

# **AUTOMATIC SOLAR PANEL CLEANING SYSTEM**

## **A PROJECT WORK I REPORT**

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*in partial fulfilment of the requirements  
for the award of the degree of*

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**DECLARATION**

We affirm that the project work I report titled “**AUTOMATIC SOLAR PANEL CLEANING SYSTEM**” being submitted in partial fulfilment of the requirements for the award of Bachelor of Engineering is the original work carried out by us . It has not formed the part of any other project report or dissertation on the basis of which a degree or award was conferred on an earlier occasion on this or any other candidate.

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## ABSTRACT

The Solar energy sector's growth highlights the importance of maintaining solar panel efficiency for optimal energy production. Neglecting panel cleanliness can lead to reduced performance due to dirt and debris accumulation. Our Company which uses the Solar panels at their power loom industry also facing the same problem . So, to tackle this issue, Automatic Solar Panel cleaning system is proposed, utilizing key components such as the L298N motor driver, gear motors, ESP WROOM 32 Dev Kit, wheels, cleaning mop, and a lithium-ion battery. The system's design integrates hardware and software components to autonomously clean solar panels effectively. Precise control of gear motors is facilitated by the LM298 motor driver, enabling systematic panel traversal. The ESP WROOM 32 Dev Kit acts as the central controller, managing motor control, power distribution, and sensor integration. Critical design aspects include creating a robust cleaning mechanism compatible with the gear motors and ensuring stable power supply from the lithium-ion battery. Integration of sensors like light or ultrasonic sensors allows for dirt detection and optimized cleaning schedules. Control algorithms on the ESP WROOM 32 coordinate motor movements, cleaning cycles, and sensor feedback. Wireless connectivity options provide remote monitoring and control, including Bluetooth connectivity for mobile phone operation, enabling users to manage cleaning tasks from anywhere within Bluetooth range. Testing and calibration phases are essential for refining motor movements, cleaning efficiency, and system reliability. Once deployed, the system autonomously cleans panels based on preset schedules or sensor inputs. This automated cleaning system offers a practical solution for maintaining solar panel efficiency, particularly in dusty environments. It reduces manual labour and ensures consistent cleaning cycles, enhancing energy output from solar installations while minimizing maintenance needs. Future improvements may focus on refining cleaning algorithms, incorporating predictive maintenance features, and scaling the system for larger solar arrays

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## LIST OF ABBREIVATIONS

AWG	-	American Wire Gauge
ESP	-	Espressif System
I2C	-	Inter-Integrated Circuit
IDE	-	Integrated Development Environment
IoT	-	Internet of Things
PWM	-	Pulse Width Modulation
SPI	-	Serial Peripheral Interface
TTL	-	Transistor Transistor Logic
UART	-	Universal Asynchronous Receiver/Transmitter
USB	-	Universal Serial Bus

## CHAPTER 1

### INTRODUCTION

The global shift towards sustainable energy solutions has prompted industries worldwide to explore renewable energy sources like solar power as viable alternatives to traditional fossil fuels[1]. Solar panels have become increasingly popular for businesses seeking to reduce operational costs, minimize environmental impact, and demonstrate corporate responsibility. While solar panels offer significant benefits in terms of clean energy production, their efficiency can be compromised over time due to factors such as dust accumulation, debris deposition, and environmental wear[2].

Regular maintenance is crucial to ensuring optimal performance and maximizing the return on investment from solar installations. To address the challenges of solar panel maintenance, innovative technologies such as automatic solar panel cleaning systems have gained traction[3]. These systems utilize advanced components such as motor drivers, gear motors, microcontrollers, sensors, and cleaning mechanisms to autonomously clean solar panels, thereby improving their efficiency and longevity. Automatic solar panel cleaning systems address these maintenance challenges effectively. These systems employ advanced technologies like precision motor control, sensors, and intelligent algorithms to autonomously clean panels, ensuring consistent peak performance[4]. Implementing these systems not only upholds sustainability commitments but also optimizes energy output and financial savings[5]. Cleaner panels absorb sunlight more efficiently, enhancing both environmental and economic benefits. The adoption of automatic solar panel cleaning systems reflects a forward-thinking approach, blending efficiency gains with environmental stewardship[6]. This strategy resonates well in today's dynamic corporate landscape, making it an appealing choice for businesses aiming for sustainable energy management and operational excellence.

Figure 1.1 depicts the comprehensive layout of the automatic solar panel cleaning system. This system is intricately connected and managed via Bluetooth communication with the ESP32 microcontroller. The remaining circuitry, including sensors, motors, and power distribution components, is integrated directly into the ESP32

controller[7]. This arrangement streamlines the system's design and operation, enabling efficient control and monitoring of the cleaning process.



**Figure 1.1 Automatic Solar Panel cleaning system.**

## **1.1 OBJECTIVE**

To create an automatic solar panel cleaning system ensuring consistent performance and durability of solar installations. Beginning with research and stakeholder input, we'll design a robust system architecture, carefully selecting components for efficiency and reliability. Development involves creating both hardware and software elements, rigorously testing prototypes to refine functionality. Upon integration and installation, we'll monitor system performance, optimizing as needed. Training and documentation will ensure smooth operation, with ongoing support and continuous improvement driving long-term success.

### **1.1.1 SCOPE**

The development of an automatic solar panel cleaning system encompasses designing and integrating efficient cleaning mechanisms using precision motor control, sensors, and intelligent algorithms. This includes hardware integration of essential components like motor drivers, gear motors, and power management systems. The development of control algorithms and software logic for sensor integration, wireless

connectivity, and remote monitoring is crucial. Testing and validation procedures will ensure the system's reliability and efficiency under diverse environmental conditions. Scalability, adaptability, and economic impact assessments are also part of the scope to ensure the system's effectiveness in optimizing energy output, reducing maintenance costs, and aligning with sustainability objectives.

## **1.2 SYSTEM SPECIFICATION**

### **1.2.1 HARDWARE REQUIREMENTS**

- L298N Motor driver
- ESP wroom 32 controller
- 12v gear motors
- Lithium Ion battery
- Wheels
- Mop
- Wires

### **1.2.2 SOFTWARE REQUIREMENTS**

- Arduino IDE

### **1.2.3 HARDWARE DESCRIPTION**

Hardware description represents the various hardware tools which are used in this project.

#### **1.2.3.1 L298N Motor driver**

The L298N is a popular dual H-Bridge motor driver integrated circuit (IC) that is commonly used in robotics and motor control applications. Here are some typical specifications and features of the L298N motor driver:

- Motor Channels: The L298N can control two DC motors or one stepper motor with bidirectional control.
- Motor Voltage: Supports motor voltages ranging from 5V to 35V DC.
- Maximum Current: Each channel can handle a continuous current of up to 2A (with a peak current of 3A) without a heat sink. With a proper heat sink, the current handling capacity can be increased.

- **Logic Voltage:** Supports logic input voltages from 5V to 7V (typical). **Control Modes:** Provides direction and speed control for DC motors, and step and direction control for stepper motors.
- **Built-in Diodes:** Includes built-in flyback diodes (freewheeling diodes) for inductive load protection.
- **Logic Inputs:** Uses TTL logic inputs for control (high-level input for one direction, low-level input for the opposite direction).
- **Enable Pins:** Enable pins (EN) allow the user to enable or disable the motor outputs, which can be useful for motor power management.
- **Protection Features:** Built-in thermal shutdown and crossover-current protection.
- **Heat Dissipation:** The L298N IC requires proper heat sinking or cooling for continuous high-current operation.
- **Package:** Available in a Multiwatt15 package.
- **Compatibility:** Suitable for use with a wide range of microcontrollers, Arduino boards, and other control systems.

When using the L298N motor driver, it's important to adhere to the specified voltage and current ratings, implement appropriate heat dissipation measures if needed, and follow proper wiring and control logic to ensure safe and efficient motor operation.



**Figure 1.2 L289N Motor driver**

#### **1.2.3.2 ESP wroom 32 controller**

The ESP-WROOM-32 Dev Kit is based on the ESP32 microcontroller, which is known for its versatility and powerful features. Here are some typical specifications and features of the ESP-WROOM-32 Dev Kit:

- Microcontroller: ESP32 dual-core Tensilica LX6 microcontroller running at up to 240 MHz clock frequency.
- Wireless Connectivity: Integrated Wi-Fi (802.11 b/g/n) and Bluetooth (Bluetooth Low Energy or BLE) capabilities for wireless communication and IoT applications.
- Memory: Up to 520 KB SRAM and 448 KB ROM for program and data storage, as well as external SPI flash support.
- GPIO Pins: Multiple General Purpose Input/Output pins (GPIOs) for interfacing with sensors, actuators, and external devices.
- Analog Inputs: Multiple ADC (Analog-to-Digital Converter) channels for analog sensor interfacing.
- Digital Interfaces: SPI, I2C, UART and PWM interfaces for communication with peripherals.
- Operating Voltage: Typically operates at 3.3V, but has voltage tolerance for 5V inputs on certain pins with appropriate level shifting.
- Programming: Supports programming using the Arduino IDE, Espressif IDF (IoT Development Framework), and other development environments.
- Development Tools: Comes with built-in USB-to-UART bridge (CP2102) for easy programming and debugging.
- Power Consumption: Offers low-power modes and optimizations for battery-powered and energy-efficient applications.
- Integrated Peripherals: Includes temperature sensor, touch sensor, hall sensor, and built-in LED indicators for easy debugging.
- Form Factor: Compact and easily embeddable into projects, with options for breadboard-friendly headers or surface-mount configurations.



**Figure 1.3 ESP wroom 32 controller**

The ESP-WROOM-32 Dev Kit is widely used in IoT projects, home automation, robotics, and other applications requiring wireless connectivity, sensor interfacing, and real-time data processing capabilities.

#### **1.2.3.3 12v Gear motor**

When integrating 12V gear motors into your project, choosing an appropriate motor driver is crucial for optimal performance and safety. The motor driver should be compatible with a 12V power supply to effectively drive the gear motors. It's important to match the motor driver's current rating with or exceed the stall current of the gear motors to ensure it can handle the peak current demands during operation without overheating or damage. Bidirectional control capability allows for motor rotation in both directions, while PWM support enables precise speed control, essential for various applications. Incorporating motor drivers with built-in protection features such as overcurrent protection and thermal shutdown enhances system reliability and protects the motors and driver circuitry. Consideration of control interfaces such as PWM, analog voltage control, or serial communication ensures seamless integration with your control system or microcontroller setup. These considerations collectively contribute to a robust and efficient motor control system for your 12V gear motors, meeting your project's requirements effectively.



**Figure 1.4 12v Gear Motor**

#### **1.2.3.4 Lithium Ion Battery**

Lithium-ion batteries, known for their high energy density and rechargeable nature, boast several key specifications essential for various electronic applications. These batteries typically operate at voltages ranging from 3.7V for single cells to higher voltages for multiple cells in series configurations. Capacity, measured in ampere-hours (Ah) or milliampere-hours (mAh), indicates the amount of charge the

battery can store and deliver over time. The charging voltage and current levels must align with the battery's specifications to ensure safe and efficient charging. Moreover, lithium-ion batteries exhibit low self-discharge rates, retaining stored energy for extended periods when not in use. However, proper handling and charging are crucial as these batteries can be sensitive to overcharging, deep discharge, and high temperatures, necessitating the use of appropriate charging circuits and protection mechanisms. Overall, understanding and adhering to the specifications and recommended operating conditions of lithium-ion batteries are paramount for their reliable and safe use in electronic devices and systems.



**Figure 1.5 Lithium Ion Battery**

#### **1.2.3.5 Wheels**

Wheel specifications play a crucial role in determining the performance, stability, and safety of vehicles, machinery, and robotic systems. The diameter of the wheel affects speed and torque, with larger diameters often providing higher speeds but requiring more torque. Wheel width influences traction and stability, with wider wheels offering better traction but potentially increasing rolling resistance. Materials such as rubber, plastic, metal, or composites are chosen based on load-bearing capacity and durability requirements. Load capacity is a key consideration, ensuring wheels can support the intended weight safely. Wheel type, whether solid, pneumatic, or semi-pneumatic, impacts shock absorption and terrain compatibility. Hub type and bearings influence mounting, rotation, and smoothness of operation. Temperature and chemical resistance are vital for wheels used in extreme environments, and customization options allow tailoring wheels to specific needs like tread pattern and colour. Considering these specifications ensures selecting wheels suitable for the intended application's performance, durability, and environmental conditions.





**Figure 1.6 Wheels**

#### **1.2.3.6 Mop**

Mops come in various sizes, shapes, and materials, offering versatility for different cleaning tasks. The mop's material, such as cotton, microfiber, or sponge, determines its absorbency and cleaning effectiveness. Size and shape impact coverage area, while handle length and material influence user comfort during cleaning. Consider the mop type based on whether you need wet mops for floors, dust mops for dry surfaces, or specialized mops like spin or steam mops for specific cleaning needs. Durability, compatibility with cleaning solutions, and ease of maintenance are key factors to ensure long-term usability and efficiency in keeping spaces clean and hygienic.

#### **1.2.3.7 Wires**

Wires used in electrical and electronic applications come with specific specifications crucial for safe and efficient operation. These specifications include wire gauge (AWG), insulation material, voltage and temperature ratings, current capacity, flexibility, and environmental considerations. Choosing the right wire gauge ensures it can handle the required current without overheating, while the insulation material and voltage rating protect against electrical hazards. Temperature ratings ensure wires can operate safely in different temperature ranges, and flexibility is important for ease of installation and routing. Considering these specifications helps ensure reliable performance and safety in wiring systems across various applications.

## **1.2.4 SOFTWARE DESCRIPTION**

Software description represents the software tools which are used to develop the project

### **1.2.4.1 Arduino IDE**

The Arduino Integrated Development Environment (IDE) is a software platform designed to simplify the development of Arduino-based projects. It provides an easy-to-use interface for writing, compiling, and uploading code to Arduino microcontroller boards. The Arduino IDE supports the C and C++ programming languages, making it accessible to both beginners and experienced developers. Key features of the Arduino IDE include a text editor with syntax highlighting and auto-completion, a serial monitor for debugging and communication with Arduino boards, and a library manager for easily adding and managing libraries. The IDE also offers a variety of example sketches and tutorials to help users get started with their projects quickly. Overall, the Arduino IDE plays a crucial role in enabling users to create interactive electronic projects using Arduino boards and sensors with ease.

## CHAPTER 2

### ABOUT THE COMPANY

#### 2.1 COMPANY DETAILS

**COMPANY NAME** : JAI SAI SOLAR SOLUTION

**ADDRESS** : No.272, Thay Nagar, Kanchi Kovil Road ,  
Perundurai,  
Erode (Dt) – 638052,  
Tamilnadu,  
India.

**DESCRIPTION** : The Company integrates the Solar Panel Systems to mitigate power costs in manufacturing operations. It employs sustainable energy practices through the utilization of solar panels to power its power loom industry. Figure 2.1 represents the Solar panel System they are using for their power production.



**Figure 2.1** Solar panel System in the company

## 2.2 PROBLEM STATEMENT

As Solar panels contribute major part for their electricity, yet environmental conditions cause frequent dust accumulation, diminishing efficiency. Manual cleaning is often the only recourse, impractical in many locations. This hampers production and sustainability efforts. An urgent need exists for efficient, automated cleaning solutions to maintain peak performance. Innovations in solar panel maintenance can strengthen efficiency and viability in diverse environments, advancing renewable energy goals globally.

Figure 2.2 represents the cleaning method of the company, they are cleaning manually using the mop and by spraying water. Because of this method they are losing their one day production , so they need a automatic solar panel cleaning System.



**Figure 2.2 Solar panel cleaning method of the company**

## **CHAPTER 3**

### **EXISTING METHOD**

While there are several methods for automatic solar panel cleaning currently in use, one common of automatic solar panel cleaning systems employ water-based methods, such as spraying or dripping water onto the panels to dislodge dirt and debris. While effective in cleaning, this approach can lead to significant water usage, especially in arid regions or areas facing water scarcity. Additionally, the runoff from cleaning operations can carry pollutants and contaminants, potentially harming local ecosystems if not properly managed.

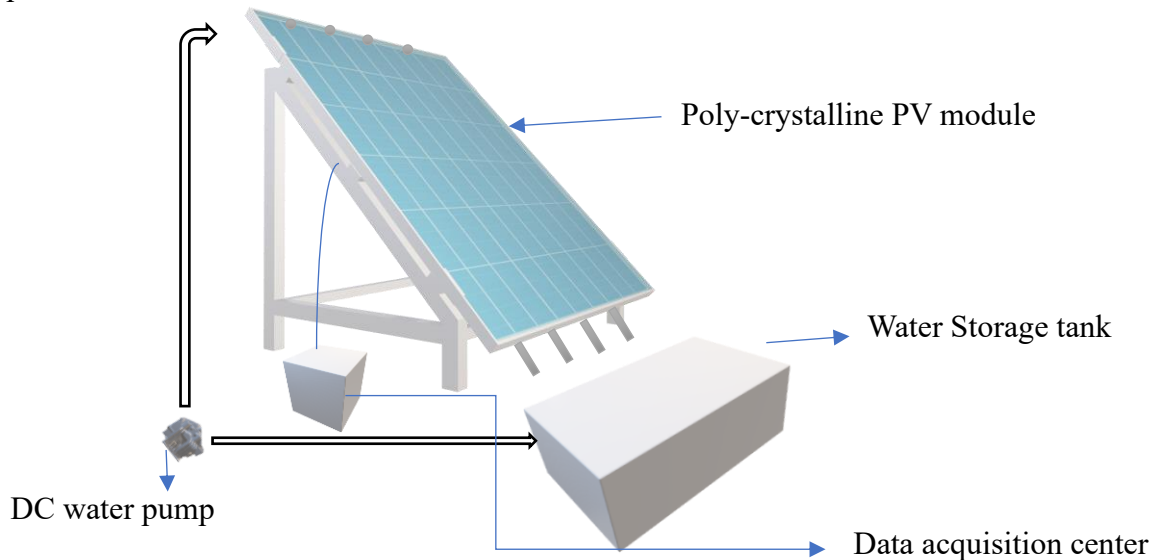
#### **3.1 WORKING OF EXISTING METHOD**

An automatic solar panel cleaning system that utilizes water operates through a sophisticated process designed to efficiently remove dirt, dust, and debris from the surface of solar panels. At its core lies a water distribution system comprising pipes, pumps, and strategically positioned nozzles. This system draws water from a reservoir or water source, pumps it through the pipes, and releases it through the nozzles onto the solar panel array. Controlled by a central unit, often powered by a microcontroller like the ESP32, the system orchestrates the cleaning process. It regulates the flow of water, initiates cleaning cycles based on predetermined schedules or sensor inputs, and monitors key parameters throughout the operation. This central control mechanism ensures precision and efficiency in the cleaning process.

The cleaning cycle typically begins when triggered by preset schedules or environmental conditions sensed by onboard sensors. Once initiated, the water distribution system springs into action, spraying water evenly across the surface of the solar panels. The force of the water, combined with the pressure from the nozzles, effectively dislodges dirt and debris, allowing them to be washed away. Importantly, the system incorporates mechanisms for managing water usage and runoff to minimize waste and environmental impact. This may include recycling water for multiple cleaning cycles or directing runoff to designated drainage channels or collection tanks. By carefully managing water resources, the system ensures responsible stewardship of this valuable resource.

Throughout the cleaning process, the system continuously monitors performance metrics such as water usage, cleaning efficiency, and energy output. This data informs

optimization efforts, allowing for adjustments to cleaning parameters and schedules to maintain consistent performance over time. In addition to efficiency considerations, safety features are integrated into the system to prevent damage to the solar panels or surrounding infrastructure. These may include sensors to detect obstructions or malfunctions, emergency shutoff mechanisms, and fail-safe protocols, ensuring the safety and integrity of the cleaning operation.



**Figure 3.1 Model of solar panel cleaning system using water**

The Figure 3.2 depicts a solar panel cleaning system equipped with a sprinkler setup operates through a carefully orchestrated process designed to efficiently remove dirt and debris from the panel surfaces. Initially, a network of strategically positioned sprinklers is established around the solar panel array to ensure comprehensive coverage. This network is connected to a water distribution system comprising pumps, pipes, and valves, responsible for supplying water to the sprinklers.

Controlled by a central unit, typically powered by a microcontroller like the ESP32, the system regulates the activation of the sprinklers, adjusts water flow rates, and monitors overall performance. The cleaning cycle is initiated based on predetermined schedules or triggered by environmental sensors detecting dirt accumulation or reduced energy output. Upon activation, the sprinklers release a fine mist or spray of water onto the panel surfaces, effectively dislodging dirt and debris. As the water flows over the panels, it carries away the contaminants, leaving the surfaces clean.

To mitigate water wastage and environmental impact, the system incorporates mechanisms for managing drainage and runoff, such as water recycling and runoff

collection. Continuous monitoring of key parameters ensures optimal cleaning efficiency and system performance. Safety features are also integrated to safeguard the panels and surrounding infrastructure. Overall, the solar panel cleaning system with a sprinkler setup offers a reliable and efficient solution for maintaining solar panel performance and promoting sustainability in energy production.



**Figure 3.2 Solar panel cleaning system using sprinkler**



## CHAPTER 4

### PROPOSED METHOD

The automatic solar panel cleaning system integrates various components, including an ESP32 development kit microcontroller, motor driver, gear motor, brush mounted on a movable bot, wheels driven by gear motors, and a lithium-ion battery. Controlled via Bluetooth connectivity with a smartphone, the system offers a streamlined approach to solar panel maintenance with notable advantages. Operating on a predetermined schedule or triggered by sensor inputs, the ESP32 microcontroller orchestrates the cleaning process.

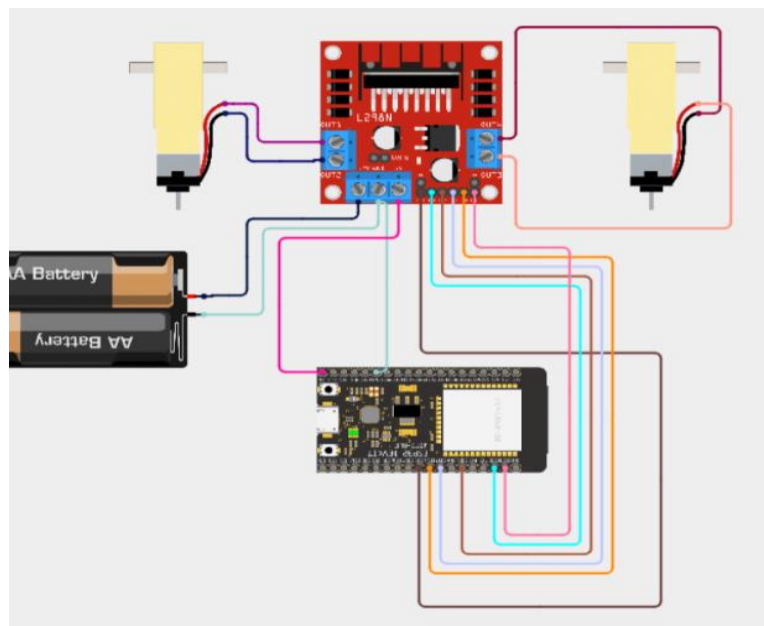
It communicates with the motor driver to control the gear motors, facilitating precise movement of the cleaning bot across the surface of the solar panels. The brush, affixed to the bot, effectively dislodges dirt and debris, ensuring thorough cleaning without damaging the panels. The gear motors, powered by the lithium-ion battery, drive the wheels of the cleaning bot, enabling it to traverse the panel array autonomously. This autonomous operation reduces the need for manual intervention, saving time and labour costs associated with traditional cleaning methods. Additionally, the lithium-ion battery provides a stable power supply, ensuring uninterrupted cleaning cycles even in remote or off-grid locations. The integration of Bluetooth connectivity allows users to control the cleaning system conveniently from their smartphones. Through a dedicated mobile application, users can initiate cleaning cycles, adjust settings, and monitor system performance in real-time. This remote accessibility enhances flexibility and convenience, enabling efficient management of cleaning tasks from anywhere within Bluetooth range.

One of the primary advantages of the automatic solar panel cleaning system is its ability to maintain optimal panel performance and longevity. By removing dirt, dust, and debris regularly, the system ensures maximum sunlight absorption and energy production, thereby enhancing the overall efficiency of the solar installation. This leads to increased energy output and revenue generation over the system's lifespan. Moreover, the autonomous operation of the cleaning system reduces the risk of human error and ensures consistent cleaning quality. By adhering to preset schedules or responding to sensor inputs, the system minimizes the likelihood of dirt buildup and potential damage to the panels.



This proactive approach to maintenance helps prolong the lifespan of the solar panels and reduces the need for costly repairs or replacements in the long run. In summary, the automatic solar panel cleaning system offers a reliable, efficient, and user-friendly solution for maintaining solar panel efficiency and performance. By leveraging advanced technology and automation, it optimizes energy output, reduces maintenance costs, and promotes sustainability in renewable energy production.

#### 4.1 CIRCUIT DIAGRAM



**Figure 4.1 Circuit design for Automatic Solar panel cleaning System**

#### 4.2 WORKING

- **Data Processing:** The ESP-WROOM-32 Dev Kit acts as the central processing unit, receiving data from the mobile phone via Bluetooth connectivity and processing it using programmed algorithms.
- **Motor Control:** The L298N motor driver controls the movement of the 12V gear motors attached to cleaning mechanisms, such as mops or brushes. The motor driver receives commands from the ESP-WROOM-32 to start the cleaning process when necessary.

- **Movement and Cleaning:** When the system determines that cleaning is needed, it activates the gear motors to move the cleaning mechanisms across the solar panels. The wheels attached to the gear motors facilitate smooth traversal across the panel surfaces.
- **Power Management:** A suitable power source, such as a rechargeable lithium-ion battery or solar panel setup, powers the entire system. The ESP-WROOM-32 manages power distribution and optimization to ensure efficient cleaning operations while conserving energy.
- **Wireless Control and Monitoring:** The ESP-WROOM-32's capabilities include wireless connectivity, allowing users to monitor and control the cleaning system remotely via Bluetooth or other wireless protocols. This feature adds convenience and flexibility to system operation and maintenance.

## **CHAPTER 5**

### **RESULTS AND DISCUSSION**

#### **5.1 DESIGNED HARDWARE MODEL**

The results of the automatic solar panel cleaning system can vary depending on its design and features. Still there are some general issues and benefits of an automatic solar panel cleaning system.

Implementing an automatic solar panel cleaning system using the L298N motor driver, ESP WROOM 32, gear motors, and wheels offers several advantages.

Regular cleaning ensures optimal solar panel efficiency by preventing dust and debris accumulation, leading to higher energy output over time. Automated cleaning reduces the need for manual labour or expensive cleaning services, lowering maintenance costs for solar installations. It reduce the risk of accidents associated with manual cleaning processes, promoting safety for maintenance personnel.

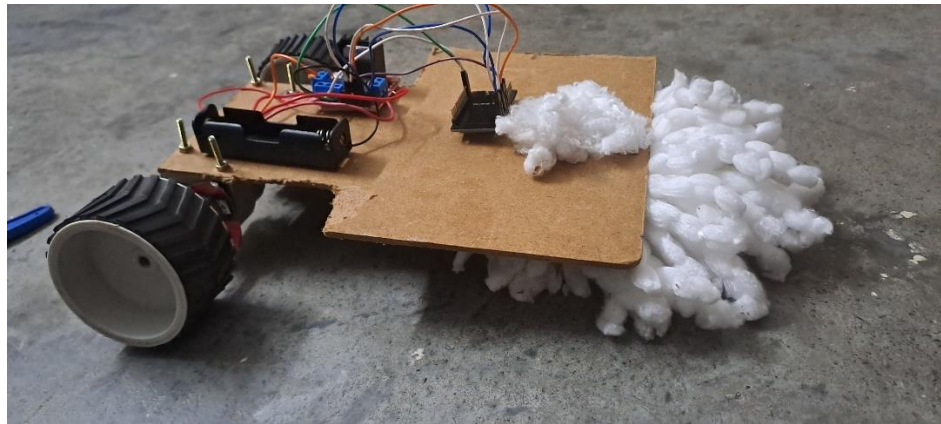
Keeping solar panels clean prolongs their lifespan by minimizing wear and tear caused by environmental factors and debris buildup and Cleaner solar panels contribute to a more sustainable energy generation process, aligning with environmental conservation goals. Automated systems ensure regular and consistent cleaning cycles, maintaining peak performance regardless of weather conditions or external factors.

Integration with Bluetooth technology allows for remote monitoring of cleaning status and enables users to adjust cleaning schedules or initiate cleaning cycles from a distance. The modular design of the system allows for scalability to accommodate various solar panel array sizes and configurations, making it suitable for different applications and installations. Automated cleaning eliminates the need for manual intervention, saving time and effort for maintenance personnel and allowing them to focus on other critical tasks.

By maximizing solar panel efficiency through regular cleaning, the system contributes to increased energy production and overall system performance.

Overall, implementing an automatic solar panel cleaning system offers numerous benefits that contribute to improved performance, reduced costs, and enhanced sustainability of solar energy systems.

The developed and tested hardware module is shown in the figure 5.1



**Figure 5.1 Hardware connection of Automatic solar panel cleaner**



**Figure 5.2 Compact design of the completely tested proposed model**

The hardware components of the circuit design have to be covered or shielded to protect our electronics components from the rain, humidity, sunlight like some other natural calamities. So the designed model is fixed into compact design for protecting the components. The figure 5.2 represents the compact design of the completely tested proposed model.

## **CHAPTER 6**

### **CONCLUSION AND FUTURE SCOPE**

#### **6.1 CONCLUSION**

This is the design and implementation of an automatic solar panel cleaning system using components such as the L298N motor driver, ESP WROOM 32, gear motors, and wheels represents a significant step towards optimizing solar panel efficiency and reducing maintenance costs in solar energy systems. By integrating intelligent algorithms for cleaning cycles and leveraging precise motor control capabilities, the system ensures consistent and effective cleaning without the need for external sensors. The advantages of this system include improved energy production, cost savings through reduced manual labor, enhanced safety, and scalability for various solar panel array sizes. Moreover, the incorporation of Bluetooth connectivity enables remote monitoring and control, adding convenience and flexibility to the maintenance process. Overall, this project aligns with sustainable energy practices, promotes environmental stewardship, and showcases the innovative potential of automation in renewable energy technologies.

#### **6.2 FUTURE SCOPE**

The automatic solar panel cleaning system using the L298N motor driver, ESP WROOM 32, gear motors, and wheels has promising future prospects and potential areas for further development. Future iterations can focus on developing more advanced cleaning algorithms based on machine learning or AI techniques. These algorithms can adapt cleaning patterns based on real-time environmental conditions, such as weather forecasts or specific pollution levels. While the current system operates without external sensors, integrating advanced sensors such as dust particle sensors or environmental sensors can provide precise data for optimizing cleaning schedules and strategies. Incorporating solar tracking mechanisms with the cleaning system can further enhance energy production by optimizing the solar panel's angle and position throughout the day for maximum sunlight exposure. Explore energy harvesting techniques within the cleaning system itself, such as

regenerative braking mechanisms for gear motors or utilizing solar power for onboard systems, to improve overall energy efficiency. Develop robotic cleaning platforms that can autonomously navigate and clean large-scale solar panel arrays in industrial or utility-scale installations, reducing manual intervention and enhancing cleaning accuracy. Implement predictive maintenance algorithms that monitor cleaning system components' health and performance, enabling proactive maintenance and reducing downtime. Integrate the cleaning system into broader IoT (Internet of Things) frameworks for comprehensive monitoring, data analytics, and remote management of multiple solar installations from a centralized platform. Conduct studies and assessments to quantify the environmental impact of automated cleaning systems on energy production efficiency, water savings (if water-based cleaning is used), and overall sustainability metrics.

By focusing on these future scopes, the automatic solar panel cleaning system can evolve into a highly efficient, intelligent, and sustainable solution for maintaining solar panel performance in various applications and environments.

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## ANNEXURE

### ACCEPTANCE LETTER



[www.jaisaisolar.com](http://www.jaisaisolar.com)

Date : 16.02.2024

#### LETTER OF ACCEPTANCE

Sir,

Sub : Confirmation of Project on " *Solar Panel Cleaning System* " and " *Smart door lock System* " -Reg.

Under the guidance of **Dr Maheshwaran S** and **Sathesh S**, the following students ( batch 1: **Balanisharitha P – 21ECR028** , **Charumathi K – 21ECR036** , **Ilmunisha A – 21ECL237**) and ( batch 2: **Sasikala J – 21ECR185**, **vasigaran V – 21ECR221**, **Sumesh S – 21ECL254** ) - Department of ECE at Kongu Engineering College, Perundurai have been authorized to conduct the Project Work on the "Solar Panel Cleaning System" and "Smart door lock System" at our facility. Students are permitted to meet their respective incharge during working hours only and are requested to provide progress updates via email. Payment will be issued upon completion of the work.



For JAI SAI SOLAR SOLUTION

Proprietor

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## APPRECIATION LETTER



[www.jaisaisolar.com](http://www.jaisaisolar.com)

DATE : 30-04-2024

TO,

The Principal,  
Kongu Engineering College,  
Perundurai -638052,  
Erode - 638060.

Sir,

**Sub : Appreciation for the Completion of the Project - Reg .**

I Would Like to express my Gratitude to the Students (Batch 1 : **BALANISHARITHA .P - 21ECR028 , CHARMATHI .K - 21ECR036 , ILMUNISHA .A -21ECL237** and (Batch 2 : **SASIKALA .J - 21ECR185, VASIGARAN . V - 21ECR221, SUMESH .S -21ECL254** ). Department of ECE at Kongu Engineering College Perundurai have been authorized to Conduct the Project Work on **"THE SOLAR PANEL CLEANING SYSTEM"** and **"KEYLESS ENTRY CONTROL SYSTEM USING R307 and NUMPAD"** at our Facility. Under the Supervision of **Dr.MAHESHWARAN .S and SATHESH . S** for Developing Cleaning Machine for Solar Panel Automation for Our Company . I am Very Much Satisfied with their Work and Would Look Forward to Work With them for Any Future Projects.

Thanking You,



For JAI SAI SOLAR SOLUTION

*Q.S. dani*  
Proprietor

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