

TP 5:

Projection sur un polyèdre et application en débruitage

Q1)

$$\begin{aligned} \text{Le lagrangien s'écrit: } L(x, \lambda) &= \underbrace{\frac{1}{2} \|x - p\|^2}_{f(x)} + \underbrace{\sum_{i=1}^k \lambda_i (a_i^T x - b)}_{\lambda^T g} \\ &= \frac{1}{2} \|x - p\|^2 + \langle \lambda, Ax - b \rangle \end{aligned}$$

$$\min_{x \in \mathbb{R}^d} L(x, \lambda) = \min_x f_\lambda(x)$$

f_λ est convexe ($\nabla^2 f_\lambda = 2I_k$), donc son minimiseur est le point x_λ t.q. $\nabla f_\lambda(x_\lambda) = 0$

$$\nabla f_\lambda = (x - p) + A^T \lambda \quad \Rightarrow \quad \boxed{x_\lambda = p - A^T \lambda}$$

$$\text{Ainsi } (D) = \max_{\lambda \in M} \min_{x \in \mathbb{R}^d} L(x, \lambda)$$

$$= - \min_{\lambda \in M} - f_\lambda(x_\lambda)$$

$$= - \min_{\lambda \in M} - \frac{1}{2} \|p - A^T \lambda - p\|^2 - \lambda^T (Ap - AA^T \lambda) + \lambda^T b$$

$$h(\lambda) = - \frac{1}{2} \|A^T \lambda\|^2 - \lambda^T Ap + \|A^T \lambda\|^2 + \lambda^T b$$

$$= \frac{1}{2} \|A^T \lambda\|^2 - \lambda^T Ap + \lambda^T b$$

$$\boxed{h(\lambda) = \frac{1}{2} \|A^T \lambda - p\|^2 - \frac{1}{2} \|p\|^2 + \lambda^T b}$$

$$\nabla h(\lambda) = A(\underbrace{A^T \lambda - p}_{-x_\lambda}) + b$$

$$= b - Ax_\lambda$$

Q21)

Algorithme d'Uzawa -

$$\nabla^2 h(\lambda) = AA^T \succeq 0 \quad \text{donc } h \text{ est convexe}$$

$$\text{Si } \lambda^* \text{ t.q. } S_T(\lambda^*) = \lambda^*$$

$$\Leftrightarrow P_{\mathbb{R}_+^k}(\lambda^* - \tau \nabla h(\lambda^*)) = \lambda^*$$

$$\Leftrightarrow \begin{cases} \lambda^* \in \mathbb{R}_+^k \\ \lambda^* - \tau \nabla h(\lambda^*) = \lambda^* \end{cases}$$

$$\text{on } \nabla h(\lambda^*) = 0.$$