INSTRUCTIONS:

Fill out the hazard analysis and risk assessment below.

HA-001 should be for the lane departure warning function as discussed in t HA-002 should be for the lane keeping assistance function as discussed in Then come up with your own situations and hazards for the lane assistance When finished, export your spreadsheet as a pdf file so that a reviewer can

	Hazard ID			
		Operational Mode	Operational Scenario	Environmental Details
Γ	HA-001	OM03	OS04	EN06
	HA-002	OM03	OS03	EN01
	HA-003	OM03	OS05	EN01
	HA-004	OM03	OS04	EN06

cussed in the lecture.

scussed in the lecture.

assistance system. Fill in the HA-003 and HA-004 rows.

viewer can easily see your work.

Situational Analysis		
Situation Details	Other Details (optional)	Item Usage (function)
SD02		IU01
SD02		IU02
SD01		IU01
SD02		IU01

Situation Description	Function	Deviation
Normal driving on highway during rain with	Lane Departure	DV04
Normal driving on country roads during	Lane Keeping	DV03
Normal driving on mountain pass road during	Lane Departure	DV08
Normal driving on highway during normal	Lane Keeping	DV04

Hazard Identification			
Deviation Details	Hazardous Event	Event Details	
	(resulting effect)		
LDW function applies very	EV00	Driver loses control of vehicle and	
LKA function is always	EV00	Driver takes both hands off wheel	
LDW function applies	EV04	Driver loses control of vehicle and	
LKA function applies steering	EV02	Driver loses control of vehicle and	

Hazardous Event Description	Exposure (of situation)	Rationale (for exposure)
LDW function applies very high	E3	Driving on a highway is a regular
LKA function applies oscillating	E2	Driving on a country is an irregular
LDW function applies oscillating	E1	Driving on amountain road is an
LKA function applies oscillating	E3	Driving on a highway is a regular

Hazardous Event Classification			
Severity	Rationale	Controllability	
(of potential harm)	(for severity)	(of hazardous event)	
S3	On highway roads,	C3	
S3	On country roads,	C3	
S3	On mountain roads,	C3	
S3	On highway roads,	C2	

	Determi
Rationale	ASIL
(for controllability)	Determination
Driving at high speeds in rain, drivers can lose control	С
Driving at high speeds on country roads, drivers will	В
Driving at normal speeds on mountain roads, drivers	Α
Driving at high speeds on highway roads, drivers can	В

Oscillating steering torque from LDW LKA function shall be time limited and Oscillating steering torque from LDW LKA function shall be time limited and

EXAMPLE DISCUSSED IN THE PROJECT INSTRUCTIONS - Headl

Hazard ID	
	Operational Mode
HA-001	Normal Driving

MORE EXAMPLES - Headlamp System

Hazard ID	
	Operational Mode
HA-001	OM03 - Normal Driving
HA-002	OM03 - Normal Driving
HA-003	OM03 - Normal Driving
HA-004	OM03 - Normal Driving
HA-005	OM03 - Normal Driving

DNS - Headlamp System

	S
Operational Scenario	Environmental Details
City Road	Normal Conditions

Operational Scenario	Environmental Details
OS01 - City Road	EN01 - Normal conditions
OS01 - City Road	EN04 - Snowfall (degraded view)
OS03 - Highway	EN04 - Snowfall (degraded view)
OS02 - Country Road	EN01 - Normal conditions
OS02 - Country Road EN04 - Snowfall (degraded vice	

ituational Analysis			
Situation Details	Other Details	Item Usage	
(optional)	(optional)	(function)	
Low Speed	Night time + Obstacle on the	Correctly Used	

Situation Analysis		
Situation Details	Other Details	Item Usage
(optional)	(optional)	(function)
SD03 - Low speed	Night time + Obstacle on the	IU01 - Correctly used
SD03 - Low speed	Night time + Obstacle on the	IU01 - Correctly used
SD03 - High speed	Night time + Obstacle on the	IU01 - Correctly used
SD02 - High speed	Night time + Oncoming	IU01 - Correctly used
SD04 - High speed	Night time + Obstacle on the	IU01 - Correctly used

Situation Description	Function
Normal Driving on a City Road in Normal	Low beam illuminates the

Situation Description	Function
Normal Driving on City Road during Normal	Low beam illuminates the
Normal Driving on City Road during Snowfall	Low beam illuminates the
Normal Driving on Highway during Snowfall	Low beam illuminates the
Normal Driving on Country Road during Normal	Low beam illuminates the
Normal Driving on Country Road during Snowfall	Low beam illuminates the

	Hazard Id
Deviation	Deviation Details
Function not activated	Both headlights stop working

	Hazard Id
Deviation	Deviation Details
DV01 - Function not activated	Both headlights stop working
DV01 - Function not activated	Both headlights stop working
DV01 - Function not activated	Both headlights stop working
DV01 - Function not activated	Both headlights stop working
DV01 - Function not activated	Both headlights stop working

entification		
Hazardous Event	Event Details	Hazardous Event
(resulting effect)		Description
Front collision with obstacle	Vehicle crashes into the	Total loss of low beam

entification		
Hazardous Event	Event Details	Hazardous Event
(resulting effect)		Description
EV04 - Front collision with obstacle	Vehicle crashes into the	Total loss of low beam
EV04 - Front collision with obstacle	Vehicle crashes into the	Total loss of low beam
EV04 - Front collision with obstacle	Vehicle crashes into the	Total loss of low beam
EV08 - Collision with other vehicle	Vehicle crashes into the	Total loss of low beam
EV04 - Front collision with obstacle	Vehicle crashes into the	Total loss of low beam

Exposure	Rationale
(of situation)	(for exposure)
E4 - High probability	night driving in the city is a regular

Exposure	Rationale
(of situation)	(for exposure)
E4 - High probability	night driving in the city is a regular
E1 - Very low probability	night driving in the city on
E2 - Low probability	High driving is part of regular
E4 - High probability	country driving is part of regular
E2 - Low probability	country driving is part of regular

Hazardous Severity (of potential harm) S1 - Light and moderate injuries

Hazardous
Severity
(of potential harm)
S1 - Light and moderate injuries
S1 - Light and moderate injuries
S3 - Life-threatening or fatal injuries
S3 - Life-threatening or fatal injuries
S3 - Life-threatening or fatal injuries

Event Classification	
Rationale	Controllability
(for severity)	(of hazardous event)
In city traffiic, speed of vehicle is expected to be low	C0 - Controllable in general

s Event Classification	
Rationale	Controllability
(for severity)	(of hazardous event)
In city traffiic, speed of vehicle is expected to be low	C0 - Controllable in general
In city traffiic, speed of vehicle is expected to be low	C1 - Simply controllable
On highway speed of vehicle is expected to be high	C2 - Normally controllable
On country roads speed of vehicle is expected to be high	C1 - Simply controllable
On country roads speed of vehicle is expected to be high	C3 - Difficult to control or uncontrollable

Determination of ASIL and
ASIL
Determination
QM

	Determination of ASIL and
Rationale	ASIL
(for controllability)	Determination
At city speed, most drivers will be able to	QM
On completely unilluminated city roads,	QM
When driving on highway with low beam, it	Α
Since there is usually no other form of	В
Since there is usually no other form of	В

Safety Goals

Safety Goal

Total Loss of Beam Shall

Safety Goals

Safety Goal

Total loss of low beam
Total loss of low beam

Total loss of low beam

Total loss of low beam

Total loss of low beam

Hazard & Risk Analysis Definiti

Operational Mode

ID	Mode
OM01	Parked
OM02	Ignition on
OM03	Normal driving
OM04	Backward driving
OM05	Degraded driving
OM06	Towing (active)
OM07	Towing (passive)
80MO	Service
OM09	N/A

Operational Scenario

Operationa	1 Scenario
ID	Scenario
OS01	Any Road
OS02	City Road
OS03	Country Road
OS04	Highway
OS05	Mountain Pass
OS06	Off Road
OS07	Road with gradient
OS08	Road with bump
OS09	Road tunnel
OS10	Road with construction site
OS11	N/A

Situation Details

ID	Scenario
SD01	Low speed
SD02	High speed
SD03	Normal acceleration
SD04	High acceleration
SD05	Normal braking
SD06	High braking
SD07	N/A

Item Usage

ID	Mode
IU01	Correctly used
IU02	Incorrectly used
IU03	N/A

Environmental Details

ID	Scenario
EN01	Normal conditions
EN02	Sun blares (degraded view)
EN03	Fog (degraded view)
EN04	Snowfall (degraded view)
EN05	Cross-wind (lateral force)
EN06	Rain (slippery road)

EN07	Snow (slippery road)
EN08	Glace (slippery road)
EN09	N/A

Definitions

Remarks
Car is parked, ignition is off
Car is parked, ignition is on
Car is driving
Car is driving
imp home mode
owing another car
Beeing towed by another car
/ehicle is in repair garage
ot applicable or not relevant

emarks emarks
ad type
ad attribute
ad attribute
ad attribute
ad attribute
ot applicable or not relevant

Remarks		
driving attribute		
not applicable or not relevant		

Remarks
Intended usage
Unintended usage (foreseeable)
not applicable or not relevant

Remarks
weather attribute
road attribute

road attribute	
road attribute	
not applicable or not relevant	

Reference
OM01 - Parked
OM02 - Ignition on
OM03 - Normal driving
OM04 - Backward driving
OM05 - Degraded driving
OM06 - Towing (active)
OM07 - Towing (passive)
OM08 - Service
OM09 - N/A

Reference
OS01 - Any Road
OS02 - City Road
OS03 - Country Road
OS04 - Highway
OS05 - Mountain Pass
OS06 - Off Road
OS07 - Road with gradient
OS08 - Road with bump
OS09 - Road tunnel
OS10 - Road with construction site
OS11 - N/A

Reference	
SD01 - Low speed	
SD02 - High speed	
SD03 - Normal acceleration	
SD04 - High acceleration	
SD05 - Normal braking	
SD06 - High braking	
SD07 - N/A	

Reference	
IU01 - Correctly used	
IU02 - Incorrectly used	
IU03 - N/A	

Reference
EN01 - Normal conditions
EN02 - Sun blares (degraded view)
EN03 - Fog (degraded view)
EN04 - Snowfall (degraded view)
EN05 - Cross-wind (lateral force)
EN06 - Rain (slippery road)

EN07 - Snow (slippery road)

EN08 - Glace (slippery road) EN09 - N/A

Deviation

ID	Deviation (Guideword)
DV01	Function not activated
DV02	Function unexpectedly activated
DV03	Function always activated
DV04	Actor effect is too much
DV05	Actor effect is too less
DV06	Actor action too early
DV07	Actor action too late
DV08	Actor action before
DV09	Actor action after
DV10	Actor effect is reverse
DV11	Actor effect is wrong
DV12	Sensor sensitivity is too high
DV13	Sensor sensitivity is too low
DV14	Sensor detection too early
DV15	Sensor detection too late
DV16	Sensor detection before
DV17	Sensor detection after
DV18	Sensor detection is reverse
DV19	Sensor detection is wrong
DV20	N/A

Hazardous Events (possibe effects)

ID	Hazardous Event
EV-07	None
EV-06	Front collision with oncoming traffic
EV-05	Front collision with ahead traffic
EV-04	Front collision with obstacle
EV-03	Rear collision with trailing traffic
EV-02	Side collision with other traffic
EV-01	Side collision with obstacle
EV00	Collision with other vehicle
EV01	Collision with train
EV02	Collision with pedestrian
EV03	Car spins out of control
EV04	Car comes off the road
EV05	Car catches file
EV06	N/A

Remarks	Reference
Activation error	DV01 - Function not activated
Activation error	DV02 - Function unexpectedly activated
Activation error	DV03 - Function always activated
Quantitative error	DV04 - Actor effect is too much
Quantitative error	DV05 - Actor effect is too less
Timing error	DV06 - Actor action too early
Timing error	DV07 - Actor action too late
Sequence error	DV08 - Actor action before
Sequence error	DV09 - Actor action after
Logical error	DV10 - Actor effect is reverse
Logical error	DV11 - Actor effect is wrong
Quantitative error	DV12 - Sensor sensitivity is too high
Quantitative error	DV13 - Sensor sensitivity is too low
Timing error	DV14 - Sensor detection too early
Timing error	DV15 - Sensor detection too late
Sequence error	DV16 - Sensor detection before
Sequence error	DV17 - Sensor detection after
Logical error	DV18 - Sensor detection is reverse
Logical error	DV19 - Sensor detection is wrong
not applicable or not relevant	DV20 - N/A

Remarks	Reference
	EV-07 - None
	EV-06 - Front collision with oncoming traffic
	EV-05 - Front collision with ahead traffic
	EV-04 - Front collision with obstacle
	EV-03 - Rear collision with trailing traffic
	EV-02 - Side collision with other traffic
	EV-01 - Side collision with obstacle
	EV00 - Collision with other vehicle
	EV01 - Collision with train
	EV02 - Collision with pedestrian
	EV03 - Car spins out of control
	EV04 - Car comes off the road
	EV05 - Car catches file
	EV06 - N/A

Exposure

ID	Description
E0	Incredible
E1	Very low probability
E2	Low probability
E3	Medium probability
E4	High probability

Severity

ĪD	Description
S0	No injuries
S1	Light and moderate injuries
S2	Severe and life-threatening injuries
S3	Life-threatening or fatal injuries

Controllability

ID	Description
C0	Controllable in general
C1	Simply controllable
C2	Normally controllable
C3	Difficult to control or uncontrollable

Duration (of situation)

Not specified

<1 % of average operating time

1 % to 10 % of average operating time

>10 % of average operating time

Remarks

No injuries

Light and moderate injuries

Severe and life-threatening injuries (survival probable)

Life-threatening injuries (survival uncertain), fatal injuries

Remarks

Controllable in general

99 % or more of all drivers or other traffic participants are usually able 90 % or more of all drivers or other traffic participants are usually able Less than 90 % of all drivers or other traffic participants are usually ab

Frequency (of situation)	Reference
	E0 - Incredible
Occurs less often than once a year for the great majority of drivers	E1 - Very low probability
Occurs a few times a year for the great majority of drivers	E2 - Low probability
Occurs once a month or more often for an average driver	E3 - Medium probability
Occurs during almost every drive on average	E4 - High probability

Probability of Injuries	Reference
AIS 0 and less than 10 % probability of AIS 1-6	S0 - No injuries
More than 10 % probability of AIS 1-6 (and not S2 or S3)	S1 - Light and moderate injuries
More than 10 % probability of AIS 3-6 (and not S3)	S2 - Severe and life-threatening injuries
More than 10 % probability of AIS 5-6	S3 - Life-threatening or fatal injuries

- C

	Reference
	C0 - Controllable in general
usually able to avoid harm	C1 - Simply controllable
usually able to avoid harm	C2 - Normally controllable
e usually able, or barely able, to avoid harm	C3 - Difficult to control or uncontrollable

Controllability	Exposure		Sev
		S0	S1
C1	E1	QM	QM
	E2	QM	QM
	E3	QM	QM
	E4	QM	QM
C2	E1	QM	QM
	E2	QM	QM
	E3	QM	QM
	E4	QM	Α
C3	E1	QM	QM
	E2	QM	QM
	E3	QM	А
	E4	QM	В

erity		
S2	S3	
QM	QM	
QM	QM	
QM	Α	
Α	В	
QM	QM	
QM	Α	
А	В	
В	С	
QM	Α	
Α	В	
В	С	
С	D	