diff --git a/package.xml b/package.xml

index 74c6160..60ecefa 100644

--- a/package.xml

+++ b/package.xml

@@ -14,6 +14,8 @@

<build\_depend>geometry\_msgs</build\_depend>

<build\_depend>tf2</build\_depend>

+ <build\_depend>roscpp</build\_depend>

<run\_depend>tf2</run\_depend>

+ <run\_depend>roscpp</run\_depend>

</package>

diff --git a/tests/test\_base.cc b/tests/test\_base.cc

index 05adf4e..cdaae98 100644

--- a/tests/test\_base.cc

+++ b/tests/test\_base.cc

@@ -1,8 +1,8 @@

#define BOOST\_TEST\_DYN\_LINK

#define BOOST\_TEST\_MODULE test\_base

#include <boost/test/unit\_test.hpp>

+#include <stdio.h>

-#include <ros/ros.h>

#include <geometry\_utils/GeometryUtils.h>

namespace gu = geometry\_utils;

diff --git a/tests/test\_math.cc b/tests/test\_math.cc

index f4b1181..e457125 100644

--- a/tests/test\_math.cc

+++ b/tests/test\_math.cc

@@ -2,7 +2,6 @@

#define BOOST\_TEST\_MODULE test\_math

#include <boost/test/unit\_test.hpp>

-#include <ros/ros.h>

#include <geometry\_utils/GeometryUtilsMath.h>

namespace gu = geometry\_utils;

diff --git a/tests/test\_so3error.cc b/tests/test\_so3error.cc

index 2eaed84..bd585ac 100644

--- a/tests/test\_so3error.cc

+++ b/tests/test\_so3error.cc

@@ -2,7 +2,6 @@

#define BOOST\_TEST\_MODULE test\_equals

#include <boost/test/unit\_test.hpp>

-#include <ros/ros.h>

#include <geometry\_utils/GeometryUtils.h>

namespace gu = geometry\_utils;