

تلخيص

تلخيص مادة السيجنال (فيرست)

ملخص طالب

لجنة ICE





1

الاسمين

1/3

1/3

Definitions

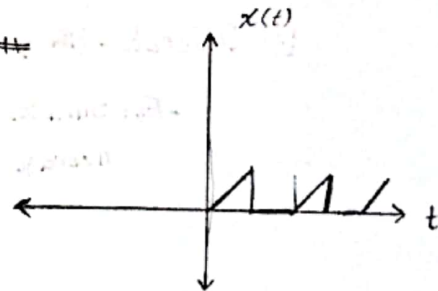
- * What is signal ?
 - Physical quantities carry information changes respect to time.
- * Signals can be represent as function of time.
- * The mathematical representation of signal contains:
 - The expression: $s(t)$
 - The time support: $t_1 \leq t \leq t_2$

Signal Classifications

I Continuous-time v.s. discrete-time signals

Continuous-time: - If the signal is defined over continuous-time, then the signal is a continuous-time signal

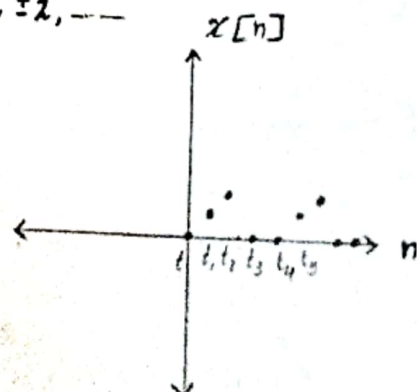
أي أنها متصلة في الوقت (معرفة في جميع الأوقات)



Discrete-Time: - If time t can only take discrete values, such as:

$$t = kT_s \quad ; \quad k = 0, \pm 1, \pm 2, \dots$$

أي أنها معرفة في فترة زمنية معين تتكرر بها (معدل أخذ العينة)



We can represent it in three way:

$$1) \quad x(nT_s) = \{0, 1, 3, 0, 2, 5, 4\}$$

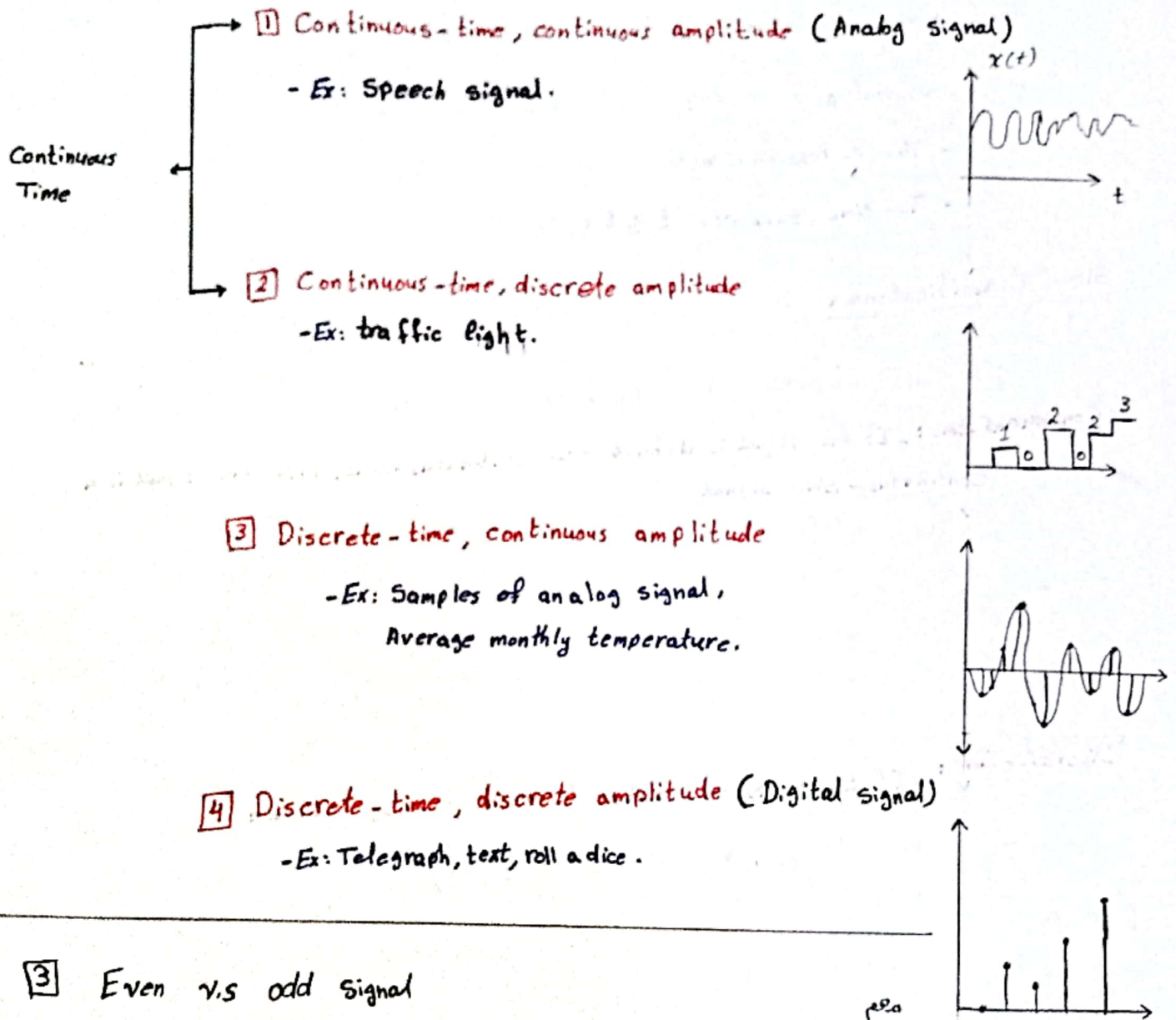
$$2) \quad x[n] = \left\{1, \frac{1}{2}, \frac{1}{4}, \dots, \left(\frac{1}{2}\right)^n\right\} = \begin{cases} \left(\frac{1}{2}\right)^n & n \geq 0 \\ 0 & n < 0 \end{cases}$$

3)

$x[n]$	0	2	0	3.5	0.5	-1
n	0	1	2	3	4	5

2 Analog v.s. Digital Signal

- In this classification we focus in the both, Amplitude and Time, there are 4 types:



3 Even v.s odd signal

$$x(t) = \overset{\text{even}}{x_e(t)} + \overset{\text{odd}}{x_o(t)}$$

$$x_e(t) = \frac{1}{2} [x(t) + x(-t)]$$

$$x_o(t) = \frac{1}{2} [x(t) - x(-t)]$$

$x(t)$ is even when:

$$x(t) = x(-t)$$

$x(t)$ is odd when:

$$x(t) = -x(-t)$$

periodic vs. Nonperiodic

$$x(t) = A_0 \cos(\omega_0 t + \theta)$$

$$x(t) = A_0 \cos(2\pi f_0 t + \theta)$$

Amplitude

frequency \rightarrow Hz

$$f_0 = \frac{1}{T_0}$$

$$\text{Hz} = 1 \text{ cycle/s}$$

$$\omega_0 = 2\pi f_0 \text{ (rad/s)}$$

$$\cos \omega_0 t = \frac{1}{2} e^{j\omega_0 t} + \frac{1}{2} e^{-j\omega_0 t}$$

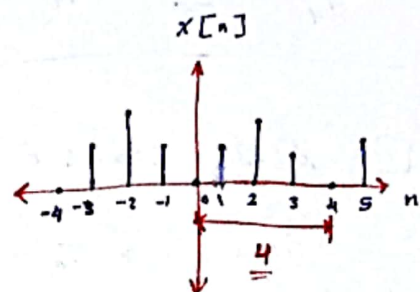
$$\sin \omega_0 t = \frac{1}{2} e^{j\omega_0 t} - \frac{1}{2} e^{-j\omega_0 t}$$

$$x[n] = x[n+N]$$

$$x[0] = x[4] = x[0+4]$$

$$x[1] = x[5] = x[1+4]$$

$N=4$ هذا يعني أنها تتكرر كل



$$x(t) = \cos(\omega_0 t + \theta)$$

$$\frac{1}{f_0} = T_0 = \frac{2\pi}{\omega_0}$$

$$x(t) = x(t + T_0) \rightarrow \cos(\omega_0 t + \theta) = \cos(\omega_0(t + T_0) + \theta)$$

$$= \cos(\omega_0 t + \theta + n\omega_0 T_0)$$

$$\omega_0 T_0 = 2n\pi$$

$$T_0 = \frac{n 2\pi}{\omega_0}$$

$$x_1(t) = \cos(3.5t) \rightarrow \omega_1 = \frac{7}{2} \rightarrow T_1 = \frac{4\pi}{7}$$

$$x_2(t) = \sin(2t) \rightarrow \omega_2 = 2 \rightarrow T_2 = \frac{2\pi}{\omega_2} = \pi$$

$$x_3(t) = 2\cos\left(\frac{7t}{6}\right) \rightarrow \omega_3 = \frac{7}{6} \rightarrow T_3 = \frac{12\pi}{7}$$

[5]

[2]

$$x_4(t) = x_1(t) + x_3(t) \\ = \cos(3.5t) + \sin(2t)$$

$$\frac{T_1}{T_2} = \frac{\frac{4\pi}{3}}{\pi} = \frac{4}{3}$$

$$\omega_5 = 5\pi \rightarrow T_5 = \frac{2\pi}{5\pi} = \frac{2}{5}$$

$$x_5(t) = x_1(t) + x_4(t)$$

$$\frac{T_1}{T_4} = \frac{\frac{4\pi}{3}}{\frac{2}{5}} = \frac{20\pi}{14}$$

$$[1] \quad x(t) = \cos\left(t + \frac{\pi}{4}\right)$$

$$\omega_0 = 1 \rightarrow T_0 = \frac{2\pi}{\omega_0} = 2\pi$$

$$[2] \quad x_1(t) = \sin \frac{2\pi}{3} t$$

$$\omega_0 = \frac{2\pi}{3} \rightarrow T_0 = \frac{2\pi}{\omega_0} = \frac{2\pi}{\frac{2\pi}{3}} = 3$$

$$[3] \quad x_2(t) = \sin \frac{\pi}{4} t$$

$$\omega_0 = \frac{\pi}{4} \rightarrow T_0 = \frac{2\pi}{\omega_0} = \frac{2\pi}{\frac{\pi}{4}} = 8$$

$$x(t) = \sin \frac{2\pi}{3} t + \sin \frac{\pi}{4} t$$

$$\frac{T_1}{T_2} = \frac{3}{8} \rightarrow 8T_1 = 3T_2 \\ 24 = 24$$

* Power vs. Energy

$$E = \int_{-\infty}^{\infty} |x(t)|^2 dt \quad 0 < E < \infty$$

$$P = \lim_{T \rightarrow \infty} \frac{E}{T} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-\infty}^{\infty} |x(t)|^2 dt \quad 0 < P < \infty$$

for Periodic
Signal

$$\rightarrow P_{av} = \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^2 dt \\ = \frac{1}{T} \int_0^T |x(t)|^2 dt$$

6

3

$$x(t) = e^{-at} u(t)$$

$$E = \int_{-\infty}^{\infty} |x(t)|^2 dt$$

$$= \int_0^{\infty} |x(t)|^2 dt = \int_0^{\infty} |e^{-at}|^2 dt = \int_0^{\infty} |e^{-2at}| dt$$

بالتكامل من 0 إلى ∞ بسبب $u(t)$

حداتها 0 ← ∞

$$= -\frac{1}{2a} e^{-2at} \Big|_0^{\infty} = -\frac{1}{2a} [e^{-2a(\infty)} - e^{-2a(0)}] = \frac{1}{2a}$$

$$\underline{P_{av} = 0} \rightarrow \text{لا يوجد } E \text{ متوسطة}$$

$$x(t) = A \cos \omega_0 t$$

$$\cos^2 x = \frac{1}{2} + \frac{1}{2} \cos 2x$$

$$= \frac{1}{T_0} \int_0^{T_0} A^2 \cos^2 \omega_0 t dt$$

$$\sin^2 x = \frac{1}{2} - \frac{1}{2} \cos 2x$$

$$= \frac{1}{T_0} \int_0^{T_0} A^2 \left[\frac{1}{2} + \frac{1}{2} \cos 2\omega_0 t \right] dt$$

$$= \frac{A^2}{T_0} \int_0^{T_0} \frac{1}{2} dt + \int_0^{T_0} \frac{1}{2} \cos 2\omega_0 t dt$$

$$= \frac{A^2}{T_0} \left[\frac{1}{2} t \right]_0^{T_0} + \frac{1}{4\omega_0} \sin 2\omega_0 t \Big|_0^{T_0}$$

if $T_0 = 2\pi/\omega_0$

$$= \frac{A^2 \omega_0}{2\pi} \left(\frac{1}{2} \cdot \frac{2\pi}{\omega_0} - 0 \right) + \left(\frac{1}{4\omega_0} \sin 2\omega_0 \frac{2\pi}{\omega_0} - 0 \right)$$

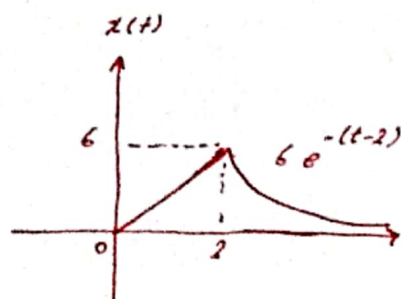
$$\begin{aligned} \sin(0) &= 0 \\ \sin(4\pi) &= 0 \end{aligned}$$

* Power vs. Energy signal

if the signal is sinusoidal:

$$P_{av} = \frac{A^2}{2}$$

Ex:



$$x(t) = \begin{cases} 3t & 0 \leq t \leq 2 \\ 6e^{-(t-2)} & 2 \leq t \\ 0 & \text{o.w} \end{cases}$$

$$\begin{aligned} E &= \int_{-\infty}^{\infty} |x(t)|^2 dt \\ &= \int_0^2 (3t)^2 dt + \int_2^{\infty} (6e^{-(t-2)})^2 dt \\ &= \int_0^2 9t^2 dt + \int_2^{\infty} 36e^{-2t+4} dt = \frac{9t^3}{3} \Big|_0^2 + 36 \int_2^{\infty} e^{-2t} \cdot e^4 dt \\ &= \frac{9t^3}{3} \Big|_0^2 + 36e^4 \int_2^{\infty} e^{-2t} dt = \frac{9}{3} [8-0] + 36 \cdot e^4 \cdot \frac{1}{2} e^{-2t} \Big|_2^{\infty} \\ &= 24 + 36 \cdot \frac{e^4}{2} [e^{-4}] = 42 \text{ J} \end{aligned}$$

Ex: $x_2(t) = 4 \cos\left(\frac{2\pi}{10} t\right)$

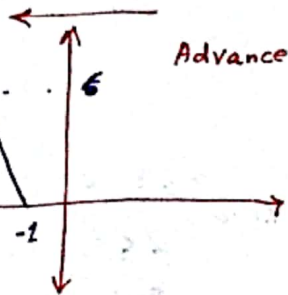
$$P_{av} = \frac{(4)^2}{2} = 8 \text{ W}$$

$$P_{av} = \frac{1}{T_0} \int_{-T_0/2}^{T_0/2} (x(t))^2 dt = \frac{1}{T_0} \int_{-T_0/2}^{T_0/2} 16 \cos^2\left(\frac{2\pi}{10} t\right) dt = \frac{1}{T_0} \int_{-T_0/2}^{T_0/2} 16 \left(\frac{1}{2} + \frac{1}{2} \cos\left(\frac{4\pi}{10} t\right)\right) dt$$

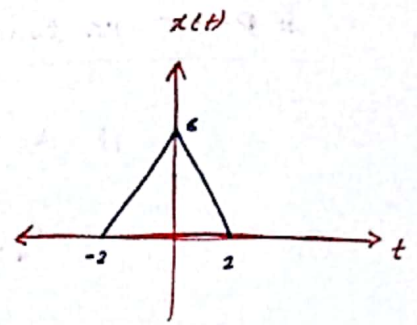
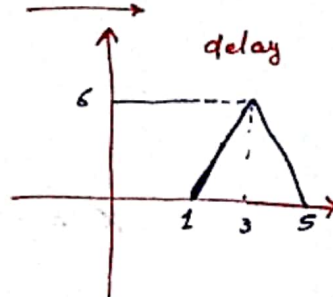
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Signal Time Transformations* Time-shifting:

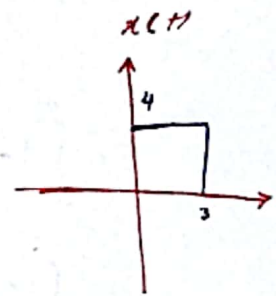
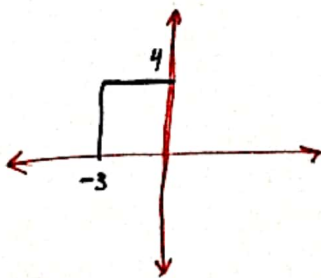
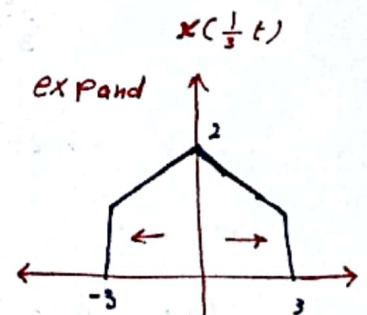
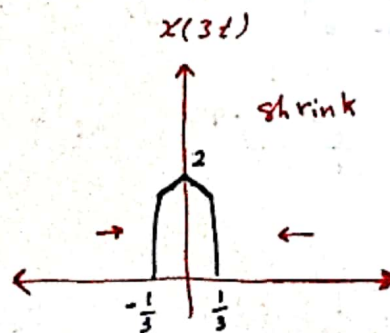
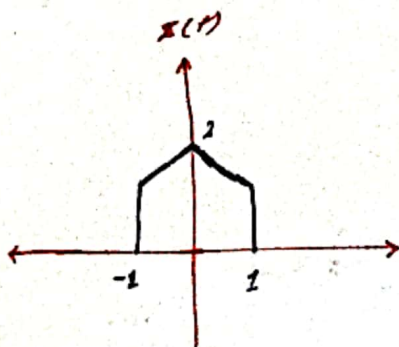
$$y(t) = x(t+3)$$



$$y(t) = x(t-3)$$

* Time-Reversal:

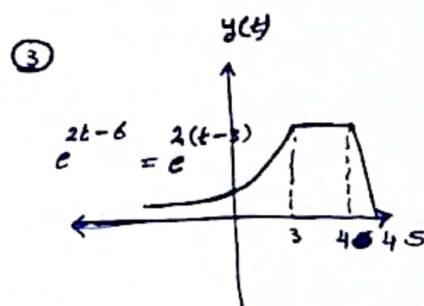
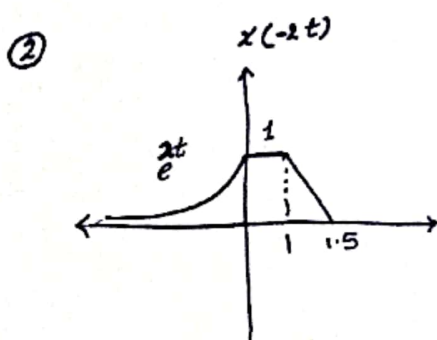
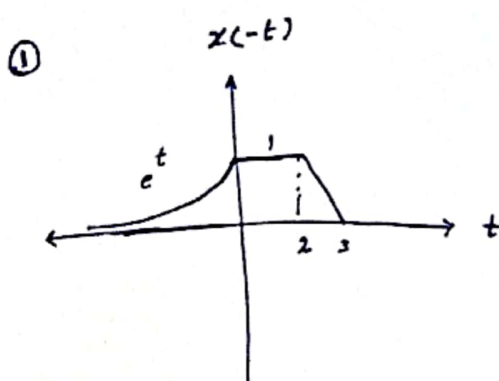
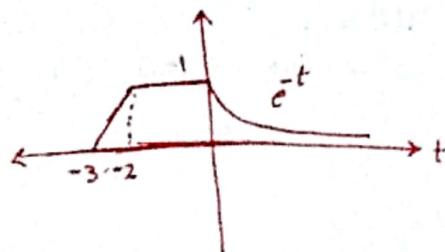
$$y(t) = x(-t)$$

* Time-scaling:

operations:

* Combined Transformation:

Ex:

 $x(t)$ Find $y(t) = x(-2t+6) = x(-2(t-3))$ 

نفسى للعادة فقط بدون رسم

$$x(t) = \begin{cases} t+3 & -3 \leq t \leq -1 \\ 1 & -2 \leq t \leq 0 \\ e^{-t} & 0 \leq t \end{cases}$$

① $x(-t) = \begin{cases} -t+3 & 3 \geq -t \geq 2 \\ 1 & 2 \geq t \geq 0 \\ e^t & t \leq 0 \end{cases}$

② $x(-2t) = \begin{cases} -2t+3 & 1.5 \geq t \geq 1 \\ 1 & 1 \geq t \geq 0 \\ e^{2t} & t \leq 0 \end{cases}$

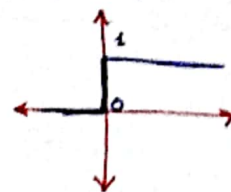
③ $x(-2(t-3)) = \begin{cases} -2(t-3)+3 & 1.5 \leq t-3 \leq 1 \\ 1 & 0 \leq t-3 \leq 1 \\ e^{2(t-3)} & t-3 \leq 0 \end{cases}$

$$= \begin{cases} -2t+9 & 4.5 \leq t \leq 4 \\ 1 & 0 \leq t \leq 4 \\ e^{2t-6} & t \leq 3 \end{cases}$$

Elementary Signals:

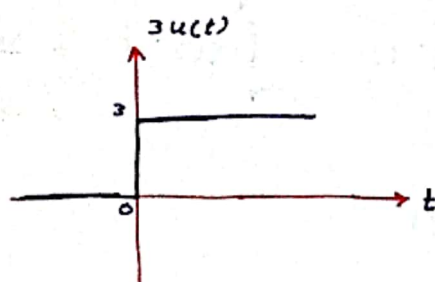
$0 \leq t < \infty$ ← تستخدم في التعريف 1 Unit step function:

$$u(t) = \begin{cases} 1 & t \geq 0 \\ 0 & \text{o.w} \end{cases}$$

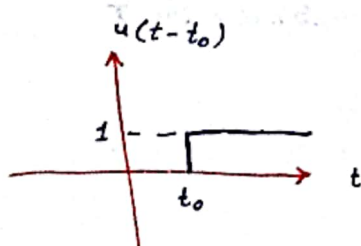


* Elementary signals :

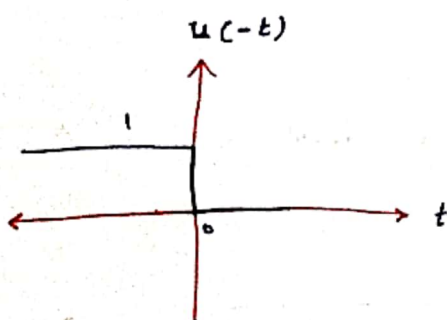
A) Unit step function :



$$u(t) = \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$$



$$u(t - t_0) = \begin{cases} 1 & t \geq t_0 \\ 0 & t < t_0 \end{cases}$$



$$u(-t) = \begin{cases} 1 & t \leq 0 \\ 0 & t > 0 \end{cases}$$

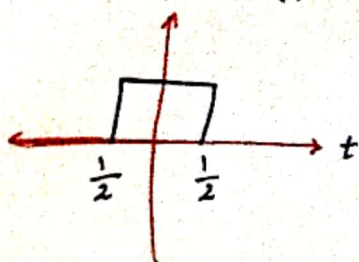
$$x(t) = \begin{cases} \cos 3t & 0 \leq t \\ 0 & \text{o.w} \end{cases}$$

↓

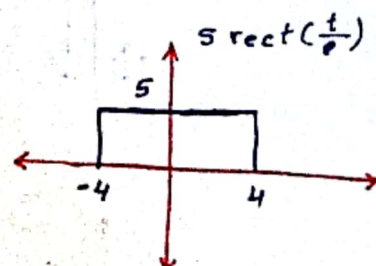
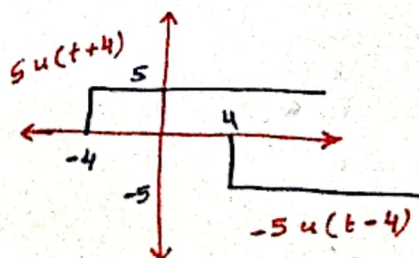
$$x(t) = \cos 3t \cdot u(t) \rightarrow \text{تجعل الزمن من 0 إلى } \infty$$

B) Pulse wave, rect function, $\Pi(t)$

$$x(t) = \text{rect}(t)$$



$$x(t) = 5 \text{rect}\left(\frac{t}{8}\right) = 5u(t+4) - 5u(t-4)$$



Find E or P_{av} for signal give as:

① $x(t) = 5 \text{ rect}\left(\frac{t}{8}\right)$

$$E = \int_{-4}^4 |x(t)|^2 dt = \int_{-4}^4 (5)^2 dt = 25 [4 - (-4)] = 25 \times 8 = 200 \text{ J}$$

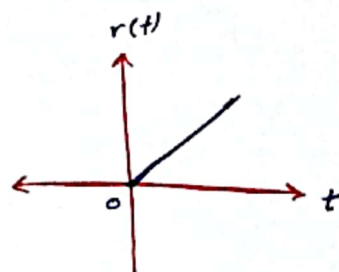
② $x(t) = 5 \text{ rect}\left(\frac{t-3}{8}\right)$

$$E = \int_{-1}^7 (5)^2 dt = 25 \times 8 = 200 \text{ J}$$

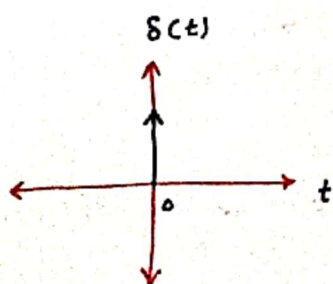
c) ramp function.

$$r(t) = t u(t)$$

$$r(t) = \int_{-\infty}^t u(\tau) d\tau = t u(t)$$



D) Impulse function, delta function:

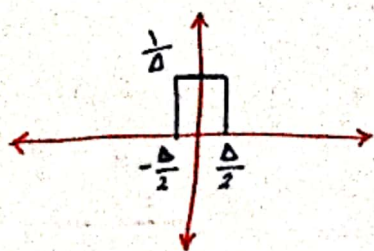


$$\delta(t) = \begin{cases} \infty & t=0 \\ 0 & \text{o.w} \end{cases}$$

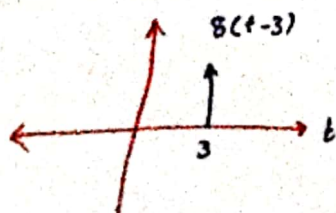
even function

$$\delta(t) = \frac{du(t)}{dt}$$

$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

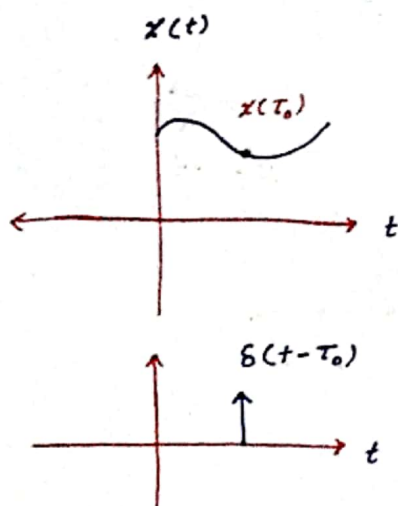


$$\int_{-1}^1 \delta(t-3) dt = 1$$



$$\int_{-1}^2 \delta(t-3) dt = 0$$

13



$$\int_{-\infty}^{\infty} x(t) \delta(t - t_0) dt = x(t_0)$$

sampling
↑

$$\int_{-\infty}^{\infty} x(t) \delta(t - t_0) dt = x(t_0) \underbrace{\int_{-\infty}^{\infty} \delta(t - t_0) dt}_1$$

$$\delta(at) = \frac{1}{|a|} \delta(t) \rightarrow \text{scaling}$$

$$Ex_1: x(t) = \int_1^2 t^2 \delta(2t - 3) dt$$

$$x(t) = \int_1^2 t^2 \delta(2(t - 1.5)) dt = \frac{1}{2} t^2 \Big|_{1.5} = \frac{1}{2} (1.5)^2 = \frac{9}{8}$$

$$Ex_2: \int_{-1}^1 (3t^2 + 1) \delta(t) dt$$

$$= (3t^2 + 1) \Big|_{t=0} = 1$$

$$Ex_3: \int_1^2 (3t^2 + 1) \delta(t) dt$$

$$= (3t^2 + 1) \Big|_{t=0} = 0$$

$$Ex_4: \int_{-\infty}^{\infty} e^{-t} \delta(2t - 2) dt$$

$$= \frac{1}{2} e^{-t} \Big|_{t=1} = \frac{1}{2} e^{-1}$$

E) Complex Exponential,

$$x(t) = e^{j\omega_0 t} = \cos \omega_0 t + j \sin \omega_0 t$$

$$\omega_0 = \frac{2\pi}{T_0}$$

$$T_0 = \frac{2\pi}{\omega_0}$$

Real Exponential:

$$x(t) = e^{at}$$

decreasing $\rightarrow -a$ increasing $\rightarrow a$

General Exponential,

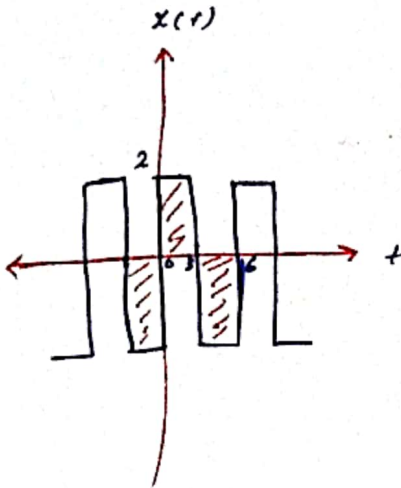
$$x(t) = e^{st} = e^{(\sigma + j\omega)t} = e^{\sigma t} \cdot e^{j\omega t} = e^{\sigma t} (\cos \omega t + j \sin \omega t)$$

15

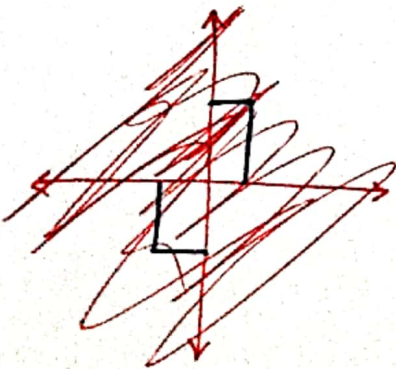
signal

الأربعاء

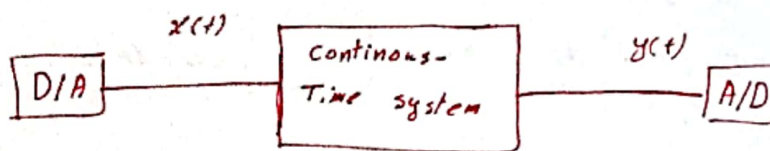
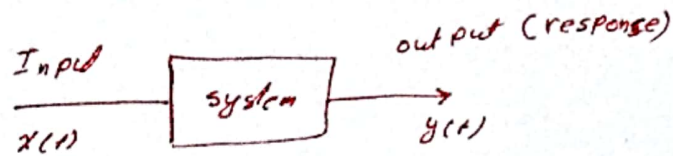
20/3
22



$$\frac{1}{6} \left(\int_{-3}^0 (-2)^2 dt + \int_0^3 (2)^2 dt \right) \text{ or } \frac{1}{6} \left(\int_0^3 (2)^2 dt + \int_3^6 (-2)^2 dt \right)$$



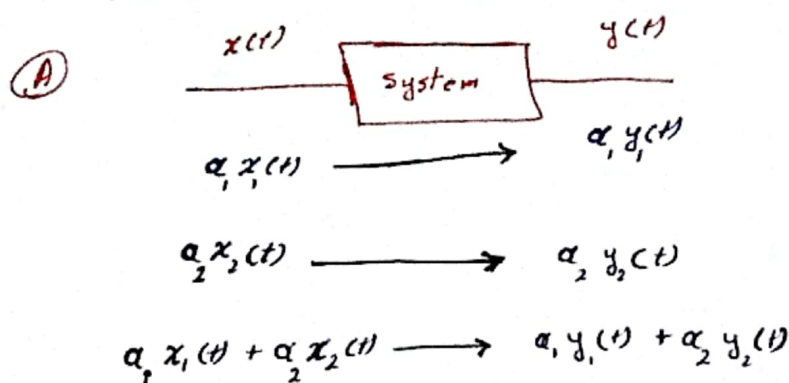
system classifications :



* Classification of systems:

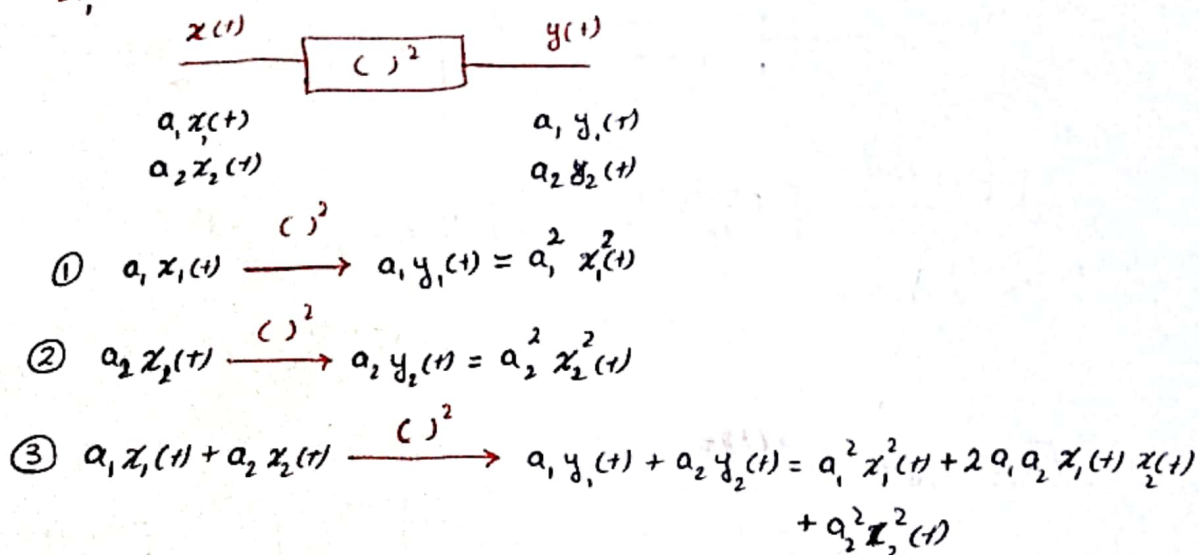
- (A) Linear v.s. non-linear
- (B) Time invariant v.s. Time variant (varying)
- (C) Dynamic v.s. static
(memory) (memoryless)
- (D) Causal v.s. Non-Causal
- (E) Invertible v.s. Non-Invertible
- (F) Stable v.s. unstable

Linear v.s. Non-linear:



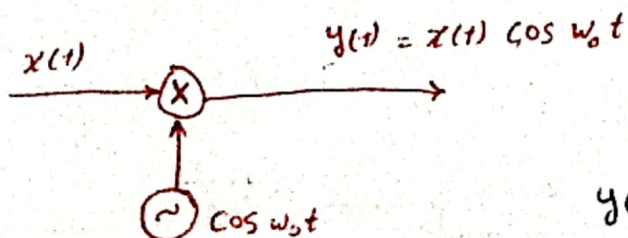
يجب أن يكون مجموع الإشارات هو نفسه وأن يكون له (Scaling) في المخرجات بنفسه مقدرة في المدخلات

Ex:



ليست Linear

Ex: Amplitude Modulation:



$$\begin{aligned}
 y(t) &= [a_1 x_1(t) + a_2 x_2(t)] \cos w_0 t \\
 &= a_1 x_1(t) \cos w_0 t + a_2 x_2(t) \cos w_0 t \\
 &= a_1 y_1(t) + a_2 y_2(t)
 \end{aligned}$$

ليس Linear

$$Ex_3: y(t) = \frac{1}{T} \int_{t-T}^t x(\tau) d\tau + B$$

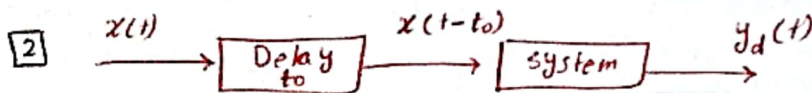
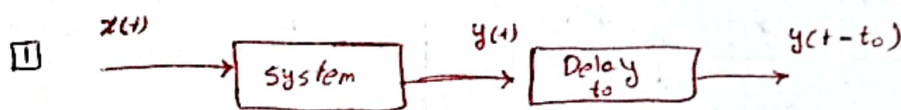
linear ليست #

$$Ex_4: y(t) = |x(t)|$$

linear ليست #

(B) Time-Varying v.s. Time-Invariant

إذا تم حدوث shift في المدخلات يجب حدوث نفسه في المخرجات



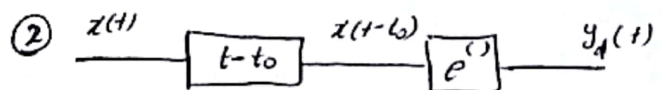
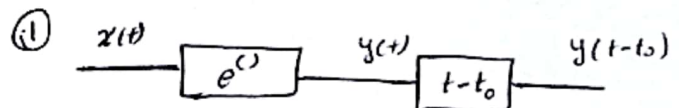
Time-Invariant , system , إذا تم تحقيق المعادلة فإن $y_d(t) = y(t-t_0)$ #

$$Ex_1: y(t) = e^{x(t)}$$

$$① y_1(t) = e^{x(t-t_0)}$$

$$② y_2(t) = e^{x(t-t_0)}$$

$$③ y_1(t) \stackrel{?}{=} y_2(t) \checkmark$$



Time-Invariant \checkmark #

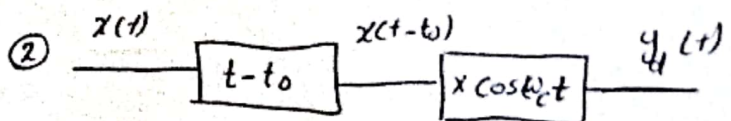
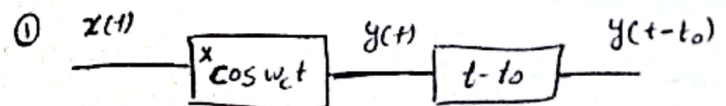
Ex_2 : Amplitude Modulation

$$y(t) = x(t) \cos \omega_c t$$

$$① y_1(t) = x(t-t_0) \cos \omega_c (t-t_0)$$

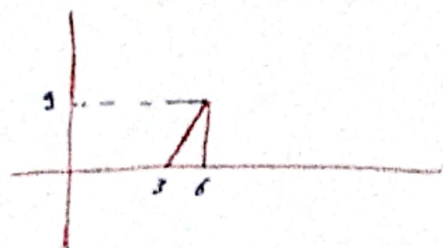
$$② y_2(t) = x(t-t_0) \cos \omega_c t$$

$$③ y_1(t) \stackrel{?}{=} y_2(t) \times$$



Time-Varying \checkmark #

#.w



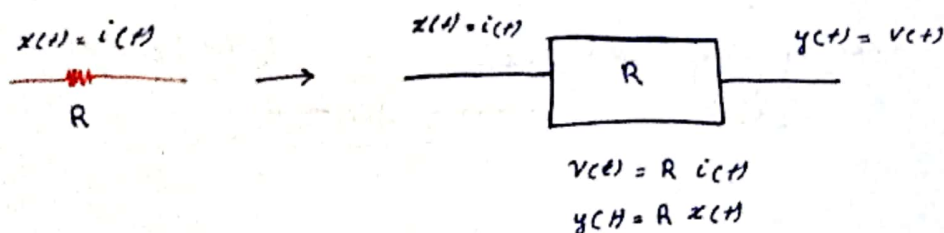
$$E = \int_3^6 (3t-9)^2 dt = 81 J$$

$$P_{av} = \lim_{T \rightarrow \infty} \frac{E}{T} = 0$$

$$= \lim_{T \rightarrow \infty} \frac{81}{T} = 0$$

③ Memory v.s. Memoryless:

* Memoryless: \rightarrow يعتمد t في اللحظة معينة



* Memory: \rightarrow يعتمد t في الماضي

$$y(t) = \sum_{i=0}^N a_i x(t - T_0)$$

$$y(5) = \sum_{i=0}^N a_i x(5 - T_0)$$

④ Causal v.s. Non causal

المرتبطة

* كل الإشارات الفيزيائية

* Causal:

$$y(t_0) = \frac{1}{2} x'(t_0) + x(t_0)$$

$$y(t_0) = \frac{4}{5} x(t_0 - 2) + x(t_0) \rightarrow \text{Memory}$$

* كل Memoryless يعتبر Causal فقط

* Non causal:

$$y(t) = x(t+5)$$

* يعتمد على المستقبل