Linear Algebra 2

Homework 4 – Coordinates and Change of Basis

Abraham Murciano

May 16, 2021

Throughout this document, $E = (e_1, e_2, \dots, e_n)$ shall denote the standard basis of \mathbb{R}^n or \mathbb{C}^n , as appropriate according to the context in which it is used.

- 1. We are given the transformation $T: \mathbb{R}^2 \to \mathbb{R}^2$ such that T(x,y) = (2x y, x 3y).
 - (a) To find $[T]_E^E$, we simply construct a matrix whose column vectors are the transformation of each of the elements in the standard basis.

$$\begin{bmatrix} T(e_1) & T(e_2) \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 1 & -3 \end{bmatrix}$$

(b) To find $[T]_C^B$, where B = ((1,1),(2,5)) and C = ((2,2),(0,1)),