -V_{in}(s)RCs$$

$$V_{out}(t) = -RC \frac{d}{dt} V_{in}(t)$$

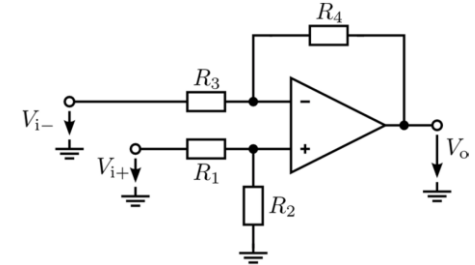


5. Instrumentation Amplifier

Precise amplification of weak, distorted sensor signals
High input impedance, internal feedback loop

Basic Instrumentation Amplifier

Amplifies voltage difference with a precise gain
Differential gain must be equal for both input branches



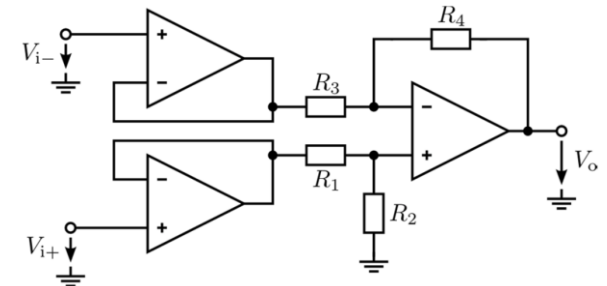
$$V_o = \frac{R_2}{R_1} \frac{1 + R_4/R_3}{1 + R_2/R_1} V_{i+} - \frac{R_4}{R_3} V_{i-}$$

Set $R_1 = R_3$, $R_2 = R_4$ to equally load both input branches:

$$V_o = G * V_{i+} - G * V_{i-}, \quad G = \frac{R_2}{R_1} = \frac{R_4}{R_3}$$

Buffered Instrumental Amplifier

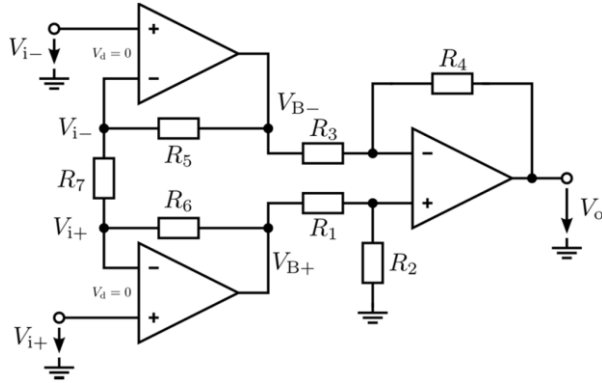
Obtain ideally high input impedance by input buffering



$$V_o = V_{icm} \left(\frac{R_2(R_3 + R_4)}{R_3(R_1 + R_2)} - \frac{R_4}{R_3} \right) + \frac{V_{id}}{2} \left(\frac{R_2(R_3 + R_4)}{R_3(R_1 + R_2)} + \frac{R_4}{R_3} \right)$$

$$CMMR = \frac{A_d}{A_{cm}} = \frac{V_o/V_{id}}{V_o/V_{icm}} = \frac{(R_3 + R_4)R_2 + (R_1 + R_2)R_4}{2 * (R_2R_3 - R_4R_1)}$$

Input stage gain



Differential & common mode gain of **input stage**:

$$A_B = \frac{V_{Bd}}{V_{id}} = \frac{V_{B+} - V_{B-}}{V_{i+} - V_{i-}} = 1 + \frac{R_5 + R_6}{R_7}$$

$$A_{cm,B} = \frac{V_{B+} + V_{B-}}{V_{i+} + V_{i-}} = 1 \rightarrow \text{no current through } R_5, R_6, R_7$$

Differential & common mode gain in **total**:

$$A'_d = \frac{V_o}{V_{id}} = \frac{A_B}{2} \left(\frac{R_2(R_3 + R_4)}{R_3(R_1 + R_2)} + \frac{R_4}{R_3} \right)$$

$$R_1 = R_3, R_2 = R_4 \rightarrow A'_d = \frac{R_2}{R_1} A_B$$

$$A_{cm} = A_{cm,B} \left(\frac{R_2(R_3 + R_4)}{R_3(R_1 + R_2)} - \frac{R_4}{R_3} \right)$$

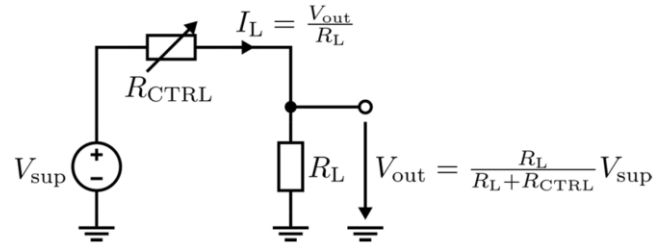
$$CMMR = \frac{A'_d}{A_{cm}} = A_B \frac{A_d}{A_{cm}} \rightarrow \text{increased by factor } A_B$$

Voltage offset: Offset voltage in combination with a small input signal is highly undesired. The output signal then reaches the saturation level even for small values of V_i and is therefore distorted.

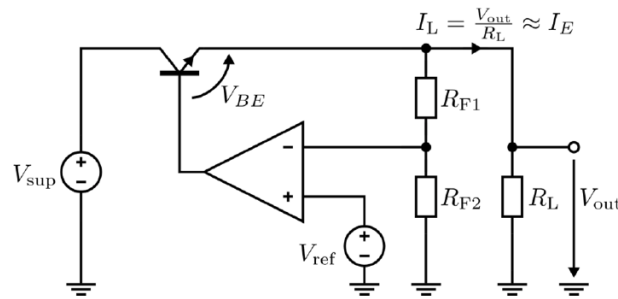
If this is not appropriate, **chopper amplifiers** can be used.

6. Voltage Regulators, Logarithmic & Anti-Logarithmic Amplifiers

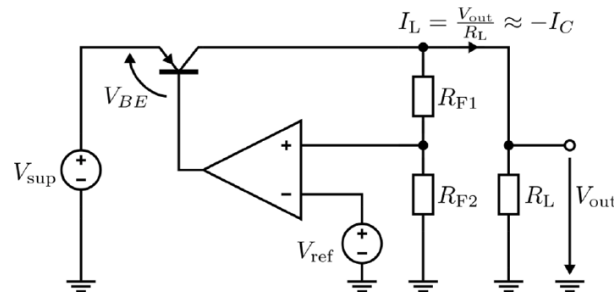
Linear voltage regulators



Non-inverting topology



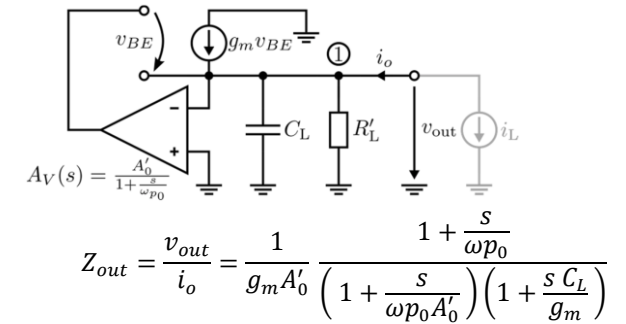
Inverting topology



$$V_{out} = \left(1 + \frac{R_{F1}}{R_{F2}} \right) V_{ref}$$

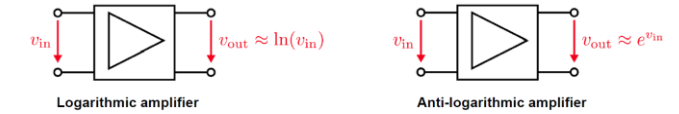
$$\text{Choose } R_{F1}, R_{F2} \gg R_L \rightarrow I_L \approx I_E / -I_C$$

Small Signal Equivalent:

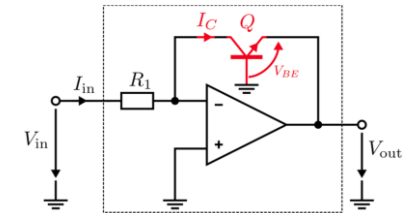


Logarithmic & Anti-Logarithmic Amplifiers

Non-linear circuit whose output voltage is proportional to the logarithm / exponential of the input voltage

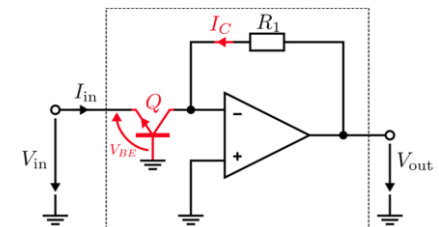


Logarithmic Amplifier: Rely on logarithmic relationship of I_C & V_{BE}



$$I_{in} = \frac{V_{in}}{R_1} = I_C = I_S e^{\frac{V_{out}}{V_T}}, V_{out} = -V_T \ln \left(\frac{I_{in}}{I_S} \right) = -V_T \ln \left(\frac{V_{in}}{R_1 I_S} \right)$$

Anti-Logarithmic Amplifier



$$V_{BE} = -V_{in}, I_C = I_S e^{\frac{V_{in}}{V_T}} \rightarrow V_{out} = I_C R_1 = I_S R_1 e^{\frac{V_{in}}{V_T}}$$

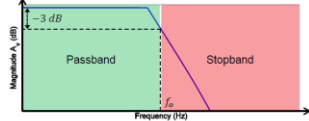
7. Active RC Filters

Filter is a frequency-selective circuit that passes a specified band of frequencies and blocks frequencies outside of it.

Passive Filters: based on passive elements such as R / L / C

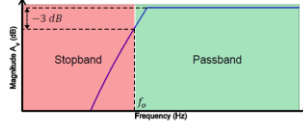
Active Filters: based on op-amps in addition to R / L / C

Low-pass filter (LPF)



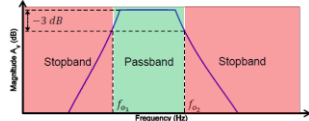
LPF passes frequencies from DC to a desired frequency f_0 .

High-pass filter (HPF)



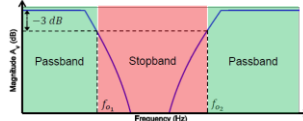
HPF passes frequencies starting from a desired frequency f_0 .

Band-pass filter (BPF)



BPF passes a band of frequencies from f_{01} to f_{02} and stops all other frequencies.

Band-stop filter (BSF)



BSF blocks a band of frequencies from f_{01} to f_{02} and passes all the other frequencies.

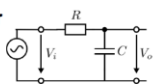
Cutoff frequency

Poles define cut-off: $|T(j\omega_c)| = \frac{1}{\sqrt{2}} \max(|T(j\omega)|)$

$$\omega_n = |p_n|, \quad BW_{-3dB} = \omega_0 / Q_0$$

First order passive filters

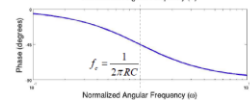
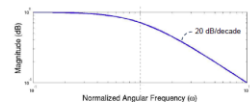
Low-pass Filter



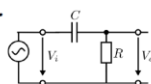
$$\text{Transfer function: } T(s) = \frac{V_o}{V_i} = \frac{1}{1 + sRC}$$

$$\text{Amplitude response: } \left| \frac{V_o(j\omega)}{V_i(j\omega)} \right| = \frac{1}{\sqrt{1 + (\omega RC)^2}}$$

$$\text{Phase response: } \angle \left(\frac{V_o(j\omega)}{V_i(j\omega)} \right) = -\tan^{-1}(\omega RC)$$



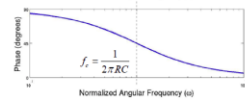
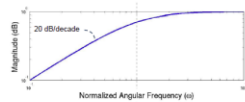
High-pass Filter



$$T(s) = \frac{V_o}{V_i} = \frac{sRC}{1 + sRC}$$

$$\left| \frac{V_o(j\omega)}{V_i(j\omega)} \right| = \frac{\omega RC}{\sqrt{1 + (\omega RC)^2}}$$

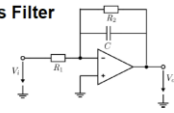
$$\angle \left(\frac{V_o(j\omega)}{V_i(j\omega)} \right) = 90^\circ - \tan^{-1}(\omega RC)$$



First order active filters

Filters and amplifies signal

Low-pass Filter

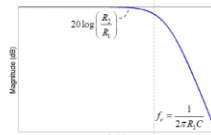


$$\text{Transfer function: } T(s) = \frac{V_o}{V_i} = -\frac{R_2}{R_1} \cdot \frac{1}{1 + sR_2C_2}$$

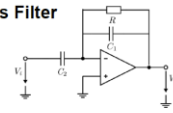
$$\text{Amplitude response: } |T(j\omega)| = \frac{R_2}{R_1} \cdot \frac{1}{\sqrt{1 + (\omega R_2C_2)^2}}$$

$$|T(j\omega=0)| = \frac{R_2}{R_1}$$

$$\text{Phase response: } \angle T(j\omega) = 180^\circ - \tan^{-1}(\omega R_2C_2)$$



High-pass Filter

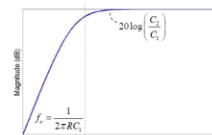


$$T(s) = \frac{V_o}{V_i} = -\frac{sR_2C_2}{1 + sR_2C_2}$$

$$|T(j\omega)| = \frac{\omega R_2C_2}{\sqrt{1 + (\omega R_2C_2)^2}}$$

$$|T(j\omega \rightarrow \infty)| = \frac{C_2}{C_1}$$

$$\angle T(j\omega) = -90^\circ - \tan^{-1}(\omega R_2C_2)$$

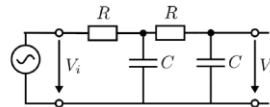
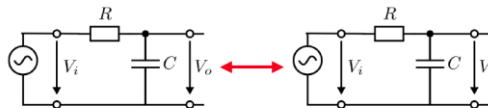


Comparison of first order filters

Passive Filters	Active Filters
2 passive elements that determine pole	3 passive elements, pole determined by elements in op-amp feedback
Fixed gain of 1 in pass band	Variable pass band gain possible
No power consumption	Op-amp consumes power
Real filter transfer function close to ideal filter function	Real filter transfer function dependent on op-amp DC-gain and gain-bandwidth product

Second order passive filters

2nd order passive filters can be synthesized from 1st order



$$T(s) = \frac{1}{s^2 + \frac{3}{RC}s + \frac{1}{R^2C^2}}, \quad \omega_0 = \frac{1}{RC}, \quad Q_0 = \frac{1}{3}$$

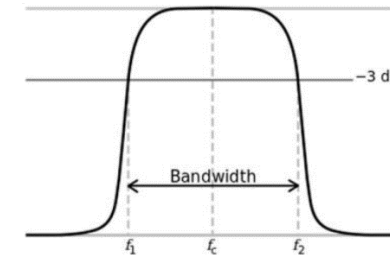
$$\text{Denominator: } D(s) = s^2 + \frac{\omega_0}{Q_0}s + \omega_0^2$$

$$\text{Poles: } p_{1,2} = -\frac{\omega_0}{2Q_0} \pm \omega_0 \sqrt{\frac{1}{4Q_0^2} - 1}$$

$$\text{Resonance frequency: } \omega_0 = 1/\sqrt{LC}$$

Quality factor:

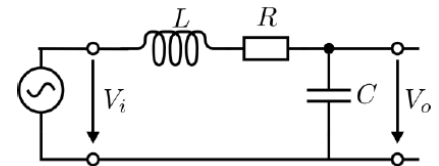
$$Q_0 = \frac{1}{R} \sqrt{L/C}$$



Energy vs. freq.

The higher Q, the narrower and sharper the peak.

Low-pass filter

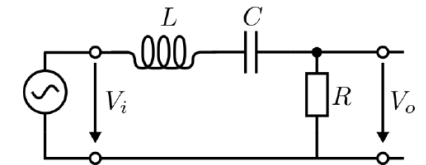


$$T(s) = \frac{\frac{1}{LC}}{s^2 + \frac{R}{L}s + \frac{1}{LC}} = \frac{\omega_0^2}{s^2 + \frac{\omega_0}{Q_0}s + \omega_0^2}$$

High-pass filter

$$T(s) = \frac{s^2 * \omega_0^2}{s^2 + \frac{\omega_0}{Q_0}s + \omega_0^2}$$

Band-pass filter

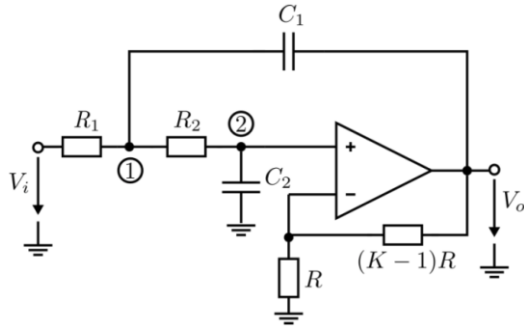


$$T(s) = \frac{s \frac{R}{L}}{s^2 + \frac{R}{L}s + \frac{1}{LC}}$$

Sallen-Key amplifier

Allow sharp gains without using inductors (expensive)

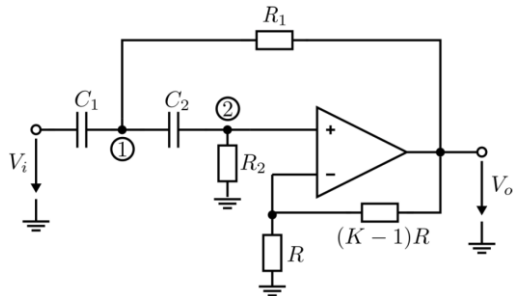
Low-pass filter



$$T(s) = \frac{K}{R_1 R_2 C_1 C_2} \frac{1}{s^2 + \left(\frac{1}{R_1 C_1} + \frac{1}{R_2 C_1} + \frac{1-K}{R_2 C_2} \right) s + \frac{1}{R_1 R_2 C_1 C_2}}$$

$$\omega_0 = \frac{1}{\sqrt{R_1 R_2 C_1 C_2}} \quad Q_0 = \frac{\omega_0}{\left(\frac{1}{R_1 C_1} + \frac{1}{R_2 C_1} + \frac{1-K}{R_2 C_2} \right)}$$

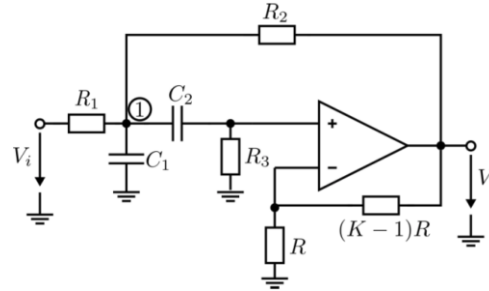
High-pass filter



$$T(s) = \frac{K s^2}{s^2 + \left(\frac{1}{R_2 C_2} + \frac{1}{R_2 C_1} + \frac{1-K}{R_1 C_1} \right) s + \frac{1}{R_1 R_2 C_1 C_2}}$$

$$\omega_0 = \frac{1}{\sqrt{R_1 R_2 C_1 C_2}} \quad Q_0 = \frac{\omega_0}{\left(\frac{1-K}{R_1 C_1} + \frac{1}{R_2 C_1} + \frac{1}{R_2 C_2} \right)}$$

Band-pass filter

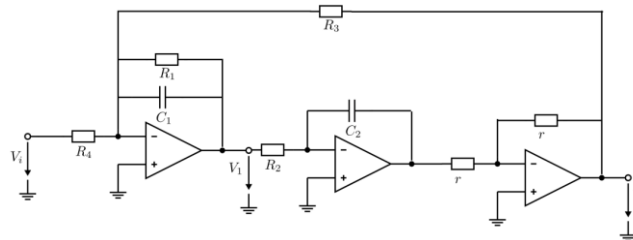


$$T(s) = \frac{\frac{K}{R_1 C_1} s}{s^2 + \left(\frac{1}{R_1 C_1} + \frac{1-K}{R_2 C_1} + \frac{1}{R_3 C_1} + \frac{1}{R_3 C_2} \right) s + \frac{R_1 + R_2}{R_1 R_2 R_3 C_1 C_2}}$$

$$\omega_0 = \sqrt{\frac{R_1 + R_2}{R_1 R_2 R_3 C_1 C_2}} \quad Q_0 = \frac{\omega_0}{\left(\frac{1}{R_1 C_1} + \frac{1}{R_3 C_2} + \frac{1}{R_3 C_1} + \frac{1-K}{R_2 C_1} \right)}$$

Tow-Thomas Biquad filter

Less sensitive to tolerance difference; combine Sallen-Keys



$$T_{LP}(s) = \frac{V_2}{V_i} = - \frac{1}{R_2 R_4 C_1 C_2} \frac{1}{s^2 + \frac{1}{R_1 C_1} s + \frac{1}{R_2 R_3 C_1 C_2}}$$

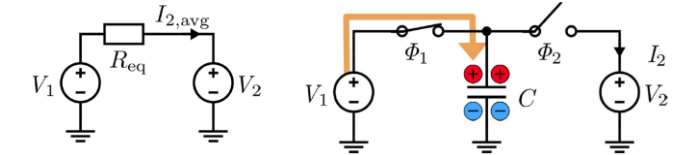
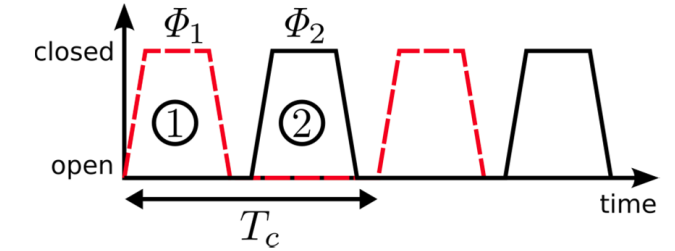
$$T_{BP}(s) = \frac{V_1}{V_i} = - \frac{\frac{1}{R_4 C_1} s}{s^2 + \frac{1}{R_1 C_1} s + \frac{1}{R_2 R_3 C_1 C_2}}$$

$$\omega_0^2 = \frac{1}{R_2 R_3 C_1 C_2} \quad Q_0 = \omega_0 R_1 C_1$$

8. Switched capacitor filters

Motivation: some systems require an active RC low-pass filter with very low f_{cutoff} → We need a large resistor in a highly integrated chip, whereby it is also inaccurate.

Concept of switched capacitor devices



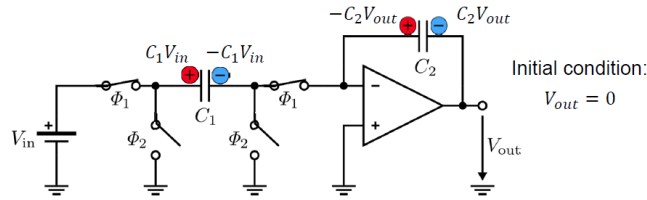
Transfer of charge ΔQ from potential V_1 to potential V_2 at a fixed rate $f_c = \frac{1}{T_c}$.

Transferred charge per T_c : $\Delta Q = C (V_1 - V_2)$

Average current: $I_{2,avg} = \frac{\Delta Q}{T_c} = \frac{C (V_1 - V_2)}{T_c}$

Equivalent resistor: $R_{eq} = \frac{T_c}{C} = \frac{1}{f_c C}$

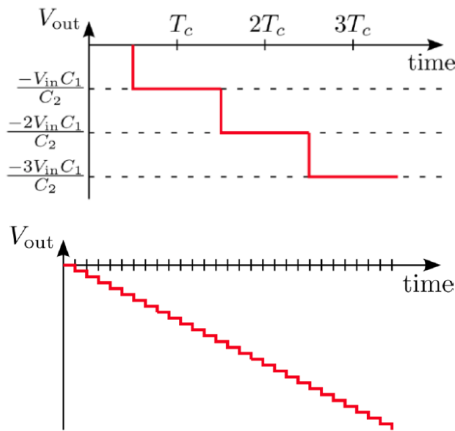
Inverting Integrator using SC



Phase 1: Φ_1 on, charge accumulates on C_1 and C_2

Phase 2: Φ_2 on, C_1 is discharged

$$C_2 V_{out}[nT_c] = C_2 V_{out}[(n-1)T_c] - C_1 V_{in}[nT_c]$$



\Rightarrow seems continuous for small enough T_c

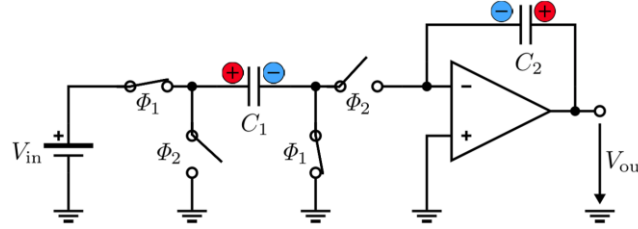
$$V_{out}[nT_c] = -\frac{C_2}{T_c C_2} \int_0^{nT_c} V_{in}(t) dt$$

Ratio of capacitors can be realized more accurate than absolute values of R and C.

Z-transform

Definition	$Z\{x[nT_c]\} = X(z)T = \sum_{k=-\infty}^{\infty} x[kT_c]z^{-k}$
Time delay	$Z\{x[(n-k)T_c]\} = z^{-k}X(z)$
Mapping to Laplace domain	$s = \frac{z-1}{T_c}$ or $s = \frac{1-z^{-1}}{T_c}$ (forward/backward Euler transform)
Mapping to $j\omega$ -axis	$z = e^{j\omega T_c} = e^{j\frac{2\pi f}{f_c} T_c}$

Non-inverting Integrator using SC



Same circuit as before, only **change of switching schedule**

\Rightarrow **Charge on C_2 is inverted** compared to before

Phase 1: C_1 is charged to V_{in}

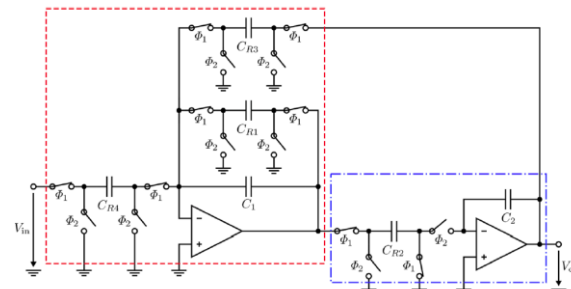
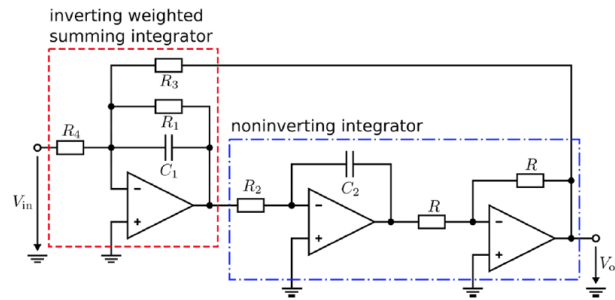
Phase 2: Charge is transferred to C_2

$$C_2 V_{out}[nT_c] = C_2 V_{out}[(n-1)T_c] + C_1 V_{in}[nT_c]$$

$$C_1 V_{in}(z) = C_2 (1 - z^{-1}) V_{out}(z)$$

$$\frac{V_{out}(z)}{V_{in}(z)} = \frac{C_1}{C_2} \frac{1}{1 - z^{-1}}$$

Switched capacitor Tow-Thomas biquad



\Rightarrow Replace all resistors by switched capacitors

$$T(z) = \frac{V_{out}(z)}{V_{in}(z)} = -\frac{C_{R4}}{C_{R3}} \frac{z^{-2} + z^{-1} \left(-2 - \frac{C_{R1}}{C_1} \right) + 1 + \frac{C_{R1}}{C_1} + \frac{C_{R2}C_{R3}}{C_1C_2}}{z^{-2} + z^{-1} \left(-2 - \frac{\omega_0 T_c}{Q} \right) + 1 + \frac{\omega_0 T_c}{Q} + (\omega_0 T_c)^2}$$

$$T(s) = \frac{k\omega_0^2}{s^2 + \frac{\omega_0}{Q}s + \omega_0^2} \rightarrow T(z) \approx \frac{k(\omega_0 T_c)^2}{z^{-2} + z^{-1} \left(-2 - \frac{\omega_0 T_c}{Q} \right) + 1 + \frac{\omega_0 T_c}{Q} + (\omega_0 T_c)^2}$$

Design equations:

$$\frac{C_{R4}}{C_{R3}} = -k, \quad \frac{C_{R2}}{C_2} = \frac{C_{R3}}{C_1} = \omega_0 T_c, \quad \frac{C_{R3}}{C_{R1}} = Q$$

Z-transform extended

Time discrete equivalent of the Laplace function.

$$X(z) = \sum_{k=-\infty}^{\infty} x[k]z^{-k}$$

Delay by n samples:

$$x[k] \rightarrow x[k-n] \Leftrightarrow X[z] \rightarrow z^{-n}X[z]$$

Transformation to frequency:

$$z = e^{i\omega T_c} = e^{\frac{i2\pi f}{f_c} T_c}$$

Differentiation:

$$Z\left(\frac{df(t)}{dt}\right) \Rightarrow F(z) \frac{1 - z^{-1}}{T_c}$$

Integration:

$$Z\left(\int f(t)dt\right) \Rightarrow F(z) \frac{T_c}{1 - z^{-1}}$$

Forward Euler Transform: $s = \frac{z-1}{T_c}$

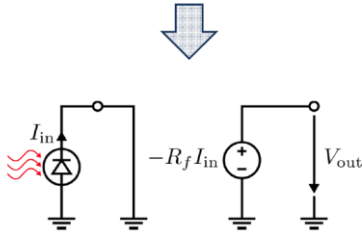
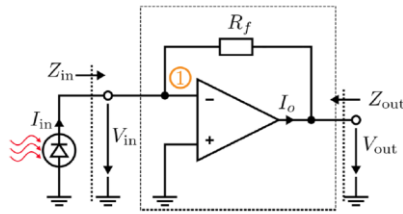
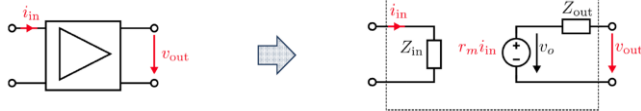
Backward Euler Transform: $s = \frac{1-z^{-1}}{T_c}$

9. Appendix

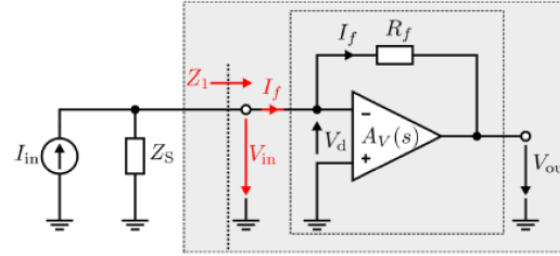
Transimpedance amplifiers

Sensing an input current & converting it to output voltage

$$r_m = \frac{dV_o}{dI_{in}}, \quad Z_{in} \rightarrow 0, \quad Z_{out} \rightarrow 0$$



Frequency Response of Transimpedance Amplifiers



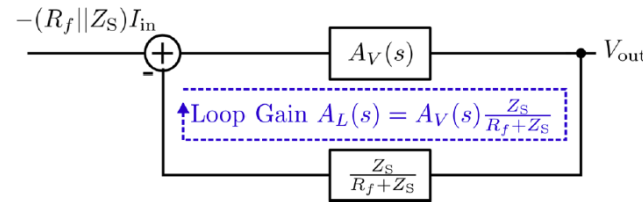
Transimpedance experiences broadbanding due to feedback:

$$Z_T' = \frac{V_{out}}{I_f} = -A_v(s)Z_1 = \frac{R_f A_0}{1 + A_0 + \frac{s}{\omega_{p_0}}} \approx \frac{R_f}{1 + \frac{s}{A_0 \omega_{p_0}}}$$

Bandwidth is limited by GBP of op-amp.

$$\text{Loop gain: } A_L(s) = A_V(s) \frac{Z_S}{R_f + Z_S}$$

$$\text{Feedback-factor: } \beta(s) = \frac{Z_S}{R_f + Z_S}$$



→ **High bandwidth trade-off:** High transimpedance gain results in lower bandwidth

Due to the capacitance $C_s' = C_s + C_{in}$ the transimpedance amplifier becomes a second-order system with DC transimpedance gain $\approx -R_f$ and a loop gain

$$A_L(s) = A_V(s) = \frac{A_0}{\left(1 + \frac{s}{\omega_{p_0}}\right) \left(1 + \frac{s}{\omega_{p_s}}\right)}$$

Step Response of Second-Order Systems

$$Z_T(s) = \frac{V_{out}}{I_{in}} = -R_f \frac{\omega_n^2}{(s - p_1)(s - p_2)} = -R_f \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

Characteristic equation: $s^2 + 2\zeta\omega_n s + \omega_n^2 = 0$:

$$\omega_n = \sqrt{A_0 \omega_{p_0} \omega_{p_s}} \quad \zeta = \frac{\omega_{p_0} + \omega_{p_s}}{2\sqrt{A_0 \omega_{p_0} \omega_{p_s}}}$$

$$p_1 = -\zeta\omega_n + \omega_n\sqrt{\zeta^2 - 1}$$

$$p_2 = -\zeta\omega_n - \omega_n\sqrt{\zeta^2 - 1}$$

$$\omega_{p_0} = -p_0 \quad A_0 \omega_{p_0} = GBP$$

$$\omega_{p_s} = \frac{1}{R_f C_s'} \quad Q = \frac{1}{2\zeta}$$

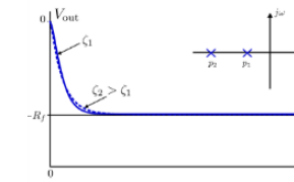
System behavior:

Overdamped ($\zeta > 1$): p_1, p_2 are real and negative

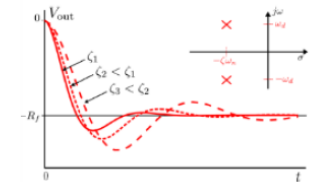
Critically damped ($\zeta = 1$): $p_1 = p_2 = -\omega_n$

Underdamped ($0 < \zeta < 1$): p_1, p_2 are complex conjugates

Overdamped

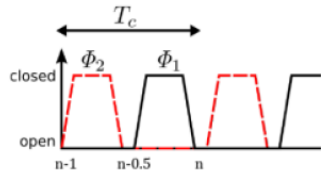
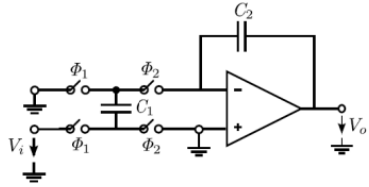


Underdamped



Switched Capacitors Examples

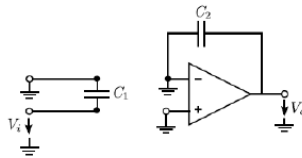
Example:



At the end of $\Phi_1(n-1)$:

$$Q_{C1} = C_1 \cdot V_i(n-1)$$

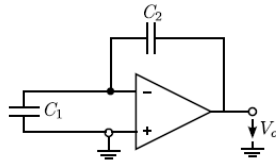
$$Q_{C2} = C_2 \cdot V_0(n-1)$$



At the end of $\Phi_2(n-0.5)$:

$$Q_{C1} = C_1 \cdot 0$$

$$Q_{C2} = C_2 \cdot V_0(n-0.5)$$



Charge conservation:

At $(n-0.5)$:

$$C_2 V_0(n-0.5) = C_2 V_0(n-1) + C_1 V_i(n-1)$$

At (n) : (nothing happens to Q_{C2})

$$C_2 V_0(n) = C_2 V_0(n-0.5)$$

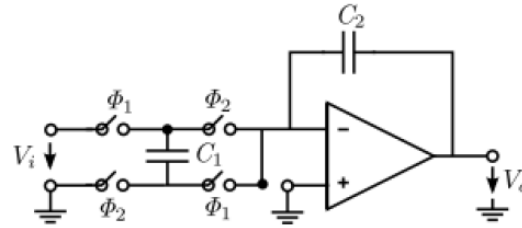
Results in:

$$C_2 V_0(n) = C_2 V_0(n-1) + C_1 V_i(n-1)$$

$$C_2 V_0(Z) = C_2 Z^{-1} V_0(Z) + C_1 Z^{-1} V_i(Z)$$

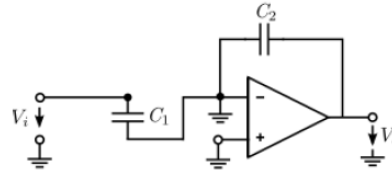
$$\frac{V_0(Z)}{V_i(Z)} = \frac{C_1}{C_2} \frac{Z^{-1}}{1 - Z^{-1}}$$

Example 2:



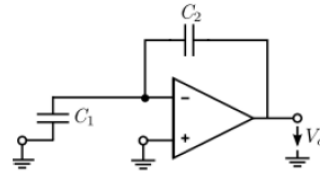
@ $\Phi_1(n-1)$:

$$Q_1 = C_1 V_i(n-1) \quad Q_2 = C_2 V_0(n-1)$$



@ $\Phi_1(n-0.5)$:

$$Q_1 = 0 \quad Q_2 = C_2 V_0(n-0.5)$$



Charge conservation:

Überlegen wo positive und negative Ladung hingeht.

Verstärker verstärkt solange bis die eingangsspannungsdifferenz 0 ist.

@ $(n-0.5)$:

$$C_2 V_0(n-0.5) = C_2 V_0(n-1) - C_1 V_i(n-1)$$

@ (n) :

$$C_2 V_0(n) = C_2 V_0(n-0.5) - C_1 V_i(n)$$

$$\Rightarrow C_2 V_0(n) = C_2 V_0(n-1) - C_1 V_i(n-1) - C_1 V_i(n)$$

$$\Rightarrow \frac{V_0(Z)}{V_i(Z)} = -\frac{C_1}{C_2} \frac{1 + Z^{-1}}{1 - Z^{-1}}$$