The Payne

For this particular case, we generate \sim 160 training spectra and \sim 160 testing spectra using B. Kurucz codes and P. Cargile line list. The Teff and log g are drawn from the MIST isochrones. We consider stellar evolution from the main sequence stars up to the red clump stars with Teff from 3500 K to 7000 K. We also consider a wide range of metallicity with [Fe/H] = -2 to 0.5.

The following will show that using only 160 models, The Payne is an extremely precise generative model for this wide range of stellar parameters.

Train neural network

This training step is quite slow. Training a single wavelength pixel typically takes 10 minutes to 1 hour. It requires running on a cluster. If you want to try this part on a personal laptop, make sure that you only train spectra with a few wavelength pixels. Note that although the training is excruciating slow, once the network is trained, fitting spectra (i.e. testing step) is very efficient.

```
# BMGITEL DATCH BIZE (I.E. TALYEL HUMBEL) WILL CARE TOHYEL TO CONVERYE
# but might converge with a smaller number of steps
mini batch size = 2
# initial step size in stochastic gradient descent
# smaller step size will be slower but will provide better convergence
eta choice = 0.1
# the minimum step size beyond which we will truncate
min eta = 0.001
# how many steps of gradient descent per loop are we going to perform
num epochs choice = 10000
# truncation criterion
trunc diff = 0.003
# maximum number of loop (to avoid infinite loop)
# i.e. max iter*num epochs choice is the maximum number of steps beyond which we will truncate
max iter = 100
# how many neurons per layer
# here we always consider two fully connected layers
n neurons = 10
# define activation function that we will use in the validation step
# make sure this function is consistent with the training function
# here we choose a sigmoid function
def act func(z):
   return 1.0/(1.0+np.exp(-z))
# restore all spectra
# the variable "spectra" has a dimension of (# pixels, # spectra)
# the variable "labels" has a dimension of (# labels, # spectra)
# for this particular training set, the labels are (teff(K), logg, Fe/H)
```

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```
temp = np.load("kurucz spectra.npz")
spectra = temp["Y u all"].T
labels = temp["labels array"]
# only use half of them to train the neural network
# we will save the other half for testing
spectra = spectra[:,::2]
labels = labels[:,::2]
# neural networks typically train a function mapping from [0,1] -> [0,1]
# so here we scale both input (labels) and output (fluxes) to [0.1,0.9]
# record how we scale the labels
x max = np.max(labels, axis=1)
x min = np.min(labels, axis=1)
# scale the labels
labels = ((labels.T - x min)*0.8/(x max-x min) + 0.1).T
# scale the fluxes
# here we assume normalized spectra
# for flux spectra this scaling has to be changed
spectra = spectra*0.8 + 0.1
# theano is a very powerful package to train neural network
# it performs "auto diff", i.e., provides analytic differentiation of any cost function
# convert labels into a theano variable
training x = theano.shared(np.asarray(labels.T, dtype='float64'))
# main network class
class Network(object):
   def init (self, layers, mini batch size):
```

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```
# initiate network properties
    self.layers = layers
    self.mini batch size = mini batch size
    self.params = [param for layer in self.layers for param in layer.params]
    self.x = T.dmatrix("x")
    self.y = T.dmatrix("y")
    init layer = self.layers[0]
    init layer.set inpt(self.x, self)
    for j in xrange(1, len(self.layers)):
        prev layer, layer = self.layers[j-1], self.layers[j]
        layer.set inpt(prev layer.output, self)
    self.output = self.layers[-1].output
   # create a property to record the cost function at each training step
    self.cost train = []
# stochastic gradient descent
def SGD(self, training x, training y, epochs, eta):
   # reset the cost for each training loop
    self.cost train = []
    # compute mini batches
   num sample = training x.get value().shape[0]
   num training batches = num sample/self.mini batch size
   # define cost function, symbolic gradients, and updates
    cost = self.layers[-1].cost(self)
    grads = T.grad(cost, self.params)
    updates = [(param, param-eta/self.mini batch size*grad)\
                   for param, grad in zip(self.params, grads)]
    i = T.lscalar()
```

```
# randomize the training data for stochastic gradient descent
        ind = np.arange(num sample)
        np.random.shuffle(ind)
        ind = theano.shared(ind)
        # define function to train a mini-batch
        train mb = theano.function([i], cost, updates=updates,
            givens={self.x: training x[ind[i*self.mini batch size:(i+1)*self.mini batch size]],
                    self.y: training y[ind[i*self.mini batch size:(i+1)*self.mini batch size]]})
        # the actual training
        for epoch in xrange(epochs):
            cost train ij = 0.
            for minibatch index in xrange(num training batches):
                # sum up all cost for each mini batch
                cost train ij += train mb(minibatch index)
            self.cost train.append(cost train ij)
# define fully connected layers
### here we choose sigmoid function to be the activation function ###
class FullyConnectedLayer(object):
    def init (self, n in, n out, activation fn=sigmoid):
        self.n in = n in
        self.n out = n out
        self.activation fn = activation fn
        # initialize weights and biases of the neural network
        self.w = theano.shared(np.asarray(np.random.normal(
                    loc=0.0, scale=np.sqrt(1.0/n out), size=(n in, n out)),
                    dtype=theano.config.floatX))
        self.b = theano.shared(np.asarray(np.random.normal(\)
                    loc=0.0, scale=1.0, size=(n out,)),
                    dtype=theano.config.floatX))
        self.params = [self.w,self.b]
```

```
# define input and output for each neural network layer
   def set inpt(self, inpt, net):
       self.inpt = inpt.reshape((net.mini batch size, self.n in))
       self.output = self.activation fn(T.dot(self.inpt, self.w) + self.b)
   ### define a cost function ###
   def cost(self,net):
       return T.sum(T.abs (net.y-self.output))
# define training function for each wavelength pixel to run in parallel
# note we create individual neural network for each wavelength pixel
def train pixel(pixel no):
   # extract flux of a wavelength pixel
   training y = theano.shared(np.asarray(np.array([spectra[pixel no,:]]).T, dtype='float64'))
   # define the network
   net = Network([
       FullyConnectedLayer(n in=training x.get value().shape[1], n out=n neurons),\
       FullyConnectedLayer(n in=n neurons, n out=training y.get value().shape[1])],\
                mini batch size)
   # initiate loop counter and step size
   loop count = 0
   step devide = 1.
   # sometimes the network can stuck at the initial point
   # so first we train for 1000 steps
   net.SGD(training x, training y, 1000, eta choice)
   # we evaluate if the cost has improved
   while (np.abs(np.mean(net.cost train[:100]) \
                   - np.mean(net.cost train[-100:]))/(np.mean(net.cost train[:100])) < 0.1)
```

```
and (100p count < max iter):
    # if not we reset the newtwork (and hence the initial point)
    # and loop until it finds a valid initial point
    net = Network([
            FullyConnectedLayer(n in=training x.get value().shape[1], n out=n neurons),\
            FullyConnectedLayer(n in=n neurons, n out=training y.get value().shape[1])],\
                      mini batch size)
    net.SGD(training x, training y, 1000, eta choice)
    # increase counter
    loop count += 1
# after a good initial point is found, we proceed to the extensive training
# initiate the deviation truncation criterion
med deviate = 1000.
# loop until the deviation is smaller than the chosen truncation criterion
# we also truncate if the step size has become too small
while (med deviate > trunc diff) and (loop count < max iter) and (eta choice/step devide > min e
    # continue to train the network if it has not converged yet
    net.SGD(training x, training y, num epochs choice, eta choice/step devide)
    # increase counter to avoid infinite loop
    loop count += 1
    # check if the current step size is too large, i.e. cost does not change much
    if np.abs(np.mean(net.cost train[:100])
              - np.mean(net.cost train[-100:]))/(np.mean(net.cost train[:100])) < 0.01:
        # if so, we make the step size smaller
        step devide = step devide*2.
    # this is the validation sten
```

```
# calcluate the deviation between the analytic approximation vs. the training models
        # in principle, we should consider validtion models here
        w array 0 = net.layers[0].w.get value().T
        b array 0 = net.layers[0].b.get value()
        w array 1 = net.layers[1].w.get value()[:,0]
        b array 1 = net.layers[1].b.get value()[0]
        predict flux = act func(np.sum(w array 1*act func(np.dot(w array 0,labels).T\
                            + b array 0), axis=1) + b array 1)
        # remember to scale back the fluxes to the normal metric
        ### here we choose the maximum absolute deviation to be the truncation criterion ###
        med deviate = np.max(np.abs((predict flux - spectra[pixel no,:])/0.8))
    # return the trained network for this pixel
    return net.
# train in parallel for all wavelength pixels
import time
start time = time.time()
pool = Pool(num CPU)
net array = pool.map(train pixel,range(spectra.shape[0]))
print time.time() - start time
# extract neural network parameters as numpy array
# the first layer
w array 0 = np.array([net array[i].layers[0].w.get value().T\
                      for i in range(spectra.shape[0])])
b array 0 = np.array([net array[i].layers[0].b.get value()\
                      for i in range(spectra.shape[0])])
# the second layer
w array 1 = np.array([net array[i].layers[1].w.get value()[:,0]\
                      for i in range(spectra.shape[0])])
```

Check how well we can predict the fluxes of spectra.

Ab-initio calculated spectrum vs. neural network reconstruction of a spectrum.

```
# restore trained neural network
temp = np.load("neural network.npz")
w array 0 = temp["w array 0"]
w array 1 = temp["w array 1"]
b array 0 = temp["b array 0"]
b array 1 = temp["b array 1"]
x min = temp["x min"]
x max = temp["x max"]
# activation function
# make sure this function is consistent with the trained network
def act func(z):
   return 1.0/(1.0+np.exp(-z))
# restore all spectra
temp = np.load("kurucz spectra.npz")
wavelength = temp["wavelength"]
spectra = temp["Y u all"].T
labels = temp["labels array"]
### testing spectra (not used in the training steps) ###
spectra testing = spectra[:,1::2]
labels testing = labels[:,1::2]
# scale labels as before
labels testing = ((labels testing.T - x min)*0.8/(x max-x min) + 0.1).T
# predict flux using the neural network
predict flux array = []
```

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```
# for each of the spectra
for i in range(labels testing.shape[1]):
    # we predict the flux ...
    predict flux array.append(act func(np.sum(w array 1*(act func(np.dot(w array 0,\)
                    labels testing[:,i]) + b array 0)), axis=1) + b array 1))
# convert into a numpy array
predict testing = np.array(predict flux array).T
# recall that the predicted fluxes are scaled to [0.1,0.9]
# so here we have to rescale it back to the normal metric
predict testing = (predict testing - 0.1)/0.8
### we perform the same for training spectra ###
spectra training = spectra[:,0::2]
labels training = labels[:,0::2]
labels training = ((labels training.T - x min)*0.8/(x max-x min) + 0.1).T
predict flux array = []
for i in range(labels training.shape[1]):
    predict flux array.append(act func(np.sum(w array 1*(act func(np.dot(w array 0,\)
                    labels training[:,i]) + b array 0)), axis=1) + b array 1))
predict training = np.array(predict flux array).T
predict training = (predict training - 0.1)/0.8
# initiate the plot
fig = plt.figure(figsize=[22,50]);
ax = fig.add subplot(111)
ax.spines['top'].set color('none')
ax.spines['bottom'].set color('none')
ax.spines['left'].set color('none')
ax.spines['right'].set color('none')
ax.tick params(labelcolor='w', top='off', bottom='off', left='off', right='off')
```

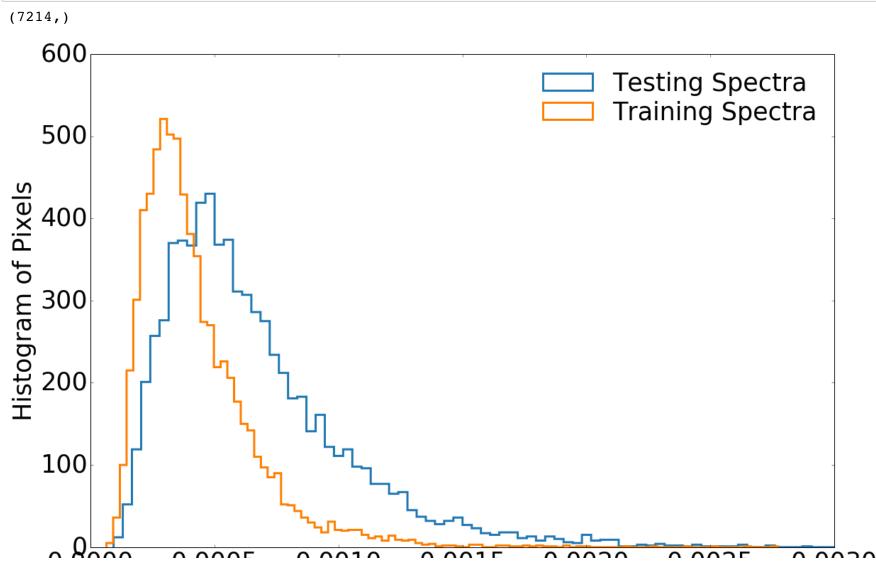
```
# axis labels
ax.set xlabel("Wavelength [nm]", labelpad=30, fontsize=50);
ax.set ylabel("Normalized Flux", labelpad=30, fontsize=50);
# break wavelength into different subplots
for i in range(8):
   ax = fig.add subplot(8,1,i+1)
   plt.xlim([1500+i*25.,1500+(i+1)*25])
   plt.ylim([0.5,1.1])
    ax.tick params(axis='x', pad=20);
    plt.plot(wavelength/10, spectra testing[:,0],\
             color=cb2[0], lw=2, label="Ab-Initio Calculation")
   plt.plot(wavelength/10, predict testing[:,0],\
            color=cb2[3], lw=2, label="The Payne Reconstruction", alpha=0.8)
# plot legend
plt.legend(loc="lower right", fontsize=35, frameon=False,\
               borderpad=0.2, labelspacing=0.2, scatterpoints=1)
# save figure
plt.tight layout()
plt.savefig("flux prediction.png")
     0.7
     0.6
     0.5
      1600
                       1605
                                       1610
                                                        1615
                                                                         1620
                                                                                         1625
```



Evaluate the median absolute deviation of all wavelength pixels.

```
In [2]: # initiate plot
        fig = plt.figure(figsize=[18,12]);
        ax = fiq.qca();
        # axis labels
        ax.set xlabel(r"Median Absolute Deviation");
        ax.set ylabel(r"Histogram of Pixels");
        # plotting range
        plt.xlim([0,0.003])
        # ploting histogram
        plt.hist(np.median(np.abs(spectra testing-predict testing), axis=1), bins=100,\
                 histtype="step", lw=3, label="Testing Spectra", )
        plt.hist(np.median(np.abs(spectra training-predict training), axis=1), bins=100,\
                 histtype="step", lw=3, label="Training Spectra")
        print np.median(np.abs(spectra testing-predict testing), axis=1).shape
        # plot legend
        plt.legend(loc="upper right", fontsize=35, frameon=False,\
```

```
borderpad=0.2, labelspacing=0.2, scatterpoints=1)
# save figure
plt.tight_layout()
plt.savefig("flux_deviation.png")
```



Median Absolute Deviation

Fitting spectra with the trained network.

```
In [5]: # import python packages
       import numpy as np
       from multiprocessing import Pool
       from scipy.optimize import curve fit
       # number of processors for parallel computing
       num CPU = 4
       # restore testing spectra
       temp = np.load("kurucz spectra.npz")
       spectra = temp["Y u all"].T
       labels = temp["labels array"]
       spectra testing = spectra[:,1::2]
       labels testing = labels[:,1::2]
       # scale the flux to the neural network scale
       # if the fluxes have uncertainties, also remember to scale the uncertainties
       spectra testing = spectra testing*0.8 + 0.1
       # restore trained neural network
       temp = np.load("neural network.npz")
       w array 0 = temp["w array 0"]
       w_array_1 = temp["w_array_1"]
       h array 0 - tomp["h array 0"]
```

```
n array o - cempl n array o l
b array 1 = temp["b array 1"]
x min = temp["x min"]
x max = temp["x max"]
# activation function
# make sure this function is consistent with the trained network
def act func(z):
    return 1.0/(1.0+np.exp(-z))
# predict spectrum
def predict spec(input param, *labels):
    predict flux = act func(np.sum(w array 1*(act func(np.dot(w array 0,labels)\)
                                             + b array 0)), axis=1) + b array 1)
    return predict flux
# define function to perform testing steps in batch (over many spectra)
def fit spectrum(spec no):
    try:
        # here we set the noise (sigma) to be 0.01 dex
        # but note that we assume noiseless spectra in our testing case
        # here we also start with the right initial point
        # in practice multiple resets might be needed
        popt, pcov = curve fit(predict spec, [spec no], spectra testing[:,spec no],\
                                   p0 = (labels testing[:,spec no]-x min)*0.8/(x max-x min) + 0.1, \
                                   sigma=0.01,\
                                   absolute sigma=True, bounds=(0,1))
    except:
        # if the minimization does not converge, return some nul values
        popt = np.zeros(labels testing.shape[0]) - 9999.
    return popt
# fit spectra in parallel
pool = Pool(num CPU)
best fit results = np.arrav(pool.map(fit spectrum.range(spectra testing.shape(11))).T
```

```
# recall that we have scaled the labels to train the network
# here we rescale the best-fitting results back to the original scale
best_fit_results = ((best_fit_results.T-0.1)*(x_max-x_min)/0.8+x_min).T
```

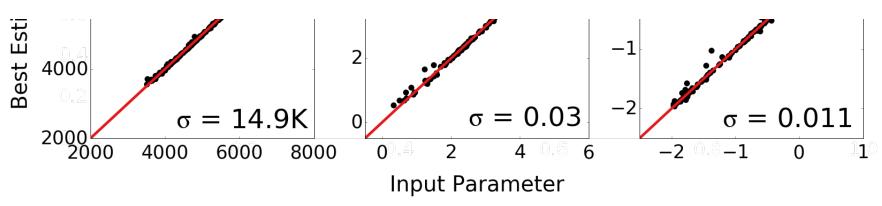
Plot the best fitting results vs. input parameters

```
In [4]: # import python packages
       %matplotlib inline
       import matplotlib.pyplot as plt
       from matplotlib import rcParams
       import numpy as np
       # define plot properties
       def rqb(r,q,b):
          return (float(r)/256.,float(g)/256.,float(b)/256.)
       cb2 = [rgb(31,120,180), rgb(255,127,0), rgb(51,160,44), rgb(227,26,28), \
             rgb(166,206,227), rgb(253,191,111), rgb(178,223,138), rqb(251,154,153)]
       rcParams['lines.linewidth'] = 1
       rcParams['axes.color cycle'] = cb2
       rcParams['font.family'] = 'Bitstream Vera Sans'
       rcParams['font.size'] = 35
       # initiate the plot
       fig = plt.figure(figsize=[25,9]);
       ax = fig.add subplot(111)
       ax.spines['top'].set color('none')
       ax.spines['bottom'].set color('none')
```

```
ax.spines['left'].set color('none')
ax.spines['right'].set color('none')
ax.tick params(labelcolor='w', top='off', bottom='off', left='off', right='off')
# axis labels
ax.set xlabel("Input Parameter", fontsize=40, labelpad=30);
ax.set ylabel("Best Estimate", fontsize=40, labelpad=50);
# label name
label name = ["$\mathregular{T {eff}\;[K]}$",\
             "$\mathregular{log\,g}$",\
              "[Fe/H]"]
# loop over all labels
for u1 in range(len(label name)):
    ax = fig.add subplot(1, 3, u1+1)
   ax.tick params(axis='x', pad=10);
   plt.locator params(nbins=5)
   # plot results
   plt.scatter(labels testing[u1,:], best fit results[u1,:], color="black", s=100)
   # plotting parameters
    # for Teff
    if u1 == 0:
        # plotting range
        plt.xlim([2000,8000])
       plt.ylim([2000,8000])
        # plot 1-to-1 line guide line
       plt.plot([2000,8000],[2000,8000], lw=5, color=cb2[3])
        # plot the name of the label
        plt.text(2200, 7000, label name[u1], fontsize=50)
```

```
# calculate and write the 1 sigma error
       plt.text(4300, 2300, r"\mbox{mathregular} = \mbox{"}
            + "%.1f" % (np.percentile(labels_testing[u1,:]-best_fit_results[u1,:], 68.3)
                - np.percentile(labels testing[u1,:]-best fit results[u1,:], 31.7)) + "K", fontsize=
    # for logg
    if u1 == 1:
       plt.xlim([-0.5,6.0])
        plt.ylim([-0.5,6.0])
        plt.plot([-0.5,6.0],[-0.5,6.0], lw=5, color=cb2[3])
       plt.text(-0.1, 4.9, label name[u1], fontsize=50)
       plt.text(2.5, -0.1, r"\mathregular{\sigma} = "\
            + "%.2f" % (np.percentile(labels testing[u1,:]-best fit results[u1,:], 68.3)
                - np.percentile(labels testing[u1,:]-best fit results[u1,:], 31.7)), fontsize=50)
    # for [Fe/H]
    if u1 == 2:
       plt.xlim([-2.5,1.0])
       plt.ylim([-2.5,1.0])
       plt.plot([-2.5,1.0],[-2.5,1.0], lw=5, color=cb2[3])
       plt.text(-2.3, 0.4, label name[u1], fontsize=50)
       plt.text(-1.2, -2.3, r"\mathregular{\sigma} = "\
            + "%.3f" % (np.percentile(labels testing[u1,:]-best fit results[u1,:], 68.3)\
                - np.percentile(labels testing[u1,:]-best fit results[u1,:], 31.7)), fontsize=50)
# save figure
plt.tight layout(w pad=0.7,h pad=0.7)
plt.savefig("fitting results.png")
   8000
                                          log g
```

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In []: