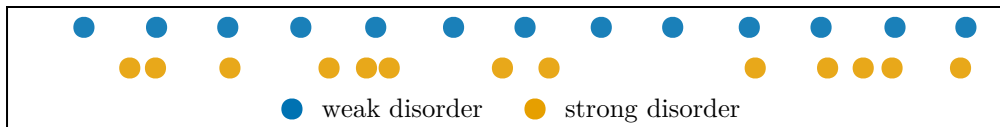


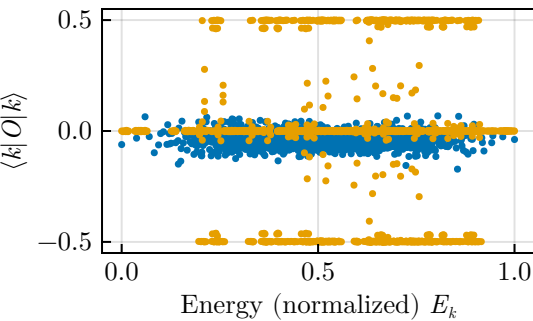
(a)

Positions



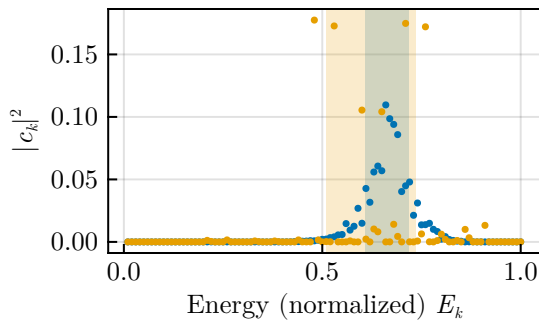
(b)

Eigenstate expectation



(c)

Eigenstate occupation



(d)

Time trace

