Below cells configure the python / conda environment and performs setup tasks such as configuring the logging mechanisms. Please note it can take some time for the conda environment to completes its setup. # Enable python module autoreload %load ext autoreload %autoreload 2 #Image constants nrg image s3 source = "s3://live-demo-images/brewarrina/" nrg image storage directory = "../../Images/" patch size = 512 # in pixels, value needs to match that of the UNet CNN image scale = 1024 ignore nonsquare images = False **#Unet model constants** unet model = "../../Models/CNN/flood standard unet 512x512 7epochs binaryloss" #Contour constants minimum_contour_size = 100 # pixels #Log file constants log_file_prefix = "NOTEBOOK_LOG" log storage directory = "../../Logs/" #Output settings raster_shp_output_prefix = "brewarrina" output_directory = "../../Out/" In []: !pip install patchify !pip install 'opency-python>=4.5.3.56' # required as older versions fail opening some jp2 images !conda install -y -c conda-forge gdal fiona rasterio # this will take a long time ~25mins In []: # imports modules - this could be moved to a seperate file once modules have stabilised. *#~~ Standard Libraries* import os from os import environ environ["OPENCV_IO_ENABLE_JASPER"] = "true" import sys import datetime import logging import shutil import gc *#~~ Utility Libraries* import numpy as np import matplotlib.pyplot as plt import pickle import boto3 try: from urlparse import urlparse except ImportError: from urllib.parse import urlparse from IPython.display import clear output **#--** Mapping from osgeo import gdal from osgeo import osr import fiona import rasterio from rasterio.io import MemoryFile import rasterio.merge #-- image processing import cv2 from patchify import patchify from PIL import Image #-- CNN import tensorflow as tf from keras.models import load_model **#--** patch smoothing import scipy.signal from tqdm import tqdm from smooth_tiled_predictions import predict_img_with_smooth_windowing In []: cell error = False # Configure logging # safeguard to prevent accidently running this more than once, running more than once breaks logging functionality if not 'logger intiated' in globals(): logger = logging.getLogger(log_file_prefix) # To use differen't log level for file and console timestamp = datetime.datetime.utcnow().strftime('%Y%m%d %H-%M-%S') formatter = logging.Formatter('[%(asctime)s] %(name)s %(levelname)s - %(message)s') # File settings filename = os.path.join(log storage directory , f"{log file prefix} {timestamp}.log") file handler = logging.FileHandler(filename=filename) file handler.setLevel(logging.DEBUG) file handler.setFormatter(formatter)

This notebook is designed to be an end to end solution that is able to extract flood extents from supplied imagery. Alot of the techniques and files regarding Unet for this NoteBook were obtained from this git repository.

■ image_scale - Int: Image size to scale image to during preprocessing. patch_size needs to evenly divide into this (eg and image 1024x1024 will get 4 patches at 512x512). Default value is: 1024

■ raster_shp_output_prefix - String: Prefix for output shape and raster files. Output files names will also include date and time the file was created. eg "brewarrina_20211010_07-08-01.jp2"

• ignore_nonsquare_images Boolean: Notebook will ignore and not process non square images. Otherwise non square images will be rescaled to image_scale. Scaling non square images can cause unexpected results.

■ nrg_image_s3_source - String: Amazon S3 source directory containing flood images destined for processing eg. s3://ss-csu-dataset/raw/Brewarrina_Flood_2021_04_15cm_NRG/

■ patch_size - Int: Image size that the Unet model is expecting. After image is scaled to image_scale. Preprocessing will patchify images into patch_size.

All configurations are contained within the Notebook settings cell. There are no other configurable options outside of the Notebook settings cell.

nrg_image_storage_directoryString: Storage directory where flood images will be stored for processing.

■ minimum contour size - Int: Minimum pixel area for a contour / polygon to be considered valid

#stream stdout settings

File settings

logging.basicConfig(

logger intiated = True

handlers=[

except Exception as e:

else:

if cell error:

cell error = True

level=logging.DEBUG,

file handler

raise SystemExit("Execution Stopped")

keys.append(k)

fn = os.path.split(k)[-1]

raise SystemExit("Execution Stopped")

if file.endswith(".jp2"):

if len(nrg image paths) > 0:

cell error = False

split the s3 path in to components

for k in keys:

download files

if cell error:

cell error = False

nrg image paths = []

Count images

except Exception as e:

cell error = True

else:

if cell error:

cell error = False

open the unet model

except Exception as e:

if cell error:

cell error = False

binary masks = []

try:

cell error = True

used_nrg_image_paths = [] # loop through all images

for i in range(len(nrg image paths)):

#reject non square images

shape = nrg_raw_image.shape

#scale image if required

window_size=patch_size,

build image path

open the image

continue

nrg_raw_image,

nb classes=2, pred_func=(

except Exception as e:

open images as geo data sets

logger.info(f"Combining images")

profile.update(

count=1)

ds.close()

get dataset profile profile = ds.profile

dtype=rasterio.uint8,

mem_ds = memfile.open(**profile) mem ds.write(binary masks[i], 1)

append data set to array

memfile = MemoryFile()

datasets.append(mem ds)

#combine datasets and save to disk

open dataset and read flood layer

flood_layer = merged_dataset.read(1)

merged dataset = rasterio.open(raster file) logger.debug(f"Reading flood extent raster")

logger.info(f"Finished combining images")

cell error = False

datasets = []

try:

continue

if cell_error:

else:

cell error = True

raise SystemExit("Execution Stopped")

Combine Extracted Flood Extents

for i in range(len(used_nrg_image_paths)):

logger.debug(f"Opening {used nrg image paths[i]}")

logger.debug(f"Opening temporary memory file for binary image")

timestamp = datetime.datetime.utcnow().strftime('%Y%m%d %H-%M-%S')

logger.debug(f"Opening binary raster image as raster dataset")

logger.info(f"Finished converting polygons to shape file")

zip_file_name = (f"{x.year}{x.month}{x.day}{x.hour}{x.minute}_Outputs")

logger.info(f"Success compressing and writing outputs to {zip file}.zip")

os.remove(os.path.join(nrg_image_storage_directory, file))

logger.info(f"Removing files from outputs storage {output directory}")

logger.info(f"Removing files from images storage {nrg image storage directory}")

logger.info(f"Starting compression of {output directory}, writing to {zip file}.zip")

zip_file = os.path.join(f"{output_directory}/../", zip_file_name)

shutil.make archive(f"{zip file}", 'zip', output directory)

for file in os.listdir(nrg_image_storage_directory):

for file in os.listdir(output directory):

if file.endswith(".zip") or os.path.isdir(file):

if file.endswith(".zip") or os.path.isdir(file):

os.remove(os.path.join(output_directory, file))

logger.error(f"Unable to compress and clean up: {e}", exc info=True)

Compress and clean up

x = datetime.datetime.now()

logger.info(f"Cleaning up")

pass

else:

else:

except Exception as e:

In []:

try:

rasterio.merge.merge(datasets, dst path=raster file, dst kwds=profile)

raster file = os.path.join(output directory, f"{raster shp output prefix} {timestamp}.jp2")

logger.debug(f"Merging {len(datasets)} binary images and writing to {raster file}")

ds = rasterio.open(used nrg image paths[i])

Get image paths

except Exception as e:

cell error = True

#populate list of image paths

get all file names

next token = results.get('NextContinuationToken')

client.download file(bucket, k, dest_pathname)

logger.debug(f"Downloading {fn} to {local} from bucket {bucket}")

logger.info(f"Started downloading all files from {nrg image s3 source} to {nrg image storage directory}")

logger.info(f"Directory {nrg_image_storage_directory} contains {len(nrg_image_paths)} images")

download dir(s3 path components.path, nrg image storage directory, s3 path components.netloc)

s3_path_components = urlparse(nrg_image_s3_source, allow_fragments=False)

logger.error(f"Unable to download images: {e}", exc_info=True)

for file in os.listdir(nrg_image_storage_directory):

logger.error(f"Unable to open images: {e}", exc info=True)

Open images and perfrom predictions

nrg image paths.append(path)

Raise exception if no images found

raise SystemExit("Execution Stopped")

Patches will then be given to the CNN for predictions.

unet = load_model(unet_model, compile=False) logger.info(f"Opened Unet model {unet model}")

image_name = os.path.split(nrg_image_paths[i])[-1]

nrg_raw_image = cv2.imread(nrg_image_paths[i])

used_nrg_image_paths.append(nrg_image_paths[i])

perform patching and prediction on source images

logger.debug(f"Performing prediction on image") prediction = predict img with smooth windowing(

nrg_raw_image = cv2.cvtColor(nrg_raw_image, cv2.COLOR_RGB2BGR)

lambda img batch subdiv: unet.predict((img batch subdiv))

nrg_raw_image = np.array(nrg_raw_image)

binary_masks.append(tmp_img >= 0.001)

raise SystemExit("Execution Stopped")

logger.info(f"Finished downloading files from {nrg image s3 source}")

path = os.path.join(nrg_image_storage_directory, file)

raise Exception(f"No images in directory {nrg image storage directory}")

logger.error(f"Unable to open Unet model {unet_model}: {e}", exc_info=True)

logger.info(f"Started opening {len(nrg_image_paths)} images in {nrg_image_storage_directory}.")

if nrg_raw_image.shape[0] != nrg_raw_image.shape[1] and ignore_nonsquare_images:

logger.debug(f"Opened {nrg_image_paths[i]}. Image shape {nrg_raw_image.shape}")

subdivisions=2, # Minimal amount of overlap for windowing. Must be an even number.

logger.debug(f"Finished predictions, final prediction shape {prediction.shape}")

logger.error(f"Unable to process file {nrg image paths[i]}: {e}", exc info=True)

logger.info(f"Finished opening and processing {len(used_nrg_image_paths)} images")

logger.debug(f"Rejected {nrg image paths[i]}, image not square. Image shape {nrg raw image.shape}")

tmp_img = cv2.resize(prediction[:,:,1], shape[0:2], interpolation=cv2.INTER_LINEAR) #todo remove resize hard code

After predicting is performed on supplied images. Returned predictions are joined together to form one large binary image. The binary image is then 'contoured' to extract edges of flood extent.

nrg_raw_image = cv2.resize(nrg_raw_image, (image_scale, image_scale), interpolation=cv2.INTER_AREA)

logger.debug(f"Scaled image {image name} to {image scale}. New image shape {nrg raw image.shape}")

dest pathname = os.path.join(local, fn)

stream handler = logging.StreamHandler(sys.stdout)

file handler = logging.FileHandler(filename=global_filename)

logger.error(f"Unable to configure logging: {e}.", exc_info=True)

The handlers have to be at a root level since they are the final output

Log global debug to a seperate file. Log file will include debug logs from import modules

global_filename=os.path.join(log_storage_directory , f"{log_file_prefix}_EXTRA_{timestamp}.log")

logger.info(f"Finished configuring logging. Log file: {filename}, Global log file: {global_filename}")

logger.warning(f"Logger is already configured. Log file: {filename}, Global log file: {global filename}")

stream_handler.setLevel(logging.INFO) stream handler.setFormatter(formatter)

logger.addHandler(stream handler) logger.addHandler(file handler) logger.setLevel(logging.DEBUG)

file handler.setLevel(logging.DEBUG) file_handler.setFormatter(formatter)

Flood Extent Extraction

NoteBook settings

Input Image settings

Unet model settings

Logging settings

Output settings

Contouring / polygon settings

Imports and system setup

https://github.com/bnsreenu/python_for_microscopists

All user configurable elements are contained in this cell.

unet model - String: Directory containing the pre trained Unet model

log_file_prefix - String: Prefix that will be attached to all log files.

output_directory - String: Location to store shape files, inspection and zip file.

log_storage_directory - String: Location to store log files

Log settings to file logger.debug(f"Notebook settings:\n" f"nrg_image_s3_source {nrg_image_s3_source} {type(nrg_image_s3_source)} \n" f"nrg_image_storage_directory {nrg_image_storage_directory} {type(nrg_image_storage_directory)} \n" f"image_scale {image_scale} {type(image_scale)}\n" f"patch_size {patch_size} {type(patch_size)}\n" f"ignore_nonsquare_images {ignore_nonsquare_images} {type(ignore_nonsquare_images)}\n" f"unet_model {unet_model} {type(unet_model)}\n" f"minimum_contour_size {minimum_contour_size} {type(minimum_contour_size)}\n" f"log_file_prefix {log_file_prefix} {type(log_file_prefix)}\n" f"log_storage_directory {log_storage_directory} {type(log_storage_directory)}\n" f"raster_shp_output_prefix {raster_shp_output_prefix} {type(raster_shp_output_prefix)}\n" f"output directory {output directory} {type(output directory)}") Download images Download images from s3 bucket and store in directory nrg_image_storage_directory. Once downloaded image path will be enumerated for images of jpeg2000. Extension must be ipp2. In []: cell error = False s3 client = boto3.client('s3') def download_dir(prefix, local, bucket, client=s3 client): params: - prefix: pattern to match in s3 - local: local path to folder in which to place files - bucket: s3 bucket with target contents - client: initialized s3 client object keys = []dirs = [] next token = ' base kwargs = { 'Bucket': bucket, 'Prefix':prefix.lstrip('/'), while next token is not None: kwargs = base kwargs.copy() if next token != '': kwargs.update({'ContinuationToken': next_token}) results = client.list objects v2(**kwargs) contents = results.get('Contents') for i in contents: k = i.get('Key')**if** k[-1] != '/':

Below will load the 'pretrained' Unet model. Each jp2 image contained in nrg_image_storage_directory will be opend and preprocessed by scaling into image_scale and further patchifying images in patch_size images.

except Exception as e: logger.error(f"Error combining images: {e}", exc_info=True) cell error = True if cell error: raise SystemExit("Execution Stopped") logger.info(f"Finished combining images") cell error = False try: contour_results = [] i = 0logger.info(f"Started contouring binary image") contours, hierarchy = cv2.findContours(np.uint8(flood_layer), cv2.RETR_TREE, cv2.CHAIN_APPROX_SIMPLE) # eliminate contours less than minimum area for c in range(len(contours)): if cv2.contourArea(contours[c]) > minimum_contour_size: contour_results.append(contours[c]) # reverse orientation to create holes in shape if hierachy[0][c][3] != -1: contour results[-1] = np.flipud(contour results[-1]) logger.info(f"Found {len(contour results)} contours, {len(contours) - len(contour results)} eliminated") except Exception as e: logger.error(f"Error contouring images: {e}", exc_info=True) cell error = True if cell error: raise SystemExit("Execution Stopped") else: logger.info(f"Finished contouring / creating polygons") Shape file Create ESRI shape files using polygons created from the contouring process. def pixel2location(dx,dy): '''Convert pixel coordinates to spatial coordinates dx: x axis pixel dy: y axis pixel x = dx * pixel x size + pixel x offset y = dy * pixel_y_size + pixel_y_offset return x,y # define shp schema schema = { 'geometry':'MultiPolygon', 'properties':[('tag','str')] cell error = False logger.info("Started converting contours / polygons to shape file") # get the transform data transform = merged_dataset.transform pixel x offset = transform[2] pixel_x_size = transform[0] pixel y offset = transform[5] pixel y size = transform[4] logger.debug(f"Spatial data: X pixel width = {pixel_x_size}m, Y pixel height = {pixel_y_size}m, pixel (0, 0) location = {pixel_x_offset}, {pixel_y_offset}") # loop through each contour if len(contour results) > 0: logger.debug(f"{len(contour_results)} polygons will be created") # Convert pixel data points to spatial multi polygon = [] for contour in range(len(contour results)): polygon = [] multi_polygon.append(polygon)

convert polygon pixel points to spatial points and store for pixel in contour_results[contour]: #convert x, y = pixel2location(pixel[0][0], pixel[0][1]) #store polygon.append([x, y]) # write to shape file shp_file_output = os.path.join(output_directory, f"{raster_shp_output_prefix}_{timestamp}.shp") logger.debug(f"Writing {shp_file_output}") with fiona.open(shp_file_output, 'w', 'ESRI Shapefile', schema=schema, crs=merged_dataset.crs) as shp_file: logger.debug(f"Shape file espg: {shp_file.crs}") shp file.write({ 'geometry' : { 'type': 'MultiPolygon', 'coordinates': [multi_polygon]}, # Here the xyList is in brackets 'properties': { 'tag': ' flood extent' }) except Exception as e: logger.error(f"Unable to write shape file {shp file output}: {e}", exc info=True) else: logger.debug(f"No polygons. No shape file will be generated") if cell_error: logger.warn(f"Finished converting polygons to shape file with errors")

Compress (zip) the output files and remove any temporary files created or downloaded onto the local machine. A zip file containing the output results will be left in the respository root.