### Spatial Point Processes

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## What is a spatial point pattern?

- A spatial point pattern is a dataset giving the observed spatial locations of things or events.
- One important task is to identify spatial trends in the density of points.

# Types of points

- The points in a point pattern may carry all kind of attributes.
- These attributes are called marks

## Example

Introduction 000

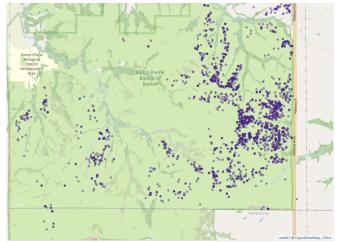


Fig 1. Location points for Grasshopper Sparrows in the Konza Prairie Biological Station located in Kansas from 2013 to 2021.

#### Point Process definition

A point process is a random mechanism whose outcome is a point pattern.

 We want to know the mechanism behind the generation of the points, not the points themselves.



### Basics

• Suppose Area A is a subset of a Euclidean space; Then we can define the event  $\epsilon$  of a point  $X_i$  for i=1,2,...,n as:

$$\epsilon_{X_n}(A) = \begin{cases} 1 & \text{if } X_n \in A \\ 0 & \text{if } X_n \notin A \end{cases}$$

 $\bullet$  If we define the counting measure N, we can get the random number of points which fall in the Area A:

$$N(A) = \sum_{n} \epsilon_{X_n(A)}$$



• We define intensity  $\lambda$  as the expected number of points falling in the area A.

$$\mu(A) = EN(A) = \lambda$$

- Also called Complete Spatial Randomness (CSR)
- Has two key properties:
  - Homogeneity: Points have no preference for any spatial location
  - Independence: Points have no influence on the location of other points

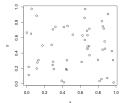
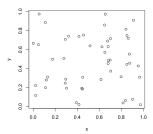


Fig 2. Simulation of CSR with 50 points



```
set.seed(2024)
x <- runif(50, 0, 1)
y <- runif(50, 0, 1)
plot(x,y)</pre>
```



- We define a inhomogeneous Poisson point process (IPPP) when intensity  $\lambda$  is **spatially varying**.
- Key properties:
  - Intensity function: The expected number of points falling in a region A is the integral  $\mu = \int_A \lambda(u) du$
  - Independence: Random patterns are independent of each other



## Recall the example

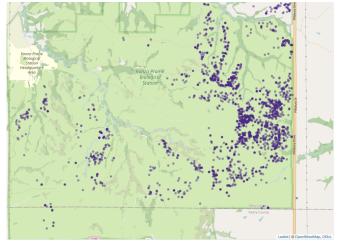


Fig 1. Location points for Grasshopper Sparrows in the Konza Prairie Biological Station located in Kansas from 2013 to 2021.

## Building a Inhomogeneous Point Process

- Lewis-Shedler rejection method (1979):
  - We start by simulating a homogeneous Poisson process with intensity  $\lambda_{\text{max}}$ .
  - We retain each event  $\epsilon$  of the homogeneous process with probability  $\frac{\lambda(\epsilon)}{\lambda_{\max}}.$



• First, we will create our intensity function lambda. In this case,  $(xy)^2$ :

```
set.seed(2024)
lambda <- function(x,y){
(x*y)*(x*y)
```

 We create a matrix points for the points that we will generate:

```
points <- matrix(NA, ncol = 2, n = 50)</pre>
```

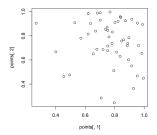
We generate the for loop to create our points:

```
for(i in 1:50){
  repeat{
  x <- runif(1, 0, 1)
  y <- runif(1, 0, 1)
  if(runif(1) < lambda(x,y)) {
   points[i,] <- c(x,y)
  break}
  }
}</pre>
```



# Building a Inhomogeneous Point Process

We plot matrix points for the points that we generate: plot(points[,1],points[,2])



## Getting into the Point Process itself

- We know that our points are being generated from an intensity  $\lambda$ . Can we visualize our intensity function?
- We will start with a  $10 \times 10$  grid:

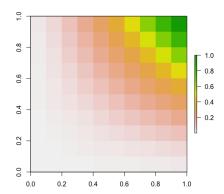
```
# creating grid
x <- seq(from = 0.1, to = 1, by = 0.1)
y <- seq(from = 0.1, to = 1, by = 0.1)
# giving values to all grids
newp <- outer(lambda(x,1), lambda(1,y))
newp <- apply(newp, 2, rev)
newp</pre>
```

# Getting into the Point Process itself

• Now we use the raster package:

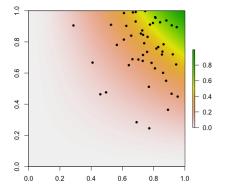
```
# loading library
library(raster)
r <- raster(nrows=10, ncols=10, xmn=0,
xmx=1, ymn=0, ymx=1)
vals <- newp
r <- setValues(r, vals)
```

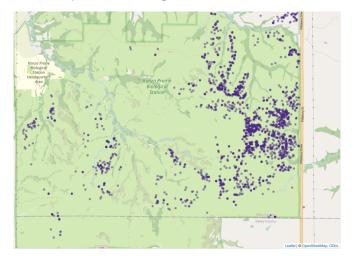
And we plot! plot(r)



# Getting into the Point Process itself

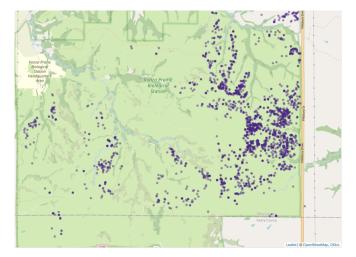
• The more grids, the smoother it gets!





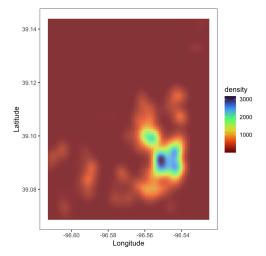


$$heta_i \sim \mathsf{Bern}(p_i)$$
  $p_i \sim \mathsf{IPPP}(\lambda_i)$  In  $\lambda_i = eta_0 + eta_1 X_i + eta_2 Y_i$ 

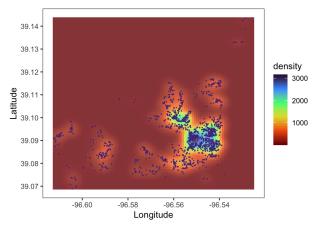




# Intensity function with a kernel density function



## Our full model...for now





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