



# Machine Learning

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### Content

- 1. The Big Picture
- 2. Supervised Learning
  - Linear Regression, Logistic Regression, Support Vector
     Machines, Trees, Random Forests, Boosting, Artificial Neural
     Networks
- 3. Unsupervised Learning
  - Principal Component Analysis, K-means, Mean Shift

### Supervised Learning

- Linear Regression
- Logistic Regression
- Support Vector Machines
- Trees (Decision and Regression)
- Random Forests
- Boosting
- Artificial Neural Networks

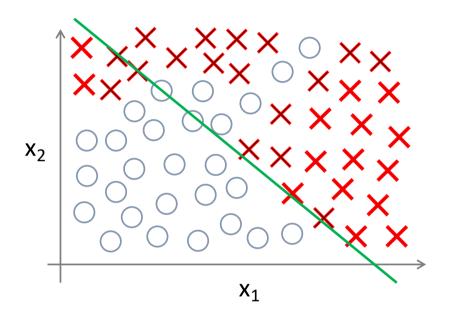
### History

- Logical Neuron (1943 Warren McCulloch and Walter Pitts)
  - Logical operations
  - No activation function
- Linear Threshold Unit
  - · real numbers, weight,
  - step activation function
- Perceptron (1957 Rosenblatt)
  - single layer of LTU
  - Trained with Hebb's rule
  - Weakness of perceptron (1969 Marvin Minsky and Seymour Papert)

- Multi Layer Perceptron (MLP) (1986 D. Rumelhart, G. Hinton, R. Williams)
  - Artificial Neural Network
  - Sigmoid activation function
  - Backpropagation
- Deep Neural Networks
  - More data, more power
  - More layers
  - Different activation functions
  - Different Architectures

### Non Linear Classification

A linear model will certainly underfit!

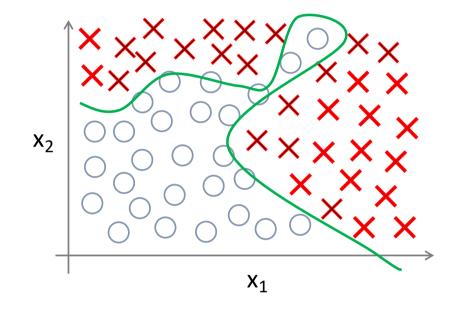


$$g(w_0 + w_1x_1 + w_2x_2)$$

### Non Linear Classification

A non linear model in a high dimensional space may be a solution, but...

... what if we have many many features?!



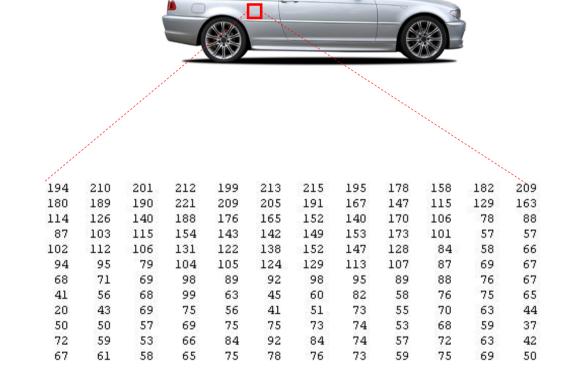
$$g(w_0 + w_1x_1 + w_2x_2 + \dots + w_{12}x_1^2 + w_{13}x_2^2 \dots + w_{25}x_1^d + w_{26}x_2^d)$$

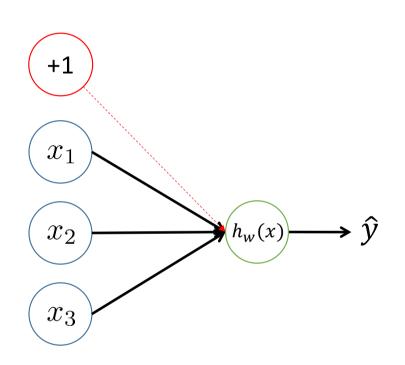
### Non Linear Classification: Computer Vision

A non linear model in a high dimensional space may be a solution, but...

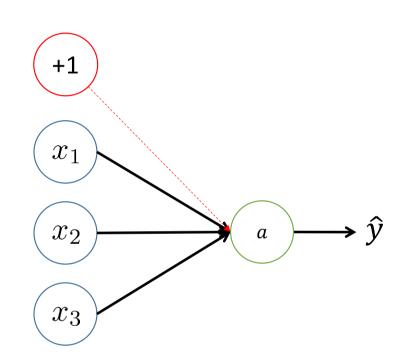
... what if we have many many features?!

... like in computer vision





$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \\ \vdots \end{bmatrix} \quad w = \begin{bmatrix} w_0 \\ w_1 \\ w_2 \\ w_3 \\ \vdots \end{bmatrix} \qquad \hat{y} = h_w(x) = g(w^T x)$$



$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \\ \vdots \end{bmatrix} \quad w = \begin{bmatrix} w_0 \\ w_1 \\ w_2 \\ w_3 \\ \vdots \end{bmatrix} \qquad \hat{y} = h_w(x) = g(w^T x)$$

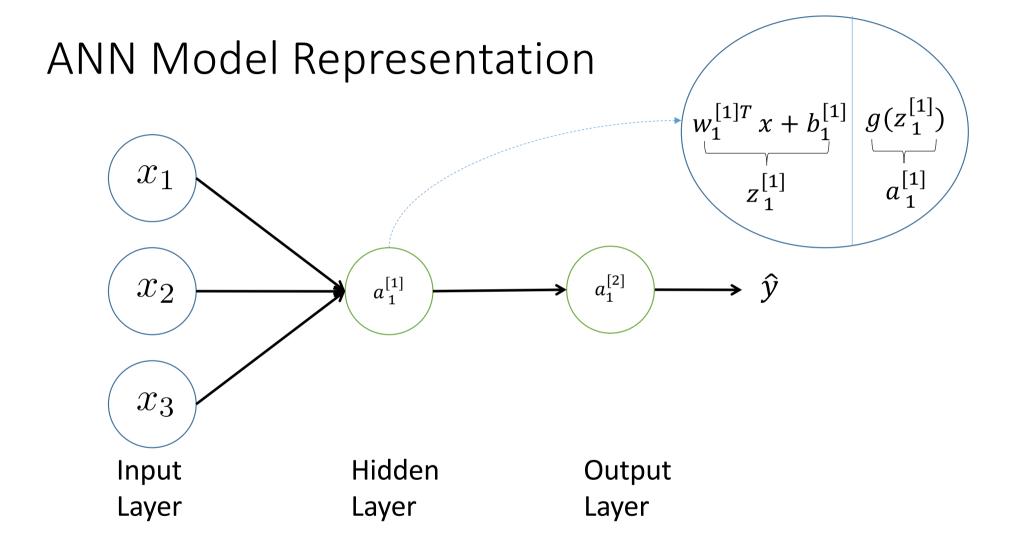
$$\hat{y} = h_w(x) = g(w^T x)$$

#### Change notation

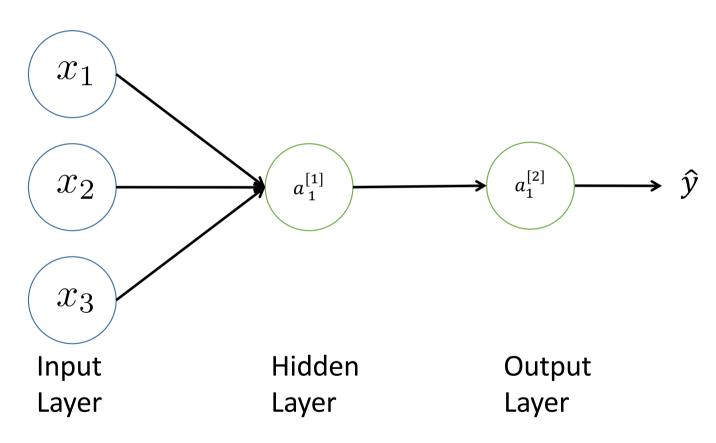
$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \end{bmatrix} \qquad w = \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ \vdots \end{bmatrix}$$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \end{bmatrix} \qquad w = \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ \vdots \end{bmatrix} \qquad Z = w^T x + b,$$

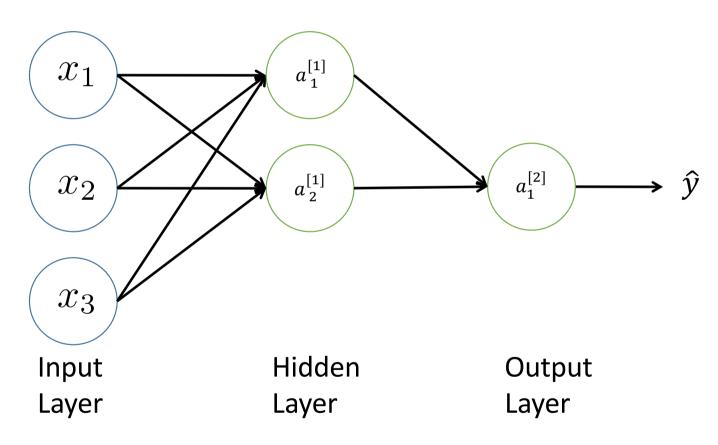
$$\hat{y} = a = g(z)$$

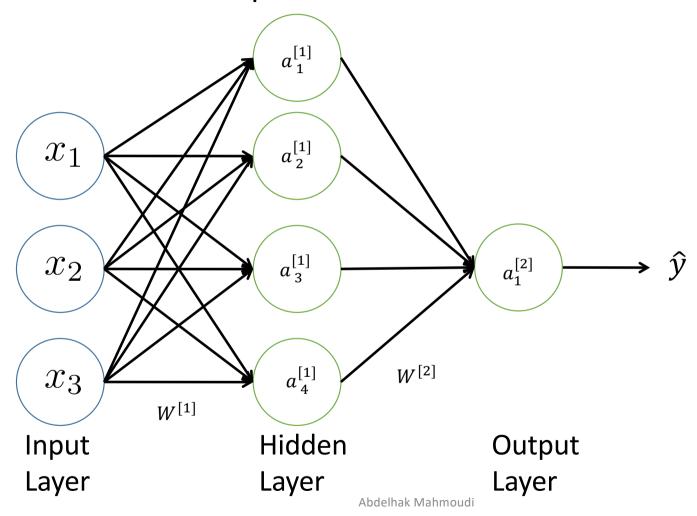


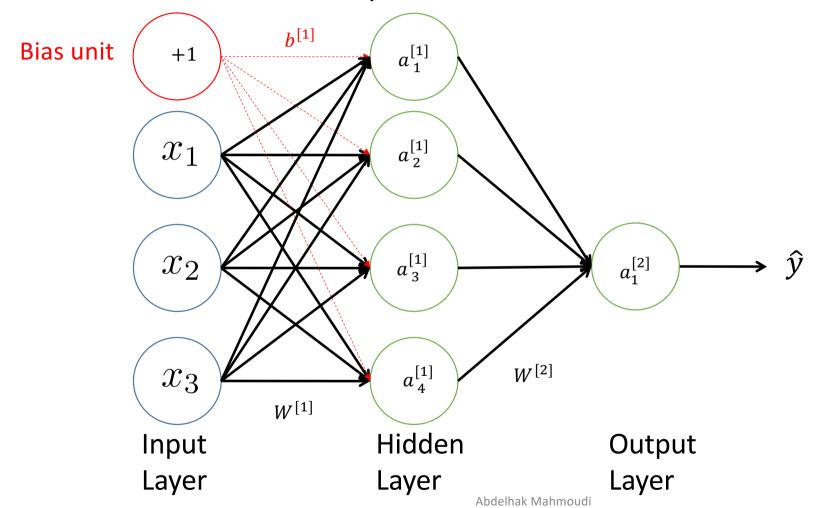
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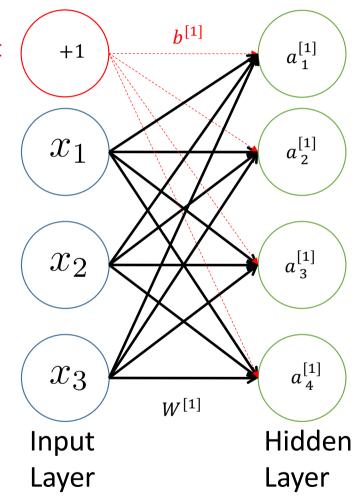
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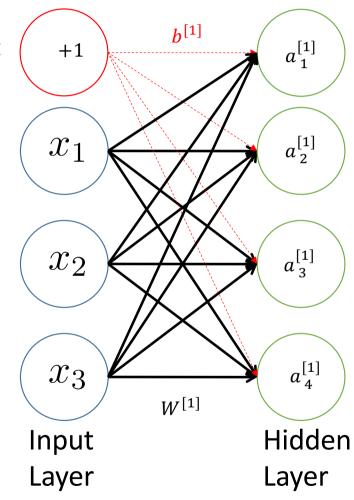


Bias unit



$$\begin{split} z_1^{[1]} &= w_1^{[1]T} \ x + b_1^{[1]}, \ a_1^{[1]} = g(z_1^{[1]}) \\ z_2^{[1]} &= w_2^{[1]T} \ x + b_2^{[1]}, \ a_2^{[1]} = g(z_2^{[1]}) \\ z_3^{[1]} &= w_3^{[1]T} \ x + b_3^{[1]}, \ a_3^{[1]} = g(z_3^{[1]}) \\ z_4^{[1]} &= w_4^{[1]T} \ x + b_4^{[1]}, \ a_4^{[1]} = g(z_4^{[1]}) \end{split}$$

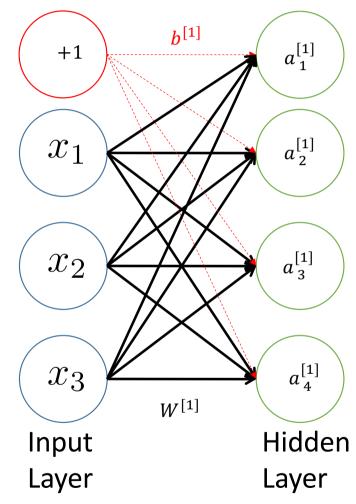
Bias unit



$$\begin{aligned} z_{1}^{[1]} &= W_{1}^{[1]T} x + b_{1}^{[1]}, & a_{1}^{[1]} \\ z_{2}^{[1]} &= w_{2}^{[1]T} x + b_{1}^{[1]}, & a_{1}^{[1]} &= g(z_{1}^{[1]}) \\ z_{2}^{[1]} &= w_{2}^{[1]T} x + b_{2}^{[1]}, & a_{2}^{[1]} &= g(z_{2}^{[1]}) \\ z_{3}^{[1]} &= w_{3}^{[1]T} x + b_{3}^{[1]}, & a_{3}^{[1]} &= g(z_{3}^{[1]}) \\ z_{4}^{[1]} &= w_{4}^{[1]T} x + b_{4}^{[1]}, & a_{4}^{[1]} &= g(z_{4}^{[1]}) \end{aligned}$$

$$W^{[1]} = \begin{bmatrix} w_1^{[1]T} \\ w_2^{[1]T} \\ w_3^{[1]T} \\ w_4^{[1]T} \end{bmatrix} = \begin{bmatrix} w_{11}^{[1]} & w_{12}^{[1]} & w_{13}^{[1]} \\ w_{21}^{[1]} & w_{22}^{[1]} & w_{23}^{[1]} \\ w_{31}^{[1]} & w_{32}^{[1]} & w_{33}^{[1]} \\ w_{41}^{[1]} & w_{42}^{[1]} & w_{43}^{[1]} \end{bmatrix}$$

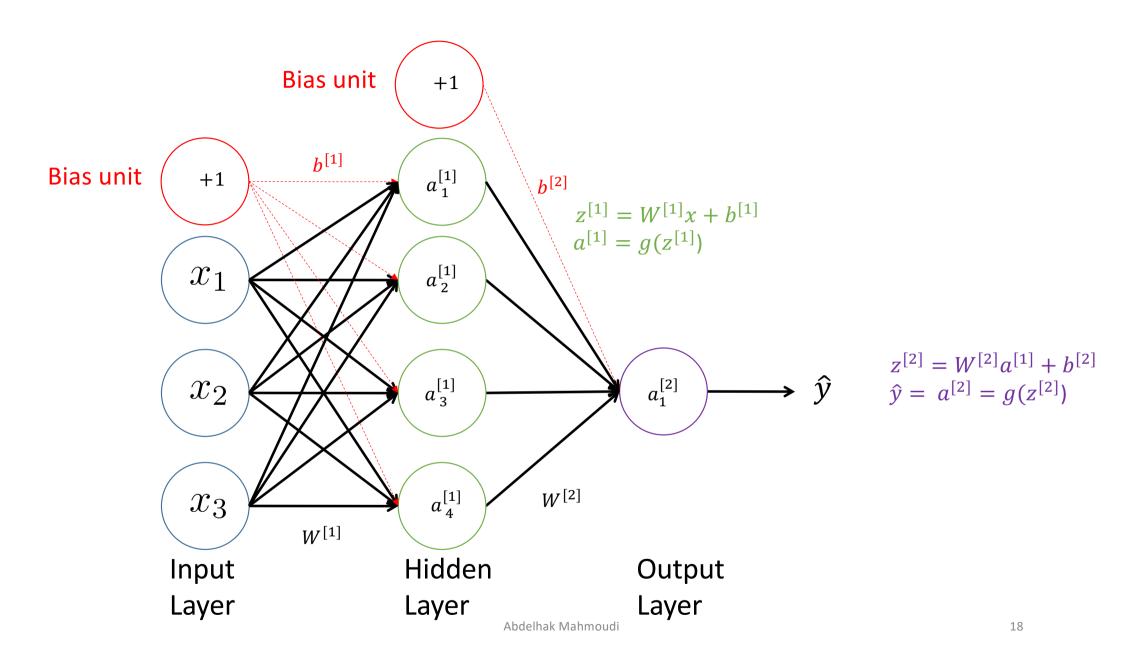
Bias unit



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$$z^{[1]} = W^{[1]}x + b^{[1]}$$
  
 $a^{[1]} = g(z^{[1]})$ 



### ANN Model Representation: Vectorization

$$z^{[1]} = W^{[1]}x + b^{[1]}$$
  
 $a^{[1]} = g(z^{[1]})$ 

$$z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$
  
 $\hat{y} = a^{[2]} = g(z^{[2]})$ 

For one example

$$Z^{[1]} = W^{[1]}X + b^{[1]}$$

$$A^{[1]} = g(Z^{[1]})$$

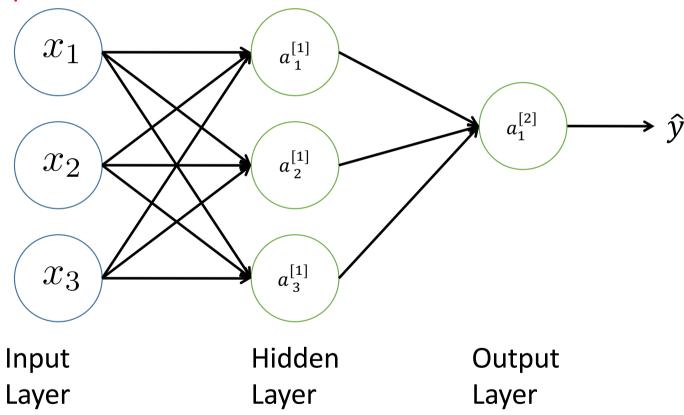
$$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$$

$$A^{[2]} = g(Z^{[2]})$$

For All Examples (matrix notation)

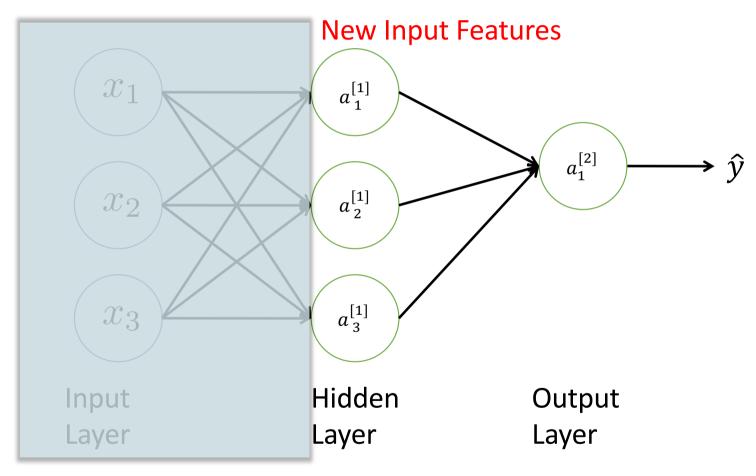
### ANN Representation: Learning its own features

### **Input Features**



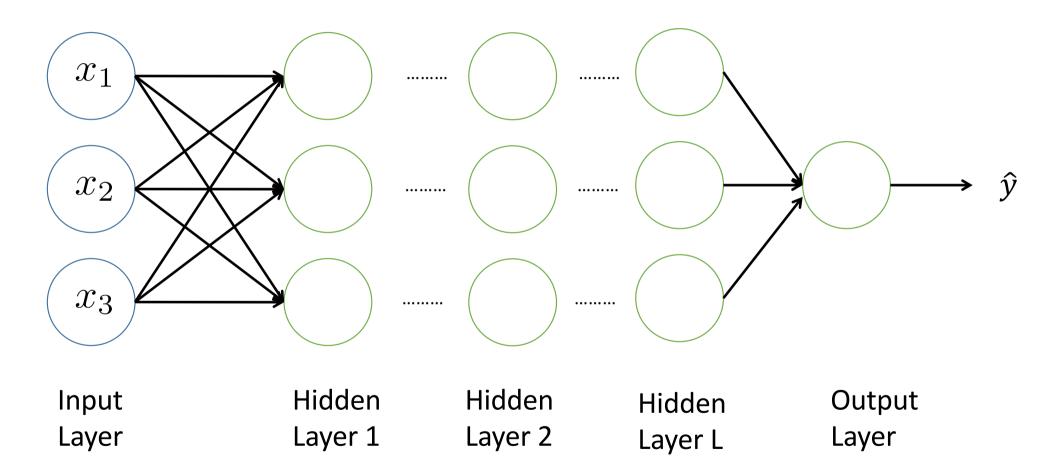
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### ANN Representation: Learning its own features



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### ANN Representation: Deep NN

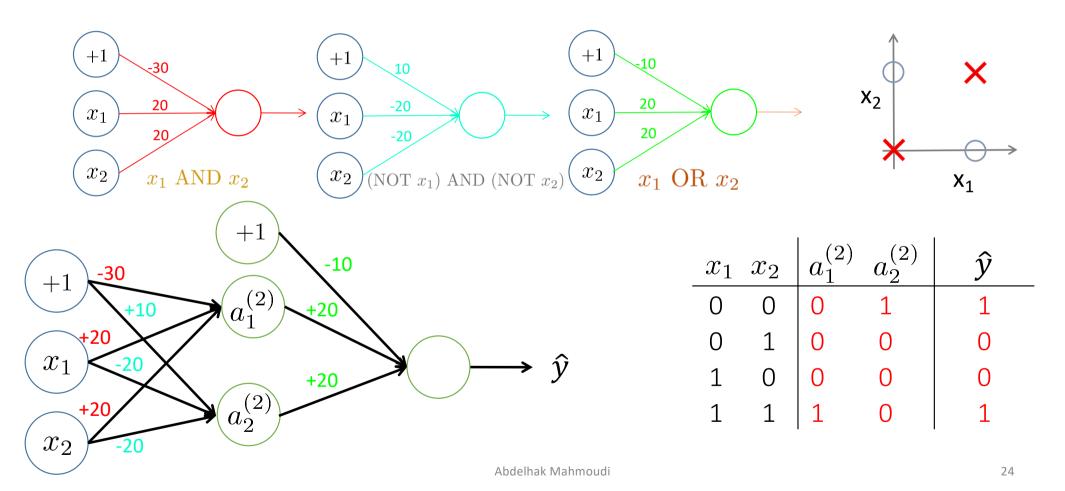


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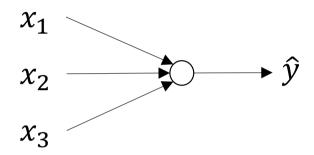
### Why ANN?

- Features Generation
  - Learn Features by it self
- Data non linearly separable
  - Learn complex non linear functions
- Deals with Unstructured data
  - Convolutional Neural Networks (Vision)
  - Recurrent Neural Networks (Sequence)
  - Generative Adversarial Networks (Generate data)

### Simple Example



### **ANN Learning**



Remember Logistic Regression

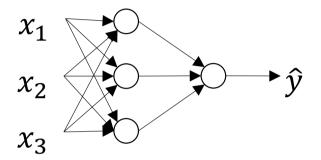
$$x \longrightarrow z = w^{T}x + b \longrightarrow a = g(z) \longrightarrow \mathcal{L}(a, y)$$

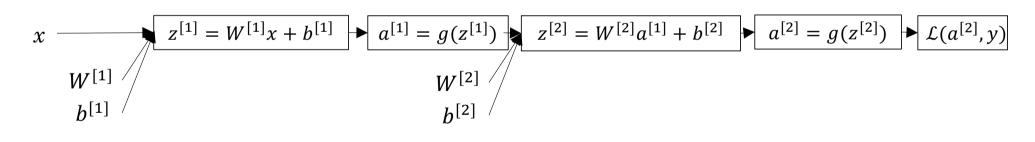
$$dw \qquad dz \qquad da$$

$$db$$
Notation: 
$$dt = \frac{\partial \mathcal{L}}{\partial t}$$

$$\mathcal{L}(a,y) = -\frac{1}{m} \left[ \sum_{i=1}^{m} y^{(i)} \log a^{(i)} + (1-y^{(i)}) \log (1-a^{(i)}) \right]$$

### ANN Learning: Forward Propagation

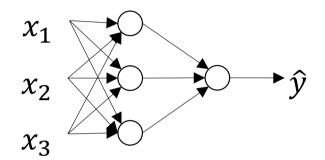


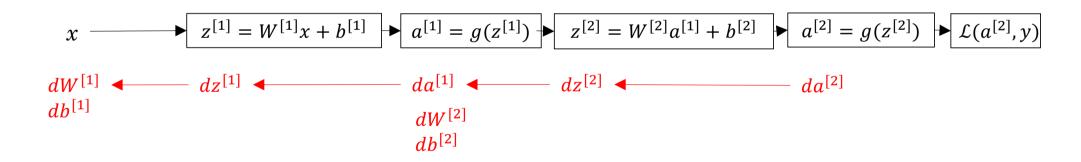


**Cost Function** 

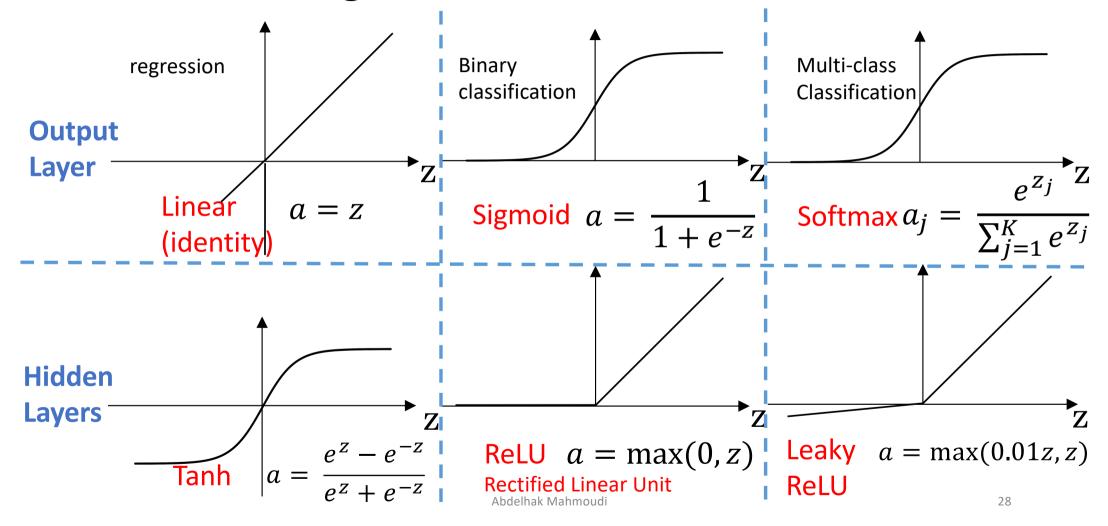
$$\mathcal{L}(a^{[2]}, y) = -\frac{1}{m} \sum_{i=0}^{m} \left( y^{(i)} \log(a^{[2](i)}) + (1 - y^{(i)}) \log(1 - a^{[2](i)}) \right)$$

### ANN Learning: Backward Propagation

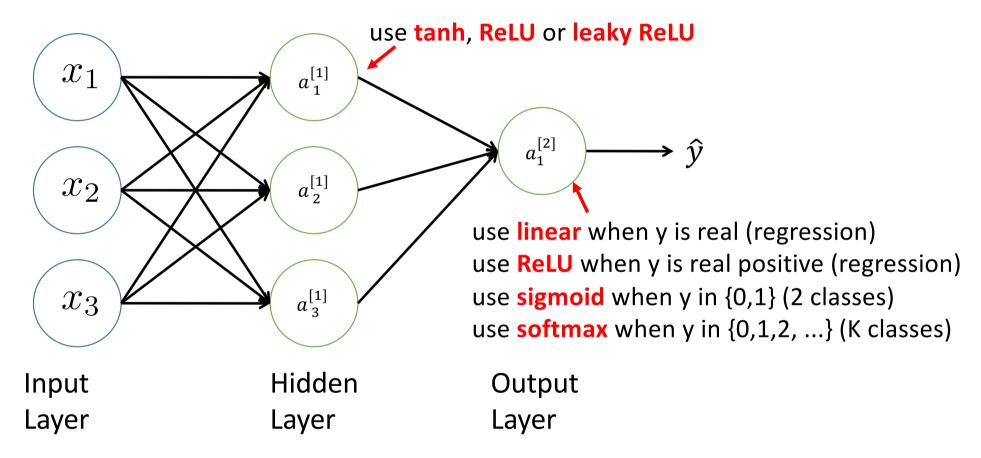




### ANN Learning: Activation Functions



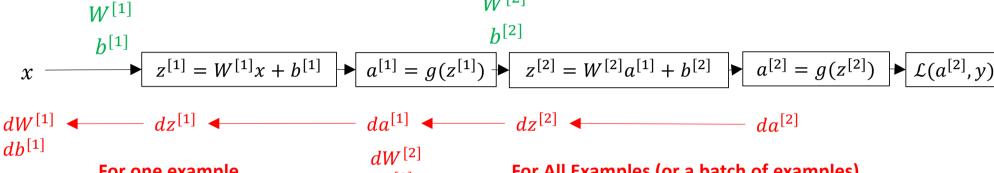
### ANN Learning: Activation Functions



ANN Learning	: Backward	Propagation
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f <sup>o</sup> g	(f' º g) × g'	
f(g(x))	f'(g(x))g'(x)	
$\frac{dy}{dx} = \frac{dy}{du}\frac{du}{dx}$		

30



#### For one example

$$\begin{split} dz^{[2]} &= a^{[2]} - y \\ dW^{[2]} &= dz^{[2]} a^{[1]^T} \\ db^{[2]} &= dz^{[2]} \\ dz^{[1]} &= W^{[2]T} dz^{[2]} * g^{[1]'}(z^{[1]}) \\ dW^{[1]} &= dz^{[1]} x^T \\ db^{[1]} &= dz^{[1]} \end{split}$$

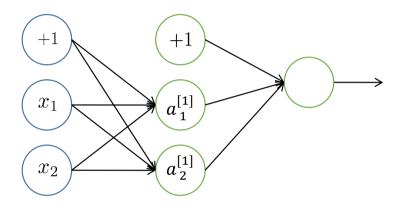
 $dW^{[2]}$  $dh^{[2]}$ 

 $W^{[2]}$ 

#### For All Examples (or a batch of examples)

$$\begin{split} dZ^{[2]} &= A^{[2]} - Y \\ dW^{[2]} &= \frac{1}{m} dZ^{[2]} A^{[1]^T} \\ db^{[2]} &= \frac{1}{m} np. \, sum(dZ^{[2]}, axis = 1, keepdims = True) \\ dZ^{[1]} &= W^{[2]T} dZ^{[2]} * g^{[1]'}(Z^{[1]}) \\ dW^{[1]} &= \frac{1}{m} dZ^{[1]} X^T \\ db^{[1]} &= \frac{1}{m} np. \, sum(dZ^{[1]}, axis = 1, keepdims = True) \end{split}$$

### ANN Learning: Random Initialization

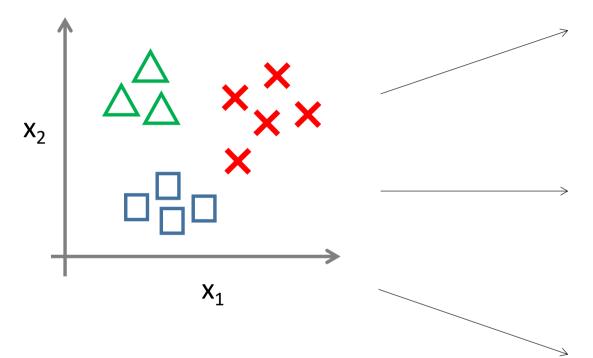


If  $W^{[1]}$  and  $b^{[1]}$  are initialized with zeros, after each update, parameters corresponding to inputs going into each of the two hidden units are identical, which results in  $a_1^{[1]} = a_2^{[1]}$ 

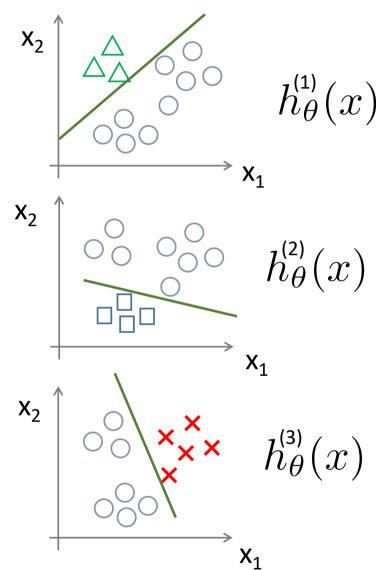
### ANN Implementation

- 1. Pick a network architecture
  - No. of input units: Dimension of features
  - No. output units: Number of classes
  - No. hidden layers
  - $\circ$  No. hidden units: (have same no. in every layer, the more the better)
- 2. Randomly initialize weights
- 3. Repeat (chose a number of iterations)
  - 1. Implement forward propagation
  - 2. Compute cost function
  - 3. Implement backward propagation to compute partial derivatives
  - 4. Update the W and b:  $W^{[l]} =: W^{[l]} \alpha dW^{[l]}$   $b^{[l]} =: b^{[l]} \alpha db^{[l]}$

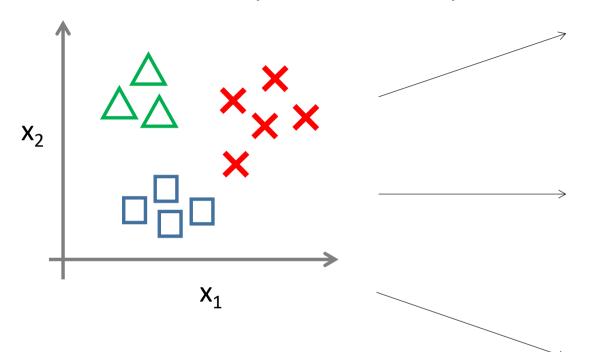
### Multi-Class (N-classes)

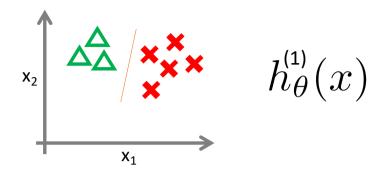


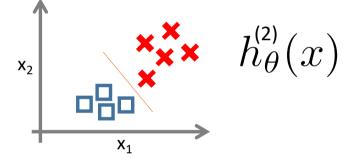
- One-vs-All (One-vs-Rest)
- Train N binary classifiers
- Classify to the class with higher  $h_{\theta}(x)$



### Multi-Class (N-classes)







- One-vs-One
- Train N(N-1)/2 binary Classifiers
- Classify to the most frequently assigned class

